DPGEN2

DeepModeling

Apr 19, 2024

USER GUIDE

DPGEN2 is the 2nd generation of the Deep Potential GENerator.

Important: The project DeePMD-kit is licensed under GNU LGPLv3.0.

CHAPTER

ONE

GUIDE ON DPGEN2 COMMANDS

One may use dpgen2 through command line interface. A full documentation of the cli is found *here*

1.1 Submit a workflow

The dpgen2 workflow can be submitted via the `submit` command

```
dpgen2 submit input.json
```

where `input.json` is the input script. A guide of writing the script is found *here*. When a workflow is submitted, a ID (WFID) of the workflow will be printed for later reference.

1.2 Check the convergence of a workflow

The convergence of stages of the workflow can be checked by the `status` command. It prints the indexes of the finished stages, iterations, and the accurate, candidate and failed ratio of explored configurations of each iteration.

```
$ dpgen2 status input.json WFID
#   stage  id_stg.    iter.      accu.      cand.      fail.
# Stage    0  --------------------
        0        0        0     0.8333     0.1667     0.0000
        0        1        1     0.7593     0.2407     0.0000
        0        2        2     0.7778     0.2222     0.0000
        0        3        3     1.0000     0.0000     0.0000
# Stage    0  converged YES  reached max numb iterations NO
# All stages converged
```

1.3 Watch the progress of a workflow

The progress of a workflow can be watched on-the-fly

```
$ dpgen2 watch input.json WFID
INFO:root:steps iter-000000--prep-run-train------------------------ finished
INFO:root:steps iter-000000--prep-run-explore--------------------- finished
INFO:root:steps iter-000000--prep-run-fp-------------------------- finished
INFO:root:steps iter-000000--collect-data------------------------- finished
```

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```
INFO:root:steps iter-000001--prep-run-train---------------------- finished
INFO:root:steps iter-000001--prep-run-explore--------------------- finished
...
```

The artifacts can be downloaded on-the-fly with `-d` flag. Note that the existing files are automatically skipped if one sets `dflow_config["archive_mode"] = None`.

1.4 Show the keys of steps

Each dpgen2 step is assigned a unique key. The keys of the finished steps can be checked with `showkey` command

```
                0 : iter-000000--prep-train
          1 -> 4 : iter-000000--run-train-0000 -> iter-000000--run-train-0003
                5 : iter-000000--prep-lmp
          6 -> 14 : iter-000000--run-lmp-000000 -> iter-000000--run-lmp-000008
               15 : iter-000000--select-confs
               16 : iter-000000--prep-fp
         17 -> 20 : iter-000000--run-fp-000000 -> iter-000000--run-fp-000003
               21 : iter-000000--collect-data
               22 : iter-000000--scheduler
               23 : iter-000000--id
               24 : iter-000001--prep-train
         25 -> 28 : iter-000001--run-train-0000 -> iter-000001--run-train-0003
               29 : iter-000001--prep-lmp
         30 -> 38 : iter-000001--run-lmp-000000 -> iter-000001--run-lmp-000008
               39 : iter-000001--select-confs
               40 : iter-000001--prep-fp
         41 -> 44 : iter-000001--run-fp-000000 -> iter-000001--run-fp-000003
               45 : iter-000001--collect-data
               46 : iter-000001--scheduler
               47 : iter-000001--id
```

1.5 Resubmit a workflow

If a workflow stopped abnormally, one may submit a new workflow with some steps of the old workflow reused.

```
dpgen2 resubmit input.json WFID --reuse 0-41
```

The steps of workflow WDID 0-41 (0<=id<41, note that 41 is not included) will be reused in the new workflow. The indexes of the steps are printed by `dpgen2 showkey`. In the example, all the steps before the `iter-000001--run-fp-000000` will be used in the new workflow.

CHAPTER

TWO

COMMAND LINE INTERFACE

DPGEN2: concurrent learning workflow generating the machine learning potential energy models.

```
usage: dpgen2 [-h] [-v]
              {submit,resubmit,showkey,status,download,watch,gui,terminate,stop,suspend,
↪delete,retry,resume,restart}
              ...
```

2.1 Named Arguments

-v, --version show program's version number and exit

2.2 Valid subcommands

command Possible choices: submit, resubmit, showkey, status, download, watch, gui, terminate, stop, suspend, delete, retry, resume, restart

2.3 Sub-commands

2.3.1 submit

Submit DPGEN2 workflow

```
dpgen2 submit [-h] CONFIG
```

Positional Arguments

CONFIG the config file in json format defining the workflow.

2.3.2 resubmit

Submit DPGEN2 workflow resuing steps from an existing workflow

```
dpgen2 resubmit [-h] [-l] [-u REUSE [REUSE ...]] [-k] [-f] CONFIG ID
```

Positional Arguments

CONFIG the config file in json format defining the workflow.

ID the ID of the existing workflow.

Named Arguments

-l, --list list the Steps of the existing workflow.

Default: False

-u, --reuse specify which Steps to reuse.

-k, --keep-schedule if set then keep schedule of the old workflow. otherwise use the schedule defined in the input file

Default: False

-f, --fold if set then super OPs are folded to be reused in the new workflow

Default: False

2.3.3 showkey

Print the keys of the successful DPGEN2 steps

```
dpgen2 showkey [-h] CONFIG ID
```

Positional Arguments

CONFIG the config file in json format.

ID the ID of the existing workflow.

2.3.4 status

Print the status (stage, iteration, convergence) of the DPGEN2 workflow

```
dpgen2 status [-h] CONFIG ID
```

Positional Arguments

CONFIG the config file in json format.

ID the ID of the existing workflow.

2.3.5 download

Typically there are three ways of using the command

1. list all supported steps and their input/output artifacts $ dpgen2 download CONFIG ID -l

2. donwload all the input/output of all the steps. $ dpgen2 download CONFIG ID

3. donwload specified input/output artifacts of certain steps. For example $ dpgen2 download CONFIG ID -i 0-8 8 9 -d prep-run-train/input/init_data prep-run-explore/output/trajs

The command will download the init_data of prep-run-train's input and trajs of the prep-run-explore's output from iterations 0 to 9 (by -i 0-8 8 9). The supported step and the names of input/output can be checked by the -l flag.

```
dpgen2 download [-h] [-l] [-k KEYS [KEYS ...]]
                [-i ITERATIONS [ITERATIONS ...]]
                [-d STEP_DEFINITIONS [STEP_DEFINITIONS ...]] [-p PREFIX] [-n]
                CONFIG ID
```

Positional Arguments

CONFIG the config file in json format.

ID the ID of the existing workflow.

Named Arguments

-l, --list-supported list all supported steps artifacts

Default: False

-k, --keys the keys of the downloaded steps. If not provided download all artifacts

-i, --iterations the iterations to be downloaded, support ranging expression as 0-10.

-d, --step-definitions the definition for downloading step artifacts

-p, --prefix the prefix of the path storing the download artifacts

-n, --no-check-point if specified, download regardless whether check points exist.

Default: True

2.3.6 watch

Watch a DPGEN2 workflow

```
dpgen2 watch [-h] [-k KEYS [KEYS ...]] [-f FREQUENCY] [-d] [-p PREFIX] [-n]
             CONFIG ID
```

Positional Arguments

CONFIG	the config file in json format.
ID	the ID of the existing workflow.

Named Arguments

-k, --keys	the subkey to watch. For example, 'prep-run-train' 'prep-run-explore'
	Default: ['prep-run-train', 'prep-run-explore', 'prep-run-fp', 'collect-data']
-f, --frequency	the frequency of workflow status query. In unit of second
	Default: 600.0
-d, --download	whether to download artifacts of a step when it finishes
	Default: False
-p, --prefix	the prefix of the path storing the download artifacts
-n, --no-check-point	if specified, download regardless whether check points exist.
	Default: True

2.3.7 gui

Serve DP-GUI.

```
dpgen2 gui [-h] [-p PORT] [--bind_all]
```

Named Arguments

-p, --port	The port to serve DP-GUI on.
	Default: 6042
--bind_all	Serve on all public interfaces. This will expose your DP-GUI instance to the network on both IPv4 and IPv6 (where available).
	Default: False

2.3.8 terminate

Terminate a DPGEN2 workflow.

```
dpgen2 terminate [-h] CONFIG ID
```

Positional Arguments

CONFIG the config file in json format.

ID the ID of the workflow.

2.3.9 stop

Stop a DPGEN2 workflow.

```
dpgen2 stop [-h] CONFIG ID
```

Positional Arguments

CONFIG the config file in json format.

ID the ID of the workflow.

2.3.10 suspend

Suspend a DPGEN2 workflow.

```
dpgen2 suspend [-h] CONFIG ID
```

Positional Arguments

CONFIG the config file in json format.

ID the ID of the workflow.

2.3.11 delete

Delete a DPGEN2 workflow.

```
dpgen2 delete [-h] CONFIG ID
```

Positional Arguments

CONFIG the config file in json format.

ID the ID of the workflow.

2.3.12 retry

Retry a DPGEN2 workflow.

```
dpgen2 retry [-h] CONFIG ID
```

Positional Arguments

CONFIG the config file in json format.

ID the ID of the workflow.

2.3.13 resume

Resume a DPGEN2 workflow.

```
dpgen2 resume [-h] CONFIG ID
```

Positional Arguments

CONFIG the config file in json format.

ID the ID of the workflow.

2.3.14 restart

restart a DPGEN2 workflow (for debug mode only).

```
dpgen2 restart [-h] CONFIG ID
```

Positional Arguments

CONFIG the config file in json format.

ID the ID of the workflow.

CHAPTER

THREE

GUIDE ON WRITING INPUT SCRIPTS FOR DPGEN2 COMMANDS

3.1 Preliminaries

The reader of this doc is assumed to be familiar with the concurrent learning algorithm that the dpgen2 implements. If not, one may check this paper.

3.2 The input script for all dpgen2 commands

For all the dpgen2 commands, one need to provide `dflow2` global configurations. For example,

```
    "dflow_config" : {
        "host" : "http://address.of.the.host:port"
    },
    "dflow_s3_config" : {
        "endpoint" : "address.of.the.s3.sever:port"
    },
```

The `dpgen` simply pass all keys of `"dflow_config"` to `dflow.config` and all keys of `"dflow_s3_config"` to `dflow.s3_config`.

3.3 The input script for `submit` and `resubmit`

The full documentation of the `submit` and `resubmit` script can be *found here*. This documentation provides a fast guide on how to write the input script.

In the input script of `dpgen2 submit` and `dpgen2 resubmit`, one needs to provide the definition of the workflow and how they are executed in the input script. One may find an example input script in the dpgen2 Al-Mg alloy example.

The definition of the workflow can be provided by the following sections:

3.3.1 Inputs

This section provides the inputs to start a dpgen2 workflow. An example for the Al-Mg alloy

```
"inputs": {
        "type_map":                ["Al", "Mg"],
        "mass_map":                [27, 24],
        "init_data_sys":        [
                "path/to/init/data/system/0",
                "path/to/init/data/system/1"
        ],
}
```

The key *"init_data_sys"* provides the initial training data to kick-off the training of deep potential (DP) models.

3.3.2 Training

This section defines how a model is trained.

```
"train" : {
        "type" : "dp",
        "numb_models" : 4,
        "config" : {},
        "template_script" : "/path/to/the/template/input.json",
        "_comment" : "all"
}
```

The `"type" : "dp"` tell the traning method is *"dp"*, i.e. calling DeePMD-kit to train DP models. The `"config"` key defines the training configs, see *the full documentation*. The *"template_script"* provides the template training script in `json` format.

3.3.3 Exploration

This section defines how the configuration space is explored.

```
"explore" : {
        "type" : "lmp",
        "config" : {
                "command": "lmp -var restart 0"
        },
        "convergence": {
            "type" :        "fixed-levels",
            "conv_accuracy" :        0.9,
            "level_f_lo":        0.05,
            "level_f_hi":        0.50,
            "_comment" : "all"
        },
        "max_numb_iter" :        5,
        "fatal_at_max" :        false,
        "configurations":        [
                {
                "type": "alloy",
```

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```
                "lattice" : ["fcc", 4.57],
                "replicate" : [2, 2, 2],
                "numb_confs" : 30,
                "concentration" : [[1.0, 0.0], [0.5, 0.5], [0.0, 1.0]]
                },
                {
                "type" : "file",
                "prefix": "/file/prefix",
                "files" : ["relpath/to/confs/*"],
                "fmt" : "deepmd/npy"
                }
        ],
        "stages":       [
            [
                {
                    "_comment" : "stage 0, task group 0",
                    "type" : "lmp-md",
                    "ensemble": "nvt", "nsteps":  50, "temps": [50, 100], "trj_freq": 10,
                    "conf_idx": [0], "n_sample" : 3
                },
                {
                    "_comment" : "stage 0, task group 1",
                    "type" : "lmp-template",
                    "lmp" : "template.lammps", "plm" : "template.plumed",
                    "trj_freq" : 10, "revisions" : {"V_NSTEPS" : [40], "V_TEMP" : [150,␣
↪200]},
                    "conf_idx": [0], "n_sample" : 3
                }
            ],
            [
                {
                    "_comment" : "stage 1, task group 0",
                    "type" : "lmp-md",
                    "ensemble": "npt", "nsteps":  50, "press": [1e0], "temps": [50, 100,␣
↪200], "trj_freq": 10,
                    "conf_idx": [1], "n_sample" : 3
                }
            ]
        ]
}
```

The *"type" : "lmp"* means that configurations are explored by LAMMPS DPMD runs. The *"config"* key defines the lmp configs. The *"configurations"* provides the initial configurations (coordinates of atoms and the simulation cell) of the DPMD simulations. It is a list. The elements of the list are `dict`s that defines how the configurations are generated

- Automatic alloy configuration generator. See *the detailed doc* for the allowed keys.
- Configurations load from files. See *the detailed doc* for the allowed keys.

The *"stages"* defines the exploration stages. It is of type `list[list[dict]]`. The outer `list` enumerate the exploration stages, the inner list enumerate the task groups of the stage. Each `dict` defines a stage. See *the full documentation of the task group* for writting task groups.

The *"n_sample"* tells the number of confgiruations randomly sampled from the set picked by *"conf_idx"* from

"configurations" for each exploration task. All configurations has the equal possibility to be sampled. The default value of "n_sample" is null, in this case all picked configurations are sampled. In the example, we have 3 samples for stage 0 task group 0 and 2 thermodynamic states (NVT, T=50 and 100K), then the task group has 3x2=6 NVT DPMD tasks.

3.3.4 FP

This section defines the first-principle (FP) calculation .

```
"fp" : {
        "type": "vasp",
        "task_max":        2,
        "run_config": {
                "command": "source /opt/intel/oneapi/setvars.sh && mpirun -n 16 vasp_std"
        },
        "inputs_config": {
                "pp_files":        {"Al" : "vasp/POTCAR.Al", "Mg" : "vasp/POTCAR.Mg"},
                "kspacing":        0.32,
                "incar": "vasp/INCAR"
        }
}
```

The *"type" : "vasp"* means that first-principles are VASP calculations. The *"run_config"* key defines the configs for running VASP tasks. The *"task_max"* key defines the maximal number of vasp calculations in each dpgen2 iteration. The *"pp_files"*, *"kspacing"* and *"incar"* keys provides the pseudopotential files, spacing for kspace sampling and the template incar file, respectively.

3.3.5 Configuration of dflow step

The execution units of the dpgen2 are the dflow Steps. How each step is executed is defined by the *"step_configs"*.

```
"step_configs":{
        "prep_train_config" : {
                "_comment" : "content omitted"
        },
        "run_train_config" : {
                "_comment" : "content omitted"
        },
        "prep_explore_config" : {
                "_comment" : "content omitted"
        },
        "run_explore_config" : {
                "_comment" : "content omitted"
        },
        "prep_fp_config" : {
                "_comment" : "content omitted"
        },
        "run_fp_config" : {
                "_comment" : "content omitted"
        },
        "select_confs_config" : {
                "_comment" : "content omitted"
```

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```
        },
        "collect_data_config" : {
                "_comment" : "content omitted"
        },
        "cl_step_config" : {
                "_comment" : "content omitted"
        },
        "_comment" : "all"
},
```

The configs for prepare training, run training, prepare exploration, run exploration, prepare fp, run fp, select configurations, collect data and concurrent learning steps are given correspondingly.

Any of the config in the *"step_configs"* can be ommitted. If so, the configs of the step is set to the default step configs, which is provided by the following section, for example,

```
"default_step_config" : {
        "template_config" : {
            "image" : "dpgen2:x.x.x"
        }
},
```

The way of writing the *"default_step_config"* is the same as any step config in the *"step_configs"*.

CHAPTER

FOUR

ARGUMENTS OF THE SUBMIT SCRIPT

Note: One can load, modify, and export the input file by using our effective web-based tool DP-GUI online or hosted using the *command line interface* `dpgen2 gui`. All parameters below can be set in DP-GUI. By clicking "SAVE JSON", one can download the input file.

dflow_config:

type: `dict` | `NoneType`, optional, default: `None`
argument path: `dflow_config`

The configuration passed to dflow

dflow_s3_config:

type: `dict` | `NoneType`, optional, default: `None`
argument path: `dflow_s3_config`

The S3 configuration passed to dflow

default_step_config:

type: `dict`, optional, default: `{}`
argument path: `default_step_config`

The default step configuration.

template_config:

type: `dict`, optional, default: `{'image': 'dptechnology/dpgen2:latest'}`
argument path: `default_step_config/template_config`

The configs passed to the PythonOPTemplate.

image:

type: `str`, optional, default: `dptechnology/dpgen2:latest`
argument path: `default_step_config/template_config/image`

The image to run the step.

timeout:

type: `NoneType` | `int`, optional, default: `None`
argument path: `default_step_config/template_config/timeout`

The time limit of the OP. Unit is second.

retry_on_transient_error:

type: NoneType | int, optional, default: None

argument path: default_step_config/template_config/retry_on_transient_error

The number of retry times if a TransientError is raised.

timeout_as_transient_error:

type: bool, optional, default: False

argument path: default_step_config/template_config/timeout_as_transient_error

Treat the timeout as TransientError.

envs:

type: dict | NoneType, optional, default: None

argument path: default_step_config/template_config/envs

The environmental variables.

template_slice_config:

type: dict, optional

argument path: default_step_config/template_slice_config

The configs passed to the Slices.

group_size:

type: NoneType | int, optional, default: None

argument path: default_step_config/template_slice_config/group_size

The number of tasks running on a single node. It is efficient for a large number of short tasks.

pool_size:

type: NoneType | int, optional, default: None

argument path: default_step_config/template_slice_config/pool_size

The number of tasks running at the same time on one node.

continue_on_failed:

type: bool, optional, default: False

argument path: default_step_config/continue_on_failed

If continue the the step is failed (FatalError, TransientError, A certain number of retrial is reached...).

continue_on_num_success:

type: NoneType | int, optional, default: None

argument path: default_step_config/continue_on_num_success

Only in the sliced OP case. Continue the workflow if a certain number of the sliced jobs are successful.

continue_on_success_ratio:

type: NoneType | float, optional, default: None
argument path: default_step_config/continue_on_success_ratio

Only in the sliced OP case. Continue the workflow if a certain ratio of the sliced jobs are successful.

parallelism:

type: NoneType | int, optional, default: None
argument path: default_step_config/parallelism

The parallelism for the step

executor:

type: dict | NoneType, optional, default: None
argument path: default_step_config/executor

The executor of the step.

Depending on the value of *type*, different sub args are accepted.

type:

type: str (flag key)
argument path: default_step_config/executor/type
possible choices: *dispatcher*

The type of the executor.

When type is set to dispatcher:

bohrium_config:

type: dict | NoneType, optional, default: None
argument path: bohrium_config

Configurations for the Bohrium platform.

username:

type: str
argument path: bohrium_config/username

The username of the Bohrium platform

password:

type: str
argument path: bohrium_config/password

The password of the Bohrium platform

project_id:

type: int
argument path: bohrium_config/project_id

The project ID of the Bohrium platform

host:

type: str, optional, default: https://workflows.deepmodeling.com
argument path: bohrium_config/host

The host name of the Bohrium platform. Will overwrite *dflow_config['host']*

k8s_api_server:

type: str, optional, default: https://workflows.deepmodeling.com
argument path: bohrium_config/k8s_api_server

The k8s server of the Bohrium platform. Will overwrite *dflow_config['k8s_api_server']*

repo_key:

type: str, optional, default: oss-bohrium
argument path: bohrium_config/repo_key

The repo key of the Bohrium platform. Will overwrite *dflow_s3_config['repo_key']*

storage_client:

type: str, optional, default: dflow.plugins.bohrium.TiefblueClient
argument path: bohrium_config/storage_client

The storage client of the Bohrium platform. Will overwrite *dflow_s3_config['storage_client']*

step_configs:

type: dict, optional, default: {}
argument path: step_configs

Configurations for executing dflow steps

prep_train_config:

type: dict, optional, default: {'template_config': {'image': 'dptechnology/dpgen2:latest', 'timeout': None, 'retry_on_transient_error': None, 'timeout_as_transient_error': False, 'envs': None}, 'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'parallelism': None, 'executor': None}
argument path: step_configs/prep_train_config

Configuration for prepare train

template_config:

type: dict, optional, default: {'image': 'dptechnology/dpgen2:latest'}
argument path: step_configs/prep_train_config/template_config

The configs passed to the PythonOPTemplate.

image:

type: str, optional, default: dptechnology/dpgen2:latest

argument path: step_configs/prep_train_config/template_config/image

The image to run the step.

timeout:

type: NoneType | int, optional, default: None

argument path: step_configs/prep_train_config/template_config/timeout

The time limit of the OP. Unit is second.

retry_on_transient_error:

type: NoneType | int, optional, default: None

argument path: step_configs/prep_train_config/template_config/retry_on_transient_error

The number of retry times if a TransientError is raised.

timeout_as_transient_error:

type: bool, optional, default: False

argument path: step_configs/prep_train_config/template_config/timeout_as_transient_error

Treat the timeout as TransientError.

envs:

type: dict | NoneType, optional, default: None

argument path: step_configs/prep_train_config/template_config/envs

The environmental variables.

template_slice_config:

type: dict, optional

argument path: step_configs/prep_train_config/template_slice_config

The configs passed to the Slices.

group_size:

type: NoneType | int, optional, default: None

argument path: step_configs/prep_train_config/template_slice_config/group_size

The number of tasks running on a single node. It is efficient for a large number of short tasks.

pool_size:

type: NoneType | int, optional, default: None

argument path: step_configs/prep_train_config/template_slice_config/pool_size

The number of tasks running at the same time on one node.

continue_on_failed:

type: bool, optional, default: False

argument path:
step_configs/prep_train_config/continue_on_failed

If continue the the step is failed (FatalError, TransientError, A certain number of retrial is reached...).

continue_on_num_success:

type: NoneType | int, optional, default: None
argument path: step_configs/prep_train_config/continue_on_num_success

Only in the sliced OP case. Continue the workflow if a certain number of the sliced jobs are successful.

continue_on_success_ratio:

type: NoneType | float, optional, default: None
argument path: step_configs/prep_train_config/continue_on_success_ratio

Only in the sliced OP case. Continue the workflow if a certain ratio of the sliced jobs are successful.

parallelism:

type: NoneType | int, optional, default: None
argument path:
step_configs/prep_train_config/parallelism

The parallelism for the step

executor:

type: dict | NoneType, optional, default: None
argument path: step_configs/prep_train_config/executor

The executor of the step.

Depending on the value of *type*, different sub args are accepted.

type:

type: str (flag key)
argument path:
step_configs/prep_train_config/executor/type
possible choices: *dispatcher*

The type of the executor.

When type is set to dispatcher:

run_train_config:

type: dict, optional, default: {'template_config': {'image': 'dptechnology/dpgen2:latest', 'timeout': None, 'retry_on_transient_error': None, 'timeout_as_transient_error': False, 'envs': None}, 'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'parallelism': None, 'executor': None}

argument path: step_configs/run_train_config

Configuration for run train

template_config:

type: dict, optional, default: {'image': 'dptechnology/dpgen2:latest'}
argument path: step_configs/run_train_config/template_config

The configs passed to the PythonOPTemplate.

image:

type: str, optional, default: dptechnology/dpgen2:latest
argument path: step_configs/run_train_config/template_config/image

The image to run the step.

timeout:

type: NoneType | int, optional, default: None
argument path: step_configs/run_train_config/template_config/timeout

The time limit of the OP. Unit is second.

retry_on_transient_error:

type: NoneType | int, optional, default: None
argument path: step_configs/run_train_config/template_config/retry_on_transient_error

The number of retry times if a TransientError is raised.

timeout_as_transient_error:

type: bool, optional, default: False
argument path: step_configs/run_train_config/template_config/timeout_as_transient_error

Treat the timeout as TransientError.

envs:

type: dict | NoneType, optional, default: None
argument path: step_configs/run_train_config/template_config/envs

The environmental variables.

template_slice_config:

type: dict, optional
argument path: step_configs/run_train_config/template_slice_config

The configs passed to the Slices.

group_size:

type: NoneType | int, optional, default: None

argument path: step_configs/run_train_config/template_slice_config/group_size

The number of tasks running on a single node. It is efficient for a large number of short tasks.

pool_size:

type: NoneType | int, optional, default: None
argument path: step_configs/run_train_config/template_slice_config/pool_size

The number of tasks running at the same time on one node.

continue_on_failed:

type: bool, optional, default: False
argument path: step_configs/run_train_config/continue_on_failed

If continue the the step is failed (FatalError, TransientError, A certain number of retrial is reached…).

continue_on_num_success:

type: NoneType | int, optional, default: None
argument path: step_configs/run_train_config/continue_on_num_success

Only in the sliced OP case. Continue the workflow if a certain number of the sliced jobs are successful.

continue_on_success_ratio:

type: NoneType | float, optional, default: None
argument path: step_configs/run_train_config/continue_on_success_ratio

Only in the sliced OP case. Continue the workflow if a certain ratio of the sliced jobs are successful.

parallelism:

type: NoneType | int, optional, default: None
argument path: step_configs/run_train_config/parallelism

The parallelism for the step

executor:

type: dict | NoneType, optional, default: None
argument path: step_configs/run_train_config/executor

The executor of the step.

Depending on the value of *type*, different sub args are accepted.

type:

type: str (flag key)

argument path: step_configs/run_train_config/executor/type

possible choices: *dispatcher*

The type of the executor.

When type is set to dispatcher:

prep_explore_config:

type: dict, optional, default: {'template_config': {'image': 'dptechnology/dpgen2:latest', 'timeout': None, 'retry_on_transient_error': None, 'timeout_as_transient_error': False, 'envs': None}, 'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'parallelism': None, 'executor': None}

argument path: step_configs/prep_explore_config

Configuration for prepare exploration

template_config:

type: dict, optional, default: {'image': 'dptechnology/dpgen2:latest'}

argument path: step_configs/prep_explore_config/template_config

The configs passed to the PythonOPTemplate.

image:

type: str, optional, default: dptechnology/dpgen2:latest

argument path: step_configs/prep_explore_config/template_config/image

The image to run the step.

timeout:

type: NoneType | int, optional, default: None

argument path: step_configs/prep_explore_config/template_config/timeout

The time limit of the OP. Unit is second.

retry_on_transient_error:

type: NoneType | int, optional, default: None

argument path: step_configs/prep_explore_config/template_config/retry_on_transient_error

The number of retry times if a TransientError is raised.

timeout_as_transient_error:

type: bool, optional, default: False

argument path:
step_configs/prep_explore_config/
template_config/timeout_as_transient_error

Treat the timeout as TransientError.

envs:

type: dict | NoneType, optional, default: None
argument path: step_configs/
prep_explore_config/template_config/envs

The environmental variables.

template_slice_config:

type: dict, optional
argument path: step_configs/prep_explore_config/
template_slice_config

The configs passed to the Slices.

group_size:

type: NoneType | int, optional, default: None
argument path:
step_configs/prep_explore_config/
template_slice_config/group_size

The number of tasks running on a single node. It is efficient for a large number of short tasks.

pool_size:

type: NoneType | int, optional, default: None
argument path:
step_configs/prep_explore_config/
template_slice_config/pool_size

The number of tasks running at the same time on one node.

continue_on_failed:

type: bool, optional, default: False
argument path: step_configs/prep_explore_config/
continue_on_failed

If continue the the step is failed (FatalError, TransientError, A certain number of retrial is reached...).

continue_on_num_success:

type: NoneType | int, optional, default: None
argument path: step_configs/prep_explore_config/
continue_on_num_success

Only in the sliced OP case. Continue the workflow if a certain number of the sliced jobs are successful.

continue_on_success_ratio:

type: NoneType | float, optional, default: None

argument path: step_configs/prep_explore_config/continue_on_success_ratio

Only in the sliced OP case. Continue the workflow if a certain ratio of the sliced jobs are successful.

parallelism:

type: NoneType | int, optional, default: None
argument path: step_configs/prep_explore_config/parallelism

The parallelism for the step

executor:

type: dict | NoneType, optional, default: None
argument path: step_configs/prep_explore_config/executor

The executor of the step.

Depending on the value of *type*, different sub args are accepted.

type:

type: str (flag key)
argument path: step_configs/prep_explore_config/executor/type
possible choices: *dispatcher*

The type of the executor.

When type is set to dispatcher:

run_explore_config:

type: dict, optional, default: {'template_config': {'image': 'dptechnology/dpgen2:latest', 'timeout': None, 'retry_on_transient_error': None, 'timeout_as_transient_error': False, 'envs': None}, 'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'parallelism': None, 'executor': None}
argument path: step_configs/run_explore_config

Configuration for run exploration

template_config:

type: dict, optional, default: {'image': 'dptechnology/dpgen2:latest'}
argument path: step_configs/run_explore_config/template_config

The configs passed to the PythonOPTemplate.

image:

type: str, optional, default: dptechnology/dpgen2:latest

argument path: step_configs/run_explore_config/template_config/image

The image to run the step.

timeout:

type: NoneType | int, optional, default: None

argument path: step_configs/run_explore_config/template_config/timeout

The time limit of the OP. Unit is second.

retry_on_transient_error:

type: NoneType | int, optional, default: None

argument path: step_configs/run_explore_config/template_config/retry_on_transient_error

The number of retry times if a TransientError is raised.

timeout_as_transient_error:

type: bool, optional, default: False

argument path: step_configs/run_explore_config/template_config/timeout_as_transient_error

Treat the timeout as TransientError.

envs:

type: dict | NoneType, optional, default: None

argument path: step_configs/run_explore_config/template_config/envs

The environmental variables.

template_slice_config:

type: dict, optional

argument path: step_configs/run_explore_config/template_slice_config

The configs passed to the Slices.

group_size:

type: NoneType | int, optional, default: None

argument path: step_configs/run_explore_config/template_slice_config/group_size

The number of tasks running on a single node. It is efficient for a large number of short tasks.

pool_size:

type: NoneType | int, optional, default: None

argument path: step_configs/run_explore_config/template_slice_config/pool_size

The number of tasks running at the same time on one node.

continue_on_failed:

type: bool, optional, default: False
argument path: step_configs/run_explore_config/continue_on_failed

If continue the the step is failed (FatalError, TransientError, A certain number of retrial is reached…).

continue_on_num_success:

type: NoneType | int, optional, default: None
argument path: step_configs/run_explore_config/continue_on_num_success

Only in the sliced OP case. Continue the workflow if a certain number of the sliced jobs are successful.

continue_on_success_ratio:

type: NoneType | float, optional, default: None
argument path: step_configs/run_explore_config/continue_on_success_ratio

Only in the sliced OP case. Continue the workflow if a certain ratio of the sliced jobs are successful.

parallelism:

type: NoneType | int, optional, default: None
argument path: step_configs/run_explore_config/parallelism

The parallelism for the step

executor:

type: dict | NoneType, optional, default: None
argument path: step_configs/run_explore_config/executor

The executor of the step.

Depending on the value of *type*, different sub args are accepted.

type:

type: str (flag key)
argument path: step_configs/run_explore_config/executor/type
possible choices: *dispatcher*

The type of the executor.

When type is set to dispatcher:

prep_fp_config:

type: dict, optional, default: {'template_config': {'image': 'dptechnology/dpgen2:latest', 'timeout': None, 'retry_on_transient_error': None, 'timeout_as_transient_error': False, 'envs': None},

'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'parallelism': None, 'executor': None}

argument path: step_configs/prep_fp_config

Configuration for prepare fp

template_config:

type: dict, optional, default: {'image': 'dptechnology/dpgen2:latest'}

argument path: step_configs/prep_fp_config/template_config

The configs passed to the PythonOPTemplate.

image:

type: str, optional, default: dptechnology/dpgen2:latest

argument path: step_configs/prep_fp_config/template_config/image

The image to run the step.

timeout:

type: NoneType | int, optional, default: None

argument path: step_configs/prep_fp_config/template_config/timeout

The time limit of the OP. Unit is second.

retry_on_transient_error:

type: NoneType | int, optional, default: None

argument path: step_configs/prep_fp_config/template_config/retry_on_transient_error

The number of retry times if a TransientError is raised.

timeout_as_transient_error:

type: bool, optional, default: False

argument path: step_configs/prep_fp_config/template_config/timeout_as_transient_error

Treat the timeout as TransientError.

envs:

type: dict | NoneType, optional, default: None

argument path: step_configs/prep_fp_config/template_config/envs

The environmental variables.

template_slice_config:

type: dict, optional

argument path: step_configs/prep_fp_config/template_slice_config

The configs passed to the Slices.

group_size:

type: NoneType | int, optional, default: None

argument path: step_configs/prep_fp_config/template_slice_config/group_size

The number of tasks running on a single node. It is efficient for a large number of short tasks.

pool_size:

type: NoneType | int, optional, default: None

argument path: step_configs/prep_fp_config/template_slice_config/pool_size

The number of tasks running at the same time on one node.

continue_on_failed:

type: bool, optional, default: False

argument path: step_configs/prep_fp_config/continue_on_failed

If continue the the step is failed (FatalError, TransientError, A certain number of retrial is reached…).

continue_on_num_success:

type: NoneType | int, optional, default: None

argument path: step_configs/prep_fp_config/continue_on_num_success

Only in the sliced OP case. Continue the workflow if a certain number of the sliced jobs are successful.

continue_on_success_ratio:

type: NoneType | float, optional, default: None

argument path: step_configs/prep_fp_config/continue_on_success_ratio

Only in the sliced OP case. Continue the workflow if a certain ratio of the sliced jobs are successful.

parallelism:

type: NoneType | int, optional, default: None

argument path: step_configs/prep_fp_config/parallelism

The parallelism for the step

executor:

type: dict | NoneType, optional, default: None

argument path: step_configs/prep_fp_config/executor

The executor of the step.

Depending on the value of *type*, different sub args are accepted.

type:

type: str (flag key)

argument path: step_configs/prep_fp_config/executor/type

possible choices: *dispatcher*

The type of the executor.

When type is set to dispatcher:

run_fp_config:

type: dict, optional, default: {'template_config': {'image': 'dptechnology/dpgen2:latest', 'timeout': None, 'retry_on_transient_error': None, 'timeout_as_transient_error': False, 'envs': None}, 'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'parallelism': None, 'executor': None}

argument path: step_configs/run_fp_config

Configuration for run fp

template_config:

type: dict, optional, default: {'image': 'dptechnology/dpgen2:latest'}

argument path: step_configs/run_fp_config/template_config

The configs passed to the PythonOPTemplate.

image:

type: str, optional, default: dptechnology/dpgen2:latest

argument path: step_configs/run_fp_config/template_config/image

The image to run the step.

timeout:

type: NoneType | int, optional, default: None

argument path: step_configs/run_fp_config/template_config/timeout

The time limit of the OP. Unit is second.

retry_on_transient_error:

type: NoneType | int, optional, default: None

argument path: step_configs/run_fp_config/template_config/retry_on_transient_error

The number of retry times if a TransientError is raised.

timeout_as_transient_error:

type: bool, optional, default: False

argument path: step_configs/run_fp_config/template_config/timeout_as_transient_error

Treat the timeout as TransientError.

envs:

type: dict | NoneType, optional, default: None

argument path: step_configs/run_fp_config/template_config/envs

The environmental variables.

template_slice_config:

type: dict, optional

argument path: step_configs/run_fp_config/template_slice_config

The configs passed to the Slices.

group_size:

type: NoneType | int, optional, default: None

argument path: step_configs/run_fp_config/template_slice_config/group_size

The number of tasks running on a single node. It is efficient for a large number of short tasks.

pool_size:

type: NoneType | int, optional, default: None

argument path: step_configs/run_fp_config/template_slice_config/pool_size

The number of tasks running at the same time on one node.

continue_on_failed:

type: bool, optional, default: False

argument path: step_configs/run_fp_config/continue_on_failed

If continue the the step is failed (FatalError, TransientError, A certain number of retrial is reached…).

continue_on_num_success:

type: NoneType | int, optional, default: None

argument path: step_configs/run_fp_config/continue_on_num_success

Only in the sliced OP case. Continue the workflow if a certain number of the sliced jobs are successful.

continue_on_success_ratio:

type: NoneType | float, optional, default: None

argument path: step_configs/run_fp_config/continue_on_success_ratio

Only in the sliced OP case. Continue the workflow if a certain ratio of the sliced jobs are successful.

parallelism:

type: NoneType | int, optional, default: None
argument path: step_configs/run_fp_config/parallelism

The parallelism for the step

executor:

type: dict | NoneType, optional, default: None
argument path: step_configs/run_fp_config/executor

The executor of the step.

Depending on the value of *type*, different sub args are accepted.

type:

type: str (flag key)
argument path: step_configs/run_fp_config/executor/type
possible choices: *dispatcher*

The type of the executor.

When type is set to dispatcher:

select_confs_config:

type: dict, optional, default: {'template_config': {'image': 'dptechnology/dpgen2:latest', 'timeout': None, 'retry_on_transient_error': None, 'timeout_as_transient_error': False, 'envs': None}, 'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'parallelism': None, 'executor': None}
argument path: step_configs/select_confs_config

Configuration for the select confs

template_config:

type: dict, optional, default: {'image': 'dptechnology/dpgen2:latest'}
argument path: step_configs/select_confs_config/template_config

The configs passed to the PythonOPTemplate.

image:

type: str, optional, default: dptechnology/dpgen2:latest
argument path: step_configs/select_confs_config/template_config/image

The image to run the step.

timeout:

type: NoneType | int, optional, default: None

argument path:
step_configs/select_confs_config/
template_config/timeout

The time limit of the OP. Unit is second.

retry_on_transient_error:

type: NoneType | int, optional, default: None
argument path:
step_configs/select_confs_config/
template_config/retry_on_transient_error

The number of retry times if a TransientError is raised.

timeout_as_transient_error:

type: bool, optional, default: False
argument path:
step_configs/select_confs_config/
template_config/timeout_as_transient_error

Treat the timeout as TransientError.

envs:

type: dict | NoneType, optional, default: None
argument path: step_configs/
select_confs_config/template_config/envs

The environmental variables.

template_slice_config:

type: dict, optional
argument path: step_configs/select_confs_config/
template_slice_config

The configs passed to the Slices.

group_size:

type: NoneType | int, optional, default: None
argument path:
step_configs/select_confs_config/
template_slice_config/group_size

The number of tasks running on a single node. It is efficient for a large number of short tasks.

pool_size:

type: NoneType | int, optional, default: None
argument path:
step_configs/select_confs_config/
template_slice_config/pool_size

The number of tasks running at the same time on one node.

continue_on_failed:

type: bool, optional, default: False

argument path: step_configs/select_confs_config/continue_on_failed

If continue the the step is failed (FatalError, TransientError, A certain number of retrial is reached…).

continue_on_num_success:

type: NoneType | int, optional, default: None
argument path: step_configs/select_confs_config/continue_on_num_success

Only in the sliced OP case. Continue the workflow if a certain number of the sliced jobs are successful.

continue_on_success_ratio:

type: NoneType | float, optional, default: None
argument path: step_configs/select_confs_config/continue_on_success_ratio

Only in the sliced OP case. Continue the workflow if a certain ratio of the sliced jobs are successful.

parallelism:

type: NoneType | int, optional, default: None
argument path: step_configs/select_confs_config/parallelism

The parallelism for the step

executor:

type: dict | NoneType, optional, default: None
argument path: step_configs/select_confs_config/executor

The executor of the step.

Depending on the value of *type*, different sub args are accepted.

type:

type: str (flag key)
argument path: step_configs/select_confs_config/executor/type
possible choices: *dispatcher*

The type of the executor.

When type is set to dispatcher:

collect_data_config:

type: dict, optional, default: {'template_config': {'image': 'dptechnology/dpgen2:latest', 'timeout': None, 'retry_on_transient_error': None, 'timeout_as_transient_error': False, 'envs': None}, 'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'parallelism': None, 'executor': None}

argument path: step_configs/collect_data_config

Configuration for the collect data

template_config:

type: dict, optional, default: {'image': 'dptechnology/dpgen2:latest'}
argument path: step_configs/collect_data_config/template_config

The configs passed to the PythonOPTemplate.

image:

type: str, optional, default: dptechnology/dpgen2:latest
argument path: step_configs/collect_data_config/template_config/image

The image to run the step.

timeout:

type: NoneType | int, optional, default: None
argument path: step_configs/collect_data_config/template_config/timeout

The time limit of the OP. Unit is second.

retry_on_transient_error:

type: NoneType | int, optional, default: None
argument path: step_configs/collect_data_config/template_config/retry_on_transient_error

The number of retry times if a TransientError is raised.

timeout_as_transient_error:

type: bool, optional, default: False
argument path: step_configs/collect_data_config/template_config/timeout_as_transient_error

Treat the timeout as TransientError.

envs:

type: dict | NoneType, optional, default: None
argument path: step_configs/collect_data_config/template_config/envs

The environmental variables.

template_slice_config:

type: dict, optional
argument path: step_configs/collect_data_config/template_slice_config

The configs passed to the Slices.

group_size:

type: NoneType | int, optional, default: None

argument path: step_configs/collect_data_config/template_slice_config/group_size

The number of tasks running on a single node. It is efficient for a large number of short tasks.

pool_size:

type: NoneType | int, optional, default: None

argument path: step_configs/collect_data_config/template_slice_config/pool_size

The number of tasks running at the same time on one node.

continue_on_failed:

type: bool, optional, default: False

argument path: step_configs/collect_data_config/continue_on_failed

If continue the the step is failed (FatalError, TransientError, A certain number of retrial is reached…).

continue_on_num_success:

type: NoneType | int, optional, default: None

argument path: step_configs/collect_data_config/continue_on_num_success

Only in the sliced OP case. Continue the workflow if a certain number of the sliced jobs are successful.

continue_on_success_ratio:

type: NoneType | float, optional, default: None

argument path: step_configs/collect_data_config/continue_on_success_ratio

Only in the sliced OP case. Continue the workflow if a certain ratio of the sliced jobs are successful.

parallelism:

type: NoneType | int, optional, default: None

argument path: step_configs/collect_data_config/parallelism

The parallelism for the step

executor:

type: dict | NoneType, optional, default: None

argument path: step_configs/collect_data_config/executor

The executor of the step.

Depending on the value of *type*, different sub args are accepted.

type:

type: `str` (flag key)
argument path: `step_configs/collect_data_config/executor/type`
possible choices: *dispatcher*

The type of the executor.

When type is set to `dispatcher`:

cl_step_config:

type: `dict`, optional, default: `{'template_config': {'image': 'dptechnology/dpgen2:latest', 'timeout': None, 'retry_on_transient_error': None, 'timeout_as_transient_error': False, 'envs': None}, 'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'parallelism': None, 'executor': None}`
argument path: `step_configs/cl_step_config`

Configuration for the concurrent learning step

template_config:

type: `dict`, optional, default: `{'image': 'dptechnology/dpgen2:latest'}`
argument path: `step_configs/cl_step_config/template_config`

The configs passed to the PythonOPTemplate.

image:

type: `str`, optional, default: `dptechnology/dpgen2:latest`
argument path: `step_configs/cl_step_config/template_config/image`

The image to run the step.

timeout:

type: `NoneType` | `int`, optional, default: `None`
argument path: `step_configs/cl_step_config/template_config/timeout`

The time limit of the OP. Unit is second.

retry_on_transient_error:

type: `NoneType` | `int`, optional, default: `None`
argument path: `step_configs/cl_step_config/template_config/retry_on_transient_error`

The number of retry times if a TransientError is raised.

timeout_as_transient_error:

type: `bool`, optional, default: `False`

argument path: step_configs/cl_step_config/template_config/timeout_as_transient_error

Treat the timeout as TransientError.

envs:

type: dict | NoneType, optional, default: None

argument path: step_configs/cl_step_config/template_config/envs

The environmental variables.

template_slice_config:

type: dict, optional

argument path: step_configs/cl_step_config/template_slice_config

The configs passed to the Slices.

group_size:

type: NoneType | int, optional, default: None

argument path: step_configs/cl_step_config/template_slice_config/group_size

The number of tasks running on a single node. It is efficient for a large number of short tasks.

pool_size:

type: NoneType | int, optional, default: None

argument path: step_configs/cl_step_config/template_slice_config/pool_size

The number of tasks running at the same time on one node.

continue_on_failed:

type: bool, optional, default: False

argument path: step_configs/cl_step_config/continue_on_failed

If continue the the step is failed (FatalError, TransientError, A certain number of retrial is reached...).

continue_on_num_success:

type: NoneType | int, optional, default: None

argument path: step_configs/cl_step_config/continue_on_num_success

Only in the sliced OP case. Continue the workflow if a certain number of the sliced jobs are successful.

continue_on_success_ratio:

type: NoneType | float, optional, default: None

argument path: step_configs/cl_step_config/continue_on_success_ratio

Only in the sliced OP case. Continue the workflow if a certain ratio of the sliced jobs are successful.

parallelism:

type: NoneType | int, optional, default: None
argument path: step_configs/cl_step_config/parallelism

The parallelism for the step

executor:

type: dict | NoneType, optional, default: None
argument path: step_configs/cl_step_config/executor

The executor of the step.

Depending on the value of *type*, different sub args are accepted.

type:

type: str (flag key)
argument path: step_configs/cl_step_config/executor/type
possible choices: *dispatcher*

The type of the executor.

When type is set to dispatcher:

upload_python_packages:

type: typing.List[str] | str | NoneType, optional, default: None, alias: *upload_python_package*
argument path: upload_python_packages

Upload python package, for debug purpose

inputs:

type: dict
argument path: inputs

The input parameter and artifacts for dpgen2

type_map:

type: typing.List[str]
argument path: inputs/type_map

The type map. e.g. ["Al", "Mg"]. Al and Mg will have type 0 and 1, respectively.

mass_map:

type: typing.List[float]
argument path: inputs/mass_map

The mass map. e.g. [27., 24.]. Al and Mg will be set with mass 27. and 24. amu, respectively.

init_data_prefix:

type: str | NoneType, optional, default: None

argument path: inputs/init_data_prefix

The prefix of initial data systems

mixed_type:

type: bool, optional, default: False
argument path: inputs/mixed_type

Use *deepmd/npy/mixed* format for storing training data.

do_finetune:

type: bool, optional, default: False
argument path: inputs/do_finetune

Finetune the pretrained model before the first iteration. If it is set to True, then an additional step, finetune-step, which is based on a branch of "PrepRunDPTrain," will be added before the dpgen_step. In the finetune-step, the internal flag finetune_mode is set to "finetune," which means SuperOP "PrepRunDPTrain" is now used as the "Finetune." In this step, we finetune the pretrained model in the train step and modify the template after training. After that, in the normal dpgen-step, the flag do_finetune is set as "train-init," which means we use *–init-frz-model* to train based on models from the previous iteration. The "do_finetune" flag is set to False by default, while the internal flag finetune_mode is set to "no," which means anything related to finetuning will not be done.

init_data_sys:

type: typing.List[str] | str | NoneType, optional, default: None
argument path: inputs/init_data_sys

The inital data systems

multitask:

type: bool, optional, default: False
argument path: inputs/multitask

Do multitask training

head:

type: str | NoneType, optional, default: None
argument path: inputs/head

Head to use in the multitask training

multi_init_data:

type: dict | NoneType, optional, default: None
argument path: inputs/multi_init_data

The inital data for multitask, it should be a dict, whose keys are task names and each value is a dictcontaining fields *prefix* and *sys* for initial data of each task

valid_data_prefix:

type: str | NoneType, optional, default: None
argument path: inputs/valid_data_prefix

The prefix of validation data systems

valid_data_sys:

type: typing.List[str] | str | NoneType, optional, default: None
argument path: inputs/valid_data_sys

The validation data systems

train:

type: dict
argument path: train

The configuration for training

Depending on the value of *type*, different sub args are accepted.

type:

type: str (flag key)
argument path: train/type
possible choices: *dp*, *dp-dist*

the type of the training

When type is set to dp:

config:

type: dict, optional, default: {'impl': 'tensorflow', 'init_model_policy': 'no', 'init_model_old_ratio': 0.9, 'init_model_numb_steps': 400000, 'init_model_start_lr': 0.0001, 'init_model_start_pref_e': 0.1, 'init_model_start_pref_f': 100, 'init_model_start_pref_v': 0.0, 'init_model_with_finetune': False, 'finetune_args': '', 'multitask': False, 'head': None, 'multi_init_data_idx': None}
argument path: train[dp]/config

Number of models trained for evaluating the model deviation

impl:

type: str, optional, default: tensorflow, alias: *backend*
argument path: train[dp]/config/impl

The implementation/backend of DP. It can be 'tensorflow' or 'pytorch'. 'tensorflow' for default.

init_model_policy:

type: str, optional, default: no
argument path: train[dp]/config/init_model_policy

The policy of init-model training. It can be

- 'no': No init-model training. Traing from scratch.
- 'yes': Do init-model training.
- 'old_data_larger_than:XXX': Do init-model if the training data size of the previous model is larger than XXX. XXX is an int number.

init_model_old_ratio:

type: float, optional, default: 0.9
argument path: train[dp]/config/init_model_old_ratio

The frequency ratio of old data over new data

init_model_numb_steps:

type: int, optional, default: 400000, alias: *init_model_stop_batch*
argument path: train[dp]/config/init_model_numb_steps

The number of training steps when init-model

init_model_start_lr:

type: float, optional, default: 0.0001
argument path: train[dp]/config/init_model_start_lr

The start learning rate when init-model

init_model_start_pref_e:

type: float, optional, default: 0.1
argument path: train[dp]/config/init_model_start_pref_e

The start energy prefactor in loss when init-model

init_model_start_pref_f:

type: float, optional, default: 100
argument path: train[dp]/config/init_model_start_pref_f

The start force prefactor in loss when init-model

init_model_start_pref_v:

type: float, optional, default: 0.0
argument path: train[dp]/config/init_model_start_pref_v

The start virial prefactor in loss when init-model

init_model_with_finetune:

type: bool, optional, default: False
argument path: train[dp]/config/init_model_with_finetune

Use finetune for init model

finetune_args:

type: str, optional, default: (empty string)
argument path: train[dp]/config/finetune_args

Extra arguments for finetuning

multitask:

type: bool, optional, default: False
argument path: train[dp]/config/multitask

Do multitask training

head:

type: str | NoneType, optional, default: None
argument path: train[dp]/config/head

Head to use in the multitask training

multi_init_data_idx:

type: dict | NoneType, optional, default: None
argument path: train[dp]/config/multi_init_data_idx

A dict mapping from task name to list of indices in the init data

numb_models:

type: int, optional, default: 4
argument path: train[dp]/numb_models

Number of models trained for evaluating the model deviation

template_script:

type: typing.List[str] | str
argument path: train[dp]/template_script

File names of the template training script. It can be a *List[str]*, the length of which is the same as *numb_models*. Each template script in the list is used to train a model. Can be a *str*, the models share the same template training script.

init_models_paths:

type: typing.List[str] | NoneType, optional, default: None, alias: *training_iter0_model_path*
argument path: train[dp]/init_models_paths

the paths to initial models

When type is set to dp-dist:

config:

type: dict, optional, default: {'impl': 'tensorflow', 'init_model_policy': 'no', 'init_model_old_ratio': 0.9, 'init_model_numb_steps': 400000, 'init_model_start_lr': 0.0001, 'init_model_start_pref_e': 0.1, 'init_model_start_pref_f': 100, 'init_model_start_pref_v': 0.0, 'init_model_with_finetune': False, 'finetune_args': '', 'multitask': False, 'head': None, 'multi_init_data_idx': None}
argument path: train[dp-dist]/config

Configuration of training

impl:

type: str, optional, default: tensorflow, alias: *backend*
argument path: train[dp-dist]/config/impl

The implementation/backend of DP. It can be 'tensorflow' or 'pytorch'. 'tensorflow' for default.

init_model_policy:

type: str, optional, default: no
argument path:
train[dp-dist]/config/init_model_policy

The policy of init-model training. It can be

- 'no': No init-model training. Traing from scratch.
- 'yes': Do init-model training.
- 'old_data_larger_than:XXX': Do init-model if the training data size of the previous model is larger than XXX. XXX is an int number.

init_model_old_ratio:

type: float, optional, default: 0.9
argument path:
train[dp-dist]/config/init_model_old_ratio

The frequency ratio of old data over new data

init_model_numb_steps:

type: int, optional, default: 400000, alias:
init_model_stop_batch
argument path:
train[dp-dist]/config/init_model_numb_steps

The number of training steps when init-model

init_model_start_lr:

type: float, optional, default: 0.0001
argument path:
train[dp-dist]/config/init_model_start_lr

The start learning rate when init-model

init_model_start_pref_e:

type: float, optional, default: 0.1
argument path:
train[dp-dist]/config/init_model_start_pref_e

The start energy prefactor in loss when init-model

init_model_start_pref_f:

type: float, optional, default: 100

argument path:
train[dp-dist]/config/init_model_start_pref_f

The start force prefactor in loss when init-model

init_model_start_pref_v:

type: float, optional, default: 0.0
argument path:
train[dp-dist]/config/init_model_start_pref_v

The start virial prefactor in loss when init-model

init_model_with_finetune:

type: bool, optional, default: False
argument path:
train[dp-dist]/config/init_model_with_finetune

Use finetune for init model

finetune_args:

type: str, optional, default: (empty string)
argument path: train[dp-dist]/config/finetune_args

Extra arguments for finetuning

multitask:

type: bool, optional, default: False
argument path: train[dp-dist]/config/multitask

Do multitask training

head:

type: str | NoneType, optional, default: None
argument path: train[dp-dist]/config/head

Head to use in the multitask training

multi_init_data_idx:

type: dict | NoneType, optional, default: None
argument path:
train[dp-dist]/config/multi_init_data_idx

A dict mapping from task name to list of indices in the init data

template_script:

type: typing.List[str] | str
argument path: train[dp-dist]/template_script

File names of the template training script. It can be a *List[str]*, the length of which is the same as *numb_models*. Each template script in the list is used to train a model. Can be a *str*, the models share the same template training script.

student_model_path:

type: str, optional

argument path: train[dp-dist]/student_model_path

The path of student model

explore:

type: dict
argument path: explore

The configuration for exploration

Depending on the value of *type*, different sub args are accepted.

type:

type: str (flag key)
argument path: explore/type
possible choices: *lmp*, *calypso*

The type of the exploration

When type is set to lmp:

The exploration by LAMMPS simulations

config:

type: dict, optional, default: {'command': 'lmp', 'teacher_model_path': None, 'shuffle_models': False, 'head': None}
argument path: explore[lmp]/config

Configuration of lmp exploration

command:

type: str, optional, default: lmp
argument path: explore[lmp]/config/command

The command of LAMMPS

teacher_model_path:

type: str | BinaryFileInput | NoneType, optional, default: None
argument path: explore[lmp]/config/teacher_model_path

The teacher model in *Knowledge Distillation*

shuffle_models:

type: bool, optional, default: False
argument path: explore[lmp]/config/shuffle_models

Randomly pick a model from the group of models to drive theexploration MD simulation

head:

type: str | NoneType, optional, default: None
argument path: explore[lmp]/config/head

Select a head from multitask

max_numb_iter:

type: int, optional, default: 10
argument path: explore[lmp]/max_numb_iter

Maximum number of iterations per stage

fatal_at_max:

type: bool, optional, default: True
argument path: explore[lmp]/fatal_at_max

Fatal when the number of iteration per stage reaches the *max_numb_iter*

output_nopbc:

type: bool, optional, default: False
argument path: explore[lmp]/output_nopbc

Remove pbc of the output configurations

convergence:

type: dict
argument path: explore[lmp]/convergence

The method of convergence check.

Depending on the value of *type*, different sub args are accepted.

type:

type: str (flag key)
argument path: explore[lmp]/convergence/type
possible choices: *fixed-levels*, *fixed-levels-max-select*, *adaptive-lower*

the type of the condidate selection and convergence check method.

When type is set to fixed-levels:

The configurations with force model deviation between *level_f_lo*, *level_f_hi* or virial model deviation between *level_v_lo* and *level_v_hi* are treated as candidates (The virial model deviation check is optional). The configurations will be randomly sampled from candidates for FP calculations. If the ratio of accurate (below *level_f_lo* and *level_v_lo*) is higher then *conv_accuracy*, the stage is treated as converged.

level_f_lo:

type: float
argument path: explore[lmp]/convergence[fixed-levels]/level_f_lo

The lower trust level of force model deviation

level_f_hi:

type: float
argument path: explore[lmp]/convergence[fixed-levels]/level_f_hi

The higher trust level of force model deviation

level_v_lo:

type: NoneType | float, optional, default: None
argument path: explore[lmp]/convergence[fixed-levels]/level_v_lo

The lower trust level of virial model deviation

level_v_hi:

type: NoneType | float, optional, default: None
argument path: explore[lmp]/convergence[fixed-levels]/level_v_hi

The higher trust level of virial model deviation

conv_accuracy:

type: float, optional, default: 0.9
argument path: explore[lmp]/convergence[fixed-levels]/conv_accuracy

If the ratio of accurate frames is larger than this value, the stage is converged

When type is set to fixed-levels-max-select:

The configurations with force model deviation between *level_f_lo*, *level_f_hi* or virial model deviation between *level_v_lo* and *level_v_hi* are treated as candidates (The virial model deviation check is optional). The configurations with maximal model deviation in the candidates are sent for FP calculations. If the ratio of accurate (below *level_f_lo* and *level_v_lo*) is higher then *conv_accuracy*, the stage is treated as converged.

level_f_lo:

type: float
argument path: explore[lmp]/convergence[fixed-levels-max-select]/level_f_lo

The lower trust level of force model deviation

level_f_hi:

type: float
argument path: explore[lmp]/convergence[fixed-levels-max-select]/level_f_hi

The higher trust level of force model deviation

level_v_lo:

type: NoneType | float, optional, default: None
argument path: explore[lmp]/convergence[fixed-levels-max-select]/level_v_lo

The lower trust level of virial model deviation

level_v_hi:

type: NoneType | float, optional, default: None

argument path: explore[lmp]/convergence[fixed-levels-max-select]/level_v_hi

The higher trust level of virial model deviation

conv_accuracy:

type: float, optional, default: 0.9

argument path: explore[lmp]/convergence[fixed-levels-max-select]/conv_accuracy

If the ratio of accurate frames is larger than this value, the stage is converged

When type is set to adaptive-lower:

The method of adaptive adjust the lower trust levels. In each step of iterations, a number (set by *numb_candi_f* or *numb_candi_v*) or a ratio (set by *rate_candi_f* or *rate_candi_v*) of configurations with a model deviation lower than the higher trust level (*level_f_hi*, *level_v_hi*) are treated as candidates. The lowest model deviation of the candidates are treated as the lower trust level. If the lower trust level does not change significant (controlled by *conv_tolerance*) in *n_checked_steps*, the stage is treated as converged.

level_f_hi:

type: float, optional, default: 0.5

argument path: explore[lmp]/convergence[adaptive-lower]/level_f_hi

The higher trust level of force model deviation

numb_candi_f:

type: int, optional, default: 200

argument path: explore[lmp]/convergence[adaptive-lower]/numb_candi_f

The number of force frames that has a model deviation lower than *level_f_hi* treated as candidate.

rate_candi_f:

type: float, optional, default: 0.01

argument path: explore[lmp]/convergence[adaptive-lower]/rate_candi_f

The ratio of force frames that has a model deviation lower than *level_f_hi* treated as candidate.

level_v_hi:

type: NoneType | float, optional, default: None

argument path: explore[lmp]/convergence[adaptive-lower]/level_v_hi

The higher trust level of virial model deviation

numb_candi_v:

type: int, optional, default: 0
argument path: explore[lmp]/convergence[adaptive-lower]/numb_candi_v

The number of virial frames that has a model deviation lower than *level_v_hi* treated as candidate.

rate_candi_v:

type: float, optional, default: 0.0
argument path: explore[lmp]/convergence[adaptive-lower]/rate_candi_v

The ratio of virial frames that has a model deviation lower than *level_v_hi* treated as candidate.

n_checked_steps:

type: int, optional, default: 2
argument path: explore[lmp]/convergence[adaptive-lower]/n_checked_steps

The number of steps to check the convergence.

conv_tolerance:

type: float, optional, default: 0.05
argument path: explore[lmp]/convergence[adaptive-lower]/conv_tolerance

The convergence tolerance.

candi_sel_prob:

type: str, optional, default: uniform
argument path: explore[lmp]/convergence[adaptive-lower]/candi_sel_prob

The method for selecting candidates. It can be 'uniform': all candidates are of the same probability. 'inv_pop_f' or 'inv_pop_f:nhist': the probability is inversely propotional to the population of a histogram between leven_f_lo and level_f_hi. The number of bins in the histogram is set by nhist, which should be an integer. The default is 10.

configurations:

type: list, alias: *configuration*
argument path: explore[lmp]/configurations

A list of initial configurations.

This argument takes a list with each element containing the following:

Depending on the value of *type*, different sub args are accepted.

type:

type: str (flag key)
argument path: explore[lmp]/configurations/type

possible choices: *alloy*, *file*

the type of the initial configuration generator.

When type is set to `alloy`:

Generate alloys with *a certain lattice or user proided structure*, the elements randomly occuping the lattice with *user provided probability* .

numb_confs:

type: `int`, optional, default: `1`
argument path:
`explore[lmp]/configurations[alloy]/numb_confs`

The number of configurations to generate

lattice:

type: `list | tuple`
argument path:
`explore[lmp]/configurations[alloy]/lattice`

The lattice. Should be a list providing ["lattice_type", lattice_const], or a list providing ["/path/to/dpdata/system", "fmt"]. The two styles are distinguished by the type of the second element. Currently "lattice_type" can be "bcc", "fcc", "hcp", "sc" or "diamond".

replicate:

type: `list | NoneType`, optional, default: `None`
argument path:
`explore[lmp]/configurations[alloy]/replicate`

The number of replicates in each direction

concentration:

type: `list | NoneType`, optional, default: `None`
argument path:
`explore[lmp]/configurations[alloy]/concentration`

The concentration of each element. *List[List[float]]* or *List[float]* or *None*. If *List[float]*, the concentrations of each element. The length of the list should be the same as the *type_map*. If *List[List[float]]*, a list of concentrations (*List[float]*) is randomly picked from the List. If *None*, the elements are assumed to be of equal concentration.

cell_pert_frac:

type: `float`, optional, default: `0.0`
argument path:
`explore[lmp]/configurations[alloy]/cell_pert_frac`

The faction of cell perturbation

atom_pert_dist:

type: `float`, optional, default: `0.0`

argument path:
explore[lmp]/configurations[alloy]/atom_pert_dist

The distance of atomic position perturbation

When type is set to file:

Generate alloys from user provided file(s). The file(s) are assume to be load by *dpdata*.

files:

type: str | list
argument path:
explore[lmp]/configurations[file]/files

The paths to the configuration files. widecards are supported.

prefix:

type: str | NoneType, optional, default: None
argument path:
explore[lmp]/configurations[file]/prefix

The prefix of file paths.

fmt:

type: str, optional, default: auto
argument path: explore[lmp]/configurations[file]/fmt

The format (dpdata accepted formats) of the files.

remove_pbc:

type: bool, optional, default: False
argument path:
explore[lmp]/configurations[file]/remove_pbc

The remove the pbc of the data. shift the coords to the center of box so it can be used with lammps.

stages:

type: typing.List[typing.List[dict]]
argument path: explore[lmp]/stages

The definition of exploration stages of type *List[List[ExplorationTaskGroup]*. The outer list provides the enumeration of the exploration stages. Then each stage is defined by a list of exploration task groups. Each task group is described in *the task group definition*

When type is set to calypso:

The exploration by CALYPSO structure prediction

config:

type: dict, optional, default: {'command': 'lmp', 'teacher_model_path': None, 'shuffle_models': False, 'head': None}

argument path: explore[calypso]/config

Configuration of lmp exploration

command:

type: str, optional, default: lmp
argument path: explore[calypso]/config/command

The command of LAMMPS

teacher_model_path:

type: str | BinaryFileInput | NoneType, optional, default: None
argument path: explore[calypso]/config/teacher_model_path

The teacher model in *Knowledge Distillation*

shuffle_models:

type: bool, optional, default: False
argument path: explore[calypso]/config/shuffle_models

Randomly pick a model from the group of models to drive theexploration MD simulation

head:

type: str | NoneType, optional, default: None
argument path: explore[calypso]/config/head

Select a head from multitask

max_numb_iter:

type: int, optional, default: 10
argument path: explore[calypso]/max_numb_iter

Maximum number of iterations per stage

fatal_at_max:

type: bool, optional, default: True
argument path: explore[calypso]/fatal_at_max

Fatal when the number of iteration per stage reaches the *max_numb_iter*

output_nopbc:

type: bool, optional, default: False
argument path: explore[calypso]/output_nopbc

Remove pbc of the output configurations

convergence:

type: dict

argument path: `explore[calypso]/convergence`

The method of convergence check.

Depending on the value of *type*, different sub args are accepted.

`type:`

type: `str` (flag key)
argument path: `explore[calypso]/convergence/type`
possible choices: *`fixed-levels`*, *`fixed-levels-max-select`*, *`adaptive-lower`*

the type of the condidate selection and convergence check method.

When type is set to `fixed-levels`:

The configurations with force model deviation between *level_f_lo*, *level_f_hi* or virial model deviation between *level_v_lo* and *level_v_hi* are treated as candidates (The virial model deviation check is optional). The configurations will be randomly sampled from candidates for FP calculations. If the ratio of accurate (below *level_f_lo* and *level_v_lo*) is higher then *conv_accuracy*, the stage is treated as converged.

`level_f_lo:`

type: `float`
argument path: `explore[calypso]/convergence[fixed-levels]/level_f_lo`

The lower trust level of force model deviation

`level_f_hi:`

type: `float`
argument path: `explore[calypso]/convergence[fixed-levels]/level_f_hi`

The higher trust level of force model deviation

`level_v_lo:`

type: `NoneType` | `float`, optional, default: `None`
argument path: `explore[calypso]/convergence[fixed-levels]/level_v_lo`

The lower trust level of virial model deviation

`level_v_hi:`

type: `NoneType` | `float`, optional, default: `None`
argument path: `explore[calypso]/convergence[fixed-levels]/level_v_hi`

The higher trust level of virial model deviation

`conv_accuracy:`

type: `float`, optional, default: `0.9`
argument path: `explore[calypso]/convergence[fixed-levels]/conv_accuracy`

If the ratio of accurate frames is larger than this value, the stage is converged

When type is set to `fixed-levels-max-select`:

The configurations with force model deviation between *level_f_lo*, *level_f_hi* or virial model deviation between *level_v_lo* and *level_v_hi* are treated as candidates (The virial model deviation check is optional). The configurations with maximal model deviation in the candidates are sent for FP calculations. If the ratio of accurate (below *level_f_lo* and *level_v_lo*) is higher then *conv_accuracy*, the stage is treated as converged.

level_f_lo:

type: `float`
argument path: `explore[calypso]/convergence[fixed-levels-max-select]/level_f_lo`

The lower trust level of force model deviation

level_f_hi:

type: `float`
argument path: `explore[calypso]/convergence[fixed-levels-max-select]/level_f_hi`

The higher trust level of force model deviation

level_v_lo:

type: `NoneType | float`, optional, default: `None`
argument path: `explore[calypso]/convergence[fixed-levels-max-select]/level_v_lo`

The lower trust level of virial model deviation

level_v_hi:

type: `NoneType | float`, optional, default: `None`
argument path: `explore[calypso]/convergence[fixed-levels-max-select]/level_v_hi`

The higher trust level of virial model deviation

conv_accuracy:

type: `float`, optional, default: `0.9`
argument path: `explore[calypso]/convergence[fixed-levels-max-select]/conv_accuracy`

If the ratio of accurate frames is larger than this value, the stage is converged

When type is set to `adaptive-lower`:

The method of adaptive adjust the lower trust levels. In each step of iterations, a number (set by *numb_candi_f* or *numb_candi_v*) or a ratio (set by *rate_candi_f* or *rate_candi_v*) of configurations with a model deviation lower than the higher trust level (*level_f_hi*, *level_v_hi*) are treated as candidates. The lowest model deviation of the candidates are treated as the lower trust level. If the lower trust level

does not change significant (controlled by *conv_tolerance*) in *n_checked_steps*, the stage is treated as converged.

level_f_hi:

type: float, optional, default: 0.5
argument path: explore[calypso]/convergence[adaptive-lower]/level_f_hi

The higher trust level of force model deviation

numb_candi_f:

type: int, optional, default: 200
argument path: explore[calypso]/convergence[adaptive-lower]/numb_candi_f

The number of force frames that has a model deviation lower than *level_f_hi* treated as candidate.

rate_candi_f:

type: float, optional, default: 0.01
argument path: explore[calypso]/convergence[adaptive-lower]/rate_candi_f

The ratio of force frames that has a model deviation lower than *level_f_hi* treated as candidate.

level_v_hi:

type: NoneType | float, optional, default: None
argument path: explore[calypso]/convergence[adaptive-lower]/level_v_hi

The higher trust level of virial model deviation

numb_candi_v:

type: int, optional, default: 0
argument path: explore[calypso]/convergence[adaptive-lower]/numb_candi_v

The number of virial frames that has a model deviation lower than *level_v_hi* treated as candidate.

rate_candi_v:

type: float, optional, default: 0.0
argument path: explore[calypso]/convergence[adaptive-lower]/rate_candi_v

The ratio of virial frames that has a model deviation lower than *level_v_hi* treated as candidate.

n_checked_steps:

type: int, optional, default: 2
argument path: explore[calypso]/convergence[adaptive-lower]/n_checked_steps

The number of steps to check the convergence.

conv_tolerance:

type: float, optional, default: 0.05
argument path: explore[calypso]/convergence[adaptive-lower]/conv_tolerance

The convergence tolerance.

candi_sel_prob:

type: str, optional, default: uniform
argument path: explore[calypso]/convergence[adaptive-lower]/candi_sel_prob

The method for selecting candidates. It can be 'uniform': all candidates are of the same probability. 'inv_pop_f' or 'inv_pop_f:nhist': the probability is inversely propotional to the population of a histogram between leven_f_lo and level_f_hi. The number of bins in the histogram is set by nhist, which should be an integer. The default is 10.

configurations:

type: list, alias: *configuration*
argument path: explore[calypso]/configurations

A list of initial configurations.

This argument takes a list with each element containing the following:

Depending on the value of *type*, different sub args are accepted.

type:

type: str (flag key)
argument path: explore[calypso]/configurations/type
possible choices: *alloy*, *file*

the type of the initial configuration generator.

When type is set to alloy:

Generate alloys with *a certain lattice or user proided structure*, the elements randomly occuping the lattice with *user provided probability* .

numb_confs:

type: int, optional, default: 1
argument path: explore[calypso]/configurations[alloy]/numb_confs

The number of configurations to generate

lattice:

type: list | tuple
argument path: explore[calypso]/configurations[alloy]/lattice

The lattice. Should be a list providing ["lattice_type", lattice_const], or a list providing ["/path/to/dpdata/system", "fmt"

]. The two styles are distinguished by the type of the second element. Currently "lattice_type" can be "bcc", "fcc", "hcp", "sc" or "diamond".

replicate:

type: list | NoneType, optional, default: None
argument path: explore[calypso]/configurations[alloy]/replicate

The number of replicates in each direction

concentration:

type: list | NoneType, optional, default: None
argument path: explore[calypso]/configurations[alloy]/concentration

The concentration of each element. *List[List[float]]* or *List[float]* or *None*. If *List[float]*, the concentrations of each element. The length of the list should be the same as the *type_map*. If *List[List[float]]*, a list of concentrations (*List[float]*) is randomly picked from the List. If *None*, the elements are assumed to be of equal concentration.

cell_pert_frac:

type: float, optional, default: 0.0
argument path: explore[calypso]/configurations[alloy]/cell_pert_frac

The faction of cell perturbation

atom_pert_dist:

type: float, optional, default: 0.0
argument path: explore[calypso]/configurations[alloy]/atom_pert_dist

The distance of atomic position perturbation

When type is set to file:

Generate alloys from user provided file(s). The file(s) are assume to be load by *dpdata*.

files:

type: str | list
argument path: explore[calypso]/configurations[file]/files

The paths to the configuration files. widecards are supported.

prefix:

type: str | NoneType, optional, default: None
argument path: explore[calypso]/configurations[file]/prefix

The prefix of file paths.

fmt:

type: str, optional, default: auto
argument path: explore[calypso]/configurations[file]/fmt

The format (dpdata accepted formats) of the files.

remove_pbc:

type: bool, optional, default: False
argument path: explore[calypso]/configurations[file]/remove_pbc

The remove the pbc of the data. shift the coords to the center of box so it can be used with lammps.

stages:

type: typing.List[typing.List[dict]]
argument path: explore[calypso]/stages

The definition of exploration stages of type *List[List[ExplorationTaskGroup]*. The outer list provides the enumeration of the exploration stages. Then each stage is defined by a list of exploration task groups. Each task group is described in *the task group definition*

fp:

type: dict
argument path: fp

The configuration for FP

Depending on the value of *type*, different sub args are accepted.

type:

type: str (flag key)
argument path: fp/type
possible choices: *vasp*, *gaussian*, *deepmd*, *fpop_abacus*

the type of the fp

When type is set to vasp:

inputs_config:

type: dict
argument path: fp[vasp]/inputs_config

Configuration for preparing vasp inputs

incar:

type: str
argument path: fp[vasp]/inputs_config/incar

The path to the template incar file

pp_files:

type: dict
argument path: fp[vasp]/inputs_config/pp_files

The pseudopotential files set by a dict, e.g. {"Al" : "path/to/the/al/pp/file", "Mg" : "path/to/the/mg/pp/file"}

kspacing:

type: float
argument path: fp[vasp]/inputs_config/kspacing

The spacing of k-point sampling. *ksapcing* will overwrite the incar template

kgamma:

type: bool, optional, default: True
argument path: fp[vasp]/inputs_config/kgamma

If the k-mesh includes the gamma point. *kgamma* will overwrite the incar template

run_config:

type: dict
argument path: fp[vasp]/run_config

Configuration for running vasp tasks

command:

type: str, optional, default: vasp
argument path: fp[vasp]/run_config/command

The command of VASP

out:

type: str, optional, default: data
argument path: fp[vasp]/run_config/out

The output dir name of labeled data. In *deepmd/npy* format provided by *dpdata*.

log:

type: str, optional, default: fp.log
argument path: fp[vasp]/run_config/log

The log file name of VASP

task_max:

type: int, optional, default: 10
argument path: fp[vasp]/task_max

Maximum number of vasp tasks for each iteration

When type is set to gaussian:

inputs_config:

type: dict
argument path: fp[gaussian]/inputs_config

Configuration for preparing vasp inputs

keywords:

type: str | list
argument path: fp[gaussian]/inputs_config/keywords

Gaussian keywords, e.g. force b3lyp/6-31g**. If a list, run multiple steps.

multiplicity:

type: str | int, optional, default: auto
argument path: fp[gaussian]/inputs_config/multiplicity

spin multiplicity state. It can be a number. If auto, multiplicity will be detected automatically, with the following rules:

fragment_guesses=True multiplicity will +1 for each radical, and +2 for each oxygen molecule

fragment_guesses=False multiplicity will be 1 or 2, but +2 for each oxygen molecule.

charge:

type: int, optional, default: 0
argument path: fp[gaussian]/inputs_config/charge

molecule charge. Only used when charge is not provided by the system

basis_set:

type: str, optional
argument path: fp[gaussian]/inputs_config/basis_set

custom basis set

keywords_high_multiplicity:

type: str, optional
argument path: fp[gaussian]/inputs_config/keywords_high_multiplicity

keywords for points with multiple raicals. multiplicity should be auto. If not set, fallback to normal keywords

fragment_guesses:

type: bool, optional, default: False
argument path: fp[gaussian]/inputs_config/fragment_guesses

initial guess generated from fragment guesses. If True, multiplicity should be auto

nproc:

type: int, optional, default: 1
argument path: fp[gaussian]/inputs_config/nproc

Number of CPUs to use

run_config:

type: dict
argument path: fp[gaussian]/run_config

Configuration for running vasp tasks

command:

type: str, optional, default: g16
argument path: fp[gaussian]/run_config/command

The command of Gaussian

out:

type: str, optional, default: data
argument path: fp[gaussian]/run_config/out

The output dir name of labeled data. In *deepmd/npy* format provided by *dpdata*.

task_max:

type: int, optional, default: 10
argument path: fp[gaussian]/task_max

Maximum number of vasp tasks for each iteration

When type is set to deepmd:

inputs_config:

type: dict
argument path: fp[deepmd]/inputs_config

Configuration for preparing vasp inputs

run_config:

type: dict
argument path: fp[deepmd]/run_config

Configuration for running vasp tasks

teacher_model_path:

type: str | BinaryFileInput
argument path:
fp[deepmd]/run_config/teacher_model_path

The path of teacher model, which can be loaded by deepmd.infer.DeepPot

out:

type: str, optional, default: data
argument path: fp[deepmd]/run_config/out

The output dir name of labeled data. In *deepmd/npy* format provided by *dpdata*.

log:

type: str, optional, default: fp.log
argument path: fp[deepmd]/run_config/log

The log file name of dp

task_max:

type: int, optional, default: 10
argument path: fp[deepmd]/task_max

Maximum number of vasp tasks for each iteration

When type is set to fpop_abacus:

inputs_config:

type: dict
argument path: fp[fpop_abacus]/inputs_config

Configuration for preparing vasp inputs

input_file:

type: str
argument path: fp[fpop_abacus]/inputs_config/input_file

A template INPUT file.

pp_files:

type: dict
argument path: fp[fpop_abacus]/inputs_config/pp_files

The pseudopotential files for the elements. For example: {"H": "/path/to/H.upf", "O": "/path/to/O.upf"}.

element_mass:

type: dict | NoneType, optional, default: None
argument path: fp[fpop_abacus]/inputs_config/element_mass

Specify the mass of some elements. For example: {"H": 1.0079, "O": 15.9994}.

kpt_file:

type: str | NoneType, optional, default: None

argument path:
fp[fpop_abacus]/inputs_config/kpt_file

The KPT file, by default None.

orb_files:

type: dict | NoneType, optional, default: None
argument path:
fp[fpop_abacus]/inputs_config/orb_files

The numerical orbital fiels for the elements, by default None. For example: {"H": "/path/to/H.orb", "O": "/path/to/O.orb"}.

deepks_descriptor:

type: str | NoneType, optional, default: None
argument path:
fp[fpop_abacus]/inputs_config/deepks_descriptor

The deepks descriptor file, by default None.

deepks_model:

type: str | NoneType, optional, default: None
argument path:
fp[fpop_abacus]/inputs_config/deepks_model

The deepks model file, by default None.

run_config:

type: dict
argument path: fp[fpop_abacus]/run_config

Configuration for running vasp tasks

command:

type: str, optional, default: abacus
argument path: fp[fpop_abacus]/run_config/command

The command of abacus

out:

type: str, optional, default: data
argument path: fp[fpop_abacus]/run_config/out

The output dir name of labeled data. In *deepmd/npy* format provided by *dpdata*.

task_max:

type: int, optional, default: 10
argument path: fp[fpop_abacus]/task_max

Maximum number of vasp tasks for each iteration

name:

type: str, optional, default: dpgen

argument path: `name`

The workflow name, 'dpgen' for default

4.1 Task group definition

4.1.1 LAMMPS task group

`task_group:`

type: `dict`
argument path: `task_group`

Depending on the value of *type*, different sub args are accepted.

`type:`

type: `str` (flag key)
argument path: `task_group/type`
possible choices: *`lmp-md`*, *`lmp-template`*, *`customized-lmp-template`*

the type of the task group

When type is set to `lmp-md` (or its alias `lmp-npt`):

Lammps MD tasks. DPGEN will generate the lammps input script

`conf_idx:`

type: `list`, alias: *sys_idx*
argument path: `task_group[lmp-md]/conf_idx`

The configurations of *configurations[conf_idx]* will be used to generate the initial configurations of the tasks. This key provides the index of selected item in the *configurations* array.

`n_sample:`

type: `NoneType` | `int`, optional, default: `None`
argument path: `task_group[lmp-md]/n_sample`

Number of configurations. If this number is smaller than the number of configruations in *configruations[conf_idx]*, then *n_sample* configruations are randomly sampled from *configruations[conf_idx]*, otherwise all configruations in *configruations[conf_idx]* will be used. If not provided, all configruations in *configruations[conf_idx]* will be used.

`temps:`

type: `list`, alias: *Ts*
argument path: `task_group[lmp-md]/temps`

A list of temperatures in K. Also used to initialize the temperature

`press:`

type: `list`, optional, alias: *Ps*
argument path: `task_group[lmp-md]/press`

A list of pressures in bar.

ens:

type: str, optional, default: nve, alias: *ensemble*
argument path: task_group[lmp-md]/ens

The ensemble. Allowd options are 'nve', 'nvt', 'npt', 'npt-a', 'npt-t'. 'npt-a' stands for anisotrpic box sampling and 'npt-t' stands for triclinic box sampling.

dt:

type: float, optional, default: 0.001
argument path: task_group[lmp-md]/dt

The time step

nsteps:

type: int, optional, default: 100
argument path: task_group[lmp-md]/nsteps

The number of steps

trj_freq:

type: int, optional, default: 10, aliases: *t_freq*, *trj_freq*, *traj_freq*
argument path: task_group[lmp-md]/trj_freq

The number of steps

tau_t:

type: float, optional, default: 0.05
argument path: task_group[lmp-md]/tau_t

The time scale of thermostat

tau_p:

type: float, optional, default: 0.5
argument path: task_group[lmp-md]/tau_p

The time scale of barostat

pka_e:

type: NoneType | float, optional, default: None
argument path: task_group[lmp-md]/pka_e

The energy of primary knock-on atom

neidelay:

type: NoneType | int, optional, default: None
argument path: task_group[lmp-md]/neidelay

The delay of updating the neighbor list

no_pbc:

type: bool, optional, default: False
argument path: task_group[lmp-md]/no_pbc

Not using the periodic boundary condition

use_clusters:

type: bool, optional, default: False
argument path: task_group[lmp-md]/use_clusters

Calculate atomic model deviation

relative_f_epsilon:

type: NoneType | float, optional, default: None
argument path: task_group[lmp-md]/relative_f_epsilon

Calculate relative force model deviation

relative_v_epsilon:

type: NoneType | float, optional, default: None
argument path: task_group[lmp-md]/relative_v_epsilon

Calculate relative virial model deviation

When type is set to lmp-template:

Lammps MD tasks defined by templates. User provide lammps (and plumed) template for lammps tasks. The variables in templates are revised by the revisions key. Notice that the lines for pair style, dump and plumed are reserved for the revision of dpgen2, and the users should not write these lines by themselves. Rather, users notify dpgen2 the poistion of the line for *pair_style* by writting 'pair_style deepmd', the line for *dump* by writting 'dump dpgen_dump'. If plumed is used, the line for *fix plumed* shouldbe written exactly as 'fix dpgen_plm'.

conf_idx:

type: list, alias: *sys_idx*
argument path: task_group[lmp-template]/conf_idx

The configurations of *configurations[conf_idx]* will be used to generate the initial configurations of the tasks. This key provides the index of selected item in the *configurations* array.

n_sample:

type: NoneType | int, optional, default: None
argument path: task_group[lmp-template]/n_sample

Number of configurations. If this number is smaller than the number of configruations in *configruations[conf_idx]*, then *n_sample* configruations are randomly sampled from *configruations[conf_idx]*, otherwise all configruations in *configruations[conf_idx]* will be used. If not provided, all configruations in *configruations[conf_idx]* will be used.

lmp_template_fname:

type: str, aliases: *lmp_template*, *lmp*
argument path: task_group[lmp-template]/lmp_template_fname

The file name of lammps input template

plm_template_fname:

type: str | NoneType, optional, default: None, aliases: *plm_template*, *plm*

argument path: task_group[lmp-template]/plm_template_fname

The file name of plumed input template

revisions:

type: dict, optional, default: {}
argument path: task_group[lmp-template]/revisions

traj_freq:

type: int, optional, default: 10, aliases: *t_freq*, *trj_freq*, *trj_freq*
argument path: task_group[lmp-template]/traj_freq

The frequency of dumping configurations and thermodynamic states

When type is set to customized-lmp-template:

Lammps MD tasks defined by user customized shell commands and templates. User provided shell script generates a series of folders, and each folder contains a lammps template task group.

conf_idx:

type: list, alias: *sys_idx*
argument path: task_group[customized-lmp-template]/conf_idx

The configurations of *configurations[conf_idx]* will be used to generate the initial configurations of the tasks. This key provides the index of selected item in the *configurations* array.

n_sample:

type: NoneType | int, optional, default: None
argument path: task_group[customized-lmp-template]/n_sample

Number of configurations. If this number is smaller than the number of configruations in *configruations[conf_idx]*, then *n_sample* configruations are randomly sampled from *configruations[conf_idx]*, otherwise all configruations in *configruations[conf_idx]* will be used. If not provided, all configruations in *configruations[conf_idx]* will be used.

custom_shell_commands:

type: list
argument path:
task_group[customized-lmp-template]/custom_shell_commands

Customized shell commands to be run for each configuration. The commands require *input_lmp_conf_name* as input conf file, *input_lmp_tmpl_name* and *input_plm_tmpl_name* as templates, and *input_extra_files* as extra input files. By running the commands a series folders in pattern *output_dir_pattern* are supposed to be generated, and each folder is supposed to contain a configuration file *output_lmp_conf_name*, a lammps template file *output_lmp_tmpl_name* and a plumed template file *output_plm_tmpl_name*.

revisions:

type: dict, optional, default: {}
argument path: task_group[customized-lmp-template]/revisions

The revisions. Should be a dict providing the key - list of desired values pair. Key is the word to be replaced in the templates, and it may appear in both the lammps and plumed input templates. All values in the value list will be enmerated.

traj_freq:

type: int, optional, default: 10, aliases: *t_freq*, *trj_freq*, *trj_freq*
argument path: task_group[customized-lmp-template]/traj_freq

The frequency of dumping configurations and thermodynamic states

input_lmp_conf_name:

type: str, optional, default: conf.lmp
argument path:
task_group[customized-lmp-template]/input_lmp_conf_name

Input conf file name for the shell commands.

input_lmp_tmpl_name:

type: str, optional, default: in.lammps, aliases: *lmp_template*, *lmp*
argument path:
task_group[customized-lmp-template]/input_lmp_tmpl_name

The file name of lammps input template

input_plm_tmpl_name:

type: str | NoneType, optional, default: None, aliases: *plm_template*, *plm*
argument path:
task_group[customized-lmp-template]/input_plm_tmpl_name

The file name of plumed input template

input_extra_files:

type: list, optional, default: []
argument path:
task_group[customized-lmp-template]/input_extra_files

Extra files that may be needed to execute the shell commands

output_dir_pattern:

type: str | list, optional, default: *
argument path:
task_group[customized-lmp-template]/output_dir_pattern

Pattern of resultant folders generated by the shell commands.

output_lmp_conf_name:

type: str, optional, default: conf.lmp
argument path:
task_group[customized-lmp-template]/output_lmp_conf_name

Generated conf file name.

output_lmp_tmpl_name:

type: str, optional, default: in.lammps

argument path:
task_group[customized-lmp-template]/output_lmp_tmpl_name

Generated lmp input file name.

output_plm_tmpl_name:

type: str, optional, default: input.plumed
argument path:
task_group[customized-lmp-template]/output_plm_tmpl_name

Generated plm input file name.

4.1.2 CALYPSO task group

task_group:

type: dict
argument path: task_group

CALYPSO structure prediction tasks. DPGEN will generate the calypso input script

numb_of_species:

type: int
argument path: task_group/numb_of_species

number of species.

name_of_atoms:

type: list
argument path: task_group/name_of_atoms

name of atoms.

atomic_number:

type: list
argument path: task_group/atomic_number

atomic number of each element.

numb_of_atoms:

type: list
argument path: task_group/numb_of_atoms

number of each atom.

distance_of_ions:

type: list
argument path: task_group/distance_of_ions

the distance matrix between different elements.

pop_size:

type: int, optional, default: 30
argument path: task_group/pop_size

the number of structures would be generated in each step.

max_step:

type: int, optional, default: 5
argument path: task_group/max_step

the max iteration number of CALYPSO loop.

system_name:

type: str, optional, default: CALYPSO
argument path: task_group/system_name

system name.

numb_of_formula:

type: list, optional, default: [1, 1]
argument path: task_group/numb_of_formula

the formula range of simulation cell.

pressure:

type: float, optional, default: 0.001
argument path: task_group/pressure

the aim pressure (in Kbar) when using MLP to optimize structures.

fmax:

type: float, optional, default: 0.01
argument path: task_group/fmax

the converge criterion. The force on all individual atoms should be less than *fmax*.

volume:

type: float, optional, default: 0
argument path: task_group/volume

the volume of simulation cell in one formula.

ialgo:

type: int, optional, default: 2
argument path: task_group/ialgo

the evolution algorithm of CALYPSO. 1: global pso, 2: local pso, 3: sabc.

pso_ratio:

type: float, optional, default: 0.6
argument path: task_group/pso_ratio

the ratio of structures generated by evolution algorithm in one step.

icode:

type: int, optional, default: 15
argument path: task_group/icode

the software of structure optimization. 1: VASP, 15: DP.

numb_of_lbest:

type: int, optional, default: 4
argument path: task_group/numb_of_lbest

the number of evolution direction when using LPSO.

numb_of_local_optim:

type: int, optional, default: 3
argument path: task_group/numb_of_local_optim

the number of making structure optimization when using dft.

command:

type: str, optional, default: sh submit.sh
argument path: task_group/command

the command of running structure optimization.

max_time:

type: int, optional, default: 9000
argument path: task_group/max_time

the max time (in second) of structure optimization.

pick_up:

type: bool, optional, default: False
argument path: task_group/pick_up

whether to continue the calculation.

pick_step:

type: int, optional, default: 0
argument path: task_group/pick_step

from which step to continue the calculation.

parallel:

type: bool, optional, default: False
argument path: task_group/parallel

whether to run calypso in parallel.

split:

type: bool, optional, default: True
argument path: task_group/split

sperate generating structures and structure optimizations. in dpgen2, split must be True.

spec_space_group:

type: list, optional, default: [2, 230]
argument path: task_group/spec_space_group

the range of spacegroup.

vsc:

type: bool, optional, default: False
argument path: task_group/vsc

whether to run calypso in variational stoichiometry way.

ctrl_range:

type: list, optional, default: [[1, 10]]
argument path: task_group/ctrl_range

the atom range of each atoms.

max_numb_atoms:

type: int, optional, default: 100
argument path: task_group/max_numb_atoms

the max number of atoms.

CHAPTER

FIVE

DEVELOPERS' GUIDE

5.1 The concurrent learning algorithm

DPGEN2 implements the concurrent learning algorithm named DP-GEN, described in this paper. It is noted that other types of workflows, like active learning, should be easily implemented within the infrastructure of DPGEN2.

The DP-GEN algorithm is iterative. In each iteration, four steps are consecutively executed: training, exploration, selection, and labeling.

1. **Training**. A set of DP models are trained with the same dataset and the same hyperparameters. The only difference is the random seed initializing the model parameters.
2. **Exploration**. One of the DP models is used to explore the configuration space. The strategy of exploration highly depends on the purpose of the application case of the model. The simulation technique for exploration can be molecular dynamics, Monte Carlo, structure search/optimization, enhanced sampling, or any combination of them. Current DPGEN2 only supports exploration based on molecular simulation platform LAMMPS.
3. **Selection**. Not all the explored configurations are labeled, rather, the model prediction errors on the configurations are estimated by the ***model deviation***, which is defined as the standard deviation in predictions of the set of the models. The critical configurations with large and not-that-large errors are selected for labeling. The configurations with very large errors are not selected because the large error is usually caused by non-physical configurations, e.g. overlapping atoms.
4. **Labeling**. The selected configurations are labeled with energy, forces, and virial calculated by a method of first-principles accuracy. The usually used method is the density functional theory implemented in VASP, Quantum Expresso, CP2K, and etc.. The labeled data are finally added to the training dataset to start the next iteration.

In each iteration, the quality of the model is improved by selecting and labeling more critical data and adding them to the training dataset. The DP-GEN iteration is converged when no more critical data can be selected.

5.2 Overview of the DPGEN2 Implementation

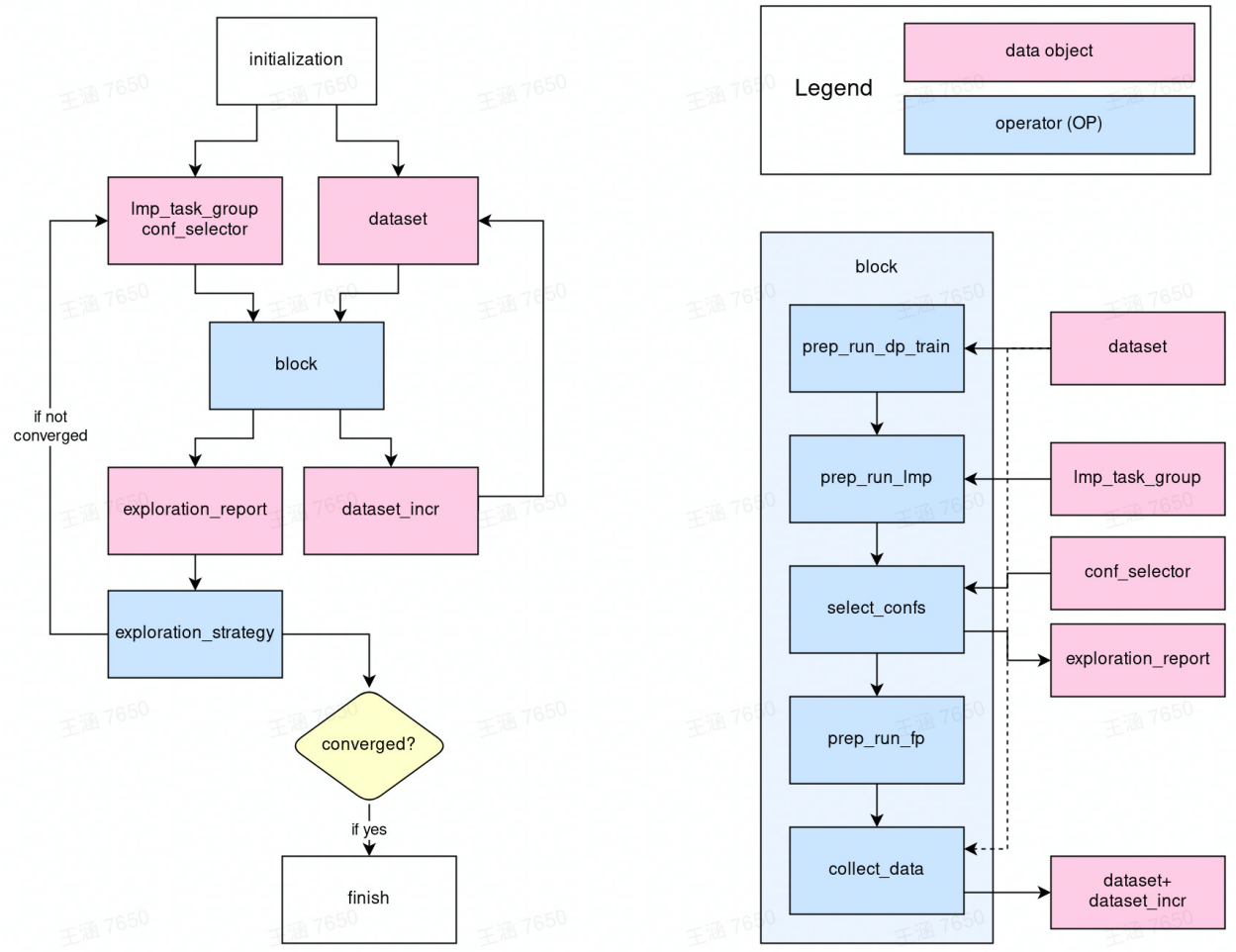
The implementation DPGEN2 is based on the workflow platform dflow, which is a python wrapper of the Argo Workflows, an open-source container-native workflow engine on Kubernetes.

The DP-GEN algorithm is conceptually modeled as a computational graph. The implementation is then considered as two lines: the operators and the workflow.

1. **Operators**. Operators are implemented in Python v3. The operators should be implemented and tested ***without*** the workflow.
2. **Workflow**. Workflow is implemented on dflow. Ideally, the workflow is implemented and tested with all operators mocked.

5.3 The DPGEN2 workflow

The workflow of DPGEN2 is illustrated in the following figure



In the center is the `block` operator, which is a super-OP (an OP composed by several OPs) for one DP-GEN iteration, i.e. the super-OP of the training, exploration, selection, and labeling steps. The inputs of the `block` OP are `lmp_task_group`, `conf_selector` and `dataset`.

- `lmp_task_group`: definition of a group of LAMMPS tasks that explore the configuration space.

- `conf_selector`: defines the rule by which the configurations are selected for labeling.
- `dataset`: the training dataset.

The outputs of the `block` OP are

- `exploration_report`: a report recording the result of the exploration. For example, home many configurations are accurate enough and how many are selected as candidates for labeling.
- `dataset_incr`: the increment of the training dataset.

The `dataset_incr` is added to the training `dataset`.

The `exploration_report` is passed to the `exploration_strategy` OP. The `exploration_strategy` implements the strategy of exploration. It reads the `exploration_report` generated by each iteration (`block`), then tells if the iteration is converged. If not, it generates a group of LAMMPS tasks (`lmp_task_group`) and the criteria of selecting configurations (`conf_selector`). The `lmp_task_group` and `conf_selector` are then used by `block` of the next iteration. The iteration closes.

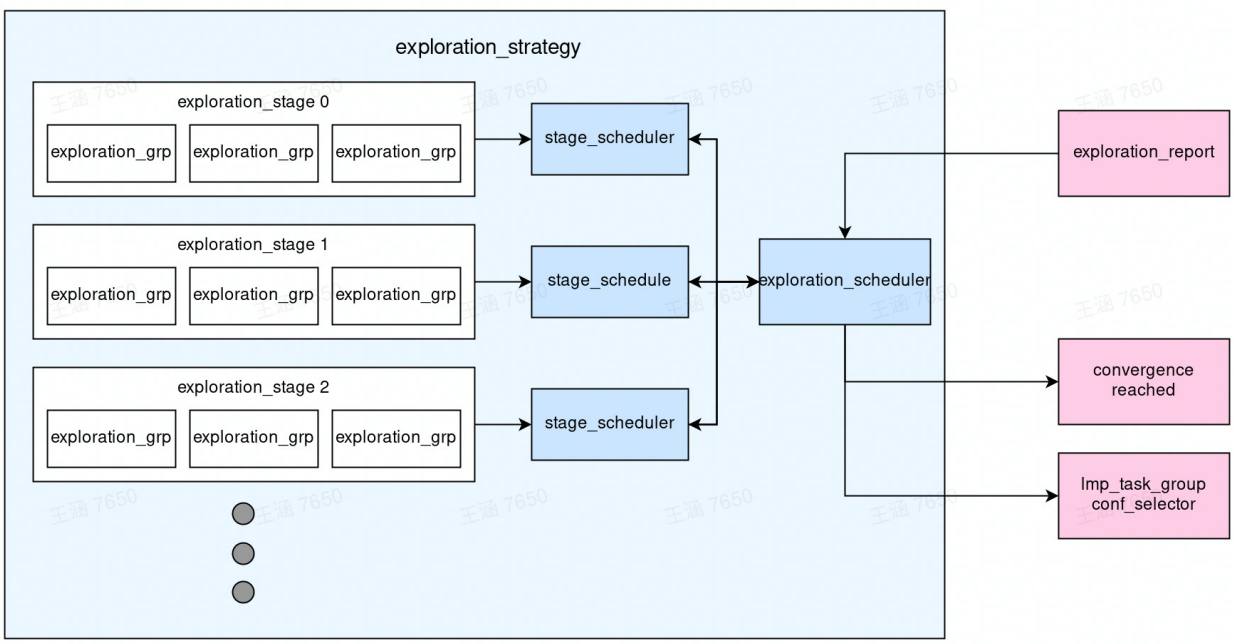
5.3.1 Inside the `block` operator

The inside of the super-OP `block` is displayed on the right-hand side of the figure. It contains the following steps to finish one DPGEN iteration

- `prep_run_dp_train`: prepares training tasks of DP models and runs them.
- `prep_run_lmp`: prepares the LAMMPS exploration tasks and runs them.
- `select_confs`: selects configurations for labeling from the explored configurations.
- `prep_run_fp`: prepares and runs first-principles tasks.
- `collect_data`: collects the `dataset_incr` and adds it to the `dataset`.

5.3.2 The exploration strategy

The exploration strategy defines how the configuration space is explored by the concurrent learning algorithm. The design of the exploration strategy is graphically illustrated in the following figure. The exploration is composed of stages. Only the DP-GEN exploration is converged at one stage (no configuration with a large error is explored), the exploration goes to the next iteration. The whole procedure is controlled by `exploration_scheduler`. Each stage has its schedule, which talks to the `exploration_scheduler` to generate the schedule for the DP-GEN algorithm.



Some concepts are explained below:

- **Exploration group**. A group of LAMMPS tasks shares similar settings. For example, a group of NPT MD simulations in a certain thermodynamic space.
- **Exploration stage**. The `exploration_stage` contains a list of exploration groups. It contains all information needed to define the `lmp_task_group` used by the `block` in the DP-GEN iteration.
- **Stage scheduler**. It guarantees the convergence of the DP-GEN algorithm in each `exploration_stage`. If the exploration is not converged, the `stage_scheduler` generates `lmp_task_group` and `conf_selector` from the `exploration_stage` for the next iteration (probably with a different initial condition, i.e. different initial configurations and randomly generated initial velocity).
- **Exploration scheduler**. The scheduler for the DP-GEN algorithm. When DP-GEN is converged in one of the stages, it goes to the next stage until all planned stages are used.

5.4 How to contribute

Anyone interested in the DPGEN2 project may contribute OPs, workflows, and exploration strategies.

- To contribute OPs, one may check the *guide on writing operators*
- To contribute workflows, one may take the DP-GEN workflow as an example. It is implemented in dpgen2/flow/dpgen_loop.py and tested with all operators mocked in test/test_dpgen_loop.py
- To contribute the exploration strategy, one may check the *guide on writing exploration strategies*

CHAPTER

SIX

OPERATORS

There are two types of OPs in DPGEN2

- *OP*. An execution unit the the workflow. It can be roughly viewed as a piece of Python script taking some input and gives some outputs. An OP cannot be used in the `dflow` until it is embedded in a super-OP.
- *Super-OP*. An execution unite that is composed by one or more OP and/or super-OPs.

Techinically, OP is a Python class derived from `dflow.python.OP`. It serves as the `PythonOPTemplate` of `dflow.Step`.

The super-OP is a Python class derived from `dflow.Steps`. It contains `dflow.Steps` as building blocks, and can be used as OP template to generate a `dflow.Step`. The explanation of the concepts `dflow.Step` and `dflow.Steps`, one may refer to the manual of dflow.

6.1 The super-OP `PrepRunDPTrain`

In the following we will take the `PrepRunDPTrain` super-OP as an example to illustrate how to write OPs in DPGEN2.

`PrepRunDPTrain` is a super-OP that prepares several DeePMD-kit training tasks, and submit all of them. This super-OP is composed by two `dflow.Steps` building from `dflow.python.OPs` `PrepDPTrain` and `RunDPTrain`.

```
from dflow import (
    Step,
    Steps,
)
from dflow.python import(
    PythonOPTemplate,
    OP,
    Slices,
)

class PrepRunDPTrain(Steps):
    def __init__(
            self,
            name : str,
            prep_train_op : OP,
            run_train_op : OP,
            prep_train_image : str = "dflow:v1.0",
            run_train_image : str = "dflow:v1.0",
    ):
                ...
```

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```
        self = _prep_run_dp_train(
            self,
            self.step_keys,
            prep_train_op,
            run_train_op,
            prep_train_image = prep_train_image,
            run_train_image = run_train_image,
        )
```

The construction of the `PrepRunDPTrain` takes prepare-training `OP` and run-training `OP` and their docker images as input, and implemented in internal method `_prep_run_dp_train`.

```
def _prep_run_dp_train(
        train_steps,
        step_keys,
        prep_train_op : OP = PrepDPTrain,
        run_train_op : OP = RunDPTrain,
        prep_train_image : str = "dflow:v1.0",
        run_train_image : str = "dflow:v1.0",
):
    prep_train = Step(
        ...
        template=PythonOPTemplate(
            prep_train_op,
            image=prep_train_image,
            ...
        ),
        ...
    )
    train_steps.add(prep_train)

    run_train = Step(
        ...
        template=PythonOPTemplate(
            run_train_op,
            image=run_train_image,
            ...
        ),
        ...
    )
    train_steps.add(run_train)

    train_steps.outputs.artifacts["scripts"]._from = run_train.outputs.artifacts["script
↪"]
    train_steps.outputs.artifacts["models"]._from = run_train.outputs.artifacts["model"]
    train_steps.outputs.artifacts["logs"]._from = run_train.outputs.artifacts["log"]
    train_steps.outputs.artifacts["lcurves"]._from = run_train.outputs.artifacts["lcurve
↪"]

    return train_steps
```

In `_prep_run_dp_train`, two instances of `dflow.Step`, i.e. `prep_train` and `run_train`, generated from `prep_train_op` and `run_train_op`, respectively, are added to `train_steps`. Both of `prep_train_op` and

`run_train_op` are OPs (python classes derived from `dflow.python.OP`s) that will be illustrated later. `train_steps` is an instance of `dflow.Steps`. The outputs of the second OP `run_train` are assigned to the outputs of the `train_steps`.

The `prep_train` prepares a list of paths, each of which contains all necessary files to start a DeePMD-kit training tasks.

The `run_train` slices the list of paths, and assign each item in the list to a DeePMD-kit task. The task is executed by `run_train_op`. This is a very nice feature of `dflow`, because the developer only needs to implement how one DeePMD-kit task is executed, and then all the items in the task list will be executed in parallel. See the following code to see how it works

```
    run_train = Step(
        'run-train',
        template=PythonOPTemplate(
            run_train_op,
            image=run_train_image,
            slices = Slices(
                "int('{{item}}')",
                input_parameter = ["task_name"],
                input_artifact = ["task_path", "init_model"],
                output_artifact = ["model", "lcurve", "log", "script"],
            ),
        ),
        parameters={
            "config" : train_steps.inputs.parameters["train_config"],
            "task_name" : prep_train.outputs.parameters["task_names"],
        },
        artifacts={
            'task_path' : prep_train.outputs.artifacts['task_paths'],
            "init_model" : train_steps.inputs.artifacts['init_models'],
            "init_data": train_steps.inputs.artifacts['init_data'],
            "iter_data": train_steps.inputs.artifacts['iter_data'],
        },
        with_sequence=argo_sequence(argo_len(prep_train.outputs.parameters["task_names
↪"]), format=train_index_pattern),
        key = step_keys['run-train'],
    )
```

The input parameter `"task_names"` and artifacts `"task_paths"` and `"init_model"` are sliced and supplied to each DeePMD-kit task. The output artifacts of the tasks (`"model"`, `"lcurve"`, `"log"` and `"script"`) are stacked in the same order as the input lists. These lists are assigned as the outputs of `train_steps` by

```
    train_steps.outputs.artifacts["scripts"]._from = run_train.outputs.artifacts["script
↪"]
    train_steps.outputs.artifacts["models"]._from = run_train.outputs.artifacts["model"]
    train_steps.outputs.artifacts["logs"]._from = run_train.outputs.artifacts["log"]
    train_steps.outputs.artifacts["lcurves"]._from = run_train.outputs.artifacts["lcurve
↪"]
```

6.2 The OP RunDPTrain

We will take RunDPTrain as an example to illustrate how to implement an OP in DPGEN2. The source code of this OP is found here

Firstly of all, an OP should be implemented as a derived class of dflow.python.OP.

The dflow.python.OP requires static type define for the input and output variables, i.e. the signatures of an OP. The input and output signatures of the dflow.python.OP are given by classmethods get_input_sign and get_output_sign.

```
from dflow.python import (
    OP,
    OPIO,
    OPIOSign,
    Artifact,
)
class RunDPTrain(OP):
    @classmethod
    def get_input_sign(cls):
        return OPIOSign({
            "config" : dict,
            "task_name" : str,
            "task_path" : Artifact(Path),
            "init_model" : Artifact(Path),
            "init_data" : Artifact(List[Path]),
            "iter_data" : Artifact(List[Path]),
        })

    @classmethod
    def get_output_sign(cls):
        return OPIOSign({
            "script" : Artifact(Path),
            "model" : Artifact(Path),
            "lcurve" : Artifact(Path),
            "log" : Artifact(Path),
        })
```

All items not defined as Artifact are treated as parameters of the OP. The concept of parameter and artifact are explained in the dflow document. To be short, the artifacts can be pathlib.Path or a list of pathlib.Path. The artifacts are passed by the file system. Other data structures are treated as parameters, they are passed as variables encoded in str. Therefore, a large amout of information should be stored in artifacts, otherwise they can be considered as parameters.

The operation of the OP is implemented in method execute, and are run in docker containers. Again taking the execute method of RunDPTrain as an example

```
    @OP.exec_sign_check
    def execute(
            self,
            ip : OPIO,
    ) -> OPIO:
        ...
        task_name = ip['task_name']
```

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```
        task_path = ip['task_path']
        init_model = ip['init_model']
        init_data = ip['init_data']
        iter_data = ip['iter_data']
        ...
        work_dir = Path(task_name)
        ...
        # here copy all files in task_path to work_dir
        ...
        with set_directory(work_dir):
            fplog = open('train.log', 'w')
            def clean_before_quit():
                fplog.close()
            # train model
            command = ['dp', 'train', train_script_name]
            ret, out, err = run_command(command)
            if ret != 0:
                clean_before_quit()
                raise FatalError('dp train failed')
            fplog.write(out)
            # freeze model
            ret, out, err = run_command(['dp', 'freeze', '-o', 'frozen_model.pb'])
            if ret != 0:
                clean_before_quit()
                raise FatalError('dp freeze failed')
            fplog.write(out)
            clean_before_quit()

        return OPIO({
            "script" : work_dir / train_script_name,
            "model" : work_dir / "frozen_model.pb",
            "lcurve" : work_dir / "lcurve.out",
            "log" : work_dir / "train.log",
        })
```

The inputs and outputs variables are recorded in data structure `dflow.python.OPIO`, which is initialized by a Python dict. The keys in the input/output `dict`, and the types of the input/output variables will be checked against their signatures by decorator `OP.exec_sign_check`. If any key or type does not match, an exception will be raised.

It is noted that all input artifacts of the `OP` are read-only, therefore, the first step of the `RunDPTrain.execute` is to copy all necessary input files from the directory `task_path` prepared by `PrepDPTrain` to the working directory `work_dir`.

`with_directory` method creates the `work_dir` and swithes to the directory before the execution, and then exits the directoy when the task finishes or an error is raised.

In what follows, the training and model frozen bash commands are executed consecutively. The return code is check and a `FatalError` is raised if a non-zero code is detected.

Finally the trained model file, input script, learning curve file and the log file are recored in a `dflow.python.OPIO` and returned.

CHAPTER

SEVEN

EXPLORATION

DPGEN2 allows developers to contribute exploration strategies. The exploration strategy defines how the configuration space is explored by molecular simulations in each DPGEN iteration. Notice that we are not restricted to molecular dynamics, any molecular simulation is, in priciple, allowed. For example, Monte Carlo, enhanced sampling, structure optimization, and so on.

An *exploration strategy* takes the history of exploration as input, and gives back DPGEN the exploration tasks (we call it **task group**) and the rule to select configurations from the trajectories generated by the tasks (we call it **configuration selector**).

One can contribute from three aspects:

- *The stage scheduler*
- *The exploration task groups*
- *Configuration selector*

7.1 Stage scheduler

The stage scheduler takes an exploration report passed from the exploration scheduler as input, and tells the exploration scheduler if the exploration in the stage is converged, if not, returns a group of exploration tasks and a configuration selector that are used in the next DPGEN iteration.

Detailed explanation of the concepts are found *here*.

All the stage schedulers are derived from the abstract base class `StageScheduler`. The only interface to be implemented is `StageScheduler.plan_next_iteration`. One may check the doc string for the explanation of the interface.

```
class StageScheduler(ABC):
    """
    The scheduler for an exploration stage.
    """

    @abstractmethod
    def plan_next_iteration(
            self,
            hist_reports : List[ExplorationReport],
            report : ExplorationReport,
            confs : List[Path],
    ) -> Tuple[bool, ExplorationTaskGroup, ConfSelector] :
        """
```

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```
        Make the plan for the next iteration of the stage.

        It checks the report of the current and all historical iterations of the stage,
        and tells if the iterations are converged.
        If not converged, it will plan the next ieration for the stage.

        Parameters
        ----------
        hist_reports: List[ExplorationReport]
            The historical exploration report of the stage. If this is the first␣
↪iteration of the stage, this list is empty.
        report : ExplorationReport
            The exploration report of this iteration.
        confs: List[Path]
            A list of configurations generated during the exploration. May be used to␣
↪generate new configurations for the next iteration.

        Returns
        -------
        converged: bool
            If the stage converged.
        task: ExplorationTaskGroup
            A `ExplorationTaskGroup` defining the exploration of the next iteration.␣
↪Should be `None` if the stage is converged.
        conf_selector: ConfSelector
            The configuration selector for the next iteration. Should be `None` if the␣
↪stage is converged.

        """
```

One may check more details on the *exploratin task group* and the configuration selector.

7.2 Exploration task groups

DPGEN2 defines a python class `ExplorationTask` to manage all necessry files needed to run a exploration task. It can be used as the example provided in the doc string.

```
class ExplorationTask():
    """Define the files needed by an exploration task.

    Examples
    --------
    >>> # this example dumps all files needed by the task.
    >>> files = exploration_task.files()
    ... for file_name, file_content in files.items():
    ...     with open(file_name, 'w') as fp:
    ...         fp.write(file_content)

    """
```

A collection of the exploration tasks is called exploration task group. All tasks groups are derived from the base class

`ExplorationTaskGroup`. The exploration task group can be viewd as a list of `ExplorationTasks`, one may get the list by using property `ExplorationTaskGroup.task_list`. One may add tasks, or ExplorationTaskGroup to the group by methods `ExplorationTaskGroup.add_task` and `ExplorationTaskGroup.add_group`, respectively.

```
class ExplorationTaskGroup(Sequence):
    @property
    def task_list(self) -> List[ExplorationTask]:
        """Get the `list` of `ExplorationTask`"""
        ...

    def add_task(self, task: ExplorationTask):
        """Add one task to the group."""
        ...

    def add_group(
            self,
            group : 'ExplorationTaskGroup',
    ):
        """Add another group to the group."""
        ...
```

An example of generating a group of NPT MD simulations may illustrate how to implement the `ExplorationTaskGroups`.

7.3 Configuration selector

The configuration selectors are derived from the abstract base class `ConfSelector`

```
class ConfSelector(ABC):
    """Select configurations from trajectory and model deviation files.
    """
    @abstractmethod
    def select (
            self,
            trajs : List[Path],
            model_devis : List[Path],
            traj_fmt : str = 'deepmd/npy',
            type_map : List[str] = None,
    ) -> Tuple[List[ Path ], ExplorationReport]:
```

The abstractmethod to implement is `ConfSelector.select`. `trajs` and `model_devis` are lists of files that recording the simulations trajectories and model deviations respectively. `traj_fmt` and `type_map` are parameters that may be needed for loading the trajectories by `dpdata`.

The `ConfSelector.select` returns a Path, each of which can be treated as a `dpdata.MultiSystems`, and a `ExplorationReport`.

An example of selecting configurations from LAMMPS trajectories may illustrate how to implement the `ConfSelectors`.

CHAPTER

EIGHT

DPGEN2 API

8.1 dpgen2 package

8.1.1 Subpackages

dpgen2.conf package

Submodules

dpgen2.conf.alloy_conf module

class dpgen2.conf.alloy_conf.**AlloyConf**(*lattice: System | Tuple[str, float]*, *type_map: List[str]*, *replicate: List[int] | Tuple[int] | int | None = None*)

Bases: object

Parameters

lattice Union[dpdata.System, Tuple[str,float]]
Lattice of the alloy confs. can be *dpdata.System*: lattice in *dpdata.System Tuple[str, float]*: pair of lattice type and lattice constant. lattice type can be "bcc", "fcc", "hcp", "sc" or "diamond"

replicate Union[List[int], Tuple[int], int]
replicate of the lattice

type_map List[str]
The type map

Methods

generate_file_content(numb_confs[, ...])	**Parameters**
generate_systems(numb_confs[, ...])	**Parameters**

generate_file_content(*numb_confs*, *concentration: List[List[float]] | List[float] | None = None*, *cell_pert_frac: float = 0.0*, *atom_pert_dist: float = 0.0*, *fmt: str = 'lammps/lmp'*) → List[str]

Parameters

numb_confs int
Number of configurations to generate

concentration List[List[float]] or List[float] or None
If *List[float]*, the concentrations of each element. The length of the list should be the same as the *type_map*. If *List[List[float]]*, a list of concentrations (*List[float]*) is randomly picked from the List. If *None*, the elements are assumed to be of equal concentration.

cell_pert_frac float
fraction of cell perturbation

atom_pert_dist float
the atom perturbation distance (unit angstrom).

fmt str
the format of the returned conf strings. Should be one of the formats supported by *dpdata*

Returns

conf_list List[str]
A list of file content of configurations.

`generate_systems`(*numb_confs*, *concentration: List[List[float]] | List[float] | None = None*, *cell_pert_frac: float = 0.0*, *atom_pert_dist: float = 0.0*) → List[System]

Parameters

numb_confs int
Number of configurations to generate

concentration List[List[float]] or List[float] or None
If *List[float]*, the concentrations of each element. The length of the list should be the same as the *type_map*. If *List[List[float]]*, a list of concentrations (*List[float]*) is randomly picked from the List. If *None*, the elements are assumed to be of equal concentration.

cell_pert_frac float
fraction of cell perturbation

atom_pert_dist float
the atom perturbation distance (unit angstrom).

Returns

conf_list List[dpdata.System]
A list of generated confs in *dpdata.System*.

`class dpgen2.conf.alloy_conf.AlloyConfGenerator`(*numb_confs*, *lattice: System | Tuple[str, float]*, *replicate: List[int] | Tuple[int] | int | None = None*, *concentration: List[List[float]] | List[float] | None = None*, *cell_pert_frac: float = 0.0*, *atom_pert_dist: float = 0.0*)

Bases: *ConfGenerator*

Parameters

numb_confs int
Number of configurations to generate

lattice Union[dpdata.System, Tuple[str,float]]
Lattice of the alloy confs. can be *dpdata.System*: lattice in *dpdata.System Tuple[str, float]*: pair of lattice type and lattice constant. lattice type can be "bcc", "fcc", "hcp", "sc" or "diamond"

replicate Union[List[int], Tuple[int], int]
replicate of the lattice

concentration List[List[float]] or List[float] or None
If *List[float]*, the concentrations of each element. The length of the list should be the same as the *type_map*. If *List[List[float]]*, a list of concentrations (*List[float]*) is randomly picked from the List. If *None*, the elements are assumed to be of equal concentration.

cell_pert_frac float
fraction of cell perturbation

atom_pert_dist float
the atom perturbation distance (unit angstrom).

Methods

generate(type_map)	Method of generating configurations.
get_file_content(type_map[, fmt])	Get the file content of configurations
normalize_config([data, strict])	Normalized the argument.

args
doc

static args() → List[Argument]

static doc() → str

generate(*type_map*) → MultiSystems

Method of generating configurations.

Parameters

type_map
[List[str]] The type map.

Returns

confs: dpdata.MultiSystems
The returned configurations in *dpdata.MultiSystems* format

dpgen2.conf.alloy_conf.**gen_doc**(*, *make_anchor=True*, *make_link=True*, ***kwargs*)

dpgen2.conf.alloy_conf.**generate_alloy_conf_args**()

dpgen2.conf.alloy_conf.**generate_alloy_conf_file_content**(*lattice: System | Tuple[str, float]*, *type_map: List[str]*, *numb_confs*, *replicate: List[int] | Tuple[int] | int | None = None*, *concentration: List[List[float]] | List[float] | None = None*, *cell_pert_frac: float = 0.0*, *atom_pert_dist: float = 0.0*, *fmt: str = 'lammps/lmp'*)

dpgen2.conf.alloy_conf.**normalize**(*data*)

dpgen2.conf.conf_generator module

class dpgen2.conf.conf_generator.**ConfGenerator**

Bases: ABC

Methods

generate(type_map)	Method of generating configurations.
get_file_content(type_map[, fmt])	Get the file content of configurations
normalize_config([data, strict])	Normalized the argument.

args

abstract static args() → List[Argument]

abstract generate(*type_map*) → MultiSystems

Method of generating configurations.

Parameters

type_map
[List[str]] The type map.

Returns

confs: dpdata.MultiSystems
The returned configurations in *dpdata.MultiSystems* format

get_file_content(*type_map*, *fmt='lammps/lmp'*) → List[str]

Get the file content of configurations

Parameters

type_map
[List[str]] The type map.

Returns

conf_list: List[str]
A list of file content of configurations.

classmethod normalize_config(*data: Dict = {}*, *strict: bool = True*) → Dict

Normalized the argument.

Parameters

data
[Dict] The input dict of arguments.

strict
[bool] Strictly check the arguments.

Returns

data: Dict
The normalized arguments.

dpgen2.conf.file_conf module

class dpgen2.conf.file_conf.**FileConfGenerator**(*files: str | List[str]*, *fmt: str = 'auto'*, *prefix: str | None = None*, *remove_pbc: bool | None = False*)

Bases: *ConfGenerator*

Methods

generate(type_map)	Method of generating configurations.
get_file_content(type_map[, fmt])	Get the file content of configurations
normalize_config([data, strict])	Normalized the argument.

args
doc
generate_mixed
generate_std

static args() → List[Argument]

static doc() → str

generate(*type_map*) → MultiSystems

Method of generating configurations.

Parameters

type_map
[List[str]] The type map.

Returns

confs: dpdata.MultiSystems
The returned configurations in *dpdata.MultiSystems* format

generate_mixed(*type_map*) → MultiSystems

generate_std(*type_map*) → MultiSystems

dpgen2.conf.unit_cells module

class dpgen2.conf.unit_cells.**BCC**

Bases: object

Methods

gen_box
numb_atoms
poscar_unit

gen_box()

numb_atoms()

poscar_unit(*latt*)

class dpgen2.conf.unit_cells.**DIAMOND**

Bases: object

Methods

gen_box
numb_atoms
poscar_unit

gen_box()

numb_atoms()

poscar_unit(*latt*)

class dpgen2.conf.unit_cells.**FCC**

Bases: object

Methods

gen_box
numb_atoms
poscar_unit

gen_box()

numb_atoms()

poscar_unit(*latt*)

class dpgen2.conf.unit_cells.**HCP**

Bases: object

Methods

gen_box
numb_atoms
poscar_unit

gen_box()

numb_atoms()

poscar_unit(*latt*)

class dpgen2.conf.unit_cells.**SC**

Bases: object

Methods

gen_box
numb_atoms
poscar_unit

gen_box()

numb_atoms()

poscar_unit(*latt*)

dpgen2.conf.unit_cells.**generate_unit_cell**(*crystal: str*, *latt: float = 1.0*) → System

dpgen2.entrypoint package

Submodules

dpgen2.entrypoint.args module

dpgen2.entrypoint.args.**bohrium_conf_args**()

dpgen2.entrypoint.args.**default_step_config_args**()

dpgen2.entrypoint.args.**dflow_conf_args**()

dpgen2.entrypoint.args.**dp_dist_train_args**()

dpgen2.entrypoint.args.**dp_train_args**()

dpgen2.entrypoint.args.**dpgen_step_config_args**(*default_config*)

dpgen2.entrypoint.args.**fp_args**(*inputs*, *run*)

dpgen2.entrypoint.args.**gen_doc**(*, *make_anchor=True*, *make_link=True*, ***kwargs*)

dpgen2.entrypoint.args.**input_args**()

dpgen2.entrypoint.args.**lmp_args**()

dpgen2.entrypoint.args.**make_link**(*content*, *ref_key*)

dpgen2.entrypoint.args.**normalize**(*data*)

dpgen2.entrypoint.args.**submit_args**(*default_step_config={'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'executor': None, 'parallelism': None, 'template_config': {'envs': None, 'image': 'dptechnology/dpgen2:latest', 'retry_on_transient_error': None, 'timeout': None, 'timeout_as_transient_error': False}}*)

dpgen2.entrypoint.args.**variant_conf**()

dpgen2.entrypoint.args.**variant_conv**()

dpgen2.entrypoint.args.**variant_explore**()

dpgen2.entrypoint.args.**variant_fp**()

dpgen2.entrypoint.args.**variant_train**()

dpgen2.entrypoint.common module

dpgen2.entrypoint.common.**expand_idx**(*in_list*) → List[int]

dpgen2.entrypoint.common.**expand_sys_str**(*root_dir: str | Path*) → List[str]

dpgen2.entrypoint.common.**global_config_workflow**(*wf_config*)

dpgen2.entrypoint.download module

dpgen2.entrypoint.download.**download**(*workflow_id*, *wf_config: Dict | None = {}*, *wf_keys: List | None = None*, *prefix: str | None = None*, *chk_pnt: bool = False*)

dpgen2.entrypoint.download.**download_by_def**(*workflow_id*, *wf_config: Dict = {}*, *iterations: List[int] | None = None*, *step_defs: List[str] | None = None*, *prefix: str | None = None*, *chk_pnt: bool = False*)

dpgen2.entrypoint.gui module

DP-GUI entrypoint.

dpgen2.entrypoint.gui.**start_dpgui**(*, *port: int*, *bind_all: bool*, ***kwargs*)

Host DP-GUI server.

Parameters

port
[int] The port to serve DP-GUI on.

bind_all
[bool] Serve on all public interfaces. This will expose your DP-GUI instance to the network on both IPv4 and IPv6 (where available).

****kwargs**
additional arguments

Raises

ModuleNotFoundError
The dpgui package is not installed

dpgen2.entrypoint.main module

dpgen2.entrypoint.main.**main**()

dpgen2.entrypoint.main.**main_parser**() → ArgumentParser

DPGEN2 commandline options argument parser.

Returns

argparse.ArgumentParser
the argument parser

Notes

This function is used by documentation.

dpgen2.entrypoint.main.**parse_args**(*args: List[str] | None = None*)

DPGEN2 commandline options argument parsing.

Parameters

args
[List[str]] list of command line arguments, main purpose is testing default option None takes arguments from sys.argv

dpgen2.entrypoint.showkey module

dpgen2.entrypoint.showkey.**showkey**(*wf_id*, *wf_config*)

dpgen2.entrypoint.status module

dpgen2.entrypoint.status.**status**(*workflow_id*, *wf_config: Dict | None = {}*)

dpgen2.entrypoint.submit module

dpgen2.entrypoint.submit.**copy_scheduler_plans**(*scheduler_new*, *scheduler_old*)

dpgen2.entrypoint.submit.**fold_keys**(*all_step_keys*)

dpgen2.entrypoint.submit.**get_kspacing_kgamma_from_incar**(*fname*)

dpgen2.entrypoint.submit.**get_resubmit_keys**(*wf*)

dpgen2.entrypoint.submit.**get_scheduler_ids**(*reuse_step*)

dpgen2.entrypoint.submit.**get_superop**(*key*)

dpgen2.entrypoint.submit.**make_calypso_naive_exploration_scheduler**(*config*)

dpgen2.entrypoint.submit.**make_concurrent_learning_op**(*train_style: str = 'dp'*, *explore_style: str = 'lmp'*, *fp_style: str = 'vasp'*, *prep_train_config: dict = {'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'executor': None, 'parallelism': None, 'template_config': {'envs': None, 'image': 'dptechnology/dpgen2:latest', 'retry_on_transient_error': None, 'timeout': None, 'timeout_as_transient_error': False}}*, *run_train_config: dict = {'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'executor': None, 'parallelism': None, 'template_config': {'envs': None, 'image': 'dptechnology/dpgen2:latest', 'retry_on_transient_error': None, 'timeout': None, 'timeout_as_transient_error': False}}*, *prep_explore_config: dict = {'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'executor': None, 'parallelism': None, 'template_config': {'envs': None, 'image': 'dptechnology/dpgen2:latest', 'retry_on_transient_error': None, 'timeout': None, 'timeout_as_transient_error': False}}*, *run_explore_config: dict = {'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'executor': None, 'parallelism': None, 'template_config': {'envs': None, 'image': 'dptechnology/dpgen2:latest', 'retry_on_transient_error': None, 'timeout': None, 'timeout_as_transient_error': False}}*, *prep_fp_config: dict = {'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'executor': None, 'parallelism': None, 'template_config': {'envs': None, 'image': 'dptechnology/dpgen2:latest', 'retry_on_transient_error': None, 'timeout': None, 'timeout_as_transient_error': False}}*, *run_fp_config: dict = {'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'executor': None, 'parallelism': None, 'template_config': {'envs': None, 'image': 'dptechnology/dpgen2:latest', 'retry_on_transient_error': None, 'timeout': None, 'timeout_as_transient_error': False}}*, *select_confs_config: dict = {'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'executor': None, 'parallelism': None, 'template_config': {'envs': None, 'image': 'dptechnology/dpgen2:latest', 'retry_on_transient_error': None, 'timeout':*

dpgen2.entrypoint.submit.**make_finetune_step**(*config*, *prep_train_config*, *run_train_config*, *upload_python_packages*, *numb_models*, *template_script*, *train_config*, *init_models*, *init_data*, *iter_data*, *valid_data=None*)

dpgen2.entrypoint.submit.**make_lmp_naive_exploration_scheduler**(*config*)

dpgen2.entrypoint.submit.**make_naive_exploration_scheduler**(*config*)

dpgen2.entrypoint.submit.**make_optional_parameter**(*mixed_type=False*, *finetune_mode='no'*)

dpgen2.entrypoint.submit.**print_list_steps**(*steps*)

dpgen2.entrypoint.submit.**resubmit_concurrent_learning**(*wf_config*, *wfid*, *list_steps=False*, *reuse=None*, *replace_scheduler=False*, *fold=False*)

dpgen2.entrypoint.submit.**submit_concurrent_learning**(*wf_config*, *reuse_step: List[ArgoStep] | None = None*, *replace_scheduler: bool = False*, *no_submission: bool = False*)

dpgen2.entrypoint.submit.**successful_step_keys**(*wf*)

dpgen2.entrypoint.submit.**update_reuse_step_scheduler**(*reuse_step*, *scheduler_new*)

dpgen2.entrypoint.submit.**workflow_concurrent_learning**(*config: Dict*) → Tuple[Step, Step | None]

dpgen2.entrypoint.watch module

dpgen2.entrypoint.watch.**update_finished_steps**(*wf*, *finished_keys: List[str] | None = None*, *download: bool | None = False*, *watching_keys: List[str] | None = None*, *prefix: str | None = None*, *chk_pnt: bool = False*)

dpgen2.entrypoint.watch.**watch**(*workflow_id*, *wf_config: Dict | None = {}*, *watching_keys: List | None = ['prep-run-train', 'prep-run-explore', 'prep-run-fp', 'collect-data']*, *frequency: float = 600.0*, *download: bool = False*, *prefix: str | None = None*, *chk_pnt: bool = False*)

dpgen2.entrypoint.workflow module

dpgen2.entrypoint.workflow.**add_subparser_workflow_subcommand**(*subparsers*, *command: str*)

dpgen2.entrypoint.workflow.**execute_workflow_subcommand**(*command: str*, *wfid: str*, *wf_config: dict | None = {}*)

dpgen2.exploration package

Subpackages

dpgen2.exploration.deviation package

Submodules

dpgen2.exploration.deviation.deviation_manager module

class dpgen2.exploration.deviation.deviation_manager.**DeviManager**

Bases: ABC

A class for model deviation management.

Methods

add(name, deviation)	Add a model deviation into this manager.
clear()	Clear all data in this manager.
get(name)	Gat a model deviation from this manager.

AVG_DEVI_F = 'avg_devi_f'

AVG_DEVI_V = 'avg_devi_v'

MAX_DEVI_F = 'max_devi_f'

MAX_DEVI_V = 'max_devi_v'

MIN_DEVI_F = 'min_devi_f'

MIN_DEVI_V = 'min_devi_v'

add(*name: str*, *deviation: ndarray*) → None

Add a model deviation into this manager.

Parameters

name
[str] The name of the deviation. The name is restricted to (DeviManager.MAX_DEVI_V, DeviManager.MIN_DEVI_V, DeviManager.AVG_DEVI_V, DeviManager.MAX_DEVI_F, DeviManager.MIN_DEVI_F, DeviManager.AVG_DEVI_F)

deviation
[np.ndarray] The model deviation is a one-dimensional array extracted from a trajectory file.

abstract clear() → None

Clear all data in this manager.

get(*name: str*) → List[ndarray | None]

Gat a model deviation from this manager.

Parameters

name
[str] The name of the deviation. The name is restricted to (DeviManager.MAX_DEVI_V, DeviManager.MIN_DEVI_V,

DeviManager.AVG_DEVI_V, DeviManager.MAX_DEVI_F, DeviManager.MIN_DEVI_F, DeviManager.AVG_DEVI_F)

dpgen2.exploration.deviation.deviation_std module

class dpgen2.exploration.deviation.deviation_std.**DeviManagerStd**

Bases: *DeviManager*

The class which is responsible for model deviation management.

This is the standard implementation of DeviManager. Each deviation (e.g. max_devi_f, max_devi_v in file *model_devi.out*) is stored as a List[Optional[np.ndarray]], where np.array is a one-dimensional array. A List[np.ndarray][ii][jj] is the force model deviation of the jj-th frame of the ii-th trajectory. The model deviation can be List[None], where len(List[None]) is the number of trajectory files.

Methods

add(name, deviation)	Add a model deviation into this manager.
clear()	Clear all data in this manager.
get(name)	Gat a model deviation from this manager.

clear() → None

Clear all data in this manager.

dpgen2.exploration.render package

Submodules

dpgen2.exploration.render.traj_render module

class dpgen2.exploration.render.traj_render.**TrajRender**

Bases: ABC

Methods

get_confs(traj, id_selected[, type_map, ...])	Get configurations from trajectory by selection.
get_model_devi(files)	Get model deviations from recording files.

abstract get_confs(*traj: List[Path]*, *id_selected: List[List[int]]*, *type_map: List[str] | None = None*, *conf_filters:* ConfFilters | *None = None*) → MultiSystems

Get configurations from trajectory by selection.

Parameters

traj
[List[Path]] Trajectory files

id_selected
[List[List[int]]] The selected frames. id_selected[ii][jj] is the jj-th selected frame from the ii-th trajectory. id_selected[ii] may be an empty list.

type_map
[List[str]] The type map.

Returns

ms: dpdata.MultiSystems
The configurations in dpdata.MultiSystems format

abstract get_model_devi(*files: List[Path]*) → *DeviManager*

Get model deviations from recording files.

Parameters

files
[List[Path]] The paths to the model deviation recording files

Returns

DeviManager: The class which is responsible for model deviation management.

dpgen2.exploration.render.traj_render_lammps module

class dpgen2.exploration.render.traj_render_lammps.**TrajRenderLammps**(*nopbc: bool = False*)

Bases: *TrajRender*

Methods

get_confs(trajs, id_selected[, type_map, ...])	Get configurations from trajectory by selection.
get_model_devi(files)	Get model deviations from recording files.

get_confs(*trajs: List[Path]*, *id_selected: List[List[int]]*, *type_map: List[str] | None = None*, *conf_filters: ConfFilters | None = None*) → MultiSystems

Get configurations from trajectory by selection.

Parameters

traj
[List[Path]] Trajectory files

id_selected
[List[List[int]]] The selected frames. id_selected[ii][jj] is the jj-th selected frame from the ii-th trajectory. id_selected[ii] may be an empty list.

type_map
[List[str]] The type map.

Returns

ms: dpdata.MultiSystems
The configurations in dpdata.MultiSystems format

get_model_devi(*files: List[Path]*) → *DeviManager*

Get model deviations from recording files.

Parameters

files
[List[Path]] The paths to the model deviation recording files

Returns

DeviManager: The class which is responsible for model deviation management.

dpgen2.exploration.report package

Submodules

dpgen2.exploration.report.report module

class dpgen2.exploration.report.report.**ExplorationReport**

Bases: ABC

Methods

clear()	Clear the report
converged(reports)	Check if the exploration is converged.
get_candidate_ids([max_nframes])	Get indexes of candidate configurations
no_candidate()	If no candidate configuration is found
print(stage_idx, idx_in_stage, iter_idx)	Print the report
print_header()	Print the header of report
record(model_devi)	Record the model deviations of the trajectories

abstract clear()

Clear the report

abstract converged(*reports*) → bool

Check if the exploration is converged.

Parameters

reports
Historical reports

Returns

converged bool
If the exploration is converged.

abstract get_candidate_ids(*max_nframes: int | None = None*) → List[List[int]]

Get indexes of candidate configurations

Parameters

max_nframes
The maximal number of frames of candidates.

Returns

idx: List[List[int]]
The frame indices of candidate configurations. idx[ii][jj] is the frame index of the jj-th candidate of the ii-th trajectory.

no_candidate() → bool

If no candidate configuration is found

abstract print(*stage_idx: int*, *idx_in_stage: int*, *iter_idx: int*) → str

Print the report

abstract print_header() → str

Print the header of report

abstract record(*model_devi:* DeviManager)

Record the model deviations of the trajectories

Parameters

model_devi
[DeviManager] The class which is responsible for model deviation management. Model deviations is stored as a List[Optional[np.ndarray]], where np.array is a one-dimensional array. List[np.ndarray][ii][jj] is the force model deviation of the jj-th frame of the ii-th trajectory. Model deviations can be List[None], where len(List[None]) is the number of trajectory files.

dpgen2.exploration.report.report_adaptive_lower module

class dpgen2.exploration.report.report_adaptive_lower.**ExplorationReportAdaptiveLower**(*level_f_hi: float = 0.5*, *numb_candi_f: int = 200*, *rate_candi_f: float = 0.01*, *level_v_hi: float | None = None*, *numb_candi_v: int = 0*, *rate_candi_v: float = 0.0*, *n_checked_steps: int = 2*, *conv_tolerance: float = 0.05*, *candi_sel_prob: str = 'uniform'*)

Bases: *ExplorationReport*

The exploration report that adapts the lower trust level.

This report will treat a fixed number of frames that has force model deviation lower than *level_f_hi*, and virial model deviation lower than *level_v_hi* as candidates.

The number of force frames is given by max(*numb_candi_f*, *rate_candi_f* * nframes) The number of virial frames is given by max(*numb_candi_v*, *rate_candi_v* * nframes)

The lower force trust level will be set to the lowest force model deviation of the force frames. The lower virial trust level will be set to the lowest virial model deviation of the virial frames

The exploration will be treat as converged if the differences in model deviations in the neighboring steps are less than *conv_tolerance* in the last *n_checked_steps*.

Parameters

level_f_hi float
The higher trust level of force model deviation

numb_candi_f int
The number of force frames that has a model deviation lower than *level_f_hi* treated as candidate.

rate_candi_f float
The ratio of force frames that has a model deviation lower than *level_f_hi* treated as candidate.

level_v_hi float
The higher trust level of virial model deviation

numb_candi_v int
The number of virial frames that has a model deviation lower than *level_v_hi* treated as candidate.

rate_candi_v float
The ratio of virial frames that has a model deviation lower than *level_v_hi* treated as candidate.

n_checked_steps int
The number of steps to check the convergence.

conv_tolerance float
The convergence tolerance.

candi_sel_prob str
The method for selecting candidates. It can be "uniform": all candidates are of the same probability. "inv_pop_f" or "inv_pop_f:nhist": the probability is inversely propotional to the population of a histogram between level_f_lo and level_f_hi. The number of bins in the histogram is set by nhist, which should be an integer. The default is 10.

Methods

clear()	Clear the report
converged(reports)	Check if the exploration is converged.
get_candidate_ids([max_nframes])	Get indexes of candidate configurations
no_candidate()	If no candidate configuration is found
print(stage_idx, idx_in_stage, iter_idx)	Print the report
print_header()	Print the header of report
record(model_devi)	Record the model deviations of the trajectories

accurate_ratio
args
candidate_ratio
doc
failed_ratio

accurate_ratio(*tag=None*)

static args() → List[Argument]

candidate_ratio(*tag=None*)

clear()
Clear the report

converged(*reports*) → bool

Check if the exploration is converged.

Parameters

reports
Historical reports

Returns

converged bool
If the exploration is converged.

static doc() → str

failed_ratio(*tag=None*)

get_candidate_ids(*max_nframes: int | None = None*) → List[List[int]]

Get indexes of candidate configurations

Parameters

max_nframes
The maximal number of frames of candidates.

Returns

idx: List[List[int]]
The frame indices of candidate configurations. idx[ii][jj] is the frame index of the jj-th candidate of the ii-th trajectory.

print(*stage_idx: int*, *idx_in_stage: int*, *iter_idx: int*) → str

Print the report

print_header() → str

Print the header of report

record(*model_devi:* DeviManager)

Record the model deviations of the trajectories

Parameters

model_devi
[DeviManager] The class which is responsible for model deviation management. Model deviations is stored as a List[Optional[np.ndarray]], where np.array is a one-dimensional array. List[np.ndarray][ii][jj] is the force model deviation of the jj-th frame of the ii-th trajectory. Model deviations can be List[None], where len(List[None]) is the number of trajectory files.

dpgen2.exploration.report.report_trust_levels_base module

class dpgen2.exploration.report.report_trust_levels_base.**ExplorationReportTrustLevels**(*level_f_lo*, *level_f_hi*, *level_v_lo=None*, *level_v_hi=None*, *conv_accuracy=0.9*)

Bases: *ExplorationReport*

Methods

clear()	Clear the report
converged([reports])	Check if the exploration is converged.
get_candidate_ids([max_nframes])	Get indexes of candidate configurations
no_candidate()	If no candidate configuration is found
print(stage_idx, idx_in_stage, iter_idx)	Print the report
print_header()	Print the header of report
record(model_devi)	Record the model deviations of the trajectories

accurate_ratio
args
candidate_ratio
failed_ratio

accurate_ratio(*tag=None*)

static args() → List[Argument]

candidate_ratio(*tag=None*)

clear()

Clear the report

abstract converged(*reports: List[*ExplorationReport*] | None = None*) → bool

Check if the exploration is converged.

Parameters

reports
Historical reports

Returns

converged bool
If the exploration is converged.

failed_ratio(*tag=None*)

abstract get_candidate_ids(*max_nframes: int | None = None*) → List[List[int]]

Get indexes of candidate configurations

Parameters

max_nframes
The maximal number of frames of candidates.

Returns

idx: List[List[int]]
The frame indices of candidate configurations. idx[ii][jj] is the frame index of the jj-th candidate of the ii-th trajectory.

print(*stage_idx: int*, *idx_in_stage: int*, *iter_idx: int*) → str

Print the report

print_header() → str

Print the header of report

record(*model_devi:* DeviManager)

Record the model deviations of the trajectories

Parameters

model_devi

[DeviManager] The class which is responsible for model deviation management. Model deviations is stored as a List[Optional[np.ndarray]], where np.array is a one-dimensional array. List[np.ndarray][ii][jj] is the force model deviation of the jj-th frame of the ii-th trajectory. Model deviations can be List[None], where len(List[None]) is the number of trajectory files.

dpgen2.exploration.report.report_trust_levels_max module

class dpgen2.exploration.report.report_trust_levels_max.**ExplorationReportTrustLevelsMax**(*level_f_lo*, *level_f_hi*, *level_v_lo=None*, *level_v_hi=None*, *conv_accuracy=0.9*

Bases: *ExplorationReportTrustLevels*

Methods

clear()	Clear the report
converged([reports])	Check if the exploration is converged.
get_candidate_ids([max_nframes])	Get indexes of candidate configurations
no_candidate()	If no candidate configuration is found
print(stage_idx, idx_in_stage, iter_idx)	Print the report
print_header()	Print the header of report
record(model_devi)	Record the model deviations of the trajectories

accurate_ratio
args
candidate_ratio
doc
failed_ratio

converged(*reports: List[*ExplorationReport*]* | *None* = *None*) → bool

Check if the exploration is converged.

Parameters

reports

Historical reports

Returns

converged bool

If the exploration is converged.

static doc() → str

get_candidate_ids(*max_nframes: int | None = None*) → List[List[int]]

Get indexes of candidate configurations

Parameters

max_nframes
The maximal number of frames of candidates.

Returns

idx: List[List[int]]
The frame indices of candidate configurations. idx[ii][jj] is the frame index of the jj-th candidate of the ii-th trajectory.

dpgen2.exploration.report.report_trust_levels_random module

class dpgen2.exploration.report.report_trust_levels_random.**ExplorationReportTrustLevelsRandom**(*level_f_lo*, *level_f_hi*, *level_v_lo=*, *level_v_hi=*, *conv_accura*

Bases: *ExplorationReportTrustLevels*

Methods

clear()	Clear the report
converged([reports])	Check if the exploration is converged.
get_candidate_ids([max_nframes])	Get indexes of candidate configurations
no_candidate()	If no candidate configuration is found
print(stage_idx, idx_in_stage, iter_idx)	Print the report
print_header()	Print the header of report
record(model_devi)	Record the model deviations of the trajectories

accurate_ratio
args
candidate_ratio
doc
failed_ratio

converged(*reports: List[*ExplorationReport*] | None = None*) → bool

Check if the exploration is converged.

Parameters

reports
Historical reports

Returns

converged bool
If the exploration is converged.

static doc() → str

get_candidate_ids(*max_nframes: int | None = None*) → List[List[int]]

Get indexes of candidate configurations

Parameters

max_nframes
The maximal number of frames of candidates.

Returns

idx: List[List[int]]
The frame indices of candidate configurations. idx[ii][jj] is the frame index of the jj-th candidate of the ii-th trajectory.

dpgen2.exploration.scheduler package

Submodules

dpgen2.exploration.scheduler.convergence_check_stage_scheduler module

class dpgen2.exploration.scheduler.convergence_check_stage_scheduler.**ConvergenceCheckStageScheduler**(*stage*
Ex-
plo-
ratio
se-
lec-
tor:
Con
f-
S-
e-
lec-
tor,
max
int
|
Non
=
Non
fa-
*tal_*
bool
=
True

Bases: *StageScheduler*

Methods

complete()	Tell if the stage is complete
converged()	Tell if the stage is converged
force_complete()	For complete the stage
get_reports()	Return all exploration reports
next_iteration()	Return the index of the next iteration
plan_next_iteration([report, trajs])	Make the plan for the next iteration of the stage.

reached_max_iteration

complete()

Tell if the stage is complete

Returns

converged bool
if the stage is complete

converged()

Tell if the stage is converged

Returns

converged bool
the convergence

force_complete()

For complete the stage

get_reports()

Return all exploration reports

Returns

reports List[ExplorationReport]
the reports

next_iteration()

Return the index of the next iteration

Returns

index int
the index of the next iteration

plan_next_iteration(*report:* ExplorationReport | *None* = *None*, *trajs:* *List[Path]* | *None* = *None*) → Tuple[bool, *BaseExplorationTaskGroup* | None, *ConfSelector* | None]

Make the plan for the next iteration of the stage.

It checks the report of the current and all historical iterations of the stage, and tells if the iterations are converged. If not converged, it will plan the next ieration for the stage.

Parameters

hist_reports
[List[ExplorationReport]] The historical exploration report of the stage. If this is the first iteration of the stage, this list is empty.

report
[ExplorationReport] The exploration report of this iteration.

confs
[List[Path]] A list of configurations generated during the exploration. May be used to generate new configurations for the next iteration.

Returns

stg_complete: bool
If the stage completed. Two cases may happen: 1. converged. 2. when not fatal_at_max, not converged but reached max number of iterations.

task: ExplorationTaskGroup
A *ExplorationTaskGroup* defining the exploration of the next iteration. Should be *None* if the stage is converged.

conf_selector: ConfSelector
The configuration selector for the next iteration. Should be *None* if the stage is converged.

`reached_max_iteration()`

dpgen2.exploration.scheduler.scheduler module

`class dpgen2.exploration.scheduler.scheduler.ExplorationScheduler`

Bases: `object`

The exploration scheduler.

Methods

add_stage_scheduler(stage_scheduler)	Add stage scheduler.
complete()	Tell if all stages are converged.
force_stage_complete()	Force complete the current stage
get_convergence_ratio()	Get the accurate, candidate and failed ratios of the iterations
get_iteration()	Get the index of the current iteration.
get_stage()	Get the index of current stage.
get_stage_of_iterations()	Get the stage index and the index in the stage of iterations.
plan_next_iteration([report, trajs])	Make the plan for the next DPGEN iteration.

print_convergence
print_last_iteration

`add_stage_scheduler(`*stage_scheduler:* StageScheduler`)`

Add stage scheduler.

All added schedulers can be treated as a *list* (order matters). Only one stage is converged, the iteration goes to the next iteration.

Parameters

stage_scheduler
[StageScheduler] The added stage scheduler

`complete()`

Tell if all stages are converged.

`force_stage_complete()`

Force complete the current stage

`get_convergence_ratio()`

Get the accurate, candidate and failed ratios of the iterations

Returns

accu np.ndarray
The accurate ratio. length of array the same as # iterations.

cand np.ndarray
The candidate ratio. length of array the same as # iterations.

fail np.ndarray
The failed ration. length of array the same as # iterations.

`get_iteration()`

Get the index of the current iteration.

Iteration index increase when *self.plan_next_iteration* returns valid *expl_task_grp* and *conf_selector* for the next iteration.

`get_stage()`

Get the index of current stage.

Stage index increases when the previous stage converges. Usually called after *self.plan_next_iteration*.

`get_stage_of_iterations()`

Get the stage index and the index in the stage of iterations.

`plan_next_iteration`(*report:* ExplorationReport | *None* = *None*, *trajs: List[Path]* | *None* = *None*) → Tuple[bool, *ExplorationTaskGroup* | None, *ConfSelector* | None]

Make the plan for the next DPGEN iteration.

Parameters

report
[ExplorationReport] The exploration report of this iteration.

trajs
[List[Path]] A list of configurations generated during the exploration. May be used to generate new configurations for the next iteration.

Returns

complete: bool
If all the DPGEN stages complete.

task: ExplorationTaskGroup
A *ExplorationTaskGroup* defining the exploration of the next iteration. Should be *None* if converged.

conf_selector: ConfSelector
The configuration selector for the next iteration. Should be *None* if converged.

`print_convergence()`

`print_last_iteration`(*print_header=False*)

dpgen2.exploration.scheduler.stage_scheduler module

class dpgen2.exploration.scheduler.stage_scheduler.**StageScheduler**

Bases: ABC

The scheduler for an exploration stage.

Methods

complete()	Tell if the stage is complete
converged()	Tell if the stage is converged
force_complete()	For complete the stage
get_reports()	Return all exploration reports
next_iteration()	Return the index of the next iteration
plan_next_iteration(report, trajs)	Make the plan for the next iteration of the stage.

abstract complete() → bool

Tell if the stage is complete

Returns

converged bool
if the stage is complete

abstract converged() → bool

Tell if the stage is converged

Returns

converged bool
the convergence

abstract force_complete()

For complete the stage

abstract get_reports() → List[*ExplorationReport*]

Return all exploration reports

Returns

reports List[ExplorationReport]
the reports

abstract next_iteration() → int

Return the index of the next iteration

Returns

index int
the index of the next iteration

abstract plan_next_iteration(*report:* ExplorationReport, *trajs: List[Path]*) → Tuple[bool, *ExplorationTaskGroup*, *ConfSelector*]

Make the plan for the next iteration of the stage.

It checks the report of the current and all historical iterations of the stage, and tells if the iterations are converged. If not converged, it will plan the next ieration for the stage.

Parameters

hist_reports
[List[ExplorationReport]] The historical exploration report of the stage. If this is the first iteration of the stage, this list is empty.

report
[ExplorationReport] The exploration report of this iteration.

confs
[List[Path]] A list of configurations generated during the exploration. May be used to generate new configurations for the next iteration.

Returns

stg_complete: bool
If the stage completed. Two cases may happen: 1. converged. 2. when not fatal_at_max, not converged but reached max number of iterations.

task: ExplorationTaskGroup
A *ExplorationTaskGroup* defining the exploration of the next iteration. Should be *None* if the stage is converged.

conf_selector: ConfSelector
The configuration selector for the next iteration. Should be *None* if the stage is converged.

dpgen2.exploration.selector package

Submodules

dpgen2.exploration.selector.conf_filter module

class dpgen2.exploration.selector.conf_filter.**ConfFilter**
Bases: ABC

Methods

check(coords, cell, atom_types, nopbc)	Check if the configuration is valid.

abstract check(*coords: ndarray*, *cell: ndarray*, *atom_types: ndarray*, *nopbc: bool*) → bool
Check if the configuration is valid.

Parameters

coords
[numpy.array] The coordinates, numpy array of shape natoms x 3

cell
[numpy.array] The cell tensor. numpy array of shape 3 x 3

atom_types
[numpy.array] The atom types. numpy array of shape natoms

nopbc
[bool] If no periodic boundary condition.

Returns

valid
[bool] *True* if the configuration is a valid configuration, else *False*.

class dpgen2.exploration.selector.conf_filter.**ConfFilters**

Bases: object

Methods

add
check

add(*conf_filter:* ConfFilter) → *ConfFilters*

check(*conf:* *System*) → System

dpgen2.exploration.selector.conf_selector module

class dpgen2.exploration.selector.conf_selector.**ConfSelector**

Bases: ABC

Select configurations from trajectory and model deviation files.

Methods

select

abstract select(*trajs: List[Path]*, *model_devis: List[Path]*, *type_map: List[str]* | *None* = *None*) → Tuple[List[Path], *ExplorationReport*]

dpgen2.exploration.selector.conf_selector_frame module

class dpgen2.exploration.selector.conf_selector_frame.**ConfSelectorFrames**(*traj_render:* TrajRender, *report:* ExplorationReport, *max_numb_sel: int* | *None* = *None*, *conf_filters:* ConfFilters | *None* = *None*)

Bases: *ConfSelector*

Select frames from trajectories as confs.

Parameters: trust_level: TrustLevel
The trust level

conf_filter: ConfFilters
The configuration filter

Methods

`select`(trajs, model_devis[, type_map])	Select configurations

select(*trajs: List[Path]*, *model_devis: List[Path]*, *type_map: List[str] | None = None*) → Tuple[List[Path], *ExplorationReport*]

Select configurations

Parameters

trajs
[List[Path]] A *list* of *Path* to trajectory files generated by LAMMPS

model_devis
[List[Path]] A *list* of *Path* to model deviation files generated by LAMMPS. Format: each line has 7 numbers they are used as # frame_id md_v_max md_v_min md_v_mean md_f_max md_f_min md_f_mean where *md* stands for model deviation, v for virial and f for force

type_map
[List[str]] The *type_map* of the systems

Returns

confs
[List[Path]] The selected confgurations, stored in a folder in deepmd/npy format, can be parsed as dpdata.MultiSystems. The *list* only has one item.

report
[ExplorationReport] The exploration report recoding the status of the exploration.

dpgen2.exploration.task package

Subpackages

dpgen2.exploration.task.calypso package

Submodules

dpgen2.exploration.task.calypso.caly_input module

dpgen2.exploration.task.calypso.caly_input.**make_calypso_input**(*numb_of_species: int*, *name_of_atoms: List[str]*, *atomic_number: List[int]*, *numb_of_atoms: List[int]*, *distance_of_ions*, *pop_size: int = 30*, *max_step: int = 5*, *system_name: str = 'CALYPSO'*, *numb_of_formula: List[int] = [1, 1]*, *pressure: float = 0.001*, *fmax: float = 0.01*, *volume: float = 0*, *ialgo: int = 2*, *pso_ratio: float = 0.6*, *icode: int = 15*, *numb_of_lbest: int = 4*, *numb_of_local_optim: int = 4*, *command: str = 'sh submit.sh'*, *max_time: int = 9000*, *gen_type: int = 1*, *pick_up: bool = False*, *pick_step: int = 1*, *parallel: bool = False*, *split: bool = True*, *spec_space_group: List[int] = [2, 230]*, *vsc: bool = False*, *ctrl_range: List[List[int]] = [[1, 10]]*, *max_numb_atoms: int = 100*, ***kwargs*)

dpgen2.exploration.task.lmp package

Submodules

dpgen2.exploration.task.lmp.lmp_input module

dpgen2.exploration.task.lmp.lmp_input.**make_lmp_input**(*conf_file: str*, *ensemble: str*, *graphs: List[str]*, *nsteps: int*, *dt: float*, *neidelay: int | None*, *trj_freq: int*, *mass_map: List[float]*, *temp: float*, *tau_t: float = 0.1*, *pres: float | None = None*, *tau_p: float = 0.5*, *use_clusters: bool = False*, *relative_f_epsilon: float | None = None*, *relative_v_epsilon: float | None = None*, *pka_e: float | None = None*, *ele_temp_f: float | None = None*, *ele_temp_a: float | None = None*, *nopbc: bool = False*, *max_seed: int = 1000000*, *deepmd_version='2.0'*, *trj_seperate_files=True*)

Submodules

dpgen2.exploration.task.caly_task_group module

class dpgen2.exploration.task.caly_task_group.**CalyTaskGroup**

Bases: *ExplorationTaskGroup*

Attributes

task_list
Get the *list* of *ExplorationTask*

Methods

add_group(group)	Add another group to the group.
add_task(task)	Add one task to the group.
count(value)	
index(value, [start, [stop]])	Raises ValueError if the value is not present.
make_task()	Make the CALYPSO task group.
set_params(numb_of_species, name_of_atoms, ...)	Set calypso parameters

clear

make_task() → *ExplorationTaskGroup*

Make the CALYPSO task group.

Returns

task_grp: ExplorationTaskGroup
Return one calypso task group.

set_params(*numb_of_species*, *name_of_atoms*, *atomic_number*, *numb_of_atoms*, *distance_of_ions*, *pop_size: int = 30*, *max_step: int = 5*, *system_name: str = 'CALYPSO'*, *numb_of_formula: List[int] = [1, 1]*, *pressure: float = 0.001*, *fmax: float = 0.01*, *volume: float = 0*, *ialgo: int = 2*, *pso_ratio: float = 0.6*, *icode: int = 15*, *numb_of_lbest: int = 4*, *numb_of_local_optim: int = 4*, *command: str = 'sh submit.sh'*, *max_time: int = 9000*, *gen_type: int = 1*, *pick_up: bool = False*, *pick_step: int = 1*, *parallel: bool = False*, *split: bool = True*, *spec_space_group: List[int] = [2, 230]*, *vsc: bool = True*, *ctrl_range: List[List[int]] = [[1, 10]]*, *max_numb_atoms: int = 100*)

Set calypso parameters

dpgen2.exploration.task.conf_sampling_task_group module

class dpgen2.exploration.task.conf_sampling_task_group.**ConfSamplingTaskGroup**

Bases: *ExplorationTaskGroup*

Attributes

task_list
Get the *list* of *ExplorationTask*

Methods

add_group(group)	Add another group to the group.
add_task(task)	Add one task to the group.
count(value)	
index(value, [start, [stop]])	Raises ValueError if the value is not present.
make_task()	Make the task group.
set_conf(conf_list[, n_sample, random_sample])	Set the configurations of exploration

clear

set_conf(*conf_list: List[str]*, *n_sample: int | None = None*, *random_sample: bool = False*)

Set the configurations of exploration

Parameters

conf_list str
A list of file contents

n_sample int
Number of samples drawn from the conf list each time *make_task* is called. If set to *None*, *n_sample* is set to length of the conf_list.

random_sample bool
If true the confs are randomly sampled, otherwise are consecutively sampled from the conf_list

dpgen2.exploration.task.customized_lmp_template_task_group module

class dpgen2.exploration.task.customized_lmp_template_task_group.**CustomizedLmpTemplateTaskGroup**

Bases: *ConfSamplingTaskGroup*

Attributes

task_list
Get the *list* of *ExplorationTask*

Methods

add_group(group)	Add another group to the group.
add_task(task)	Add one task to the group.
count(value)	
index(value, [start, [stop]])	Raises ValueError if the value is not present.
make_task()	Make the task group.
set_conf(conf_list[, n_sample, random_sample])	Set the configurations of exploration
set_lmp(numb_models, custom_shell_commands)	Set lammps task.

clear

make_task() → *CustomizedLmpTemplateTaskGroup*

Make the task group.

set_lmp(*numb_models: int*, *custom_shell_commands: List[str]*, *revisions: dict = {}*, *traj_freq: int = 10*, *input_lmp_conf_name: str = 'conf.lmp'*, *input_lmp_tmpl_name: str = 'in.lammps'*, *input_plm_tmpl_name: str | None = None*, *input_extra_files: List[str] = []*, *output_dir_pattern: str | List[str] = '*'*, *output_lmp_conf_name: str = 'conf.lmp'*, *output_lmp_tmpl_name: str = 'in.lammps'*, *output_plm_tmpl_name: str | None = None*) → None

Set lammps task.

Parameters

numb_models
[int] Number of models

custom_shell_commands
[str] Customized shell commands to be run for each configuration. The commands require *input_lmp_conf_name* as input conf file, *input_lmp_tmpl_name* and *input_plm_tmpl_name* as templates, and *input_extra_files* as extra input files. By running the commands a series folders in pattern *output_dir_pattern* are supposed to be generated, and each folder is supposed to contain a configuration file *output_lmp_conf_name*, a lammps template file *output_lmp_tmpl_name* and a plumed template file *output_plm_tmpl_name*.

revisions
[dict] Revision dictionary. Provided in {key: [enumerated values]} format

traj_freq
[int] Frequency along trajectory of checking model deviation

input_lmp_conf_name
[str] Input conf file name for the shell commands.

input_lmp_tmpl_name
[str] Template file name of lammps input

input_plm_tmpl_name
[str] Template file name of the plumed input

input_extra_files
[List[str]] Extra files that may be needed to execute the shell commands

output_dir_pattern
[Union[str, List[str]]] Pattern of resultant folders generated by the shell commands.

output_lmp_conf_name
[str] Generated conf file name.

output_lmp_tmpl_name
[str] Generated lmp input file name.

output_plm_tmpl_name
[str] Generated plm input file name.

dpgen2.exploration.task.lmp_template_task_group module

class dpgen2.exploration.task.lmp_template_task_group.**LmpTemplateTaskGroup**

Bases: *ConfSamplingTaskGroup*

Attributes

task_list
Get the *list* of *ExplorationTask*

Methods

add_group(group)	Add another group to the group.
add_task(task)	Add one task to the group.
count(value)	
index(value, [start, [stop]])	Raises ValueError if the value is not present.
make_task()	Make the task group.
set_conf(conf_list[, n_sample, random_sample])	Set the configurations of exploration

clear
make_cont
set_lmp

make_cont(*templates: list*, *revisions: dict*)

make_task() → *LmpTemplateTaskGroup*

Make the task group.

set_lmp(*numb_models: int*, *lmp_template_fname: str*, *plm_template_fname: str | None = None*, *revisions: dict = {}*, *traj_freq: int = 10*) → None

dpgen2.exploration.task.lmp_template_task_group.**find_only_one_key**(*lmp_lines*, *key*)

dpgen2.exploration.task.lmp_template_task_group.**revise_by_keys**(*lmp_lines*, *keys*, *values*)

dpgen2.exploration.task.lmp_template_task_group.**revise_lmp_input_dump**(*lmp_lines*, *trj_freq*)

dpgen2.exploration.task.lmp_template_task_group.**revise_lmp_input_model**(*lmp_lines*, *task_model_list*, *trj_freq*, *deepmd_version='1'*)

dpgen2.exploration.task.lmp_template_task_group.**revise_lmp_input_plm**(*lmp_lines*, *in_plm*, *out_plm='output.plumed'*)

dpgen2.exploration.task.make_task_group_from_config module

dpgen2.exploration.task.make_task_group_from_config.**caly_normalize**(*data*)

dpgen2.exploration.task.make_task_group_from_config.**caly_task_group_args**()

dpgen2.exploration.task.make_task_group_from_config.**caly_task_grp_args**()

dpgen2.exploration.task.make_task_group_from_config.**config_strip_confidx**(*config*)

dpgen2.exploration.task.make_task_group_from_config.**customized_lmp_template_task_group_args**()

dpgen2.exploration.task.make_task_group_from_config.**lmp_normalize**(*data*)

dpgen2.exploration.task.make_task_group_from_config.**lmp_task_group_args**()

dpgen2.exploration.task.make_task_group_from_config.**lmp_template_task_group_args**()

dpgen2.exploration.task.make_task_group_from_config.**make_calypso_task_group_from_config**(*config*)

dpgen2.exploration.task.make_task_group_from_config.**make_lmp_task_group_from_config**(*numb_models*, *mass_map*, *config*)

dpgen2.exploration.task.make_task_group_from_config.**make_task_group_from_config**(*numb_models*, *mass_map*, *config*)

dpgen2.exploration.task.make_task_group_from_config.**npt_task_group_args**()

dpgen2.exploration.task.make_task_group_from_config.**variant_task_group**()

dpgen2.exploration.task.npt_task_group module

class dpgen2.exploration.task.npt_task_group.**NPTTaskGroup**

Bases: *ConfSamplingTaskGroup*

Attributes

task_list
Get the *list* of *ExplorationTask*

Methods

add_group(group)	Add another group to the group.
add_task(task)	Add one task to the group.
count(value)	
index(value, [start, [stop]])	Raises ValueError if the value is not present.
make_task()	Make the LAMMPS task group.
set_conf(conf_list[, n_sample, random_sample])	Set the configurations of exploration
set_md(numb_models, mass_map, temps[, ...])	Set MD parameters

clear

make_task() → *NPTTaskGroup*

Make the LAMMPS task group.

Returns

task_grp: ExplorationTaskGroup
The returned lammps task group. The number of tasks is nconf*nT*nP. nconf is set by *n_sample* parameter of *set_conf*. nT and nP are lengths of the *temps* and *press* parameters of *set_md*.

set_md(*numb_models*, *mass_map*, *temps: List[float]*, *press: List[float] | None = None*, *ens: str = 'npt'*, *dt: float = 0.001*, *nsteps: int = 1000*, *trj_freq: int = 10*, *tau_t: float = 0.1*, *tau_p: float = 0.5*, *pka_e: float | None = None*, *neidelay: int | None = None*, *no_pbc: bool = False*, *use_clusters: bool = False*, *relative_f_epsilon: float | None = None*, *relative_v_epsilon: float | None = None*, *ele_temp_f: float | None = None*, *ele_temp_a: float | None = None*)

Set MD parameters

dpgen2.exploration.task.stage module

class dpgen2.exploration.task.stage.**ExplorationStage**

Bases: object

The exploration stage.

Methods

add_task_group(grp)	Add an exploration group
clear()	Clear all exploration group.
make_task()	Make the LAMMPS task group.

add_task_group(*grp: ExplorationTaskGroup*)

Add an exploration group

Parameters

grp
[ExplorationTaskGroup] The added exploration task group

clear()

Clear all exploration group.

make_task() → *BaseExplorationTaskGroup*

Make the LAMMPS task group.

Returns

task_grp: BaseExplorationTaskGroup
The returned lammps task group. The number of tasks is equal to the summation of task groups defined by all the exploration groups added to the stage.

dpgen2.exploration.task.task module

class dpgen2.exploration.task.task.**ExplorationTask**

Bases: object

Define the files needed by an exploration task.

Examples

```
>>> # this example dumps all files needed by the task.
>>> files = exploration_task.files()
... for file_name, file_content in files.items():
...     with open(file_name, 'w') as fp:
...         fp.write(file_content)
```

Methods

add_file(fname, fcont)	Add file to the task
files()	Get all files for the task.

add_file(*fname: str*, *fcont: str*)

Add file to the task

Parameters

fname
[str] The name of the file

fcont
[str] The content of the file.

files() → Dict

Get all files for the task.

Returns

files
[dict] The dict storing all files for the task. The file name is a key of the dict, and the file content is the corresponding value.

dpgen2.exploration.task.task_group module

class dpgen2.exploration.task.task_group.**BaseExplorationTaskGroup**

Bases: Sequence

A group of exploration tasks. Implemented as a *list* of *ExplorationTask*.

Attributes

task_list
Get the *list* of *ExplorationTask*

Methods

add_group(group)	Add another group to the group.
add_task(task)	Add one task to the group.
count(value)	
index(value, [start, [stop]])	Raises ValueError if the value is not present.

clear

add_group(*group:* ExplorationTaskGroup)

Add another group to the group.

add_task(*task:* ExplorationTask)

Add one task to the group.

clear() → None

property task_list: List[*ExplorationTask*]

Get the *list* of *ExplorationTask*

class dpgen2.exploration.task.task_group.**ExplorationTaskGroup**

Bases: ABC, *BaseExplorationTaskGroup*

Attributes

task_list

Get the *list* of *ExplorationTask*

Methods

add_group(group)	Add another group to the group.
add_task(task)	Add one task to the group.
count(value)	
index(value, [start, [stop]])	Raises ValueError if the value is not present.
make_task()	Make the task group.

clear

abstract make_task() → *ExplorationTaskGroup*

Make the task group.

class dpgen2.exploration.task.task_group.**FooTask**(*conf_name='conf.lmp'*, *conf_cont=''*, *inpu_name='in.lammps'*, *inpu_cont=''*)

Bases: *ExplorationTask*

Methods

add_file(fname, fcont)	Add file to the task
files()	Get all files for the task.

class dpgen2.exploration.task.task_group.**FooTaskGroup**(*numb_task*)

Bases: *BaseExplorationTaskGroup*

Attributes

task_list
Get the *list* of *ExplorationTask*

Methods

add_group(group)	Add another group to the group.
add_task(task)	Add one task to the group.
count(value)	
index(value, [start, [stop]])	Raises ValueError if the value is not present.

clear

property **task_list**

Get the *list* of *ExplorationTask*

dpgen2.flow package

Submodules

dpgen2.flow.dpgen_loop module

class dpgen2.flow.dpgen_loop.**ConcurrentLearning**(*name: str*, *block_op:* ConcurrentLearningBlock, *step_config: dict = {'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'executor': None, 'parallelism': None, 'template_config': {'envs': None, 'image': 'dptechnology/dpgen2:latest', 'retry_on_transient_error': None, 'timeout': None, 'timeout_as_transient_error': False}}*, *upload_python_packages: List[PathLike] | None = None*)

Bases: Steps

Attributes

init_keys
input_artifacts
input_parameters
loop_keys
output_artifacts
output_parameters

Methods

add(step)	Add a step or a list of parallel steps to the steps

add_slices
convert_to_argo
convert_to_graph
copy
deepcopy
from_dict
from_graph
handle_key
run

property init_keys

property input_artifacts

property input_parameters

property loop_keys

property output_artifacts

property output_parameters

class dpgen2.flow.dpgen_loop.**ConcurrentLearningLoop**(*name: str*, *block_op:* ConcurrentLearningBlock, *step_config: dict = {'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'executor': None, 'parallelism': None, 'template_config': {'envs': None, 'image': 'dptechnology/dpgen2:latest', 'retry_on_transient_error': None, 'timeout': None, 'timeout_as_transient_error': False}}*, *upload_python_packages: List[PathLike] | None = None*)

Bases: Steps

Attributes

input_artifacts
input_parameters
keys
output_artifacts
output_parameters

Methods

add(step)	Add a step or a list of parallel steps to the steps

add_slices
convert_to_argo
convert_to_graph
copy
deepcopy
from_dict
from_graph
handle_key
run

property input_artifacts

property input_parameters

property keys

property output_artifacts

property output_parameters

class dpgen2.flow.dpgen_loop.**MakeBlockId**(**args*, ***kwargs*)

Bases: OP

Attributes

key
workflow_name

Methods

execute(ip)	Run the OP
get_input_sign()	Get the signature of the inputs
get_output_sign()	Get the signature of the outputs

convert_to_graph
exec_sign_check
from_graph
function
get_info
get_input_artifact_link
get_input_artifact_storage_key
get_opio_info
get_output_artifact_link
get_output_artifact_storage_key
register_output_artifact
superfunction

execute(*ip: OPIO*) → OPIO

Run the OP

classmethod get_input_sign()

Get the signature of the inputs

classmethod get_output_sign()

Get the signature of the outputs

class dpgen2.flow.dpgen_loop.**SchedulerWrapper**(**args*, ***kwargs*)

Bases: OP

Attributes

key
workflow_name

Methods

execute(ip)	Run the OP
get_input_sign()	Get the signature of the inputs
get_output_sign()	Get the signature of the outputs

convert_to_graph
exec_sign_check
from_graph
function
get_info
get_input_artifact_link
get_input_artifact_storage_key
get_opio_info
get_output_artifact_link
get_output_artifact_storage_key
register_output_artifact
superfunction

execute(*ip: OPIO*) → OPIO

Run the OP

classmethod get_input_sign()

Get the signature of the inputs

classmethod get_output_sign()

Get the signature of the outputs

dpgen2.flow.dpgen_loop.**make_block_optional_parameter**(*cl_optional_parameter*)

dpgen2.fp package

Submodules

dpgen2.fp.abacus module

class dpgen2.fp.abacus.**FpOpAbacusInputs**(*input_file: str | Path*, *pp_files: Dict[str, str | Path]*, *element_mass: Dict[str, float] | None = None*, *kpt_file: str | Path | None = None*, *orb_files: Dict[str, str | Path] | None = None*, *deepks_descriptor: str | Path | None = None*, *deepks_model: str | Path | None = None*)

Bases: AbacusInputs

Methods

get_mass(element_list)	Get the mass of elements.
read_inputf(inputf)	Read INPUT and transfer to a dict.
write_deepks()	Check if INPUT is a deepks job, if yes, will return the deepks descriptor file name, else will return None.
write_pporb(element_list)	Based on element list, write the pp/orb files, and return a list of the filename.

args
get_deepks_descriptor
get_deepks_model
get_input
get_orb
get_pp
set_deepks_descriptor
set_deepks_model
set_input
set_mass
set_orb
set_pp
write_input
write_kpt

static **args**()

class dpgen2.fp.abacus.**PrepFpOpAbacus**(**args*, ***kwargs*)

Bases: OP

Attributes

key
workflow_name

Methods

execute(ip)	Run the OP
get_input_sign()	Get the signature of the inputs
get_output_sign()	Get the signature of the outputs

convert_to_graph
exec_sign_check
from_graph
function
get_info
get_input_artifact_link
get_input_artifact_storage_key
get_opio_info
get_output_artifact_link
get_output_artifact_storage_key
register_output_artifact
superfunction

execute(*ip: OPIO*) → OPIO

Run the OP

classmethod get_input_sign()

Get the signature of the inputs

classmethod get_output_sign()

Get the signature of the outputs

class dpgen2.fp.abacus.**RunFpOpAbacus**(**args*, ***kwargs*)

Bases: OP

Attributes

key
workflow_name

Methods

execute(ip)	Run the OP
get_input_sign()	Get the signature of the inputs
get_output_sign()	Get the signature of the outputs

args
convert_to_graph
exec_sign_check
from_graph
function
get_info
get_input_artifact_link
get_input_artifact_storage_key
get_opio_info
get_output_artifact_link
get_output_artifact_storage_key
register_output_artifact
superfunction

static args()

execute(*ip: OPIO*) → OPIO

Run the OP

classmethod get_input_sign()

Get the signature of the inputs

classmethod get_output_sign()

Get the signature of the outputs

dpgen2.fp.deepmd module

Prep and Run Gaussian tasks.

class dpgen2.fp.deepmd.**DeepmdInputs**(***kwargs: Any*)

Bases: object

Methods

args

static args() → List[Argument]

class dpgen2.fp.deepmd.**PrepDeepmd**(**args*, ***kwargs*)

Bases: *PrepFp*

Attributes

key
workflow_name

Methods

execute(ip)	Execute the OP.
get_input_sign()	Get the signature of the inputs
get_output_sign()	Get the signature of the outputs
prep_task(conf_frame, inputs)	Define how one Deepmd task is prepared.

convert_to_graph
exec_sign_check
from_graph
function
get_info
get_input_artifact_link
get_input_artifact_storage_key
get_opio_info
get_output_artifact_link
get_output_artifact_storage_key
register_output_artifact
superfunction

prep_task(*conf_frame: System*, *inputs*)

Define how one Deepmd task is prepared.

Parameters

conf_frame
[dpdata.System] One frame of configuration in the dpdata format.

inputs
[str or dict] This parameter is useless in deepmd.

class dpgen2.fp.deepmd.**RunDeepmd**(**args*, ***kwargs*)

Bases: *RunFp*

Attributes

key
workflow_name

Methods

args()	The argument definition of the *run_task* method.
execute(ip)	Execute the OP.
get_input_sign()	Get the signature of the inputs
get_output_sign()	Get the signature of the outputs
input_files()	The mandatory input files to run a Deepmd task.
normalize_config([data, strict])	Normalized the argument.
optional_input_files()	The optional input files to run a Deepmd task.
run_task(teacher_model_path, out, log)	Defines how one FP task runs

convert_to_graph
exec_sign_check
from_graph
function
get_info
get_input_artifact_link
get_input_artifact_storage_key
get_opio_info
get_output_artifact_link
get_output_artifact_storage_key
register_output_artifact
superfunction

`static args()` → List[Argument]

The argument definition of the *run_task* method.

Returns

arguments: List[dargs.Argument]
List of dargs.Argument defines the arguments of *run_task* method.

`input_files()` → List[str]

The mandatory input files to run a Deepmd task.

Returns

files: List[str]
A list of madatory input files names.

`optional_input_files()` → List[str]

The optional input files to run a Deepmd task.

Returns

files: List[str]
A list of optional input files names.

`run_task`(*teacher_model_path:* BinaryFileInput, *out: str*, *log: str*) → Tuple[str, str]

Defines how one FP task runs

Parameters

command
[str] The command of running Deepmd task

out
[str] The name of the output data file.

Returns

out_name: str
The file name of the output data in the dpdata.LabeledSystem format.

log_name: str
The file name of the log.

dpgen2.fp.gaussian module

Prep and Run Gaussian tasks.

class dpgen2.fp.gaussian.**GaussianInputs**(***kwargs: Any*)

Bases: object

Methods

args()	The arguments of the GaussianInputs class.

static args() → List[Argument]

The arguments of the GaussianInputs class.

class dpgen2.fp.gaussian.**PrepGaussian**(**args*, ***kwargs*)

Bases: *PrepFp*

Attributes

key
workflow_name

Methods

execute(ip)	Execute the OP.
get_input_sign()	Get the signature of the inputs
get_output_sign()	Get the signature of the outputs
prep_task(conf_frame, inputs)	Define how one Gaussian task is prepared.

convert_to_graph
exec_sign_check
from_graph
function
get_info
get_input_artifact_link
get_input_artifact_storage_key
get_opio_info
get_output_artifact_link
get_output_artifact_storage_key
register_output_artifact
superfunction

prep_task(*conf_frame: System*, *inputs:* GaussianInputs)

Define how one Gaussian task is prepared.

Parameters

conf_frame
[dpdata.System] One frame of configuration in the dpdata format.

inputs
[GaussianInputs] The GaussianInputs object handels all other input files of the task.

class dpgen2.fp.gaussian.**RunGaussian**(**args*, ***kwargs*)

Bases: *RunFp*

Attributes

key
workflow_name

Methods

args()	The argument definition of the *run_task* method.
execute(ip)	Execute the OP.
get_input_sign()	Get the signature of the inputs
get_output_sign()	Get the signature of the outputs
input_files()	The mandatory input files to run a Gaussian task.
normalize_config([data, strict])	Normalized the argument.
optional_input_files()	The optional input files to run a Gaussian task.
run_task(command, out)	Defines how one FP task runs

convert_to_graph
exec_sign_check
from_graph
function
get_info
get_input_artifact_link
get_input_artifact_storage_key
get_opio_info
get_output_artifact_link
get_output_artifact_storage_key
register_output_artifact
superfunction

static **args**() → List[Argument]

The argument definition of the *run_task* method.

Returns

arguments: List[dargs.Argument]
List of dargs.Argument defines the arguments of *run_task* method.

input_files() → List[str]

The mandatory input files to run a Gaussian task.

Returns

files: List[str]
A list of madatory input files names.

optional_input_files() → List[str]

The optional input files to run a Gaussian task.

Returns

files: List[str]
A list of optional input files names.

`run_task`(*command: str*, *out: str*) → Tuple[str, str]

Defines how one FP task runs

Parameters

command
[str] The command of running gaussian task

out
[str] The name of the output data file.

Returns

out_name: str
The file name of the output data in the dpdata.LabeledSystem format.

log_name: str
The file name of the log.

dpgen2.fp.prep_fp module

`class` dpgen2.fp.prep_fp.`PrepFp`(**args*, ***kwargs*)

Bases: OP, ABC

Prepares the working directories for first-principles (FP) tasks.

A list of (same length as ip["confs"]) working directories containing all files needed to start FP tasks will be created. The paths of the directories will be returned as *op["task_paths"]*. The identities of the tasks are returned as *op["task_names"]*.

Attributes

key
workflow_name

Methods

execute(ip)	Execute the OP.
get_input_sign()	Get the signature of the inputs
get_output_sign()	Get the signature of the outputs
prep_task(conf_frame, inputs)	Define how one FP task is prepared.

convert_to_graph
exec_sign_check
from_graph
function
get_info
get_input_artifact_link
get_input_artifact_storage_key
get_opio_info
get_output_artifact_link
get_output_artifact_storage_key
register_output_artifact
superfunction

execute(*ip: OPIO*) → OPIO

Execute the OP.

Parameters

ip

[dict] Input dict with components:

- *config* : (*dict*) Should have *config['inputs']*, which defines the input files of the FP task.
- *confs* : (*Artifact(List[Path])*) Configurations for the FP tasks. Stored in folders as deepmd/npy format. Can be parsed as dpdata.MultiSystems.

Returns

op

[dict] Output dict with components:

- *task_names*: (*List[str]*) The name of tasks. Will be used as the identities of the tasks. The names of different tasks are different.
- *task_paths*: (*Artifact(List[Path])*) The parepared working paths of the tasks. Contains all input files needed to start the FP. The order fo the Paths should be consistent with *op["task_names"]*

classmethod get_input_sign()

Get the signature of the inputs

classmethod get_output_sign()

Get the signature of the outputs

abstract prep_task(*conf_frame: System*, *inputs: Any*)

Define how one FP task is prepared.

Parameters

conf_frame

[dpdata.System] One frame of configuration in the dpdata format.

inputs

[Any] The class object handels all other input files of the task. For example, pseudopotential file, k-point file and so on.

dpgen2.fp.run_fp module

class dpgen2.fp.run_fp.**RunFp**(**args*, ***kwargs*)

Bases: OP, ABC

Execute a first-principles (FP) task.

A working directory named *task_name* is created. All input files are copied or symbol linked to directory *task_name*. The FP command is exectuted from directory *task_name*. The *op["labeled_data"]* in *"deepmd/npy"* format (HF5 in the future) provided by *dpdata* will be created.

Attributes

key
workflow_name

Methods

args()	The argument definition of the *run_task* method.
execute(ip)	Execute the OP.
get_input_sign()	Get the signature of the inputs
get_output_sign()	Get the signature of the outputs
input_files()	The mandatory input files to run a FP task.
normalize_config([data, strict])	Normalized the argument.
optional_input_files()	The optional input files to run a FP task.
run_task(**kwargs)	Defines how one FP task runs

convert_to_graph
exec_sign_check
from_graph
function
get_info
get_input_artifact_link
get_input_artifact_storage_key
get_opio_info
get_output_artifact_link
get_output_artifact_storage_key
register_output_artifact
superfunction

abstract static args() → List[Argument]

The argument definition of the *run_task* method.

Returns

arguments: List[dargs.Argument]
List of dargs.Argument defines the arguments of *run_task* method.

execute(*ip: OPIO*) → OPIO

Execute the OP.

Parameters

ip
[dict] Input dict with components:

- *config*: (*dict*) The config of FP task. Should have *config['run']*, which defines the runtime configuration of the FP task.
- *task_name*: (*str*) The name of task.
- *task_path*: (*Artifact(Path)*) The path that contains all input files prepareed by *PrepFp*.

Returns

Output dict with components:

- ***log*: (*Artifact(Path)*) The log file of FP.**
- ***labeled_data*: (*Artifact(Path)*) The path to the labeled data in *"deepmd/npy"* format provided by *dpdata*.**

Raises

TransientError
On the failure of FP execution.

FatalError
When mandatory files are not found.

`classmethod get_input_sign()`

Get the signature of the inputs

`classmethod get_output_sign()`

Get the signature of the outputs

`abstract input_files()` → List[str]

The mandatory input files to run a FP task.

Returns

files: List[str]
A list of madatory input files names.

`classmethod normalize_config`(*data: Dict = {}*, *strict: bool = True*) → Dict

Normalized the argument.

Parameters

data
[Dict] The input dict of arguments.

strict
[bool] Strictly check the arguments.

Returns

data: Dict
The normalized arguments.

`abstract optional_input_files()` → List[str]

The optional input files to run a FP task.

Returns

files: List[str]
A list of optional input files names.

abstract run_task(***kwargs*) → Tuple[str, str]

Defines how one FP task runs

Parameters

****kwargs**
Keyword args defined by the developer. The fp/run_config session of the input file will be passed to this function.

Returns

out_name: str
The file name of the output data. Should be in dpdata.LabeledSystem format.

log_name: str
The file name of the log.

dpgen2.fp.vasp module

class dpgen2.fp.vasp.**PrepVasp**(**args*, ***kwargs*)

Bases: *PrepFp*

Attributes

key
workflow_name

Methods

execute(ip)	Execute the OP.
get_input_sign()	Get the signature of the inputs
get_output_sign()	Get the signature of the outputs
prep_task(conf_frame, vasp_inputs)	Define how one Vasp task is prepared.

convert_to_graph
exec_sign_check
from_graph
function
get_info
get_input_artifact_link
get_input_artifact_storage_key
get_opio_info
get_output_artifact_link
get_output_artifact_storage_key
register_output_artifact
superfunction

prep_task(*conf_frame: System*, *vasp_inputs:* VaspInputs)

Define how one Vasp task is prepared.

Parameters

conf_frame
[dpdata.System] One frame of configuration in the dpdata format.

vasp_inputs
[VaspInputs] The VaspInputs object handels all other input files of the task.

class dpgen2.fp.vasp.**RunVasp**(**args*, ***kwargs*)

Bases: *RunFp*

Attributes

key
workflow_name

Methods

args()	The argument definition of the *run_task* method.
execute(ip)	Execute the OP.
get_input_sign()	Get the signature of the inputs
get_output_sign()	Get the signature of the outputs
input_files()	The mandatory input files to run a vasp task.
normalize_config([data, strict])	Normalized the argument.
optional_input_files()	The optional input files to run a vasp task.
run_task(command, out, log)	Defines how one FP task runs

convert_to_graph
exec_sign_check
from_graph
function
get_info
get_input_artifact_link
get_input_artifact_storage_key
get_opio_info
get_output_artifact_link
get_output_artifact_storage_key
register_output_artifact
superfunction

static args()

The argument definition of the *run_task* method.

Returns

arguments: List[dargs.Argument]
List of dargs.Argument defines the arguments of *run_task* method.

input_files() → List[str]

The mandatory input files to run a vasp task.

Returns

files: List[str]
A list of madatory input files names.

optional_input_files() → List[str]

The optional input files to run a vasp task.

Returns

files: List[str]
A list of optional input files names.

`run_task`(*command: str*, *out: str*, *log: str*) → Tuple[str, str]

Defines how one FP task runs

Parameters

command
[str] The command of running vasp task

out
[str] The name of the output data file.

log
[str] The name of the log file

Returns

out_name: str
The file name of the output data in the dpdata.LabeledSystem format.

log_name: str
The file name of the log.

dpgen2.fp.vasp_input module

`class` dpgen2.fp.vasp_input.`VaspInputs`(*kspacing: float | List[float]*, *incar: str*, *pp_files: Dict[str, str]*, *kgamma: bool = True*)

Bases: `object`

Attributes

incar_template
potcars

Methods

args
incar_from_file
make_kpoints
make_potcar
normalize_config
potcars_from_file

`static args`()

`incar_from_file`(*fname: str*)

`property incar_template`

`make_kpoints`(*box: ndarray*) → str

`make_potcar`(*atom_names*) → str

`static normalize_config`(*data={}*, *strict=True*)

property potcars

potcars_from_file(*dict_fnames: Dict[str, str]*)

dpgen2.fp.vasp_input.**make_kspacing_kpoints**(*box*, *kspacing*, *kgamma*)

dpgen2.op package

Submodules

dpgen2.op.collect_data module

class dpgen2.op.collect_data.**CollectData**(**args*, ***kwargs*)

Bases: OP

Collect labeled data and add to the iteration dataset.

After running FP tasks, the labeled data are scattered in task directories. This OP collect the labeled data in one data directory and add it to the iteration data. The data generated by this iteration will be place in *ip["name"]* subdirectory of the iteration data directory.

Attributes

key
workflow_name

Methods

execute(ip)	Execute the OP.
get_input_sign()	Get the signature of the inputs
get_output_sign()	Get the signature of the outputs

convert_to_graph
exec_sign_check
from_graph
function
get_info
get_input_artifact_link
get_input_artifact_storage_key
get_opio_info
get_output_artifact_link
get_output_artifact_storage_key
register_output_artifact
superfunction

default_optional_parameter = {'mixed_type': False}

execute(*ip: OPIO*) → OPIO

Execute the OP. This OP collect data scattered in directories given by *ip['labeled_data']* in to one *dpdata.Multisystems* and store it in a directory named *name*. This directory is appended to the list *iter_data*.

Parameters

ip
[dict] Input dict with components:

- *name*: (*str*) The name of this iteration. The data generated by this iteration will be place in a sub-directory of *name*.
- *labeled_data*: (*Artifact(List[Path])*) The paths of labeled data generated by FP tasks of the current iteration.
- *iter_data*: (*Artifact(List[Path])*) The data paths previous iterations.

Returns

Any
Output dict with components: - *iter_data*: (*Artifact(List[Path])*) The data paths of previous and the current iteration data.

classmethod get_input_sign()
Get the signature of the inputs

classmethod get_output_sign()
Get the signature of the outputs

dpgen2.op.collect_run_caly module

class dpgen2.op.collect_run_caly.**CollRunCaly**(**args*, ***kwargs*)

Bases: OP

Execute CALYPSO to generate structures in work_dir.

Changing the work directory into *task_name*. All input files have been copied or symbol linked to this directory *task_name* by *PrepCalyInput*. The CALYPSO command is exectuted from directory *task_name*. The *caly.log* and the *work_dir* will be stored in *op["log"]* and *op["work_dir"]*, respectively.

Attributes

key
workflow_name

Methods

execute(ip)	Execute the OP.
get_input_sign()	Get the signature of the inputs
get_output_sign()	Get the signature of the outputs

calypso_args
convert_to_graph
exec_sign_check
from_graph
function
get_info
get_input_artifact_link
get_input_artifact_storage_key
get_opio_info
get_output_artifact_link
get_output_artifact_storage_key
normalize_config
register_output_artifact
superfunction

`static calypso_args()`

`execute(`*ip: OPIO*`)` → OPIO

Execute the OP.

Parameters

ip

[dict] Input dict with components:

- *config*: (*dict*) The config of calypso task to obtain the command of calypso.
- *task_name*: (*str*) The name of the task (calypso_task.{idx}).
- *input_file*: (*Path*) The input file of the task (input.dat).
- *step*: (*Path*) The step file from last calypso run
- *results*: (*Path*) The results dir from last calypso run
- *opt_results_dir*: (*Path*) The results dir contains POSCAR* CONTCAR* OUTCAR* from last calypso run
- *qhull_input*: (*Path*) qhull input file *test_qconvex.in*

Returns

Any

Output dict with components: - *poscar_dir*: (*Path*) The dir contains POSCAR*.

- *task_name*: (*str*) The name of the task (calypso_task.{idx}).
- *input_file*: (*Path*) The input file of the task (input.dat).
- *step*: (*Path*) The step file.
- *results*: (*Path*) The results dir.
- *qhull_input*: (*Path*) qhull input file.

Raises

TransientError

On the failure of CALYPSO execution. Resubmit rule should be clear.

`classmethod get_input_sign()`

Get the signature of the inputs

classmethod get_output_sign()

Get the signature of the outputs

static normalize_config(*data={}*)

dpgen2.op.collect_run_caly.**config_args**()

dpgen2.op.collect_run_caly.**get_value_from_inputdat**(*filename*)

dpgen2.op.collect_run_caly.**prep_last_calypso_file**(*step*, *results*, *opt_results_dir*, *qhull_input*, *vsc*)

dpgen2.op.md_settings module

class dpgen2.op.md_settings.**MDSettings**(*ens: str*, *dt: float*, *nsteps: int*, *trj_freq: int*, *temps: List[float] | None = None*, *press: List[float] | None = None*, *tau_t: float = 0.1*, *tau_p: float = 0.5*, *pka_e: float | None = None*, *neidelay: int | None = None*, *no_pbc: bool = False*, *use_clusters: bool = False*, *relative_epsilon: float | None = None*, *relative_v_epsilon: float | None = None*, *ele_temp_f: float | None = None*, *ele_temp_a: float | None = None*)

Bases: object

Methods

to_str

to_str() → str

dpgen2.op.prep_caly_dp_optim module

class dpgen2.op.prep_caly_dp_optim.**PrepCalyDPOptim**(**args*, ***kwargs*)

Bases: OP

Prepare the working directories and input file according to slices information for structure optimization with DP.

*POSCAR_**, *frozen_model.pb* or *model.ckpt.pt*, *calypso_run_opt.py* and *calypso_check_opt.py* will be copied or symlink to each optimization directory from *ip["work_path"]*, according to the group size of ip["template_slice_config"]. The POSCAR_* will be splited into group_size parts and the name of each path will be returned in a *task_names* list and *task_dirs* list.

Attributes

key
workflow_name

Methods

execute(ip)	Execute the OP.
get_input_sign()	Get the signature of the inputs
get_output_sign()	Get the signature of the outputs

convert_to_graph
exec_sign_check
from_graph
function
get_info
get_input_artifact_link
get_input_artifact_storage_key
get_opio_info
get_output_artifact_link
get_output_artifact_storage_key
register_output_artifact
superfunction

execute(*ip: OPIO*) → OPIO

Execute the OP.

Parameters

ip

[dict] Input dict with components: - *task_name* : (*str*) - *finished* : (*str*) - *template_slice_config* : (*dict*) - *poscar_dir* : (*Path*) - *models_dir* : (*Path*) - *caly_run_opt_file* : (*Path*) - *caly_check_opt_file* : (*Path*)

Returns

op

[dict] Output dict with components:

- *task_names*: (*List[str]*)
- *task_dirs*: (*Artifact(List[Path])*)
- *caly_run_opt_file* : (*Path*)
- *caly_check_opt_file* : (*Path*)

classmethod get_input_sign()

Get the signature of the inputs

classmethod get_output_sign()

Get the signature of the outputs

dpgen2.op.prep_caly_input module

class dpgen2.op.prep_caly_input.**PrepCalyInput**(**args*, ***kwargs*)

Bases: OP

Prepare the working directories and input file for generating structures.

A calypso input file will be generated according to the given parameters (defined by *ip["caly_inputs"]*). The artifact will be return (ip[*input_files*]). The name of directory is *ip["task_names"]*.

Attributes

key
workflow_name

Methods

execute(ip)	Execute the OP.
get_input_sign()	Get the signature of the inputs
get_output_sign()	Get the signature of the outputs

convert_to_graph
exec_sign_check
from_graph
function
get_info
get_input_artifact_link
get_input_artifact_storage_key
get_opio_info
get_output_artifact_link
get_output_artifact_storage_key
register_output_artifact
superfunction

execute(*ip: OPIO*) → OPIO

Execute the OP.

Parameters

ip

[dict] Input dict with components: - *caly_task_grp* : (*BigParameter()*) Definitions for CALYPSO input file.

Returns

op

[dict] Output dict with components:

- *task_names*: (*List[str]*) The name of CALYPSO tasks. Will be used as the identities of the tasks. The names of different tasks are different.
- *input_dat_files*: (*Artifact(List[Path])*) The parepared working paths of the task containing input files (*input.dat* and *calypso_run_opt.py*) needed to generate structures by CALYPSO and make structure optimization with DP model.

- *caly_run_opt_files*: (*Artifact(List[Path])*)
- *caly_check_opt_files*: (*Artifact(List[Path])*)

classmethod get_input_sign()

Get the signature of the inputs

classmethod get_output_sign()

Get the signature of the outputs

dpgen2.op.prep_dp_train module

class dpgen2.op.prep_dp_train.**PrepDPTrain**(**args*, ***kwargs*)

Bases: OP

Prepares the working directories for DP training tasks.

A list of (*numb_models*) working directories containing all files needed to start training tasks will be created. The paths of the directories will be returned as *op["task_paths"]*. The identities of the tasks are returned as *op["task_names"]*.

Attributes

key
workflow_name

Methods

execute(ip)	Execute the OP.
get_input_sign()	Get the signature of the inputs
get_output_sign()	Get the signature of the outputs

convert_to_graph
exec_sign_check
from_graph
function
get_info
get_input_artifact_link
get_input_artifact_storage_key
get_opio_info
get_output_artifact_link
get_output_artifact_storage_key
register_output_artifact
superfunction

execute(*ip: OPIO*) → OPIO

Execute the OP.

Parameters

ip

[dict] Input dict with components:

- *template_script*: (*str* or *List[str]*) A template of the training script. Can be a *str* or *List[str]*. In the case of *str*, all training tasks share the same training input template, the only difference is the random number used to initialize the network parameters. In the case of *List[str]*, one training task uses one template from the list. The random numbers used to initialize the network parameters are differnt. The length of the list should be the same as *numb_models*.
- *numb_models*: (*int*) Number of DP models to train.

Returns

op

[dict] Output dict with components:

- *task_names*: (*List[str]*) The name of tasks. Will be used as the identities of the tasks. The names of different tasks are different.
- *task_paths*: (*Artifact(List[Path])*) The parepared working paths of the tasks. The order fo the Paths should be consistent with *op["task_names"]*

classmethod get_input_sign()

Get the signature of the inputs

classmethod get_output_sign()

Get the signature of the outputs

dpgen2.op.prep_lmp module

dpgen2.op.prep_lmp.**PrepExplorationTaskGroup**

alias of *PrepLmp*

class dpgen2.op.prep_lmp.**PrepLmp**(**args*, ***kwargs*)

Bases: OP

Prepare the working directories for LAMMPS tasks.

A list of working directories (defined by *ip["task"]*) containing all files needed to start LAMMPS tasks will be created. The paths of the directories will be returned as *op["task_paths"]*. The identities of the tasks are returned as *op["task_names"]*.

Attributes

key
workflow_name

Methods

execute(ip)	Execute the OP.
get_input_sign()	Get the signature of the inputs
get_output_sign()	Get the signature of the outputs

convert_to_graph
exec_sign_check
from_graph
function
get_info
get_input_artifact_link
get_input_artifact_storage_key
get_opio_info
get_output_artifact_link
get_output_artifact_storage_key
register_output_artifact
superfunction

execute(*ip: OPIO*) → OPIO

Execute the OP.

Parameters

ip

[dict] Input dict with components: - *lmp_task_grp* : (*BigParameter(Path)*) Can be pickle loaded as a ExplorationTaskGroup. Definitions for LAMMPS tasks

Returns

op

[dict] Output dict with components:

- *task_names*: (*List[str]*) The name of tasks. Will be used as the identities of the tasks. The names of different tasks are different.
- *task_paths*: (*Artifact(List[Path])*) The parepared working paths of the tasks. Contains all input files needed to start the LAMMPS simulation. The order fo the Paths should be consistent with *op["task_names"]*

classmethod get_input_sign()

Get the signature of the inputs

classmethod get_output_sign()

Get the signature of the outputs

dpgen2.op.run_caly_dp_optim module

class dpgen2.op.run_caly_dp_optim.**RunCalyDPOptim**(**args*, ***kwargs*)

Bases: OP

Perform structure optimization with DP in *ip["work_path"]*.

The *optim_results_dir* and *traj_results* will be returned as *op["optim_results_dir"]* and *op["traj_results"]*.

Attributes

key
workflow_name

Methods

execute(ip)	Execute the OP.
get_input_sign()	Get the signature of the inputs
get_output_sign()	Get the signature of the outputs

convert_to_graph
exec_sign_check
from_graph
function
get_info
get_input_artifact_link
get_input_artifact_storage_key
get_opio_info
get_output_artifact_link
get_output_artifact_storage_key
register_output_artifact
superfunction

execute(*ip: OPIO*) → OPIO

Execute the OP.

Parameters

ip

[dict] Input dict with components: - *config*: (*dict*) The config of calypso task to obtain the command of calypso. - *task_name* : (*str*) - *finished* : (*str*) - *cnt_num* : (*int*) - *task_dir* : (*Path*)

Returns

op

[dict] Output dict with components:

- *task_name*: (*str*)
- *optim_results_dir*: (*List[str]*)
- *traj_results*: (*Artifact(List[Path])*)

classmethod get_input_sign()

Get the signature of the inputs

classmethod get_output_sign()

Get the signature of the outputs

dpgen2.op.run_caly_model_devi module

class dpgen2.op.run_caly_model_devi.**RunCalyModelDevi**(**args*, ***kwargs*)

Bases: OP

calculate model deviaion of trajectories structures.

Structure optimization will be executed in *optim_path*. The trajectory will be stored in files *op["traj"]* and *op["model_devi"]*, respectively.

Attributes

key
workflow_name

Methods

execute(ip)	Execute the OP.
get_input_sign()	Get the signature of the inputs
get_output_sign()	Get the signature of the outputs

convert_to_graph
exec_sign_check
from_graph
function
get_info
get_input_artifact_link
get_input_artifact_storage_key
get_opio_info
get_output_artifact_link
get_output_artifact_storage_key
register_output_artifact
superfunction

execute(*ip: OPIO*) → OPIO

Execute the OP.

Parameters

ip

[dict] Input dict with components: - *type_map*: (*List[str]*) The type map of elements. - *task_name*: (*str*) The name of the task. - *traj_dirs*: (*Artifact(List[Path])*) The List of paths that contains trajectory files. - *models*: (*Artifact(List[Path])*) The frozen model to estimate the model deviation.

Returns

Any

Output dict with components: - *task_name*: (*str*) The name of task. - *traj*: (*Artifact(List[Path])*) The output trajectory. - *model_devi*: (*Artifact(List[Path])*) The model deviation. The order of recorded model deviations should be consistent with the order of frames in *traj*.

classmethod get_input_sign()

Get the signature of the inputs

classmethod get_output_sign()

Get the signature of the outputs

dpgen2.op.run_caly_model_devi.**atoms2lmpdump**(*atoms*, *struc_idx*, *type_map*, *ignore=False*)

down triangle cell can be obtained from cell params: a, b, c, alpha, beta, gamma. cell = cellpar_to_cell([a, b, c, alpha, beta, gamma]) lx, ly, lz = cell[0][0], cell[1][1], cell[2][2] xy, xz, yz = cell[1][0], cell[2][0], cell[2][1] (lx,ly,lz) = (xhi-xlo,yhi-ylo,zhi-zlo) xlo_bound = xlo + MIN(0.0,xy,xz,xy+xz) xhi_bound = xhi + MAX(0.0,xy,xz,xy+xz) ylo_bound = ylo + MIN(0.0,yz) yhi_bound = yhi + MAX(0.0,yz) zlo_bound = zlo zhi_bound = zhi

ref: https://docs.lammps.org/Howto_triclinic.html

dpgen2.op.run_caly_model_devi.**parse_traj**(*traj_file*)

dpgen2.op.run_caly_model_devi.**write_model_devi_out**(*devi: ndarray*, *fname: str | Path*, *header: str = ''*)

dpgen2.op.run_dp_train module

class dpgen2.op.run_dp_train.**RunDPTrain**(**args*, ***kwargs*)

Bases: OP

Execute a DP training task. Train and freeze a DP model.

A working directory named *task_name* is created. All input files are copied or symbol linked to directory *task_name*. The DeePMD-kit training and freezing commands are exectuted from directory *task_name*.

Attributes

key
workflow_name

Methods

execute(ip)	Execute the OP.
get_input_sign()	Get the signature of the inputs
get_output_sign()	Get the signature of the outputs

convert_to_graph
decide_init_model
exec_sign_check
from_graph
function
get_info
get_input_artifact_link
get_input_artifact_storage_key
get_opio_info
get_output_artifact_link
get_output_artifact_storage_key
normalize_config
register_output_artifact
skip_training
superfunction
training_args
write_data_to_input_script
write_other_to_input_script

static decide_init_model(*config*, *init_model*, *init_data*, *iter_data*, *mixed_type=False*)

default_optional_parameter = {'finetune_mode': 'no', 'mixed_type': False}

execute(*ip: OPIO*) → OPIO

Execute the OP.

Parameters

ip

[dict] Input dict with components:

- *config*: (*dict*) The config of training task. Check *RunDPTrain.training_args* for definitions.
- *task_name*: (*str*) The name of training task.
- *task_path*: (*Artifact(Path)*) The path that contains all input files prepareed by *PrepDPTrain*.
- *init_model*: (*Artifact(Path)*) A frozen model to initialize the training.
- *init_data*: (*Artifact(List[Path])*) Initial training data.
- *iter_data*: (*Artifact(List[Path])*) Training data generated in the DPGEN iterations.

Returns

Any

Output dict with components: - *script*: (*Artifact(Path)*) The training script. - *model*: (*Artifact(Path)*) The trained frozen model. - *lcurve*: (*Artifact(Path)*) The learning curve file. - *log*: (*Artifact(Path)*) The log file of training.

Raises

FatalError

On the failure of training or freezing. Human intervention needed.

classmethod get_input_sign()

Get the signature of the inputs

classmethod get_output_sign()

Get the signature of the outputs

static normalize_config(*data={}*)

static skip_training(*work_dir*, *train_dict*, *init_model*, *iter_data*, *finetune_mode*)

static training_args()

static write_data_to_input_script(*idict: dict*, *config*, *init_data: List[Path]*, *iter_data: List[Path]*, *auto_prob_str: str = 'prob_sys_size'*, *major_version: str = '1'*, *valid_data: List[Path] | None = None*)

static write_other_to_input_script(*idict*, *config*, *do_init_model*, *major_version: str = '1'*)

dpgen2.op.run_dp_train.**config_args**()

dpgen2.op.run_lmp module

class dpgen2.op.run_lmp.**RunLmp**(**args*, ***kwargs*)

Bases: OP

Execute a LAMMPS task.

A working directory named *task_name* is created. All input files are copied or symbol linked to directory *task_name*. The LAMMPS command is exectuted from directory *task_name*. The trajectory and the model deviation will be stored in files *op["traj"]* and *op["model_devi"]*, respectively.

Attributes

key
workflow_name

Methods

execute(ip)	Execute the OP.
get_input_sign()	Get the signature of the inputs
get_output_sign()	Get the signature of the outputs

convert_to_graph
exec_sign_check
from_graph
function
get_info
get_input_artifact_link
get_input_artifact_storage_key
get_opio_info
get_output_artifact_link
get_output_artifact_storage_key
lmp_args
normalize_config
register_output_artifact
superfunction

`execute`(*ip: OPIO*) → OPIO

Execute the OP.

Parameters

ip

[dict] Input dict with components:

- *config*: (*dict*) The config of lmp task. Check *RunLmp.lmp_args* for definitions.
- *task_name*: (*str*) The name of the task.
- *task_path*: (*Artifact(Path)*) The path that contains all input files prepareed by *PrepLmp*.
- *models*: (*Artifact(List[Path])*) The frozen model to estimate the model deviation. The first model with be used to drive molecular dynamics simulation.

Returns

Any

Output dict with components: - *log*: (*Artifact(Path)*) The log file of LAMMPS. - *traj*: (*Artifact(Path)*) The output trajectory. - *model_devi*: (*Artifact(Path)*) The model deviation. The order of recorded model deviations should be consistent with the order of frames in *traj*.

Raises

TransientError

On the failure of LAMMPS execution. Handle different failure cases? e.g. loss atoms.

`classmethod get_input_sign`()

Get the signature of the inputs

`classmethod get_output_sign`()

Get the signature of the outputs

`static lmp_args`()

`static normalize_config`(*data={}*)

dpgen2.op.run_lmp.**config_args**()

dpgen2.op.run_lmp.**find_only_one_key**(*lmp_lines*, *key*, *raise_not_found=True*)

dpgen2.op.run_lmp.**set_models**(*lmp_input_name: str*, *model_names: List[str]*)

dpgen2.op.select_confs module

class dpgen2.op.select_confs.**SelectConfs**(**args*, ***kwargs*)

Bases: OP

Select configurations from exploration trajectories for labeling.

Attributes

key
workflow_name

Methods

execute(ip)	Execute the OP.
get_input_sign()	Get the signature of the inputs
get_output_sign()	Get the signature of the outputs

convert_to_graph
exec_sign_check
from_graph
function
get_info
get_input_artifact_link
get_input_artifact_storage_key
get_opio_info
get_output_artifact_link
get_output_artifact_storage_key
register_output_artifact
superfunction
validate_trajs

execute(*ip: OPIO*) → OPIO

Execute the OP.

Parameters

ip

[dict] Input dict with components:

- *conf_selector*: (*ConfSelector*) Configuration selector.
- *type_map*: (*List[str]*) The type map.
- *trajs*: (*Artifact(List[Path])*) The trajectories generated in the exploration.
- *model_devis*: (*Artifact(List[Path])*) The file storing the model deviation of the trajectory. The order of model deviation storage is consistent with that of

the trajectories. The order of frames of one model deviation storage is also consistent with tat of the corresponding trajectory.

Returns

Any

Output dict with components: - *report*: (*ExplorationReport*) The report on the exploration. - *conf*: (*Artifact(List[Path])*) The selected configurations.

`classmethod get_input_sign()`

Get the signature of the inputs

`classmethod get_output_sign()`

Get the signature of the outputs

`static validate_trajs(trajs, model_devis)`

dpgen2.superop package

Submodules

dpgen2.superop.block module

`class dpgen2.superop.block.ConcurrentLearningBlock(name: str, prep_run_dp_train_op: PrepRunDPTrain, prep_run_explore_op: PrepRunLmp | PrepRunCaly, select_confs_op: Type[OP], prep_run_fp_op: PrepRunFp, collect_data_op: Type[OP], select_confs_config: dict = {'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'executor': None, 'parallelism': None, 'template_config': {'envs': None, 'image': 'dptechnology/dpgen2:latest', 'retry_on_transient_error': None, 'timeout': None, 'timeout_as_transient_error': False}}, collect_data_config: dict = {'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'executor': None, 'parallelism': None, 'template_config': {'envs': None, 'image': 'dptechnology/dpgen2:latest', 'retry_on_transient_error': None, 'timeout': None, 'timeout_as_transient_error': False}}, upload_python_packages: List[PathLike] | None = None)`

Bases: `Steps`

Attributes

input_artifacts
input_parameters
keys
output_artifacts
output_parameters

Methods

add(step)	Add a step or a list of parallel steps to the steps

add_slices
convert_to_argo
convert_to_graph
copy
deepcopy
from_dict
from_graph
handle_key
run

property input_artifacts

property input_parameters

property keys

property output_artifacts

property output_parameters

dpgen2.superop.block.**make_collect_data_optional_parameter**(*block_optional_parameter*)

dpgen2.superop.block.**make_run_dp_train_optional_parameter**(*block_optional_parameter*)

dpgen2.superop.caly_evo_step module

class dpgen2.superop.caly_evo_step.**CalyEvoStep**(*name: str*, *collect_run_caly: Type[OP]*, *prep_dp_optim: Type[OP]*, *run_dp_optim: Type[OP]*, *prep_config: dict = {'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'executor': None, 'parallelism': None, 'template_config': {'envs': None, 'image': 'dptechnology/dpgen2:latest', 'retry_on_transient_error': None, 'timeout': None, 'timeout_as_transient_error': False}}*, *run_config: dict = {'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'executor': None, 'parallelism': None, 'template_config': {'envs': None, 'image': 'dptechnology/dpgen2:latest', 'retry_on_transient_error': None, 'timeout': None, 'timeout_as_transient_error': False}}*, *upload_python_packages: List[PathLike] | None = None*)

Bases: Steps

Attributes

input_artifacts
input_parameters
keys
output_artifacts
output_parameters

Methods

add(step)	Add a step or a list of parallel steps to the steps

add_slices
convert_to_argo
convert_to_graph
copy
deepcopy
from_dict
from_graph
handle_key
run

property input_artifacts

property input_parameters

property keys

property output_artifacts

property output_parameters

dpgen2.superop.prep_run_calypso module

class dpgen2.superop.prep_run_calypso.**PrepRunCaly**(*name: str*, *prep_caly_input_op: Type[OP]*, *caly_evo_step_op: OPTemplate*, *run_caly_model_devi_op: Type[OP]*, *prep_config: dict = {'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'executor': None, 'parallelism': None, 'template_config': {'envs': None, 'image': 'dptechnology/dpgen2:latest', 'retry_on_transient_error': None, 'timeout': None, 'timeout_as_transient_error': False}}*, *run_config: dict = {'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'executor': None, 'parallelism': None, 'template_config': {'envs': None, 'image': 'dptechnology/dpgen2:latest', 'retry_on_transient_error': None, 'timeout': None, 'timeout_as_transient_error': False}}*, *upload_python_packages: List[PathLike] | None = None*)

Bases: Steps

Attributes

input_artifacts
input_parameters
keys
output_artifacts
output_parameters

Methods

add(step)	Add a step or a list of parallel steps to the steps

add_slices
convert_to_argo
convert_to_graph
copy
deepcopy
from_dict
from_graph
handle_key
run

property input_artifacts

property input_parameters

property keys

property output_artifacts

property output_parameters

dpgen2.superop.prep_run_dp_train module

class dpgen2.superop.prep_run_dp_train.**ModifyTrainScript**(**args*, ***kwargs*)

Bases: OP

Modify the training scripts to prepare them for training tasks in dpgen step.

Read the training scripts modified by finetune, and replace the original template scripts to be compatible with pre-trained models. New templates are returned as *op["template_script"]*.

Attributes

key
workflow_name

Methods

execute(ip)	Execute the OP.
get_input_sign()	Get the signature of the inputs
get_output_sign()	Get the signature of the outputs

convert_to_graph
exec_sign_check
from_graph
function
get_info
get_input_artifact_link
get_input_artifact_storage_key
get_opio_info
get_output_artifact_link
get_output_artifact_storage_key
register_output_artifact
superfunction

execute(*ip: OPIO*) → OPIO

Execute the OP.

Parameters

ip

[dict] Input dict with components:

- *scripts*: (*Artifact(Path)*) Training scripts from finetune.
- *numb_models*: (*int*) Number of DP models to train.

Returns

op
[dict] Output dict with components:

- *template_script*: (*List[dict]*) One template from one finetuning task. The length of the list should be the same as *numb_models*.

classmethod get_input_sign()
Get the signature of the inputs

classmethod get_output_sign()
Get the signature of the outputs

class dpgen2.superop.prep_run_dp_train.**PrepRunDPTrain**(*name: str, prep_train_op: ~typing.Type[~dflow.python.op.OP], run_train_op: ~typing.Type[~dpgen2.op.run_dp_train.RunDPTrain], modify_train_script_op: ~typing.Type[~dpgen2.superop.prep_run_dp_train.ModifyTrainScrip = <class 'dpgen2.superop.prep_run_dp_train.ModifyTrainScript'>, prep_config: dict = {'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'executor': None, 'parallelism': None, 'template_config': {'envs': None, 'image': 'dptechnology/dpgen2:latest', 'retry_on_transient_error': None, 'timeout': None, 'timeout_as_transient_error': False}}, run_config: dict = {'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'executor': None, 'parallelism': None, 'template_config': {'envs': None, 'image': 'dptechnology/dpgen2:latest', 'retry_on_transient_error': None, 'timeout': None, 'timeout_as_transient_error': False}}, upload_python_packages: ~typing.List[~os.PathLike] | None = None, finetune: bool = False, valid_data: ~dflow.common.S3Artifact | None = None*)

Bases: Steps

Attributes

input_artifacts
input_parameters
keys
output_artifacts
output_parameters

Methods

add(step)	Add a step or a list of parallel steps to the steps

add_slices
convert_to_argo
convert_to_graph
copy
deepcopy
from_dict
from_graph
handle_key
run

property input_artifacts

property input_parameters

property keys

property output_artifacts

property output_parameters

dpgen2.superop.prep_run_fp module

class dpgen2.superop.prep_run_fp.**PrepRunFp**(*name: str*, *prep_op: Type[OP]*, *run_op: Type[OP]*, *prep_config: dict = {'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'executor': None, 'parallelism': None, 'template_config': {'envs': None, 'image': 'dptechnology/dpgen2:latest', 'retry_on_transient_error': None, 'timeout': None, 'timeout_as_transient_error': False}}*, *run_config: dict = {'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'executor': None, 'parallelism': None, 'template_config': {'envs': None, 'image': 'dptechnology/dpgen2:latest', 'retry_on_transient_error': None, 'timeout': None, 'timeout_as_transient_error': False}}*, *upload_python_packages: List[PathLike] | None = None*)

Bases: Steps

Attributes

input_artifacts
input_parameters
keys
output_artifacts
output_parameters

Methods

add(step)	Add a step or a list of parallel steps to the steps

add_slices
convert_to_argo
convert_to_graph
copy
deepcopy
from_dict
from_graph
handle_key
run

property input_artifacts

property input_parameters

property keys

property output_artifacts

property output_parameters

dpgen2.superop.prep_run_lmp module

class dpgen2.superop.prep_run_lmp.**PrepRunLmp**(*name: str*, *prep_op: Type[OP]*, *run_op: Type[OP]*, *prep_config: dict = {'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'executor': None, 'parallelism': None, 'template_config': {'envs': None, 'image': 'dptechnology/dpgen2:latest', 'retry_on_transient_error': None, 'timeout': None, 'timeout_as_transient_error': False}}*, *run_config: dict = {'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'executor': None, 'parallelism': None, 'template_config': {'envs': None, 'image': 'dptechnology/dpgen2:latest', 'retry_on_transient_error': None, 'timeout': None, 'timeout_as_transient_error': False}}*, *upload_python_packages: List[PathLike] | None = None*)

Bases: Steps

Attributes

input_artifacts
input_parameters
keys
output_artifacts
output_parameters

Methods

add(step)	Add a step or a list of parallel steps to the steps

add_slices
convert_to_argo
convert_to_graph
copy
deepcopy
from_dict
from_graph
handle_key
run

property input_artifacts

property input_parameters

property keys

property output_artifacts

property output_parameters

dpgen2.utils package

Submodules

dpgen2.utils.binary_file_input module

Binary file inputs

class dpgen2.utils.binary_file_input.**BinaryFileInput**(*path: str | Path*, *ext: str | None = None*)

Bases: object

Methods

save_as_file

save_as_file(*path: str | Path*) → None

dpgen2.utils.bohrium_config module

dpgen2.utils.bohrium_config.**bohrium_config_from_dict**(*bohrium_config*)

dpgen2.utils.chdir module

dpgen2.utils.chdir.**chdir**(*path_key: str*)

Returns a decorator that can change the current working path.

Parameters

path_key
[str] key to OPIO

Examples

```
>>> class SomeOP(OP):
...     @chdir("path")
...     def execute(self, ip: OPIO):
...         do_something()
```

dpgen2.utils.chdir.**set_directory**(*path: Path*)

Sets the current working path within the context.

Parameters

path
[Path] The path to the cwd

Yields

None

Examples

```
>>> with set_directory("some_path"):
...     do_something()
```

dpgen2.utils.dflow_config module

dpgen2.utils.dflow_config.**dflow_config**(*config_data*)

set the dflow config by *config_data*

the keys starting with "s3_" will be treated as s3_config keys, other keys are treated as config keys.

dpgen2.utils.dflow_config.**dflow_config_lower**(*dflow_config*)

dpgen2.utils.dflow_config.**dflow_s3_config**(*config_data*)

set the s3 config by *config_data*

dpgen2.utils.dflow_config.**dflow_s3_config_lower**(*dflow_s3_config_data*)

dpgen2.utils.dflow_config.**workflow_config_from_dict**(*wf_config*)

dpgen2.utils.dflow_query module

dpgen2.utils.dflow_query.**find_slice_ranges**(*keys: List[str]*, *sliced_subkey: str*)

find range of sliced OPs that matches the pattern 'iter-[0-9]*–{sliced_subkey}-[0-9]*'

dpgen2.utils.dflow_query.**get_all_schedulers**(*wf: Any*, *keys: List[str]*)

get the output Scheduler of the all the iterations

dpgen2.utils.dflow_query.**get_iteration**(*key: str*)

dpgen2.utils.dflow_query.**get_last_iteration**(*keys: List[str]*)

get the index of the last iteraction from a list of step keys.

dpgen2.utils.dflow_query.**get_last_scheduler**(*wf: Any*, *keys: List[str]*)

get the output Scheduler of the last successful iteration

dpgen2.utils.dflow_query.**get_subkey**(*key: str*, *idx: int = -1*)

dpgen2.utils.dflow_query.**matched_step_key**(*all_keys: List[str]*, *step_keys: List[str] | None = None*)

returns the keys in *all_keys* that matches any of the *step_keys*

dpgen2.utils.dflow_query.**print_keys_in_nice_format**(*keys: List[str]*, *sliced_subkey: List[str]*, *idx_fmt_len: int = 8*)

dpgen2.utils.dflow_query.**sort_slice_ops**(*keys: List[str]*, *sliced_subkey: List[str]*)

sort the keys of the sliced ops. the keys of the sliced ops contains sliced_subkey

dpgen2.utils.download_dpgen2_artifacts module

class dpgen2.utils.download_dpgen2_artifacts.**DownloadDefinition**

Bases: `object`

Methods

add_def
add_input
add_output

add_def(*tdict*, *key*, *suffix=None*)

add_input(*input_key*, *suffix=None*)

add_output(*output_key*, *suffix=None*)

dpgen2.utils.download_dpgen2_artifacts.**download_dpgen2_artifacts**(*wf: Workflow*, *key: str*, *prefix: str | None = None*, *chk_pnt: bool = False*)

download the artifacts of a step. the key should be of format 'iter-xxxxxx–subkey-of-step-xxxxxx' the input and output artifacts will be downloaded to prefix/iter-xxxxxx/key-of-step/inputs/ and prefix/iter-xxxxxx/key-of-step/outputs/

the downloaded input and output artifacts of steps are defined by *op_download_setting*

dpgen2.utils.download_dpgen2_artifacts.**download_dpgen2_artifacts_by_def**(*wf: Workflow*, *iterations: List[int] | None = None*, *step_defs: List[str] | None = None*, *prefix: str | None = None*, *chk_pnt: bool = False*)

dpgen2.utils.download_dpgen2_artifacts.**print_op_download_setting**(*op_download_setting={'collect-data': <dp-gen2.utils.download_dpgen2_artifacts.DownloadI object>, 'prep-run-explore': <dp-gen2.utils.download_dpgen2_artifacts.DownloadI object>, 'prep-run-fp': <dp-gen2.utils.download_dpgen2_artifacts.DownloadI object>, 'prep-run-train': <dp-gen2.utils.download_dpgen2_artifacts.DownloadI object>}*)

dpgen2.utils.obj_artifact module

dpgen2.utils.obj_artifact.**dump_object_to_file**(*obj*, *fname*)

pickle dump object to a file

dpgen2.utils.obj_artifact.**load_object_from_file**(*fname*)

pickle load object from a file

dpgen2.utils.run_command module

dpgen2.utils.run_command.**run_command**(*cmd: str | List[str]*, *shell: bool = False*) → Tuple[int, str, str]

dpgen2.utils.step_config module

dpgen2.utils.step_config.**dispatcher_args**()

free style dispatcher args

dpgen2.utils.step_config.**gen_doc**(***, *make_anchor=True*, *make_link=True*, ***kwargs*)

dpgen2.utils.step_config.**init_executor**(*executor_dict*)

dpgen2.utils.step_config.**normalize**(*data*)

dpgen2.utils.step_config.**step_conf_args**()

dpgen2.utils.step_config.**template_conf_args**()

dpgen2.utils.step_config.**template_slice_conf_args**()

dpgen2.utils.step_config.**variant_executor**()

8.1.2 Submodules

8.1.3 dpgen2.constants module

- genindex
- modindex
- search

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