
DDispatcher

Deep Modeling

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DPDispatcher is a Python package used to generate HPC (High Performance Computing) scheduler systems (Slurm/PBS/LSF/dpcloudserver) jobs input scripts and submit these scripts to HPC systems and poke until they finish.

DPDispatcher will monitor (poke) until these jobs finish and download the results files (if these jobs is running on remote systems connected by SSH).

**CHAPTER
ONE**

INSTALL DPDISPATCHER

DPDispatcher can installed by pip:

```
pip install dpdispatcher
```

To add [Bohrium](#) support, execute

```
pip install dpdispatcher[bohrium]
```

CHAPTER
TWO

GETTING STARTED

DPDispatcher provides the following classes:

- *Task* class, which represents a command to be run on batch job system, as well as the essential files need by the command.
- *Submission* class, which represents a collection of jobs defined by the HPC system. And there may be common files to be uploaded by them. DPDispatcher will create and submit these jobs when a *Submission* instance execute *run_submission* method. This method will poke until the jobs finish and return.
- *Job* class, a class used by *Submission* class, which represents a job on the HPC system. *Submission* will generate jobs' submitting scripts used by HPC systems automatically with the *Task* and *Resources*
- *Resources* class, which represents the computing resources for each job within a *submission*.

You can use DPDispatcher in a Python script to submit five tasks:

```
from dpdispatcher import Machine, Resources, Task, Submission

machine = Machine.load_from_json("machine.json")
resources = Resources.load_from_json("resources.json")

task0 = Task.load_from_json("task.json")

task1 = Task(
    command="cat example.txt",
    task_work_path="dir1/",
    forward_files=["example.txt"],
    backward_files=["out.txt"],
    outlog="out.txt",
)
task2 = Task(
    command="cat example.txt",
    task_work_path="dir2/",
    forward_files=["example.txt"],
    backward_files=["out.txt"],
    outlog="out.txt",
)
task3 = Task(
    command="cat example.txt",
    task_work_path="dir3/",
    forward_files=["example.txt"],
    backward_files=["out.txt"],
    outlog="out.txt",
```

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```

)
task4 = Task(
    command="cat example.txt",
    task_work_path="dir4/",
    forward_files=["example.txt"],
    backward_files=["out.txt"],
    outlog="out.txt",
)

task_list = [task0, task1, task2, task3, task4]

submission = Submission(
    work_base="lammps_md_300K_5GPa/",
    machine=machine,
    resources=resources,
    task_list=task_list,
    forward_common_files=["graph.pb"],
    backward_common_files=[],
)
submission.run_submission()

```

where `machine.json` is

```
{
  "batch_type": "Slurm",
  "context_type": "SSHContext",
  "local_root": "/home/user123/workplace/22_new_project/",
  "remote_root": "/home/user123/dpdispatcher_work_dir/",
  "remote_profile": {
    "hostname": "39.106.xx.xxx",
    "username": "user123",
    "port": 22,
    "timeout": 10
  }
}
```

`resources.json` is

```
{
  "number_node": 1,
  "cpu_per_node": 4,
  "gpu_per_node": 1,
  "queue_name": "GPUV100",
  "group_size": 5
}
```

and `task.json` is

```
{
  "command": "lmp -i input.lammps",
  "task_work_path": "bct-0/",
  "forward_files": [

```

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```

    "conf.lmp",
    "input.lammps"
],
"backward_files": [
    "log.lammps"
],
"outlog": "log",
"errlog": "err",
}

```

You may also submit multiple GPU jobs: complex resources example

```

resources = Resources(
    number_node=1,
    cpu_per_node=4,
    gpu_per_node=2,
    queue_name="GPU_2080Ti",
    group_size=4,
    custom_flags=["#SBATCH --nice=100", "#SBATCH --time=24:00:00"],
    strategy={
        # used when you want to add CUDA_VISIBLE_DEVICES automatically
        "if_cuda_multi_devices": True
    },
    para_deg=1,
    # will unload these modules before running tasks
    module_unload_list=["singularity"],
    # will load these modules before running tasks
    module_list=["singularity/3.0.0"],
    # will source the environment files before running tasks
    source_list=["./slurm_test.env"],
    # the envs option is used to export environment variables
    # And it will generate a line like below.
    # export DP_DISPATCHER_EXPORT=test_foo_bar_baz
    envs={"DP_DISPATCHER_EXPORT": "test_foo_bar_baz"},
)

```

The details of parameters can be found in [Machine Parameters](#), [Resources Parameters](#), and [Task Parameters](#).

SUPPORTED CONTEXTS

Context is the way to connect to the remote server. One needs to set `context_type` to one of the following values:

3.1 LazyLocal

`context_type`: LazyLocal

LazyLocal directly runs jobs in the local server and local directory.

3.2 Local

`context_type`: Local

Local runs jobs in the local server, but in a different directory. Files will be copied to the remote directory before jobs start and copied back after jobs finish.

3.3 SSH

`context_type`: SSH

SSH runs jobs in a remote server. Files will be copied to the remote directory via SSH channels before jobs start and copied back after jobs finish. To use SSH, one needs to provide necessary parameters in `remote_profile`, such as `username` and `hostname`.

It's suggested to generate `SSH keys` and transfer the public key to the remote server in advance, which is more secure than password authentication.

Note that SSH context is `non-login`, so `bash_profile` files will not be executed.

3.4 Bohrium

`context_type`: Bohrium

Bohrium is the cloud platform for scientific computing. Read Bohrium documentation for details. To use Bohrium, one needs to provide necessary parameters in `remote_profile`.

3.5 HDFS

`context_type`: HDFS

The Hadoop Distributed File System (HDFS) is a distributed file system. Read Support DPDispatcher on Yarn for details.

3.6 OpenAPI

`context_type`: OpenAPI

OpenAPI is a new way to submit jobs to Bohrium. It uses `AccessKey` instead of username and password. Read Bohrium documentation for details. To use OpenAPI, one needs to provide necessary parameters in `remote_profile`.

SUPPORTED BATCH JOB SYSTEMS

Batch job system is a system to process batch jobs. One needs to set `batch_type` to one of the following values:

4.1 Bash

`batch_type`: Shell

When `batch_type` is set to Shell, dpdispatcher will generate a bash script to process jobs. No extra packages are required for Shell.

Due to lack of scheduling system, Shell runs all jobs at the same time. To avoid running multiple jobs at the same time, one could set `group_size` to 0 (means infinity) to generate only one job with multiple tasks.

4.2 Slurm

`batch_type`: Slurm, SlurmJobArray

Slurm is a job scheduling system used by lots of HPCs. One needs to make sure slurm has been setup in the remote server and the related environment is activated.

When SlurmJobArray is used, dpdispatcher submits Slurm jobs with `job arrays`. In this way, several dpdispatcher `tasks` map to a Slurm job and a dpdispatcher `job` maps to a Slurm job array. Millions of Slurm jobs can be submitted quickly and Slurm can execute all Slurm jobs at the same time. One can use `group_size` and `slurm_job_size` to control how many Slurm jobs are contained in a Slurm job array.

4.3 OpenPBS or PBSPro

`batch_type`: PBS

OpenPBS is an open-source job scheduling of the Linux Foundation and PBS Profession is its commercial solution. One needs to make sure OpenPBS has been setup in the remote server and the related environment is activated.

Note that do not use PBS for Torque.

4.4 TORQUE

batch_type: Torque

The Terascale Open-source Resource and QUEue Manager (TORQUE) is a distributed resource manager based on standard OpenPBS. However, not all OpenPBS flags are still supported in TORQUE. One needs to make sure TORQUE has been setup in the remote server and the related environment is activated.

4.5 LSF

batch_type: LSF

IBM Spectrum LSF Suites is a comprehensive workload management solution used by HPCs. One needs to make sure LSF has been setup in the remote server and the related environment is activated.

4.6 Bohrium

batch_type: Bohrium

Bohrium is the cloud platform for scientific computing. Read Bohrium documentation for details.

4.7 DistributedShell

batch_type: DistributedShell

DistributedShell is used to submit yarn jobs. Read Support DPDispatcher on Yarn for details.

4.8 Fugaku

batch_type: Fugaku

Fujitsu cloud service is a job scheduling system used by Fujitsu's HPCs such as Fugaku, ITO and K computer. It should be noted that although the same job scheduling system is used, there are some differences in the details, Fagaku class cannot be directly used for other HPCs.

Read Fujitsu cloud service documentation for details.

4.9 OpenAPI

batch_type: OpenAPI OpenAPI is a new way to submit jobs to Bohrium. It uses [AccessKey](#) instead of username and password. Read Bohrium documentation for details.

MACHINE PARAMETERS

Note: One can load, modify, and export the input file by using our effective web-based tool [DP-GUI](#). All parameters below can be set in DP-GUI. By clicking “SAVE JSON”, one can download the input file.

machine:

type: dict
argument path: machine

batch_type:

type: str
argument path: machine/batch_type

The batch job system type. Option: OpenAPI, PBS, Fugaku, Shell, DistributedShell, Slurm, SlurmJobArray, LSF, Torque, Bohrium

local_root:

type: str | NoneType
argument path: machine/local_root

The dir where the tasks and relating files locate. Typically the project dir.

remote_root:

type: str | NoneType, optional
argument path: machine/remote_root

The dir where the tasks are executed on the remote machine. Only needed when context is not lazy-local.

clean_asynchronously:

type: bool, optional, default: False
argument path: machine/clean_asynchronously

Clean the remote directory asynchronously after the job finishes.

Depending on the value of *context_type*, different sub args are accepted.

context_type:

type: str (flag key)
argument path: machine/context_type
possible choices: *LocalContext*, *BohriumContext*, *LazyLocalContext*, *SSHContext*, *HDFSContext*, *OpenAPIContext*

The connection used to remote machine. Option: HDFSSContext, SSHContext, BohriumContext, OpenAPIContext, LazyLocalContext, LocalContext

When `context_type` is set to `LocalContext` (or its aliases `localcontext`, `Local`, `local`):

remote_profile:

type: dict, optional

argument path: `machine[LocalContext]/remote_profile`

The information used to maintain the connection with remote machine. This field is empty for this context.

When `context_type` is set to `BohriumContext` (or its aliases `bohriumcontext`, `Bohrium`, `bohrium`, `DpCloudServerContext`, `dpcloudservercontext`, `DpCloudServer`, `dpcloudserver`, `LebesgueContext`, `lebesguecontext`, `Lebesgue`, `lebesgue`):

remote_profile:

type: dict

argument path: `machine[BohriumContext]/remote_profile`

The information used to maintain the connection with remote machine.

email:

type: str, optional

argument path: `machine[BohriumContext]/remote_profile/email`

Email

password:

type: str, optional

argument path: `machine[BohriumContext]/remote_profile/password`

Password

program_id:

type: int, alias: `project_id`

argument path:

`machine[BohriumContext]/remote_profile/program_id`

Program ID

retry_count:

type: int | NoneType, optional, default: 2

argument path:

`machine[BohriumContext]/remote_profile/retry_count`

The retry count when a job is terminated

ignore_exit_code:

type: bool, optional, default: True

argument path:

`machine[BohriumContext]/remote_profile/ignore_exit_code`

The job state will be marked as finished if the exit code is non-zero when set to True. Otherwise,
the job state will be designated as terminated.

keep_backup:

type: bool, optional

argument path:
`machine[BohriumContext]/remote_profile/keep_backup`
keep download and upload zip

input_data:

type: dict
argument path: `machine[BohriumContext]/remote_profile/input_data`
Configuration of job

When `context_type` is set to `LazyLocalContext` (or its aliases `lazylocalcontext`, `LazyLocal`, `lazylocal`):

remote_profile:

type: dict, optional
argument path: `machine[LazyLocalContext]/remote_profile`
The information used to maintain the connection with remote machine. This field is empty for this context.

When `context_type` is set to `SSHContext` (or its aliases `sshcontext`, `SSH`, `ssh`):

remote_profile:

type: dict
argument path: `machine[SSHContext]/remote_profile`
The information used to maintain the connection with remote machine.

hostname:

type: str
argument path: `machine[SSHContext]/remote_profile/hostname`
hostname or ip of ssh connection.

username:

type: str
argument path: `machine[SSHContext]/remote_profile/username`
username of target linux system

password:

type: str, optional
argument path: `machine[SSHContext]/remote_profile/password`
(deprecated) password of linux system. Please use `SSH keys` instead to improve security.

port:

type: int, optional, default: 22
argument path: `machine[SSHContext]/remote_profile/port`
ssh connection port.

key_filename:

type: str | NoneType, optional, default: None

argument path:
`machine[SSHContext]/remote_profile/key_filename`

key filename used by ssh connection. If left None, find key in `~/.ssh` or use password for login

passphrase:

type: `str | NoneType`, optional, default: `None`

argument path: `machine[SSHContext]/remote_profile/passphrase`

passphrase of key used by ssh connection

timeout:

type: `int`, optional, default: `10`

argument path: `machine[SSHContext]/remote_profile/timeout`

timeout of ssh connection

totp_secret:

type: `str | NoneType`, optional, default: `None`

argument path:

`machine[SSHContext]/remote_profile/totp_secret`

Time-based one time password secret. It should be a base32-encoded string extracted from the 2D code.

tar_compress:

type: `bool`, optional, default: `True`

argument path:

`machine[SSHContext]/remote_profile/tar_compress`

The archive will be compressed in upload and download if it is `True`. If not, compression will be skipped.

look_for_keys:

type: `bool`, optional, default: `True`

argument path:

`machine[SSHContext]/remote_profile/look_for_keys`

enable searching for discoverable private key files in `~/.ssh/`

When `context_type` is set to `HDFSContext` (or its aliases `hdfscontext`, `HDFS`, `hdfs`):

remote_profile:

type: `dict`, optional

argument path: `machine[HDFSContext]/remote_profile`

The information used to maintain the connection with remote machine. This field is empty for this context.

When `context_type` is set to `OpenAPIContext` (or its aliases `openapicontext`, `OpenAPI`, `openapi`):

remote_profile:

type: `dict`, optional

argument path: `machine[OpenAPIContext]/remote_profile`

The information used to maintain the connection with remote machine. This field is empty for this context.

RESOURCES PARAMETERS

Note: One can load, modify, and export the input file by using our effective web-based tool [DP-GUI](#). All parameters below can be set in DP-GUI. By clicking “SAVE JSON”, one can download the input file for.

resources:

type: dict
argument path: resources

number_node:

type: int, optional, default: 1
argument path: resources/number_node

The number of node need for each *job*

cpu_per_node:

type: int, optional, default: 1
argument path: resources/cpu_per_node

cpu numbers of each node assigned to each job.

gpu_per_node:

type: int, optional, default: 0
argument path: resources/gpu_per_node

gpu numbers of each node assigned to each job.

queue_name:

type: str, optional, default: (empty string)
argument path: resources/queue_name

The queue name of batch job scheduler system.

group_size:

type: int
argument path: resources/group_size

The number of *tasks* in a *job*. 0 means infinity.

custom_flags:

type: `list`, optional
argument path: `resources/custom_flags`

The extra lines pass to job submitting script header

strategy:

type: `dict`, optional
argument path: `resources/strategy`

strategies we use to generation job submitting scripts.

if_cuda_multi_devices:

type: `bool`, optional, default: `False`
argument path: `resources/strategy/if_cuda_multi_devices`

If there are multiple nvidia GPUS on the node, and we want to assign the tasks to different GPUS.If true, dpdispatcher will manually export environment variable CUDA_VISIBLE_DEVICES to different task.Usually, this option will be used with Task.task_need_resources variable simultaneously.

ratio_unfinished:

type: `float`, optional, default: `0.0`
argument path: `resources/strategy/ratio_unfinished`

The ratio of *tasks* that can be unfinished.

para_deg:

type: `int`, optional, default: `1`
argument path: `resources/para_deg`

Decide how many tasks will be run in parallel.

source_list:

type: `list`, optional, default: `[]`
argument path: `resources/source_list`

The env file to be sourced before the command execution.

module_purge:

type: `bool`, optional, default: `False`
argument path: `resources/module_purge`

Remove all modules on HPC system before module load (module_list)

module_unload_list:

type: `list`, optional, default: `[]`
argument path: `resources/module_unload_list`

The modules to be unloaded on HPC system before submitting jobs

module_list:

type: `list`, optional, default: `[]`
argument path: `resources/module_list`

The modules to be loaded on HPC system before submitting jobs

envs:

type: `dict`, optional, default: {}
 argument path: `resources/envs`

The environment variables to be exported on before submitting jobs

prepend_script:

type: `list`, optional, default: []
 argument path: `resources/prepend_script`
 Optional script run before jobs submitted.

append_script:

type: `list`, optional, default: []
 argument path: `resources/append_script`
 Optional script run after jobs submitted.

wait_time:

type: `int | float`, optional, default: 0
 argument path: `resources/wait_time`

The waitting time in second after a single *task* submitted

Depending on the value of `batch_type`, different sub args are accepted.

batch_type:

type: `str` (flag key)
 argument path: `resources/batch_type`
 possible choices: `PBS`, `Fugaku`, `Slurm`, `DistributedShell`, `LSF`,
`SlurmJobArray`, `OpenAPI`, `Shell`, `Torque`, `Bohrium`

The batch job system type loaded from machine/batch_type.

When `batch_type` is set to PBS (or its alias pbs):

kwargs:

type: `dict`, optional
 argument path: `resources[PBS]/kwargs`

This field is empty for this batch.

When `batch_type` is set to Fugaku (or its alias fugaku):

kwargs:

type: `dict`, optional
 argument path: `resources[Fugaku]/kwargs`

This field is empty for this batch.

When `batch_type` is set to Slurm (or its alias slurm):

kwargs:

type: `dict`, optional

argument path: `resources[Slurm]/kwargs`
Extra arguments.
custom_gpu_line:
type: `str | NoneType`, optional, default: `None`
argument path: `resources[Slurm]/kwargs/custom_gpu_line`
Custom GPU configuration, starting with `#SBATCH`

When `batch_type` is set to `DistributedShell` (or its alias `distributedshell`):

kwargs:

type: `dict`, optional
argument path: `resources[DistributedShell]/kwargs`
This field is empty for this batch.

When `batch_type` is set to `LSF` (or its alias `lsf`):

kwargs:

type: `dict`
argument path: `resources[LSF]/kwargs`
Extra arguments.

gpu_usage:
type: `bool`, optional, default: `False`
argument path: `resources[LSF]/kwargs/gpu_usage`
Choosing if GPU is used in the calculation step.

gpu_new_syntax:
type: `bool`, optional, default: `False`
argument path: `resources[LSF]/kwargs/gpu_new_syntax`
For LFS >= 10.1.0.3, new option `-gpu` for `#BSUB` could be used. If `False`, and old syntax would be used.

gpu_exclusive:
type: `bool`, optional, default: `True`
argument path: `resources[LSF]/kwargs/gpu_exclusive`
Only take effect when new syntax enabled. Control whether submit tasks in exclusive way for GPU.

custom_gpu_line:
type: `str | NoneType`, optional, default: `None`
argument path: `resources[LSF]/kwargs/custom_gpu_line`
Custom GPU configuration, starting with `#BSUB`

When `batch_type` is set to `SlurmJobArray` (or its alias `slurmjobarray`):

kwargs:

type: `dict`, optional
argument path: `resources[SlurmJobArray]/kwargs`
Extra arguments.

```
custom_gpu_line:  
    type: str | NoneType, optional, default: None  
    argument path:  
        resources[SlurmJobArray]/kwargs/custom_gpu_line  
        Custom GPU configuration, starting with #SBATCH  
  
slurm_job_size:  
    type: int, optional, default: 1  
    argument path:  
        resources[SlurmJobArray]/kwargs/slurm_job_size  
        Number of tasks in a Slurm job
```

When `batch_type` is set to OpenAPI (or its alias `openapi`):

kwargs:

```
type: dict, optional  
argument path: resources[OpenAPI]/kwargs  
This field is empty for this batch.
```

When `batch_type` is set to Shell (or its alias `shell`):

kwargs:

```
type: dict, optional  
argument path: resources[Shell]/kwargs  
This field is empty for this batch.
```

When `batch_type` is set to Torque (or its alias `torque`):

kwargs:

```
type: dict, optional  
argument path: resources[Torque]/kwargs  
This field is empty for this batch.
```

When `batch_type` is set to Bohrium (or its aliases `bohrium`, `Lebesgue`, `lebesgue`, `DpCloudServer`, `dpcloudserver`):

kwargs:

```
type: dict, optional  
argument path: resources[Bohrium]/kwargs  
This field is empty for this batch.
```


TASK PARAMETERS

Note: One can load, modify, and export the input file by using our effective web-based tool [DP-GUI](#). All parameters below can be set in DP-GUI. By clicking “SAVE JSON”, one can download the input file.

task:

type: dict
argument path: task

command:

type: str
argument path: task/command
A command to be executed of this task. The expected return code is 0.

task_work_path:

type: str
argument path: task/task_work_path
The dir where the command to be executed.

forward_files:

type: list
argument path: task/forward_files
The files to be uploaded in task_work_path before the task executed.

backward_files:

type: list
argument path: task/backward_files
The files to be download to local_root in task_work_path after the task finished

outlog:

type: str | NoneType
argument path: task/outlog
The out log file name. redirect from stdout

errlog:

type: str | NoneType

argument path: task/errlog

The err log file name. redirect from stderr

CHAPTER
EIGHT

DPDISPATCHER API

8.1 dpdispatcher package

```
class dpdispatcher.DistributedShell(*args, **kwargs)
```

Bases: *Machine*

Methods

<code>do_submit(job)</code>	Submit th job to yarn using distributed shell.
<code>get_exit_code(job)</code>	Get exit code of the job.
<code>kill(job)</code>	Kill the job.
<code>resources_arginfo()</code>	Generate the resources arginfo.
<code>resources_subfields()</code>	Generate the resources subfields.

<code>arginfo</code>	
<code>bind_context</code>	
<code>check_finish_tag</code>	
<code>check_if_recover</code>	
<code>check_status</code>	
<code>default_resources</code>	
<code>deserialize</code>	
<code>gen_command_env_cuda_devices</code>	
<code>gen_script</code>	
<code>gen_script_command</code>	
<code>gen_script_custom_flags_lines</code>	
<code>gen_script_end</code>	
<code>gen_script_env</code>	
<code>gen_script_header</code>	
<code>gen_script_wait</code>	
<code>load_from_dict</code>	
<code>load_from_json</code>	
<code>serialize</code>	
<code>sub_script_cmd</code>	
<code>sub_script_head</code>	

`check_finish_tag(job)`

DPDispatcher

`check_status(job)`

`do_submit(job)`

Submit th job to yarn using distributed shell.

Parameters

`job`

[Job class instance] job to be submitted

Returns

`job_id: string`

submit process id

`gen_script_end(job)`

`gen_script_env(job)`

`gen_script_header(job)`

`dDispatcher.DpCloudServer`

alias of *Bohrium*

`dDispatcher.DpCloudServerContext`

alias of *BohriumContext*

`class dDispatcher.Fugaku(*args, **kwargs)`

Bases: *Machine*

Methods

`do_submit(job)`

Submit a single job, assuming that no job is running there.

`get_exit_code(job)`

Get exit code of the job.

`kill(job)`

Kill the job.

`resources_arginfo()`

Generate the resources arginfo.

`resources_subfields()`

Generate the resources subfields.

<code>arginfo</code>	
<code>bind_context</code>	
<code>check_finish_tag</code>	
<code>check_if_recover</code>	
<code>check_status</code>	
<code>default_resources</code>	
<code>deserialize</code>	
<code>gen_command_env_cuda_devices</code>	
<code>gen_script</code>	
<code>gen_script_command</code>	
<code>gen_script_custom_flags_lines</code>	
<code>gen_script_end</code>	
<code>gen_script_env</code>	
<code>gen_script_header</code>	
<code>gen_script_wait</code>	
<code>load_from_dict</code>	
<code>load_from_json</code>	
<code>serialize</code>	
<code>sub_script_cmd</code>	
<code>sub_script_head</code>	

`check_finish_tag(job)`

`check_status(job)`

`default_resources(resources)`

`do_submit(job)`

Submit a single job, assuming that no job is running there.

`gen_script(job)`

`gen_script_header(job)`

`class dpdispatcher.HDFSContext(*args, **kwargs)`

Bases: `BaseContext`

Methods

<code>check_file_exists(fname)</code>	Check whether the given file exists, often used in checking whether the belonging job has finished.
<code>download(submission[, check_exists, ...])</code>	Download backward files from HDFS root dir.
<code>machine_arginfo()</code>	Generate the machine arginfo.
<code>machine_subfields()</code>	Generate the machine subfields.
<code>upload(submission[, dereference])</code>	Upload forward files and forward command files to HDFS root dir.

bind_submission	
check_finish	
clean	
get_job_root	
load_from_dict	
read_file	
write_file	

bind_submission(*submission*)**check_file_exists**(*fname*)

Check whether the given file exists, often used in checking whether the belonging job has finished.

Parameters**fname**

[string] file name to be checked

Returns**status: boolean****clean()****download**(*submission, check_exists=False, mark_failure=True, back_error=False*)

Download backward files from HDFS root dir.

Parameters**submission**

[Submission class instance] represents a collection of tasks, such as backward file names

check_exists

[bool] whether to check if the file exists

mark_failure

[bool] whether to mark the task as failed if the file does not exist

back_error

[bool] whether to download error files

Returns**none****get_job_root()****classmethod load_from_dict**(*context_dict*)**read_file**(*fname*)**upload**(*submission, dereference=True*)

Upload forward files and forward command files to HDFS root dir.

Parameters**submission**

[Submission class instance] represents a collection of tasks, such as forward file names

dereference

[bool] whether to dereference symbolic links

Returns**none****write_file**(*fname*, *write_str*)**class** dpdispatcher.**Job**(*job_task_list*, *, *resources*, *machine=None*)Bases: **object**

Job is generated by Submission automatically. A job usually has many tasks and it may request computing resources from job scheduler systems. Each Job can generate a script file to be submitted to the job scheduler system or executed locally.

Parameters**job_task_list**

[list of Task] the tasks belonging to the job

resources

[Resources] the machine resources. Passed from Submission when it constructs jobs.

machine

[machine] machine object to execute the job. Passed from Submission when it constructs jobs.

Methods**deserialize**(*job_dict*[, *machine*]) Convert the job_dict to a Submission class object.**get_job_state**() Get the jobs.**serialize**([*if_static*]) Convert the Task class instance to a dictionary.

get_hash	
handle_unexpected_job_state	
job_to_json	
register_job_id	
submit_job	

classmethod **deserialize**(*job_dict*, *machine=None*)

Convert the job_dict to a Submission class object.

Parameters**job_dict**

[dict] the dictionary which contains the job information

machine

[Machine] the machine object to execute the job

Returns**submission**

[Job] the Job class instance converted from the job_dict

get_hash()**get_job_state()**

Get the jobs. Usually, this method will query the database of slurm or pbs job scheduler system and get the results.

Notes

this method will not submit or resubmit the jobs if the job is unsubmitted.

handle_unexpected_job_state()

job_to_json()

register_job_id(job_id)

serialize(if_static=False)

Convert the Task class instance to a dictionary.

Parameters

if_static

[bool] whether dump the job runtime infomation (job_id, job_state, fail_count, job_uuid etc.) to the dictionary.

Returns

task_dict

[dict] the dictionary converted from the Task class instance

submit_job()

class dpdispatcher.LSF(*args, **kwargs)

Bases: [Machine](#)

LSF batch.

Methods

default_resources(resources)

get_exit_code(job) Get exit code of the job.

kill(job) Kill the job.

resources_arginfo() Generate the resources arginfo.

resources_subfields() Generate the resources subfields.

arginfo	
bind_context	
check_finish_tag	
check_if_recover	
check_status	
deserialize	
do_submit	
gen_command_env_cuda_devices	
gen_script	
gen_script_command	
gen_script_custom_flags_lines	
gen_script_end	
gen_script_env	
gen_script_header	
gen_script_wait	
load_from_dict	
load_from_json	
serialize	
sub_script_cmd	
sub_script_head	

`check_finish_tag(job)`

`check_status(**kwargs)`

`default_resources(resources)`

`do_submit(**kwargs)`

Submit a single job, assuming that no job is running there.

`gen_script(job)`

`gen_script_header(job)`

`kill(job)`

Kill the job.

Parameters

`job`

[Job] job

`classmethod resources_subfields() → List[Argument]`

Generate the resources subfields.

Returns

`list[Argument]`

resources subfields

`sub_script_cmd(res)`

`sub_script_head(res)`

```
class dpdispatcher.LazyLocalContext(*args, **kwargs)
```

Bases: *BaseContext*

Run jobs in the local server and local directory.

Parameters

local_root

[str] The local directory to store the jobs.

remote_root

[str, optional] The argument takes no effect.

remote_profile

[dict, optional] The remote profile. The default is {}.

***args**

The arguments.

****kwargs**

The keyword arguments.

Methods

machine_arginfo()	Generate the machine arginfo.
machine_subfields()	Generate the machine subfields.

bind_submission	
block_call	
block_checkcall	
call	
check_file_exists	
check_finish	
clean	
download	
get_job_root	
get_return	
load_from_dict	
read_file	
upload	
write_file	

bind_submission(*submission*)

block_call(*cmd*)

block_checkcall(*cmd*)

call(*cmd*)

check_file_exists(*fname*)

check_finish(*proc*)

clean()

```

download(jobs, check_exists=False, mark_failure=True, back_error=False)

get_job_root()

get_return(proc)

classmethod load_from_dict(context_dict)

read_file(fname)

upload(jobs, dereference=True)

write_file(fname, write_str)

dpdispatcher.Lebesgue
    alias of Bohrium

dpdispatcher.LebesgueContext
    alias of BohriumContext

class dpdispatcher.LocalContext(*args, **kwargs)
    Bases: BaseContext
        Run jobs in the local server and remote directory.

```

Parameters

local_root
 [str] The local directory to store the jobs.

remote_root
 [str] The remote directory to store the jobs.

remote_profile
 [dict, optional] The remote profile. The default is {}.

***args**
 The arguments.

****kwargs**
 The keyword arguments.

Methods

machine_arginfo()	Generate the machine arginfo.
machine_subfields()	Generate the machine subfields.

<code>bind_submission</code>	
<code>block_call</code>	
<code>block_checkcall</code>	
<code>call</code>	
<code>check_file_exists</code>	
<code>check_finish</code>	
<code>clean</code>	
<code>download</code>	
<code>get_job_root</code>	
<code>get_return</code>	
<code>load_from_dict</code>	
<code>read_file</code>	
<code>upload</code>	
<code>write_file</code>	

```
bind_submission(submission)
block_call(cmd)
block_checkcall(cmd)
call(cmd)
check_file_exists(fname)
check_finish(proc)
clean()
download(submission, check_exists=False, mark_failure=True, back_error=False)
get_job_root()
get_return(proc)
classmethod load_from_dict(context_dict)
read_file(fname)
upload(submission)
write_file(fname, write_str)

class dppdispatcher.Machine(*args, **kwargs)
    Bases: object
```

A machine is used to handle the connection with remote machines.

Parameters

`context`

[SubClass derived fromBaseContext] The context is used to mainatin the connection with remote machine.

Methods

<code>do_submit(job)</code>	Submit a single job, assuming that no job is running there.
<code>get_exit_code(job)</code>	Get exit code of the job.
<code>kill(job)</code>	Kill the job.
<code>resources_arginfo()</code>	Generate the resources arginfo.
<code>resources_subfields()</code>	Generate the resources subfields.

<code>arginfo</code>	
<code>bind_context</code>	
<code>check_finish_tag</code>	
<code>check_if_recover</code>	
<code>check_status</code>	
<code>default_resources</code>	
<code>deserialize</code>	
<code>gen_command_env_cuda_devices</code>	
<code>gen_script</code>	
<code>gen_script_command</code>	
<code>gen_script_custom_flags_lines</code>	
<code>gen_script_end</code>	
<code>gen_script_env</code>	
<code>gen_script_header</code>	
<code>gen_script_wait</code>	
<code>load_from_dict</code>	
<code>load_from_json</code>	
<code>serialize</code>	
<code>sub_script_cmd</code>	
<code>sub_script_head</code>	

```

alias: Tuple[str, ...] = ()

classmethod arginfo()

bind_context(context)

abstract check_finish_tag(**kwargs)

check_if_recover(submission)

abstract check_status(job)

default_resources(res)

classmethod deserialize(machine_dict)

abstract do_submit(job)
    Submit a single job, assuming that no job is running there.

gen_command_env_cuda_devices(resources)

gen_script(job)

```

```
gen_script_command(job)
gen_script_custom_flags_lines(job)
gen_script_end(job)
gen_script_env(job)
abstract gen_script_header(job)
gen_script_wait(resources)
get_exit_code(job)
```

Get exit code of the job.

Parameters

job
[Job] job

```
kill(job)
```

Kill the job.

If not implemented, pass and let the user manually kill it.

Parameters

job
[Job] job

```
classmethod load_from_dict(machine_dict)
```

```
classmethod load_from_json(json_path)
```

```
options = {'Bohrium', 'DistributedShell', 'Fugaku', 'LSF', 'OpenAPI', 'PBS',
'Shell', 'Slurm', 'SlurmJobArray', 'Torque'}
```

```
classmethod resources_arginfo() → Argument
```

Generate the resources arginfo.

Returns

Argument
resources arginfo

```
classmethod resources_subfields() → List[Argument]
```

Generate the resources subfields.

Returns

list[Argument]
resources subfields

```
serialize(if_empty_remote_profile=False)
```

```
sub_script_cmd(res)
```

```
sub_script_head(res)
```

```

subclasses_dict = {'Bohrium': <class 'dpdispatcher.dp_cloud_server.Bohrium'>,
'DistributedShell': <class 'dpdispatcher.distributed_shell.DistributedShell'>,
'DpCloudServer': <class 'dpdispatcher.dp_cloud_server.Bohrium'>, 'Fugaku': <class
'dpdispatcher.fugaku.Fugaku'>, 'LSF': <class 'dpdispatcher.lsf.LSF'>, 'Lebesgue':
<class 'dpdispatcher.dp_cloud_server.Bohrium'>, 'OpenAPI': <class
'dpdispatcher.openapi.OpenAPI'>, 'PBS': <class 'dpdispatcher.pbs.PBS'>, 'Shell':
<class 'dpdispatcher.shell.Shell'>, 'Slurm': <class 'dpdispatcher.slurm.Slurm'>,
'SlurmJobArray': <class 'dpdispatcher.slurm.SlurmJobArray'>, 'Torque': <class
'dpdispatcher.pbs.Torque'>, 'bohrium': <class
'dpdispatcher.dp_cloud_server.Bohrium'>, 'distributedshell': <class
'dpdispatcher.distributed_shell.DistributedShell'>, 'dpcloudserver': <class
'dpdispatcher.dp_cloud_server.Bohrium'>, 'fugaku': <class
'dpdispatcher.fugaku.Fugaku'>, 'lebesgue': <class
'dpdispatcher.dp_cloud_server.Bohrium'>, 'lsf': <class 'dpdispatcher.lsf.LSF'>,
'openapi': <class 'dpdispatcher.openapi.OpenAPI'>, 'pbs': <class
'dpdispatcher.pbs.PBS'>, 'shell': <class 'dpdispatcher.shell.Shell'>, 'slurm':
<class 'dpdispatcher.slurm.Slurm'>, 'slurmjobarray': <class
'dpdispatcher.slurm.SlurmJobArray'>, 'torque': <class 'dpdispatcher.pbs.Torque'>}

class dpdispatcher.OpenAPI(*args, **kwargs)
Bases: Machine

```

Methods

<code>do_submit(job)</code>	Submit a single job, assuming that no job is running there.
<code>get_exit_code(job)</code>	Get exit code of the job.
<code>kill(job)</code>	Kill the job.
<code>resources_arginfo()</code>	Generate the resources arginfo.
<code>resources_subfields()</code>	Generate the resources subfields.

<code>arginfo</code>	
<code>bind_context</code>	
<code>check_finish_tag</code>	
<code>check_if_recover</code>	
<code>check_status</code>	
<code>default_resources</code>	
<code>deserialize</code>	
<code>gen_command_env_cuda_devices</code>	
<code>gen_local_script</code>	
<code>gen_script</code>	
<code>gen_script_command</code>	
<code>gen_script_custom_flags_lines</code>	
<code>gen_script_end</code>	
<code>gen_script_env</code>	
<code>gen_script_header</code>	
<code>gen_script_wait</code>	
<code>load_from_dict</code>	
<code>load_from_json</code>	
<code>map_dp_job_state</code>	
<code>serialize</code>	
<code>sub_script_cmd</code>	
<code>sub_script_head</code>	

`check_finish_tag(job)`

`check_if_recover(submission)`

`check_status(job)`

`do_submit(job)`

Submit a single job, assuming that no job is running there.

`gen_local_script(job)`

`gen_script(job)`

`gen_script_header(job)`

`get_exit_code(job)`

Get exit code of the job.

Parameters

`job`

[Job] job

Returns

`int`

exit code

`kill(job)`

Kill the job.

Parameters

```

job
    [Job] job

static map_dp_job_state(status, exit_code, ignore_exit_code=True)

class dpdispatcher.OpenAPIContext(*args, **kwargs)
    Bases: BaseContext

```

Methods

<code>machine_arginfo()</code>	Generate the machine arginfo.
<code>machine_subfields()</code>	Generate the machine subfields.

<code>bind_submission</code>	
<code>check_file_exists</code>	
<code>check_finish</code>	
<code>check_home_file_exists</code>	
<code>clean</code>	
<code>download</code>	
<code>load_from_dict</code>	
<code>read_file</code>	
<code>read_home_file</code>	
<code>upload</code>	
<code>upload_job</code>	
<code>write_file</code>	
<code>write_home_file</code>	
<code>write_local_file</code>	

```

bind_submission(submission)
check_file_exists(fname)
check_home_file_exists(fname)
clean()
download(submission)
classmethod load_from_dict(context_dict)
read_file(fname)
read_home_file(fname)
upload(submission)
upload_job(job, common_files=None)
write_file(fname, write_str)
write_home_file(fname, write_str)
write_local_file(fname, write_str)

class dpdispatcher.PBS(*args, **kwargs)
    Bases: Machine

```

Methods

<code>do_submit(job)</code>	Submit a single job, assuming that no job is running there.
<code>get_exit_code(job)</code>	Get exit code of the job.
<code>kill(job)</code>	Kill the job.
<code>resources_arginfo()</code>	Generate the resources arginfo.
<code>resources_subfields()</code>	Generate the resources subfields.

<code>arginfo</code>	
<code>bind_context</code>	
<code>check_finish_tag</code>	
<code>check_if_recover</code>	
<code>check_status</code>	
<code>default_resources</code>	
<code>deserialize</code>	
<code>gen_command_env_cuda_devices</code>	
<code>gen_script</code>	
<code>gen_script_command</code>	
<code>gen_script_custom_flags_lines</code>	
<code>gen_script_end</code>	
<code>gen_script_env</code>	
<code>gen_script_header</code>	
<code>gen_script_wait</code>	
<code>load_from_dict</code>	
<code>load_from_json</code>	
<code>serialize</code>	
<code>sub_script_cmd</code>	
<code>sub_script_head</code>	

`check_finish_tag(job)`

`check_status(job)`

`default_resources(resources)`

`do_submit(job)`

Submit a single job, assuming that no job is running there.

`gen_script(job)`

`gen_script_header(job)`

`kill(job)`

Kill the job.

Parameters

`job`

[Job] job

```
class dpdispatcher.Resources(number_node, cpu_per_node, gpu_per_node, queue_name, group_size, *,
                             custom_flags=[], strategy={'if_cuda_multi_devices': False, 'ratio_unfinished':
                             0.0}, para_deg=1, module_unload_list=[], module_purge=False,
                             module_list=[], source_list=[], envs={}, prepend_script=[],
                             append_script=[], wait_time=0, **kwargs)
```

Bases: `object`

Resources is used to describe the machine resources we need to do calculations.

Parameters

`number_node`

[int] The number of node need for each *job*.

`cpu_per_node`

[int] cpu numbers of each node.

`gpu_per_node`

[int] gpu numbers of each node.

`queue_name`

[str] The queue name of batch job scheduler system.

`group_size`

[int] The number of *tasks* in a *job*.

`custom_flags`

[list of Str] The extra lines pass to job submitting script header

`strategy`

[dict] strategies we use to generation job submitting scripts. `if_cuda_multi_devices` : bool

If there are multiple nvidia GPUS on the node, and we want to assign the tasks to different GPUS. If true, dpdispatcher will manually export environment variable `CUDA_VISIBLE_DEVICES` to different task. Usually, this option will be used with `Task.task_need_resources` variable simultaneously.

`ratio_unfinished`

[float] The ratio of *task* that can be unfinished.

`para_deg`

[int] Decide how many tasks will be run in parallel. Usually run with `strategy['if_cuda_multi_devices']`

`source_list`

[list of Path] The env file to be sourced before the command execution.

`wait_time`

[int] The waiting time in second after a single task submitted. Default: 0.

Methods

arginfo	
deserialize	
load_from_dict	
load_from_json	
serialize	

```
static arginfo(detail_kwargs=True)

classmethod deserialize(resources_dict)

classmethod load_from_dict(resources_dict)

classmethod load_from_json(json_file)

serialize()

class dpdispatcher.SSHContext(*args, **kwargs)
```

Bases: *BaseContext***Attributes**

sftp
ssh

Methods

block_checkcall (cmd[, asynchronously, ...])	Run command with arguments.
machine_arginfo()	Generate the machine arginfo.
machine_subfields()	Generate the machine subfields.

bind_submission	
block_call	
call	
check_file_exists	
check_finish	
clean	
close	
download	
get_job_root	
get_return	
load_from_dict	
read_file	
upload	
write_file	

bind_submission(*submission*)

block_call(*cmd*)

block_checkcall(*cmd*, *asynchronously=False*, *stderr_whitelist=None*)

Run command with arguments. Wait for command to complete. If the return code was zero then return, otherwise raise RuntimeError.

Parameters**cmd**

[str] The command to run.

asynchronously

[bool, optional, default=False] Run command asynchronously. If True, *nohup* will be used to run the command.

stderr_whitelist

[list of str, optional, default=None] If not None, the stderr will be checked against the whitelist. If the stderr contains any of the strings in the whitelist, the command will be considered successful.

call(*cmd*)**check_file_exists**(*fname*)**check_finish**(*cmd_pipes*)**clean()****close()****download**(*submission*, *check_exists=False*, *mark_failure=True*, *back_error=False*)**get_job_root()****get_return**(*cmd_pipes*)**classmethod load_from_dict**(*context_dict*)**classmethod machine_subfields()** → List[Argument]

Generate the machine subfields.

Returns**list[Argument]**

machine subfields

read_file(*fname*)**property sftp****property ssh****upload**(*submission*, *dereference=True*)**write_file**(*fname*, *write_str*)**class dpdispatcher.Shell**(*args, **kwargs)

Bases: [Machine](#)

Methods

<code>do_submit(job)</code>	Submit a single job, assuming that no job is running there.
<code>get_exit_code(job)</code>	Get exit code of the job.
<code>kill(job)</code>	Kill the job.
<code>resources_arginfo()</code>	Generate the resources arginfo.
<code>resources_subfields()</code>	Generate the resources subfields.

<code>arginfo</code>	
<code>bind_context</code>	
<code>check_finish_tag</code>	
<code>check_if_recover</code>	
<code>check_status</code>	
<code>default_resources</code>	
<code>deserialize</code>	
<code>gen_command_env_cuda_devices</code>	
<code>gen_script</code>	
<code>gen_script_command</code>	
<code>gen_script_custom_flags_lines</code>	
<code>gen_script_end</code>	
<code>gen_script_env</code>	
<code>gen_script_header</code>	
<code>gen_script_wait</code>	
<code>load_from_dict</code>	
<code>load_from_json</code>	
<code>serialize</code>	
<code>sub_script_cmd</code>	
<code>sub_script_head</code>	

`check_finish_tag(job)`

`check_status(job)`

`default_resources(resources)`

`do_submit(job)`

Submit a single job, assuming that no job is running there.

`gen_script(job)`

`gen_script_header(job)`

`kill(job)`

Kill the job.

Parameters

`job`

[Job] job

`class dpdispatcher.Slurm(*args, **kwargs)`

Bases: `Machine`

Methods

<code>get_exit_code(job)</code>	Get exit code of the job.
<code>kill(job)</code>	Kill the job.
<code>resources_arginfo()</code>	Generate the resources arginfo.
<code>resources_subfields()</code>	Generate the resources subfields.

<code>arginfo</code>	
<code>bind_context</code>	
<code>check_finish_tag</code>	
<code>check_if_recover</code>	
<code>check_status</code>	
<code>default_resources</code>	
<code>deserialize</code>	
<code>do_submit</code>	
<code>gen_command_env_cuda_devices</code>	
<code>gen_script</code>	
<code>gen_script_command</code>	
<code>gen_script_custom_flags_lines</code>	
<code>gen_script_end</code>	
<code>gen_script_env</code>	
<code>gen_script_header</code>	
<code>gen_script_wait</code>	
<code>load_from_dict</code>	
<code>load_from_json</code>	
<code>serialize</code>	
<code>sub_script_cmd</code>	
<code>sub_script_head</code>	

`check_finish_tag(job)`
`check_status(**kwargs)`
`default_resources(resources)`
`do_submit(**kwargs)`

Submit a single job, assuming that no job is running there.

`gen_script(job)`
`gen_script_header(job)`

`kill(job)`
Kill the job.

Parameters

job
[Job] job

`classmethod resources_subfields() → List[Argument]`

Generate the resources subfields.

Returns

list[Argument]
resources subfields

```
class dpdispatcher.Submission(work_base, machine=None, resources=None, forward_common_files=[], backward_common_files=[], *, task_list=[])
Bases: object
```

A submission represents a collection of tasks. These tasks usually locate at a common directory. And these Tasks may share common files to be uploaded and downloaded.

Parameters

work_base

[Path] the base directory of the local tasks. It is usually the dir name of project .

machine

[Machine] machine class object (for example, PBS, Slurm, Shell) to execute the jobs. The machine can still be bound after the instantiation with the bind_submission method.

resources

[Resources] the machine resources (cpu or gpu) used to generate the slurm/pbs script

forward_common_files

[list] the common files to be uploaded to other computers before the jobs begin

backward_common_files

[list] the common files to be downloaded from other computers after the jobs finish

task_list

[list of Task] a list of tasks to be run.

Methods

<code>async_run_submission(**kwargs)</code>	Async interface of run_submission.
<code>bind_machine(machine)</code>	Bind this submission to a machine.
<code>check_all_finished()</code>	Check whether all the jobs in the submission.
<code>check_ratio_unfinished(ratio_unfinished)</code>	Calculate the ratio of unfinished tasks in the submission.
<code>deserialize(submission_dict[, machine])</code>	Convert the submission_dict to a Submission class object.
<code>generate_jobs()</code>	After tasks register to the self.belonging_tasks, This method generate the jobs and add these jobs to self.belonging_jobs.
<code>handle_unexpected_submission_state()</code>	Handle unexpected job state of the submission.
<code>run_submission(*[, dry_run, exit_on_submit, ...])</code>	Main method to execute the submission.
<code>serialize([if_static])</code>	Convert the Submission class instance to a dictionary.
<code>update_submission_state()</code>	Check whether all the jobs in the submission.

clean_jobs	
download_jobs	
get_hash	
register_task	
register_task_list	
remove_unfinished_tasks	
submission_from_json	
submission_to_json	
try_download_result	
try_recover_from_json	
upload_jobs	

```
async async_run_submission(**kwargs)
```

Async interface of run_submission.

Examples

```
>>> import asyncio
>>> from dpdispatcher import Machine, Resource, Submission
>>> async def run_jobs():
...     background_task = set()
...     # task1
...     task1 = Task(...)
...     submission1 = Submission(..., task_list=[task1])
...     background_task = asyncio.create_task(
...         submission1.async_run_submission(check_interval=2, clean=False)
...     )
...     # task2
...     task2 = Task(...)
...     submission2 = Submission(..., task_list=[task1])
...     background_task = asyncio.create_task(
...         submission2.async_run_submission(check_interval=2, clean=False)
...     )
...     background_tasks.add(background_task)
...     result = await asyncio.gather(*background_tasks)
...
...     return result
>>> run_jobs()
```

May raise Error if pass *clean=True* explicitly when submit to pbs or slurm.

bind_machine(machine)

Bind this submission to a machine. update the machine's context remote_root and local_root.

Parameters

machine

[Machine] the machine to bind with

check_all_finished()

Check whether all the jobs in the submission.

Notes

This method will not handle unexpected job state in the submission.

check_ratio_unfinished(*ratio_unfinished*: float) → bool

Calculate the ratio of unfinished tasks in the submission.

Parameters

ratio_unfinished

[float] the ratio of unfinished tasks in the submission

Returns

bool

whether the ratio of unfinished tasks in the submission is larger than ratio_unfinished

clean_jobs()

classmethod deserialize(*submission_dict*, *machine*=None)

Convert the submission_dict to a Submission class object.

Parameters

submission_dict

[dict] path-like, the base directory of the local tasks

machine

[Machine] Machine class Object to execute the jobs

Returns

submission

[Submission] the Submission class instance converted from the submission_dict

download_jobs()

generate_jobs()

After tasks register to the self.belonging_tasks, This method generate the jobs and add these jobs to self.belonging_jobs. The jobs are generated by the tasks randomly, and there are self.resources.group_size tasks in a task. Why we randomly shuffle the tasks is under the consideration of load balance. The random seed is a constant (to be concrete, 42). And this insures that the jobs are equal when we re-run the program.

get_hash()

handle_unexpected_submission_state()

Handle unexpected job state of the submission. If the job state is unsubmitted, submit the job. If the job state is terminated (killed unexpectedly), resubmit the job. If the job state is unknown, raise an error.

register_task(*task*)

register_task_list(*task_list*)

remove_unfinished_tasks()

run_submission(*, *dry_run=False*, *exit_on_submit=False*, *clean=True*, *check_interval=30*)

Main method to execute the submission. First, check whether old Submission exists on the remote machine, and try to recover from it. Second, upload the local files to the remote machine where the tasks to be executed. Third, run the submission defined previously. Forth, wait until the tasks in the submission finished and download the result file to local directory. If dry_run is True, submission will be uploaded but not be executed and exit. If exit_on_submit is True, submission will exit.

serialize(*if_static=False*)

Convert the Submission class instance to a dictionary.

Parameters**if_static**

[bool] whether dump the job runtime infomation (like job_id, job_state, fail_count) to the dictionary.

Returns**submission_dict**

[dict] the dictionary converted from the Submission class instance

classmethod submission_from_json(*json_file_name='submission.json'*)**submission_to_json()****try_download_result()****try_recover_from_json()****update_submission_state()**

Check whether all the jobs in the submission.

Notes

this method will not handle unexpected (like resubmit terminated) job state in the submission.

upload_jobs()

```
class dpdispatcher.Task(command, task_work_path, forward_files=[], backward_files=[], outlog='log',
                        errlog='err')
```

Bases: `object`

A task is a sequential command to be executed, as well as the files it depends on to transmit forward and backward.

Parameters**command**

[Str] the command to be executed.

task_work_path

[Path] the directory of each file where the files are dependent on.

forward_files

[list of Path] the files to be transmitted to remote machine before the command execute.

backward_files

[list of Path] the files to be transmitted from remote machine after the comand finished.

outlog

[Str] the filename to which command redirect stdout

errlog

[Str] the filename to which command redirect stderr

Methods

<code>deserialize(task_dict)</code>	Convert the task_dict to a Task class object.
<code>get_task_state(context)</code>	Get the task state by checking the tag file.

<code>arginfo</code>	
<code>get_hash</code>	
<code>load_from_dict</code>	
<code>load_from_json</code>	
<code>serialize</code>	

static arginfo()**classmethod deserialize(task_dict)**

Convert the task_dict to a Task class object.

Parameters**task_dict**

[dict] the dictionary which contains the task information

Returns**task**

[Task] the Task class instance converted from the task_dict

get_hash()**get_task_state(context)**

Get the task state by checking the tag file.

Parameters**context**

[Context] the context of the task

classmethod load_from_dict(task_dict: dict) → Task**classmethod load_from_json(json_file)****serialize()****class dpdispatcher.Torque(*args, **kwargs)**Bases: *PBS***Methods**

<code>do_submit(job)</code>	Submit a single job, assuming that no job is running there.
<code>get_exit_code(job)</code>	Get exit code of the job.
<code>kill(job)</code>	Kill the job.
<code>resources_arginfo()</code>	Generate the resources arginfo.
<code>resources_subfields()</code>	Generate the resources subfields.

arginfo
bind_context
check_finish_tag
check_if_recover
check_status
default_resources
deserialize
gen_command_env_cuda_devices
gen_script
gen_script_command
gen_script_custom_flags_lines
gen_script_end
gen_script_env
gen_script_header
gen_script_wait
load_from_dict
load_from_json
serialize
sub_script_cmd
sub_script_head

check_status(job)
gen_script_header(job)

dpdispatcher.info()

Show basic information about dpdispatcher, its location and version.

8.1.1 Subpackages

dpdispatcher.dpcloudserver package

```
class dpdispatcher.dpcloudserver.Client(email=None, password=None, debug=False, ticket=None,
                                         base_url='https://bohrium.dp.tech/')
```

Bases: object

Methods

download
download_from_url
get
get_job_detail
get_job_result_url
get_log
get_tasks_list
job_create
kill
post
refresh_token
upload

```
download(oss_file, save_file, endpoint, bucket_name)
download_from_url(url, save_file)
get(url, header=None, params=None, retry=5)
get_job_detail(job_id)
get_job_result_url(job_id)
get_log(job_id)
get_tasks_list(group_id, per_page=30)
job_create(job_type, oss_path, input_data, program_id=None, group_id=None)
kill(job_id)
post(url, data=None, header=None, params=None, retry=5)
refresh_token(retry=3)
upload(oss_task_zip, zip_task_file, endpoint, bucket_name)
```

Submodules

dpdispatcher.dpcloudserver.client module

```
class dpdispatcher.dpcloudserver.client.Client(email=None, password=None, debug=False,
                                              ticket=None, base_url='https://bohrium.dp.tech/')
Bases: object
```

Methods

download	
download_from_url	
get	
get_job_detail	
get_job_result_url	
get_log	
get_tasks_list	
job_create	
kill	
post	
refresh_token	
upload	

```
download(oss_file, save_file, endpoint, bucket_name)
download_from_url(url, save_file)
get(url, header=None, params=None, retry=5)
```

```
get_job_detail(job_id)
get_job_result_url(job_id)
get_log(job_id)
get_tasks_list(group_id, per_page=30)
job_create(job_type, oss_path, input_data, program_id=None, group_id=None)
kill(job_id)
post(url, data=None, header=None, params=None, retry=5)
refresh_token(retry=3)
upload(oss_task_zip, zip_task_file, endpoint, bucket_name)

exception dpdispatcher.dpcloudserver.client.RequestInfoException
    Bases: Exception
```

dpdispatcher.dpcloudserver.config module

dpdispatcher.dpcloudserver.retcodes module

```
class dpdispatcher.dpcloudserver.retcodes.RETCODE
    Bases: object

    DATAERR = '2002'
    DBERR = '2000'
    IOERR = '2003'
    NODATA = '2300'
    OK = '0000'
    PARAMERR = '2101'
    PWDERR = '2104'
    REQERR = '2200'
    ROLEERR = '2103'
    THIRDERR = '2001'
    TOKENINVALID = '2100'
    UNDERDEBUG = '2301'
    UNKNOWNERR = '2400'
    USERERR = '2102'
    VERIFYERR = '2105'
```

dpp dispatcher.dpcloudserver.temp_test module**dpp dispatcher.dpcloudserver.zip_file module**

```
dpp dispatcher.dpcloudserver.zip_file.unzip_file(zip_file, out_dir='.')
dpp dispatcher.dpcloudserver.zip_file.zip_file_list(root_path, zip_filename, file_list=[])
```

8.1.2 Submodules**8.1.3 dpp dispatcher.JobStatus module**

```
class dpp dispatcher.JobStatus.JobStatus(value)
Bases: IntEnum
An enumeration.
completing = 6
finished = 5
running = 3
terminated = 4
unknown = 100
unsubmitted = 1
waiting = 2
```

8.1.4 dpp dispatcher.arginfo module**8.1.5 dpp dispatcher.base_context module**

```
class dpp dispatcher.base_contextBaseContext(*args, **kwargs)
Bases: object
```

Methods

<i>machine_arginfo()</i>	Generate the machine arginfo.
<i>machine_subfields()</i>	Generate the machine subfields.

bind_submission	
check_finish	
clean	
download	
load_from_dict	
read_file	
upload	
write_file	

```
alias: Tuple[str, ...] = ()  
bind_submission(submission)  
check_finish(proc)  
abstract clean()  
abstract download(submission, check_exists=False, mark_failure=True, back_error=False)  
classmethod load_from_dict(context_dict)  
classmethod machine_arginfo() → Argument  
    Generate the machine arginfo.  
  
    Returns  
        Argument  
            machine arginfo  
  
    classmethod machine_subfields() → List[Argument]  
        Generate the machine subfields.  
  
        Returns  
            list[Argument]  
                machine subfields  
  
options = {'BohriumContext', 'HDFSContext', 'LazyLocalContext', 'LocalContext',  
          'OpenAPIContext', 'SSHContext'}  
  
abstract read_file(fname)
```

```

subclasses_dict = {'Bohrium': <class
'dpdispatcher.dp_cloud_server_context.BohriumContext'>, 'BohriumContext': <class
'dpdispatcher.dp_cloud_server_context.BohriumContext'>, 'DpCloudServer': <class
'dpdispatcher.dp_cloud_server_context.BohriumContext'>, 'DpCloudServerContext': <class
'dpdispatcher.dp_cloud_server_context.BohriumContext'>, 'HDFS': <class
'dpdispatcher.hdfs_context.HDFSContext'>, 'HDFSContext': <class
'dpdispatcher.hdfs_context.HDFSContext'>, 'LazyLocal': <class
'dpdispatcher.lazy_local_context.LazyLocalContext'>, 'LazyLocalContext': <class
'dpdispatcher.lazy_local_context.LazyLocalContext'>, 'Lebesgue': <class
'dpdispatcher.dp_cloud_server_context.BohriumContext'>, 'LebesgueContext': <class
'dpdispatcher.dp_cloud_server_context.BohriumContext'>, 'Local': <class
'dpdispatcher.local_context.LocalContext'>, 'LocalContext': <class
'dpdispatcher.local_context.LocalContext'>, 'OpenAPI': <class
'dpdispatcher.openapi_context.OpenAPIContext'>, 'OpenAPIContext': <class
'dpdispatcher.openapi_context.OpenAPIContext'>, 'SSH': <class
'dpdispatcher.ssh_context.SSHContext'>, 'SSHContext': <class
'dpdispatcher.ssh_context.SSHContext'>, 'bohrium': <class
'dpdispatcher.dp_cloud_server_context.BohriumContext'>, 'bohriumcontext': <class
'dpdispatcher.dp_cloud_server_context.BohriumContext'>, 'dpcloudserver': <class
'dpdispatcher.dp_cloud_server_context.BohriumContext'>, 'dpcloudservercontext': <class
'dpdispatcher.dp_cloud_server_context.BohriumContext'>, 'hdfs': <class
'dpdispatcher.hdfs_context.HDFSContext'>, 'hdfscontext': <class
'dpdispatcher.hdfs_context.HDFSContext'>, 'lazylocal': <class
'dpdispatcher.lazy_local_context.LazyLocalContext'>, 'lazylocalcontext': <class
'dpdispatcher.lazy_local_context.LazyLocalContext'>, 'lebesgue': <class
'dpdispatcher.dp_cloud_server_context.BohriumContext'>, 'lebesguecontext': <class
'dpdispatcher.dp_cloud_server_context.BohriumContext'>, 'local': <class
'dpdispatcher.local_context.LocalContext'>, 'localcontext': <class
'dpdispatcher.local_context.LocalContext'>, 'openapi': <class
'dpdispatcher.openapi_context.OpenAPIContext'>, 'openapicontext': <class
'dpdispatcher.openapi_context.OpenAPIContext'>, 'ssh': <class
'dpdispatcher.ssh_context.SSHContext'>, 'sshcontext': <class
'dpdispatcher.ssh_context.SSHContext'>}

abstract upload(submission)

abstract write_file(fname, write_str)

```

8.1.6 dpdispatcher.distributed_shell module

```

class dpdispatcher.distributed_shell.DistributedShell(*args, **kwargs)
Bases: Machine

```

Methods

<code>do_submit(job)</code>	Submit th job to yarn using distributed shell.
<code>get_exit_code(job)</code>	Get exit code of the job.
<code>kill(job)</code>	Kill the job.
<code>resources_arginfo()</code>	Generate the resources arginfo.
<code>resources_subfields()</code>	Generate the resources subfields.

<code>arginfo</code>	
<code>bind_context</code>	
<code>check_finish_tag</code>	
<code>check_if_recover</code>	
<code>check_status</code>	
<code>default_resources</code>	
<code>deserialize</code>	
<code>gen_command_env_cuda_devices</code>	
<code>gen_script</code>	
<code>gen_script_command</code>	
<code>gen_script_custom_flags_lines</code>	
<code>gen_script_end</code>	
<code>gen_script_env</code>	
<code>gen_script_header</code>	
<code>gen_script_wait</code>	
<code>load_from_dict</code>	
<code>load_from_json</code>	
<code>serialize</code>	
<code>sub_script_cmd</code>	
<code>sub_script_head</code>	

`check_finish_tag(job)`

`check_status(job)`

`do_submit(job)`

Submit th job to yarn using distributed shell.

Parameters

`job`
[Job class instance] job to be submitted

Returns

`job_id: string`
submit process id

`gen_script_end(job)`

`gen_script_env(job)`

`gen_script_header(job)`

8.1.7 dpdispatcher.dp_cloud_server module

```
class dpdispatcher.dp_cloud_server.Bohrium(*args, **kwargs)
    Bases: Machine
```

Methods

<code>do_submit(job)</code>	Submit a single job, assuming that no job is running there.
<code>get_exit_code(job)</code>	Get exit code of the job.
<code>kill(job)</code>	Kill the job.
<code>resources_arginfo()</code>	Generate the resources arginfo.
<code>resources_subfields()</code>	Generate the resources subfields.

<code>arginfo</code>	
<code>bind_context</code>	
<code>check_finish_tag</code>	
<code>check_if_recover</code>	
<code>check_status</code>	
<code>default_resources</code>	
<code>deserialize</code>	
<code>gen_command_env_cuda_devices</code>	
<code>gen_local_script</code>	
<code>gen_script</code>	
<code>gen_script_command</code>	
<code>gen_script_custom_flags_lines</code>	
<code>gen_script_end</code>	
<code>gen_script_env</code>	
<code>gen_script_header</code>	
<code>gen_script_wait</code>	
<code>load_from_dict</code>	
<code>load_from_json</code>	
<code>map_dp_job_state</code>	
<code>serialize</code>	
<code>sub_script_cmd</code>	
<code>sub_script_head</code>	

```
alias: Tuple[str, ...] = ('Lebesgue', 'DpCloudServer')
```

```
check_finish_tag(job)
```

```
check_if_recover(submission)
```

```
check_status(job)
```

```
do_submit(job)
```

Submit a single job, assuming that no job is running there.

```
gen_local_script(job)
```

```
gen_script(job)
```

```

gen_script_header(job)
get_exit_code(job) → int
    Get exit code of the job.

    Parameters
        job
            [Job] job

kill(job)
    Kill the job.

    Parameters
        job
            [Job] job

static map_dp_job_state(status, exit_code, ignore_exit_code=True)
dpdispatcher.dp_cloud_server.DpCloudServer
alias of Bohrium

dpdispatcher.dp_cloud_server.Lebesgue
alias of Bohrium

```

8.1.8 dpdispatcher.dp_cloud_server_context module

```

class dpdispatcher.dp_cloud_server_context.BohriumContext(*args, **kwargs)
Bases: BaseContext

```

Methods

<u>machine_arginfo()</u>	Generate the machine arginfo.
<u>machine_subfields()</u>	Generate the machine subfields.

<u>bind_submission</u>	
<u>check_file_exists</u>	
<u>check_finish</u>	
<u>check_home_file_exits</u>	
<u>clean</u>	
<u>download</u>	
<u>load_from_dict</u>	
<u>read_file</u>	
<u>read_home_file</u>	
<u>upload</u>	
<u>upload_job</u>	
<u>write_file</u>	
<u>write_home_file</u>	
<u>write_local_file</u>	

```

alias: Tuple[str, ...] = ('DpCloudServerContext', 'LebesgueContext')

```

```
bind_submission(submission)
check_file_exists(fname)
check_home_file_exists(fname)
clean()
download(submission)
classmethod load_from_dict(context_dict)
classmethod machine_subfields() → List[Argument]
```

Generate the machine subfields.

Returns

```
list[Argument]
machine subfields
```

```
read_file(fname)
read_home_file(fname)
upload(submission)
upload_job(job, common_files=None)
write_file(fname, write_str)
write_home_file(fname, write_str)
write_local_file(fname, write_str)
```

dpdispatcher.dp_cloud_server_context.DpCloudServerContext

alias of *BohriumContext*

dpdispatcher.dp_cloud_server_context.LebesgueContext

alias of *BohriumContext*

8.1.9 dpdispatcher.dpdisp module

```
dpdispatcher.dpdisp.main()
```

8.1.10 dpdispatcher.fugaku module

```
class dpdispatcher.fugaku.Fugaku(*args, **kwargs)
```

Bases: *Machine*

Methods

<code>do_submit(job)</code>	Submit a single job, assuming that no job is running there.
<code>get_exit_code(job)</code>	Get exit code of the job.
<code>kill(job)</code>	Kill the job.
<code>resources_arginfo()</code>	Generate the resources arginfo.
<code>resources_subfields()</code>	Generate the resources subfields.

<code>arginfo</code>	
<code>bind_context</code>	
<code>check_finish_tag</code>	
<code>check_if_recover</code>	
<code>check_status</code>	
<code>default_resources</code>	
<code>deserialize</code>	
<code>gen_command_env_cuda_devices</code>	
<code>gen_script</code>	
<code>gen_script_command</code>	
<code>gen_script_custom_flags_lines</code>	
<code>gen_script_end</code>	
<code>gen_script_env</code>	
<code>gen_script_header</code>	
<code>gen_script_wait</code>	
<code>load_from_dict</code>	
<code>load_from_json</code>	
<code>serialize</code>	
<code>sub_script_cmd</code>	
<code>sub_script_head</code>	

check_finish_tag(*job*)
check_status(*job*)
default_resources(*resources*)
do_submit(*job*)
 Submit a single job, assuming that no job is running there.
gen_script(*job*)
gen_script_header(*job*)

8.1.11 dpdispatcher.hdfs_cli module

```
class dpdispatcher.hdfs_cli.HDFS
```

Bases: `object`

Fundamental class for HDFS basic manipulation.

Methods

<code>copy_from_local(local_path, to_uri)</code>	Returns: True on success Raises: on unexpected error.
<code>exists(uri)</code>	Check existence of hdfs uri Returns: True on exists Raises: RuntimeError.
<code>mkdir(uri)</code>	Make new hdfs directory Returns: True on success Raises: RuntimeError.
<code>remove(uri)</code>	Check existence of hdfs uri Returns: True on exists Raises: RuntimeError.

<code>copy_to_local</code>	
<code>move</code>	
<code>read_hdfs_file</code>	

```
static copy_from_local(local_path, to_uri)
```

Returns: True on success
Raises: on unexpected error.

```
static copy_to_local(from_uri, local_path)
```

```
static exists(uri)
```

Check existence of hdfs uri
Returns: True on exists
Raises: RuntimeError.

```
static mkdir(uri)
```

Make new hdfs directory
Returns: True on success
Raises: RuntimeError.

```
static move(from_uri, to_uri)
```

```
static read_hdfs_file(uri)
```

```
static remove(uri)
```

Check existence of hdfs uri
Returns: True on exists
Raises: RuntimeError.

8.1.12 dpdispatcher.hdfs_context module

```
class dpdispatcher.hdfs_context.HDFSContext(*args, **kwargs)
```

Bases: `BaseContext`

Methods

<code>check_file_exists(fname)</code>	Check whether the given file exists, often used in checking whether the belonging job has finished.
<code>download(submission[, check_exists, ...])</code>	Download backward files from HDFS root dir.
<code>machine_arginfo()</code>	Generate the machine arginfo.
<code>machine_subfields()</code>	Generate the machine subfields.
<code>upload(submission[, dereference])</code>	Upload forward files and forward command files to HDFS root dir.

bind_submission	
check_finish	
clean	
get_job_root	
load_from_dict	
read_file	
write_file	

bind_submission(*submission*)

check_file_exists(*fname*)

Check whether the given file exists, often used in checking whether the belonging job has finished.

Parameters

fname

[string] file name to be checked

Returns

status: boolean

clean()

download(*submission, check_exists=False, mark_failure=True, back_error=False*)

Download backward files from HDFS root dir.

Parameters

submission

[Submission class instance] represents a collection of tasks, such as backward file names

check_exists

[bool] whether to check if the file exists

mark_failure

[bool] whether to mark the task as failed if the file does not exist

back_error

[bool] whether to download error files

Returns

none

get_job_root()

```
classmethod load_from_dict(context_dict)
read_file(fname)
upload(submission, dereference=True)
```

Upload forward files and forward command files to HDFS root dir.

Parameters

submission

[Submission class instance] represents a collection of tasks, such as forward file names

dereference

[bool] whether to dereference symbolic links

Returns

none

```
write_file(fname, write_str)
```

8.1.13 dppdispatcher.lazy_local_context module

```
class dppdispatcher.lazy_local_context.LazyLocalContext(*args, **kwargs)
```

Bases: *BaseContext*

Run jobs in the local server and local directory.

Parameters

local_root

[str] The local directory to store the jobs.

remote_root

[str, optional] The argument takes no effect.

remote_profile

[dict, optional] The remote profile. The default is {}.

***args**

The arguments.

****kwargs**

The keyword arguments.

Methods

<code>machine_arginfo()</code>	Generate the machine arginfo.
<code>machine_subfields()</code>	Generate the machine subfields.

bind_submission	
block_call	
block_checkcall	
call	
check_file_exists	
check_finish	
clean	
download	
get_job_root	
get_return	
load_from_dict	
read_file	
upload	
write_file	

```

bind_submission(submission)
block_call(cmd)
block_checkcall(cmd)
call(cmd)
check_file_exists(fname)
check_finish(proc)
clean()
download(jobs, check_exists=False, mark_failure=True, back_error=False)
get_job_root()
get_return(proc)
classmethod load_from_dict(context_dict)
read_file(fname)
upload(jobs, dereference=True)
write_file(fname, write_str)

class dpdispatcher.lazy_local_context.SPRetObj(ret)
    Bases: object

```

Methods

read	
readlines	

```

read()
readlines()

```

8.1.14 dpdispatcher.local_context module

```
class dpdispatcher.local_context.LocalContext(*args, **kwargs)
```

Bases: *BaseContext*

Run jobs in the local server and remote directory.

Parameters

local_root

[str] The local directory to store the jobs.

remote_root

[str] The remote directory to store the jobs.

remote_profile

[dict, optional] The remote profile. The default is {}.

***args**

The arguments.

****kwargs**

The keyword arguments.

Methods

<code>machine_arginfo()</code>	Generate the machine arginfo.
<code>machine_subfields()</code>	Generate the machine subfields.

<code>bind_submission</code>	
<code>block_call</code>	
<code>block_checkcall</code>	
<code>call</code>	
<code>check_file_exists</code>	
<code>check_finish</code>	
<code>clean</code>	
<code>download</code>	
<code>get_job_root</code>	
<code>get_return</code>	
<code>load_from_dict</code>	
<code>read_file</code>	
<code>upload</code>	
<code>write_file</code>	

`bind_submission(submission)`

`block_call(cmd)`

`block_checkcall(cmd)`

`call(cmd)`

`check_file_exists(fname)`

```

check_finish(proc)
clean()
download(submission, check_exists=False, mark_failure=True, back_error=False)
get_job_root()
get_return(proc)
classmethod load_from_dict(context_dict)
read_file(fname)
upload(submission)
write_file(fname, write_str)

class dpdispatcher.local_context.SPRetObj(ret)
    Bases: object

```

Methods

read	
readlines	

read()

readlines()

8.1.15 dpdispatcher.lsf module

```

class dpdispatcher.lsf.LSF(*args, **kwargs)
    Bases: Machine
    LSF batch.

```

Methods

default_resources(*resources*)

get_exit_code (<i>job</i>)	Get exit code of the job.
kill (<i>job</i>)	Kill the job.
resources_arginfo ()	Generate the resources arginfo.
resources_subfields ()	Generate the resources subfields.

<code>arginfo</code>	
<code>bind_context</code>	
<code>check_finish_tag</code>	
<code>check_if_recover</code>	
<code>check_status</code>	
<code>deserialize</code>	
<code>do_submit</code>	
<code>gen_command_env_cuda_devices</code>	
<code>gen_script</code>	
<code>gen_script_command</code>	
<code>gen_script_custom_flags_lines</code>	
<code>gen_script_end</code>	
<code>gen_script_env</code>	
<code>gen_script_header</code>	
<code>gen_script_wait</code>	
<code>load_from_dict</code>	
<code>load_from_json</code>	
<code>serialize</code>	
<code>sub_script_cmd</code>	
<code>sub_script_head</code>	

`check_finish_tag(job)`

`check_status(**kwargs)`

`default_resources(resources)`

`do_submit(**kwargs)`

Submit a single job, assuming that no job is running there.

`gen_script(job)`

`gen_script_header(job)`

`kill(job)`

Kill the job.

Parameters

`job`

[Job] job

`classmethod resources_subfields() → List[Argument]`

Generate the resources subfields.

Returns

`list[Argument]`

resources subfields

`sub_script_cmd(res)`

`sub_script_head(res)`

8.1.16 dpdispatcher.machine module

```
class dpdispatcher.machine.Machine(*args, **kwargs)
```

Bases: `object`

A machine is used to handle the connection with remote machines.

Parameters

context

[SubClass derived fromBaseContext] The context is used to mainatin the connection with remote machine.

Methods

<code>do_submit(job)</code>	Submit a single job, assuming that no job is running there.
<code>get_exit_code(job)</code>	Get exit code of the job.
<code>kill(job)</code>	Kill the job.
<code>resources_arginfo()</code>	Generate the resources arginfo.
<code>resources_subfields()</code>	Generate the resources subfields.

<code>arginfo</code>	
<code>bind_context</code>	
<code>check_finish_tag</code>	
<code>check_if_recover</code>	
<code>check_status</code>	
<code>default_resources</code>	
<code>deserialize</code>	
<code>gen_command_env_cuda_devices</code>	
<code>gen_script</code>	
<code>gen_script_command</code>	
<code>gen_script_custom_flags_lines</code>	
<code>gen_script_end</code>	
<code>gen_script_env</code>	
<code>gen_script_header</code>	
<code>gen_script_wait</code>	
<code>load_from_dict</code>	
<code>load_from_json</code>	
<code>serialize</code>	
<code>sub_script_cmd</code>	
<code>sub_script_head</code>	

```
alias: Tuple[str, ...] = ()  
  
classmethod arginfo()  
  
bind_context(context)  
  
abstract check_finish_tag(**kwargs)  
  
check_if_recover(submission)
```

```
abstract check_status(job)
default_resources(res)
classmethod deserialize(machine_dict)
abstract do_submit(job)
Submit a single job, assuming that no job is running there.
gen_command_env_cuda_devices(resources)
gen_script(job)
gen_script_command(job)
gen_script_custom_flags_lines(job)
gen_script_end(job)
gen_script_env(job)
abstract gen_script_header(job)
gen_script_wait(resources)
get_exit_code(job)
Get exit code of the job.
```

Parameters

job
[Job] job

kill(job)

Kill the job.

If not implemented, pass and let the user manually kill it.

Parameters

job
[Job] job

classmethod load_from_dict(machine_dict)

classmethod load_from_json(json_path)

options = {'Bohrium', 'DistributedShell', 'Fugaku', 'LSF', 'OpenAPI', 'PBS', 'Shell', 'Slurm', 'SlurmJobArray', 'Torque'}

classmethod resources_arginfo() → Argument

Generate the resources arginfo.

Returns

Argument
resources arginfo

```

classmethod resources_subfields() → List[Argument]
    Generate the resources subfields.

Returns
    list[Argument]
        resources subfields

serialize(if_empty_remote_profile=False)

sub_script_cmd(res)

sub_script_head(res)

subclasses_dict = {'Bohrium': <class 'dpdispatcher.dp_cloud_server.Bohrium'>,
'DistributedShell': <class 'dpdispatcher.distributed_shell.DistributedShell'>,
'DpCloudServer': <class 'dpdispatcher.dp_cloud_server.Bohrium'>, 'Fugaku': <class
'dpdispatcher.fugaku.Fugaku'>, 'LSF': <class 'dpdispatcher.lsf.LSF'>, 'Lebesgue': <class
'dpdispatcher.dp_cloud_server.Bohrium'>, 'OpenAPI': <class
'dpdispatcher.openapi.OpenAPI'>, 'PBS': <class 'dpdispatcher.pbs.PBS'>, 'Shell': <class
'dpdispatcher.shell.Shell'>, 'Slurm': <class 'dpdispatcher.slurm.Slurm'>,
'SlurmJobArray': <class 'dpdispatcher.slurm.SlurmJobArray'>, 'Torque': <class
'dpdispatcher.pbs.Torque'>, 'bohrium': <class
'dpdispatcher.dp_cloud_server.Bohrium'>, 'distributedshell': <class
'dpdispatcher.distributed_shell.DistributedShell'>, 'dpcloudserver': <class
'dpdispatcher.dp_cloud_server.Bohrium'>, 'fugaku': <class
'dpdispatcher.fugaku.Fugaku'>, 'lebesgue': <class
'dpdispatcher.dp_cloud_server.Bohrium'>, 'lsf': <class 'dpdispatcher.lsf.LSF'>,
'openapi': <class 'dpdispatcher.openapi.OpenAPI'>, 'pbs': <class
'dpdispatcher.pbs.PBS'>, 'shell': <class 'dpdispatcher.shell.Shell'>, 'slurm': <class
'dpdispatcher.slurm.Slurm'>, 'slurmjobarray': <class
'dpdispatcher.slurm.SlurmJobArray'>, 'torque': <class 'dpdispatcher.pbs.Torque'>}

```

8.1.17 dpdispatcher.openapi module

```
class dpdispatcher.openapi.OpenAPI(*args, **kwargs)
```

Bases: *Machine*

Methods

<i>do_submit(job)</i>	Submit a single job, assuming that no job is running there.
<i>get_exit_code(job)</i>	Get exit code of the job.
<i>kill(job)</i>	Kill the job.
<i>resources_arginfo()</i>	Generate the resources arginfo.
<i>resources_subfields()</i>	Generate the resources subfields.

<code>arginfo</code>	
<code>bind_context</code>	
<code>check_finish_tag</code>	
<code>check_if_recover</code>	
<code>check_status</code>	
<code>default_resources</code>	
<code>deserialize</code>	
<code>gen_command_env_cuda_devices</code>	
<code>gen_local_script</code>	
<code>gen_script</code>	
<code>gen_script_command</code>	
<code>gen_script_custom_flags_lines</code>	
<code>gen_script_end</code>	
<code>gen_script_env</code>	
<code>gen_script_header</code>	
<code>gen_script_wait</code>	
<code>load_from_dict</code>	
<code>load_from_json</code>	
<code>map_dp_job_state</code>	
<code>serialize</code>	
<code>sub_script_cmd</code>	
<code>sub_script_head</code>	

`check_finish_tag(job)`

`check_if_recover(submission)`

`check_status(job)`

`do_submit(job)`

Submit a single job, assuming that no job is running there.

`gen_local_script(job)`

`gen_script(job)`

`gen_script_header(job)`

`get_exit_code(job)`

Get exit code of the job.

Parameters

`job`

[Job] job

Returns

`int`

exit code

`kill(job)`

Kill the job.

Parameters

```

job
    [Job] job

static map_dp_job_state(status, exit_code, ignore_exit_code=True)

```

8.1.18 dpdispatcher.openapi_context module

```

class dpdispatcher.openapi_context.OpenAPIContext(*args, **kwargs)
    Bases: BaseContext

```

Methods

machine_arginfo()	Generate the machine arginfo.
machine_subfields()	Generate the machine subfields.

bind_submission	
check_file_exists	
check_finish	
check_home_file_exits	
clean	
download	
load_from_dict	
read_file	
read_home_file	
upload	
upload_job	
write_file	
write_home_file	
write_local_file	

```

bind_submission(submission)

check_file_exists(fname)

check_home_file_exits(fname)

clean()

download(submission)

classmethod load_from_dict(context_dict)

read_file(fname)

read_home_file(fname)

upload(submission)

upload_job(job, common_files=None)

write_file(fname, write_str)

```

```
write_home_file(fname, write_str)
write_local_file(fname, write_str)
```

8.1.19 dpdispatcher.pbs module

```
class dpdispatcher.pbs.PBS(*args, **kwargs)
```

Bases: *Machine*

Methods

<code>do_submit(job)</code>	Submit a single job, assuming that no job is running there.
<code>get_exit_code(job)</code>	Get exit code of the job.
<code>kill(job)</code>	Kill the job.
<code>resources_arginfo()</code>	Generate the resources arginfo.
<code>resources_subfields()</code>	Generate the resources subfields.

<code>arginfo</code>	
<code>bind_context</code>	
<code>check_finish_tag</code>	
<code>check_if_recover</code>	
<code>check_status</code>	
<code>default_resources</code>	
<code>deserialize</code>	
<code>gen_command_env_cuda_devices</code>	
<code>gen_script</code>	
<code>gen_script_command</code>	
<code>gen_script_custom_flags_lines</code>	
<code>gen_script_end</code>	
<code>gen_script_env</code>	
<code>gen_script_header</code>	
<code>gen_script_wait</code>	
<code>load_from_dict</code>	
<code>load_from_json</code>	
<code>serialize</code>	
<code>sub_script_cmd</code>	
<code>sub_script_head</code>	

`check_finish_tag(job)`

`check_status(job)`

`default_resources(resources)`

`do_submit(job)`

Submit a single job, assuming that no job is running there.

`gen_script(job)`

```
gen_script_header(job)
```

```
kill(job)
```

Kill the job.

Parameters

job

[Job] job

```
class dpdispatcher.pbs.Torque(*args, **kwargs)
```

Bases: *PBS*

Methods

do_submit(job)	Submit a single job, assuming that no job is running there.
get_exit_code(job)	Get exit code of the job.
kill(job)	Kill the job.
resources_arginfo()	Generate the resources arginfo.
resources_subfields()	Generate the resources subfields.

arginfo	
bind_context	
check_finish_tag	
check_if_recover	
check_status	
default_resources	
deserialize	
gen_command_env_cuda_devices	
gen_script	
gen_script_command	
gen_script_custom_flags_lines	
gen_script_end	
gen_script_env	
gen_script_header	
gen_script_wait	
load_from_dict	
load_from_json	
serialize	
sub_script_cmd	
sub_script_head	

```
check_status(job)
```

```
gen_script_header(job)
```

8.1.20 dpdispatcher.shell module

```
class dpdispatcher.shell.Shell(*args, **kwargs)
```

Bases: *Machine*

Methods

<code>do_submit(job)</code>	Submit a single job, assuming that no job is running there.
<code>get_exit_code(job)</code>	Get exit code of the job.
<code>kill(job)</code>	Kill the job.
<code>resources_arginfo()</code>	Generate the resources arginfo.
<code>resources_subfields()</code>	Generate the resources subfields.

<code>arginfo</code>	
<code>bind_context</code>	
<code>check_finish_tag</code>	
<code>check_if_recover</code>	
<code>check_status</code>	
<code>default_resources</code>	
<code>deserialize</code>	
<code>gen_command_env_cuda_devices</code>	
<code>gen_script</code>	
<code>gen_script_command</code>	
<code>gen_script_custom_flags_lines</code>	
<code>gen_script_end</code>	
<code>gen_script_env</code>	
<code>gen_script_header</code>	
<code>gen_script_wait</code>	
<code>load_from_dict</code>	
<code>load_from_json</code>	
<code>serialize</code>	
<code>sub_script_cmd</code>	
<code>sub_script_head</code>	

`check_finish_tag(job)`

`check_status(job)`

`default_resources(resources)`

`do_submit(job)`

Submit a single job, assuming that no job is running there.

`gen_script(job)`

`gen_script_header(job)`

`kill(job)`

Kill the job.

Parameters

```
job
[Job] job
```

8.1.21 dpdispatcher.slurm module

```
class dpdispatcher.slurm.Slurm(*args, **kwargs)
```

Bases: *Machine*

Methods

<code>get_exit_code(job)</code>	Get exit code of the job.
<code>kill(job)</code>	Kill the job.
<code>resources_arginfo()</code>	Generate the resources arginfo.
<code>resources_subfields()</code>	Generate the resources subfields.

<code>arginfo</code>
<code>bind_context</code>
<code>check_finish_tag</code>
<code>check_if_recover</code>
<code>check_status</code>
<code>default_resources</code>
<code>deserialize</code>
<code>do_submit</code>
<code>gen_command_env_cuda_devices</code>
<code>gen_script</code>
<code>gen_script_command</code>
<code>gen_script_custom_flags_lines</code>
<code>gen_script_end</code>
<code>gen_script_env</code>
<code>gen_script_header</code>
<code>gen_script_wait</code>
<code>load_from_dict</code>
<code>load_from_json</code>
<code>serialize</code>
<code>sub_script_cmd</code>
<code>sub_script_head</code>

`check_finish_tag(job)`

`check_status(**kwargs)`

`default_resources(resources)`

`do_submit(**kwargs)`

Submit a single job, assuming that no job is running there.

`gen_script(job)`

`gen_script_header(job)`

kill(job)

Kill the job.

Parameters**job**

[Job] job

classmethod resources_subfields() → List[Argument]

Generate the resources subfields.

Returns**list[Argument]**

resources subfields

class dpdispatcher.slurm.SlurmJobArray(*args, **kwargs)Bases: *Slurm*

Slurm with job array enabled for multiple tasks in a job.

Methods

get_exit_code(job)	Get exit code of the job.
kill(job)	Kill the job.
resources_arginfo()	Generate the resources arginfo.
resources_subfields()	Generate the resources subfields.

arginfo	
bind_context	
check_finish_tag	
check_if_recover	
check_status	
default_resources	
deserialize	
do_submit	
gen_command_env_cuda_devices	
gen_script	
gen_script_command	
gen_script_custom_flags_lines	
gen_script_end	
gen_script_env	
gen_script_header	
gen_script_wait	
load_from_dict	
load_from_json	
serialize	
sub_script_cmd	
sub_script_head	

check_finish_tag(job)**check_status(**kwargs)**

```
gen_script_command(job)
gen_script_end(job)
gen_script_header(job)

classmethod resources_subfields() → List[Argument]
```

Generate the resources subfields.

Returns

```
list[Argument]
resources subfields
```

8.1.22 dpdispatcher.ssh_context module

```
class dpdispatcher.ssh_context.SSHContext(*args, **kwargs)
```

Bases: *BaseContext*

Attributes

```
sftp
ssh
```

Methods

<i>block_checkcall</i> (cmd[, asynchronously, ...])	Run command with arguments.
<i>machine_arginfo()</i>	Generate the machine arginfo.
<i>machine_subfields()</i>	Generate the machine subfields.

bind_submission	
block_call	
call	
check_file_exists	
check_finish	
clean	
close	
download	
get_job_root	
get_return	
load_from_dict	
read_file	
upload	
write_file	

bind_submission(submission)

block_call(cmd)

block_checkcall(cmd, asynchronously=False, stderr_whitelist=None)

Run command with arguments. Wait for command to complete. If the return code was zero then return, otherwise raise RuntimeError.

Parameters**cmd**

[str] The command to run.

asynchronously

[bool, optional, default=False] Run command asynchronously. If True, *nohup* will be used to run the command.

stderr_whitelist

[list of str, optional, default=None] If not None, the stderr will be checked against the whitelist. If the stderr contains any of the strings in the whitelist, the command will be considered successful.

call(cmd)**check_file_exists(fname)****check_finish(cmd_pipes)****clean()****close()****download(submission, check_exists=False, mark_failure=True, back_error=False)****get_job_root()****get_return(cmd_pipes)****classmethod load_from_dict(context_dict)****classmethod machine_subfields() → List[Argument]**

Generate the machine subfields.

Returns**list[Argument]**

machine subfields

read_file(fname)**property sftp****property ssh****upload(submission, dereference=True)****write_file(fname, write_str)****class dpdispatcher.ssh_context.SSHSession(hostname, username, password=None, port=22, key_filename=None, passphrase=None, timeout=10, totp_secret=None, tar_compress=True, look_for_keys=True)**

Bases: **object**

Attributes**remote****rsync_available****sftp**

Returns sftp.

Methods

<i>inter_handler(title, instructions, prompt_list)</i>	inter_handler: the callback for paramiko.transport.auth_interactive.
--	--

arginfo	
close	
ensure_alive	
exec_command	
get	
get_ssh_client	
put	

static arginfo()

close()

ensure_alive(max_check=10, sleep_time=10)

exec_command(kwargs)**

get(from_f, to_f)

get_ssh_client()

inter_handler(title, instructions, prompt_list)

inter_handler: the callback for paramiko.transport.auth_interactive.

The prototype for this function is defined by Paramiko, so all of the arguments need to be there, even though we don't use 'title' or 'instructions'.

The function is expected to return a tuple of data containing the responses to the provided prompts. Experimental results suggests that there will be one call of this function per prompt, but the mechanism allows for multiple prompts to be sent at once, so it's best to assume that that can happen.

Since tuples can't really be built on the fly, the responses are collected in a list which is then converted to a tuple when it's time to return a value.

Experiments suggest that the username prompt never happens. This makes sense, but the Username prompt is included here just in case.

put(from_f, to_f)

property remote: str

property rsync_available: bool

property sftp

Returns sftp. Open a new one if not existing.

8.1.23 dpdispatcher.submission module

```
class dpdispatcher.submission.Job(job_task_list, *, resources, machine=None)
Bases: object
```

Job is generated by Submission automatically. A job usually has many tasks and it may request computing resources from job scheduler systems. Each Job can generate a script file to be submitted to the job scheduler system or executed locally.

Parameters

job_task_list

[list of Task] the tasks belonging to the job

resources

[Resources] the machine resources. Passed from Submission when it constructs jobs.

machine

[machine] machine object to execute the job. Passed from Submission when it constructs jobs.

Methods

<code>deserialize(job_dict[, machine])</code>	Convert the job_dict to a Submission class object.
<code>get_job_state()</code>	Get the jobs.
<code>serialize([if_static])</code>	Convert the Task class instance to a dictionary.

<code>get_hash</code>	
<code>handle_unexpected_job_state</code>	
<code>job_to_json</code>	
<code>register_job_id</code>	
<code>submit_job</code>	

```
classmethod deserialize(job_dict, machine=None)
```

Convert the job_dict to a Submission class object.

Parameters

job_dict

[dict] the dictionary which contains the job information

machine

[Machine] the machine object to execute the job

Returns

submission

[Job] the Job class instance converted from the job_dict

get_hash()

get_job_state()

Get the jobs. Usually, this method will query the database of slurm or pbs job scheduler system and get the results.

Notes

this method will not submit or resubmit the jobs if the job is unsubmitted.

handle_unexpected_job_state()

job_to_json()

register_job_id(job_id)

serialize(if_static=False)

Convert the Task class instance to a dictionary.

Parameters

if_static

[bool] whether dump the job runtime infomation (job_id, job_state, fail_count, job_uuid etc.) to the dictionary.

Returns

task_dict

[dict] the dictionary converted from the Task class instance

submit_job()

```
class dpdispatcher.submission.Resources(number_node, cpu_per_node, gpu_per_node, queue_name,
                                         group_size, *, custom_flags=[], 
                                         strategy={'if_cuda_multi_devices': False, 'ratio_unfinished': 
                                         0.0}, para_deg=1, module_unload_list=[], 
                                         module_purge=False, module_list=[], source_list=[], envs={}, 
                                         prepend_script=[], append_script=[], wait_time=0, **kwargs)
```

Bases: `object`

Resources is used to describe the machine resources we need to do calculations.

Parameters

number_node

[int] The number of node need for each *job*.

cpu_per_node

[int] cpu numbers of each node.

gpu_per_node

[int] gpu numbers of each node.

queue_name

[str] The queue name of batch job scheduler system.

group_size

[int] The number of *tasks* in a *job*.

custom_flags

[list of Str] The extra lines pass to job submitting script header

strategy

[dict] strategies we use to generation job submitting scripts. `if_cuda_multi_devices` : bool

If there are multiple nvidia GPUS on the node, and we want to assign the tasks to different GPUS. If true, dpdispatcher will manually export environment variable `CUDA_VISIBLE_DEVICES` to different task. Usually, this option will be used with `Task.task_need_resources` variable simultaneously.

ratio_unfinished

[float] The ratio of *task* that can be unfinished.

para_deg

[int] Decide how many tasks will be run in parallel. Usually run with *strategy*['if_cuda_multi_devices']

source_list

[list of Path] The env file to be sourced before the command execution.

wait_time

[int] The waiting time in second after a single task submitted. Default: 0.

Methods

arginfo	
deserialize	
load_from_dict	
load_from_json	
serialize	

```
static arginfo(detail_kwargs=True)

classmethod deserialize(resources_dict)

classmethod load_from_dict(resources_dict)

classmethod load_from_json(json_file)

serialize()

class dpdispatcher.submission.Submission(work_base, machine=None, resources=None,
                                         forward_common_files=[], backward_common_files=[], *,
                                         task_list=[])
```

Bases: `object`

A submission represents a collection of tasks. These tasks usually locate at a common directory. And these Tasks may share common files to be uploaded and downloaded.

Parameters**work_base**

[Path] the base directory of the local tasks. It is usually the dir name of project .

machine

[Machine] machine class object (for example, PBS, Slurm, Shell) to execute the jobs. The machine can still be bound after the instantiation with the bind_submission method.

resources

[Resources] the machine resources (cpu or gpu) used to generate the slurm/pbs script

forward_common_files

[list] the common files to be uploaded to other computers before the jobs begin

backward_common_files

[list] the common files to be downloaded from other computers after the jobs finish

task_list

[list of Task] a list of tasks to be run.

Methods

<code>async_run_submission(**kwargs)</code>	Async interface of run_submission.
<code>bind_machine(machine)</code>	Bind this submission to a machine.
<code>check_all_finished()</code>	Check whether all the jobs in the submission.
<code>check_ratio_unfinished(ratio_unfinished)</code>	Calculate the ratio of unfinished tasks in the submission.
<code>deserialize(submission_dict[, machine])</code>	Convert the submission_dict to a Submission class object.
<code>generate_jobs()</code>	After tasks register to the self.belonging_tasks, This method generate the jobs and add these jobs to self.belonging_jobs.
<code>handle_unexpected_submission_state()</code>	Handle unexpected job state of the submission.
<code>run_submission(*[, dry_run, exit_on_submit, ...])</code>	Main method to execute the submission.
<code>serialize([if_static])</code>	Convert the Submission class instance to a dictionary.
<code>update_submission_state()</code>	Check whether all the jobs in the submission.

<code>clean_jobs</code>	
<code>download_jobs</code>	
<code>get_hash</code>	
<code>register_task</code>	
<code>register_task_list</code>	
<code>remove_unfinished_tasks</code>	
<code>submission_from_json</code>	
<code>submission_to_json</code>	
<code>try_download_result</code>	
<code>try_recover_from_json</code>	
<code>upload_jobs</code>	

`async async_run_submission(**kwargs)`

Async interface of run_submission.

Examples

```
>>> import asyncio
>>> from dpdispatcher import Machine, Resource, Submission
>>> async def run_jobs():
...     background_task = set()
...     # task1
...     task1 = Task(...)
...     submission1 = Submission(..., task_list=[task1])
...     background_task = asyncio.create_task(
...         submission1.async_run_submission(check_interval=2, clean=False))
...
...     # task2
...     task2 = Task(...)
...     submission2 = Submission(..., task_list=[task1])
...     background_task = asyncio.create_task(
...         submission2.async_run_submission(check_interval=2, clean=False))
```

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```
... )
...     background_tasks.add(background_task)
...     result = await asyncio.gather(*background_tasks)
...     return result
>>> run_jobs()
```

May raise Error if pass `clean=True` explicitly when submit to pbs or slurm.

`bind_machine(machine)`

Bind this submission to a machine. update the machine's context remote_root and local_root.

Parameters

`machine`

[Machine] the machine to bind with

`check_all_finished()`

Check whether all the jobs in the submission.

Notes

This method will not handle unexpected job state in the submission.

`check_ratio_unfinished(ratio_unfinished: float) → bool`

Calculate the ratio of unfinished tasks in the submission.

Parameters

`ratio_unfinished`

[float] the ratio of unfinished tasks in the submission

Returns

`bool`

whether the ratio of unfinished tasks in the submission is larger than ratio_unfinished

`clean_jobs()`

`classmethod deserialize(submission_dict, machine=None)`

Convert the submission_dict to a Submission class object.

Parameters

`submission_dict`

[dict] path-like, the base directory of the local tasks

`machine`

[Machine] Machine class Object to execute the jobs

Returns

`submission`

[Submission] the Submission class instance converted from the submission_dict

`download_jobs()`

generate_jobs()

After tasks register to the self.belonging_tasks, This method generate the jobs and add these jobs to self.belonging_jobs. The jobs are generated by the tasks randomly, and there are self.resources.group_size tasks in a task. Why we randomly shuffle the tasks is under the consideration of load balance. The random seed is a constant (to be concrete, 42). And this insures that the jobs are equal when we re-run the program.

get_hash()**handle_unexpected_submission_state()**

Handle unexpected job state of the submission. If the job state is unsubmitted, submit the job. If the job state is terminated (killed unexpectedly), resubmit the job. If the job state is unknown, raise an error.

register_task(task)**register_task_list(task_list)****remove_unfinished_tasks()****run_submission(*, dry_run=False, exit_on_submit=False, clean=True, check_interval=30)**

Main method to execute the submission. First, check whether old Submission exists on the remote machine, and try to recover from it. Second, upload the local files to the remote machine where the tasks to be executed. Third, run the submission defined previously. Forth, wait until the tasks in the submission finished and download the result file to local directory. If dry_run is True, submission will be uploaded but not be executed and exit. If exit_on_submit is True, submission will exit.

serialize(if_static=False)

Convert the Submission class instance to a dictionary.

Parameters**if_static**

[bool] whether dump the job runtime infomation (like job_id, job_state, fail_count) to the dictionary.

Returns**submission_dict**

[dict] the dictionary converted from the Submission class instance

classmethod submission_from_json(json_file_name='submission.json')**submission_to_json()****try_download_result()****try_recover_from_json()****update_submission_state()**

Check whether all the jobs in the submission.

Notes

this method will not handle unexpected (like resubmit terminated) job state in the submission.

upload_jobs()

```
class dpdispatcher.submission.Task(command, task_work_path, forward_files=[], backward_files=[],
                                    outlog='log', errlog='err')
```

Bases: `object`

A task is a sequential command to be executed, as well as the files it depends on to transmit forward and backward.

Parameters

command

[Str] the command to be executed.

task_work_path

[Path] the directory of each file where the files are dependent on.

forward_files

[list of Path] the files to be transmitted to remote machine before the command execute.

backward_files

[list of Path] the files to be transmitted from remote machine after the comand finished.

outlog

[Str] the filename to which command redirect stdout

errlog

[Str] the filename to which command redirect stderr

Methods

<code>deserialize(task_dict)</code>	Convert the task_dict to a Task class object.
<code>get_task_state(context)</code>	Get the task state by checking the tag file.

<code>arginfo</code>	
<code>get_hash</code>	
<code>load_from_dict</code>	
<code>load_from_json</code>	
<code>serialize</code>	

static arginfo()

classmethod deserialize(task_dict)

Convert the task_dict to a Task class object.

Parameters

task_dict

[dict] the dictionary which contains the task information

Returns

task

[Task] the Task class instance converted from the task_dict

get_hash()**get_task_state(*context*)**

Get the task state by checking the tag file.

Parameters**context**

[Context] the context of the task

classmethod load_from_dict(*task_dict*: *dict*) → *Task***classmethod load_from_json(*json_file*)****serialize()**

8.1.24 dpdispatcher.utils module

exception dpdispatcher.utils.RetrySignal

Bases: `Exception`

Exception to give a signal to retry the function.

dpdispatcher.utils.generate_totp(*secret*: *str*, *period*: *int* = 30, *token_length*: *int* = 6) → *str*

Generate time-based one time password (TOTP) from the secret.

Some HPCs use TOTP for two-factor authentication for safety.

Parameters**secret**

[str] The encoded secret provided by the HPC. It's usually extracted from a 2D code and base32 encoded.

period

[int, default=30] Time period where the code is valid in seconds.

token_length

[int, default=6] The token length.

Returns**token: str**

The generated token.

References

<https://github.com/lepture/otpauth/blob/49914d83d36dbcd33c9e26f65002b21ce09a6303/otpauth.py#L143-L160>

dpdispatcher.utils.get_sha256(*filename*)

Get sha256 of a file.

Parameters**filename**

[str] The filename.

Returns

sha256: str

The sha256.

```
dedispatcher.utils.hotp(key: str, period: int, token_length: int = 6, digest='sha1')
```

```
dedispatcher.utils.retry(max_retry: int = 3, sleep: typing.Union[int, float] = 60, catch_exception: typing.Type[BaseException] = <class 'dedispatcher.utils.RetrySignal'>) → Callable
```

Retry the function until it succeeds or fails for certain times.

Parameters

max_retry

[int, default=3] The maximum retry times. If None, it will retry forever.

sleep

[int or float, default=60] The sleep time in seconds.

catch_exception

[Exception, default=Exception] The exception to catch.

Returns

decorator: Callable

The decorator.

Examples

```
>>> @retry(max_retry=3, sleep=60, catch_exception=RetrySignal)
... def func():
...     raise RetrySignal("Failed")
```

```
dedispatcher.utils.rsync(from_file: str, to_file: str, port: int = 22, key_filename: Optional[str] = None,
                         timeout: Union[int, float] = 10)
```

Call rsync to transfer files.

Parameters

from_file

[str] SRC

to_file

[str] DEST

port

[int, default=22] port for ssh

key_filename

[str, optional] identity file name

timeout

[int, default=10] timeout for ssh

Raises

RuntimeError

when return code is not 0

```
dedispatcher.utils.run_cmd_with_all_output(cmd, shell=True)
```

RUNNING THE DEEPMD-KIT ON THE EXPANSE CLUSTER

Expanse is a cluster operated by the San Diego Supercomputer Center. Here we provide an example to run jobs on the expanse.

The machine parameters are provided below. Expanse uses the SLURM workload manager for job scheduling. `remote_root` has been created in advance. It's worth mentioned that we do not recommend to use the password, so `SSH keys` are used instead to improve security.

```
1 {
2     "batch_type": "Slurm",
3     "local_root": "./",
4     "remote_root": "/expanse/lustre/scratch/njzjz/temp_project/dpgeen_workdir",
5     "clean_asynchronously": true,
6     "context_type": "SSHContext",
7     "remote_profile": {
8         "hostname": "login.expanse.sdsc.edu",
9         "username": "njzjz",
10        "port": 22
11    }
12 }
```

Expanse's standard compute nodes are each powered by two 64-core AMD EPYC 7742 processors and contain 256 GB of DDR4 memory. Here, we request one node with 32 cores and 16 GB memory from the `shared` partition. Expanse does not support `--gres=gpu:0` command, so we use `custom_gpu_line` to customize the statement.

```
1 {
2     "number_node": 1,
3     "cpu_per_node": 1,
4     "gpu_per_node": 0,
5     "queue_name": "shared",
6     "group_size": 1,
7     "custom_flags": [
8         "#SBATCH -c 32",
9         "#SBATCH --mem=16G",
10        "#SBATCH --time=48:00:00",
11        "#SBATCH --account=rut149",
12        "#SBATCH --requeue"
13    ],
14     "source_list": [
15         "activate /home/njzjz/deepmd-kit"
16    ],
17     "envs": {
```

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```
18 "OMP_NUM_THREADS": 4,
19 "TF_INTRA_OP_PARALLELISM_THREADS": 4,
20 "TF_INTER_OP_PARALLELISM_THREADS": 8,
21 "DP_AUTO_PARALLELIZATION": 1
22 },
23 "batch_type": "Slurm",
24 "kwargs": {
25     "custom_gpu_line": "#SBATCH --gpus=0"
26 }
27 }
```

The following task parameter runs a DeePMD-kit task, forwarding an input file and backwarding graph files. Here, the data set will be used among all the tasks, so it is not included in the *forward_files*. Instead, it should be included in the submission's *forward_common_files*.

```
1 {
2     "command": "dp train input.json && dp freeze && dp compress",
3     "task_work_path": "model1/",
4     "forward_files": [
5         "input.json"
6     ],
7     "backward_files": [
8         "frozen_model.pb",
9         "frozen_model_compressed.pb"
10    ],
11    "outlog": "log",
12    "errlog": "err"
13 }
```

RUNNING GAUSSIAN 16 WITH FAILURE ALLOWED

Typically, a task will retry three times if the exit code is not zero. Sometimes, one may allow non-zero code. For example, when running large amounts of Gaussian 16 single-point calculation tasks, some of the Gaussian 16 tasks may throw SCF errors and return a non-zero code. One can append ||: to the command:

```
1  {
2      "command": "g16 < input > output ||:",
3      "task_work_path": "p1/",
4      "forward_files": [
5          "input"
6      ],
7      "backward_files": [
8          "output"
9      ]
10 }
```

This command ensures the task will always provide zero code.

RUNNING MULTIPLE MD TASKS ON A GPU WORKSTATION

In this example, we are going to show how to run multiple MD tasks on a GPU workstation. This workstation does not install any job scheduling packages installed, so we will use `Shell` as `batch_type`.

```
1 {
2     "batch_type": "Shell",
3     "local_root": "./",
4     "remote_root": "/data2/jinzhe/dpgen_workdir",
5     "clean_asynchronously": true,
6     "context_type": "SSHContext",
7     "remote_profile": {
8         "hostname": "mandu.iqb.rutgers.edu",
9         "username": "jz748",
10        "port": 22
11    }
12 }
```

The workstation has 48 cores of CPUs and 8 RTX3090 cards. Here we hope each card runs 6 tasks at the same time, as each task does not consume too many GPU resources. Thus, `strategy/if_cuda_multi_devices` is set to `true` and `para_deg` is set to 6.

```
1 {
2     "number_node": 1,
3     "cpu_per_node": 48,
4     "gpu_per_node": 8,
5     "queue_name": "shell",
6     "group_size": 0,
7     "strategy": {
8         "if_cuda_multi_devices": true
9     },
10    "source_list": [
11        "activate /home/jz748/deepmd-kit"
12    ],
13    "envs": {
14        "OMP_NUM_THREADS": 1,
15        "TF_INTRA_OP_PARALLELISM_THREADS": 1,
16        "TF_INTER_OP_PARALLELISM_THREADS": 1
17    },
18    "para_deg": 6
19 }
```

Note that `group_size` should be set to 0 (means infinity) to ensure there is only one job and avoid running multiple jobs

at the same time.

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TWELVE**

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