
DPGEN2

DeepModeling

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USER GUIDE

1	Guide on dpngen2 commands	3
1.1	Submit a workflow	3
1.2	Check the convergence of a workflow	3
1.3	Watch the progress of a workflow	3
1.4	Show the keys of steps	4
1.5	Resubmit a workflow	4
2	Command line interface	5
2.1	Named Arguments	5
2.2	Valid subcommands	5
2.3	Sub-commands	5
2.3.1	submit	5
2.3.2	resubmit	6
2.3.3	showkey	6
2.3.4	status	6
2.3.5	download	7
2.3.6	watch	7
3	Guide on writing input scripts for dpngen2 commands	9
3.1	Preliminaries	9
3.2	The input script for all dpngen2 commands	9
3.3	The input script for submit and resubmit	9
3.3.1	Inputs	10
3.3.2	Training	10
3.3.3	Exploration	10
3.3.4	FP	12
3.3.5	Configuration of dflow step	12
4	Arguments of the submit script	15
5	DPGEN2 configurations	51
5.1	Op configs	51
5.1.1	RunDPTrain	51
5.1.2	RunLmp	52
5.1.3	RunVasp	52
5.2	Alloy configs	52
5.3	Task group configs	53
5.4	Step configs	56
6	Developers' guide	59
6.1	The concurrent learning algorithm	59

6.2	Overview of the DPGEN2 Implementation	60
6.3	The DPGEN2 workflow	60
6.3.1	Inside the block operator	61
6.3.2	The exploration strategy	61
6.4	How to contribute	62
7	Operators	63
7.1	The super-OP PrepRunDPTrain	63
7.2	The OP RunDPTrain	66
8	Exploration	69
8.1	Stage scheduler	69
8.2	Exploration task groups	70
8.3	Configuration selector	71
9	DPGEN2 API	73
9.1	dpgen2 package	73
9.1.1	Subpackages	73
9.1.2	Submodules	114
9.1.3	dpgen2.constants module	114
	Python Module Index	115
	Index	117

DPGEN2 is the 2nd generation of the Deep Potential GENERator.

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GUIDE ON DPGEN2 COMMANDS

One may use `dpgen2` through command line interface. A full documentation of the cli is found [here](#)

1.1 Submit a workflow

The `dpgen2` workflow can be submitted via the `submit` command

```
dpgen2 submit input.json
```

where `input.json` is the input script. A guide of writing the script is found [here](#). When a workflow is submitted, a ID (WFID) of the workflow will be printed for later reference.

1.2 Check the convergence of a workflow

The convergence of stages of the workflow can be checked by the `status` command. It prints the indexes of the finished stages, iterations, and the accurate, candidate and failed ratio of explored configurations of each iteration.

```
$ dpgen2 status input.json WFID
# stage id_stg. iter.   accu.   cand.   fail.
# Stage  0  -----
#         0      0      0      0.8333  0.1667  0.0000
#         0      1      1      0.7593  0.2407  0.0000
#         0      2      2      0.7778  0.2222  0.0000
#         0      3      3      1.0000  0.0000  0.0000
# Stage  0 converged YES reached max numb iterations NO
# All stages converged
```

1.3 Watch the progress of a workflow

The progress of a workflow can be watched on-the-fly

```
$ dpgen2 watch input.json WFID
INFO:root:steps iter-000000--prep-run-train----- finished
INFO:root:steps iter-000000--prep-run-lmp----- finished
INFO:root:steps iter-000000--prep-run-fp----- finished
INFO:root:steps iter-000000--collect-data----- finished
```

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```
INFO:root:steps iter-000001--prep-run-train----- finished
INFO:root:steps iter-000001--prep-run-lmp----- finished
...
```

The artifacts can be downloaded on-the-fly with `-d` flag. Note that the existing files are automatically skipped if one sets `dflow_config["archive_mode"] = None`.

1.4 Show the keys of steps

Each `dpgen2` step is assigned a unique key. The keys of the finished steps can be checked with `showkey` command

```

  0 : iter-000000--prep-train
  1 -> 4 : iter-000000--run-train-0000 -> iter-000000--run-train-0003
  5 : iter-000000--prep-lmp
  6 -> 14 : iter-000000--run-lmp-000000 -> iter-000000--run-lmp-000008
 15 : iter-000000--select-confs
 16 : iter-000000--prep-fp
 17 -> 20 : iter-000000--run-fp-000000 -> iter-000000--run-fp-000003
 21 : iter-000000--collect-data
 22 : iter-000000--scheduler
 23 : iter-000000--id
 24 : iter-000001--prep-train
 25 -> 28 : iter-000001--run-train-0000 -> iter-000001--run-train-0003
 29 : iter-000001--prep-lmp
 30 -> 38 : iter-000001--run-lmp-000000 -> iter-000001--run-lmp-000008
 39 : iter-000001--select-confs
 40 : iter-000001--prep-fp
 41 -> 44 : iter-000001--run-fp-000000 -> iter-000001--run-fp-000003
 45 : iter-000001--collect-data
 46 : iter-000001--scheduler
 47 : iter-000001--id
```

1.5 Resubmit a workflow

If a workflow stopped abnormally, one may submit a new workflow with some steps of the old workflow reused.

```
dpgen2 resubmit input.json WFID --reuse 0-41
```

The steps of workflow `WDID 0-41` ($0 \leq \text{id} < 41$, note that 41 is not included) will be reused in the new workflow. The indexes of the steps are printed by `dpgen2 showkey`. In the example, all the steps before the `iter-000001--run-fp-000000` will be used in the new workflow.

COMMAND LINE INTERFACE

DPGEN2: concurrent learning workflow generating the machine learning potential energy models.

```
usage: dpgen2 [-h] [--version]
             {submit,resubmit,showkey,status,download,watch} ...
```

2.1 Named Arguments

--version show program's version number and exit

2.2 Valid subcommands

command Possible choices: submit, resubmit, showkey, status, download, watch

2.3 Sub-commands

2.3.1 submit

Submit DPGEN2 workflow

```
dpgen2 submit [-h] [-o] CONFIG
```

Positional Arguments

CONFIG the config file in json format defining the workflow.

Named Arguments

-o, --old-compatible compatible with old-style input script used in dpgen2 < 0.0.6.
Default: False

2.3.2 resubmit

Submit DPGEN2 workflow resuing steps from an existing workflow

```
dpgen2 resubmit [-h] [-l] [--reuse REUSE [REUSE ...]] [-o] CONFIG ID
```

Positional Arguments

CONFIG the config file in json format defining the workflow.
ID the ID of the existing workflow.

Named Arguments

-l, --list list the Steps of the existing workflow.
Default: False

--reuse specify which Steps to reuse.

-o, --old-compatible compatible with old-style input script used in dpgen2 < 0.0.6.
Default: False

2.3.3 showkey

Print the keys of the successful DPGEN2 steps

```
dpgen2 showkey [-h] CONFIG ID
```

Positional Arguments

CONFIG the config file in json format.
ID the ID of the existing workflow.

2.3.4 status

Print the status (stage, iteration, convergence) of the DPGEN2 workflow

```
dpgen2 status [-h] CONFIG ID
```

Positional Arguments

CONFIG	the config file in json format.
ID	the ID of the existing workflow.

2.3.5 download

Download the artifacts of DPGEN2 steps

```
dpngen2 download [-h] [-k KEYS [KEYS ...]] [-p PREFIX] CONFIG ID
```

Positional Arguments

CONFIG	the config file in json format.
ID	the ID of the existing workflow.

Named Arguments

-k, --keys	the keys of the downloaded steps. If not provided download all artifacts
-p, --prefix	the prefix of the path storing the download artifacts

2.3.6 watch

Watch a DPGEN2 workflow

```
dpngen2 watch [-h] [-k KEYS [KEYS ...]] [-f FREQUENCY] [-d] [-p PREFIX]
             CONFIG ID
```

Positional Arguments

CONFIG	the config file in json format.
ID	the ID of the existing workflow.

Named Arguments

-k, --keys	the subkey to watch. For example, 'prep-run-train' 'prep-run-lmp' Default: ['prep-run-train', 'prep-run-lmp', 'prep-run-fp', 'collect-data']
-f, --frequency	the frequency of workflow status query. In unit of second Default: 600.0
-d, --download	whether to download artifacts of a step when it finishes Default: False
-p, --prefix	the prefix of the path storing the download artifacts

GUIDE ON WRITING INPUT SCRIPTS FOR DPGEN2 COMMANDS

3.1 Preliminaries

The reader of this doc is assumed to be familiar with the concurrent learning algorithm that the `dpgen2` implements. If not, one may check [this paper](#).

3.2 The input script for all `dpgen2` commands

For all the `dpgen2` commands, one need to provide `dflow2` global configurations. For example,

```
"dflow_config" : {  
  "host" : "http://address.of.the.host:port"  
},  
"dflow_s3_config" : {  
  "endpoint" : "address.of.the.s3.sever:port"  
},
```

The `dpgen` simply pass all keys of `"dflow_config"` to `dflow.config` and all keys of `"dflow_s3_config"` to `dflow.s3_config`.

3.3 The input script for `submit` and `resubmit`

The full documentation of the `submit` and `resubmit` script can be [found here](#). This documentation provides a fast guide on how to write the input script.

In the input script of `dpgen2 submit` and `dpgen2 resubmit`, one needs to provide the definition of the workflow and how they are executed in the input script. One may find an example input script in the `dpgen2 Al-Mg alloy` example.

The definition of the workflow can be provided by the following sections:

3.3.1 Inputs

This section provides the inputs to start a dpgen2 workflow. An example for the Al-Mg alloy

```
"inputs": {
  "type_map":          ["Al", "Mg"],
  "mass_map":         [27, 24],
  "init_data_sys":   [
    "path/to/init/data/system/0",
    "path/to/init/data/system/1"
  ],
}
```

The key "init_data_sys" provides the initial training data to kick-off the training of deep potential (DP) models.

3.3.2 Training

This section defines how a model is trained.

```
"train" : {
  "type" : "dp",
  "numb_models" : 4,
  "config" : {},
  "template_script" : {
    "_comment" : "omitted content of template script"
  },
  "_comment" : "all"
}
```

The "type" : "dp" tell the training method is "dp", i.e. calling [DeePMD-kit](#) to train DP models. The "config" key defines the training configs, see [the full documentation](#). The "template_script" provides the template training script in json format.

3.3.3 Exploration

This section defines how the configuration space is explored.

```
"explore" : {
  "type" : "lmp",
  "config" : {
    "command": "lmp -var restart 0"
  },
  "max_numb_iter" : 5,
  "conv_accuracy" : 0.9,
  "fatal_at_max" : false,
  "f_trust_lo": 0.05,
  "f_trust_hi": 0.50,
  "configurations": [
    {
      "lattice" : ["fcc", 4.57],
      "replicate" : [2, 2, 2],
      "numb_confs" : 30,
    }
  ]
}
```

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```

        "concentration" : [[1.0, 0.0], [0.5, 0.5], [0.0, 1.0]]
    }
    {
        "lattice" : ["fcc", 4.57],
        "replicate" : [3, 3, 3],
        "numb_confs" : 30,
        "concentration" : [[1.0, 0.0], [0.5, 0.5], [0.0, 1.0]]
    }
],
"stages": [
    [
        {
            "_comment" : "stage 0, task group 0",
            "type" : "lmp-md",
            "ensemble": "nvt", "nsteps": 50, "temps": [50, 100], "trj_freq": 10,
            "conf_idx": [0], "n_sample" : 3
        },
        {
            "_comment" : "stage 1, task group 0",
            "type" : "lmp-template",
            "lmp" : "template.lammps", "plm" : "template.plumed",
            "trj_freq" : 10, "revisions" : {"V_NSTEPS" : [40], "V_TEMP" : [150, ↵
↵200]},
            "conf_idx": [0], "n_sample" : 3
        }
    ],
    [
        {
            "_comment" : "stage 1, task group 0",
            "type" : "lmp-md",
            "ensemble": "npt", "nsteps": 50, "press": [1e0], "temps": [50, 100, ↵
↵200], "trj_freq": 10,
            "conf_idx": [1], "n_sample" : 3
        }
    ],
],
}

```

The "type" : "lmp" means that configurations are explored by LAMMPS DPMD runs. The "config" key defines the lmp configs, see [the full documentation](#). The "configurations" provides the initial configurations (coordinates of atoms and the simulation cell) of the DPMD simulations. It is a list. The elements of the list can be

- list[str]: The strings provides the path to the configuration files.
- dict: Automatic alloy configuration generator. See the detailed doc of the allowed keys.

The "stages" defines the exploration stages. It is of type list[list[dict]]. The outer list enumerate the exploration stages, the inner list enumerate the task groups of the stage. Each dict defines a stage. See [the full documentation of the target group](#) for writing task groups.

"n_sample" tells the number of configurations randomly sampled from the set picked by "conf_idx" from configurations for each exploration task. All configurations has the equal possibility to be sampled. The default value of "n_sample" is null, in this case all picked configurations are sampled. In the example, we have 3 samples for stage 0 task group 0 and 2 thermodynamic states (NVT, T=50 and 100K), then the task group has 3x2=6 NVT DPMD tasks.

3.3.4 FP

This section defines the first-principle (FP) calculation .

```
"fp" : {
  "type" :      "vasp",
  "config" : {
    "command": "source /opt/intel/oneapi/setvars.sh && mpirun -n 16 vasp_std"
  },
  "task_max":   2,
  "pp_files":   {"Al" : "vasp/POTCAR.Al", "Mg" : "vasp/POTCAR.Mg"},
  "incar":      "vasp/INCAR",
  "_comment" : "all"
}
```

The "type" : "vasp" means that first-principles are VASP calculations. The "config" key defines the vasp configs, see *the full documentation*. The "task_max" key defines the maximal number of vasp calculations in each dpgen2 iteration. The "pp_files" and "incar" keys provides the pseudopotential files and the template incar file.

3.3.5 Configuration of dflow step

The execution units of the dpgen2 are the dflow Steps. How each step is executed is defined by the "step_configs".

```
"step_configs":{
  "prep_train_config" : {
    "_comment" : "content omitted"
  },
  "run_train_config" : {
    "_comment" : "content omitted"
  },
  "prep_explore_config" : {
    "_comment" : "content omitted"
  },
  "run_explore_config" : {
    "_comment" : "content omitted"
  },
  "prep_fp_config" : {
    "_comment" : "content omitted"
  },
  "run_fp_config" : {
    "_comment" : "content omitted"
  },
  "select_confs_config" : {
    "_comment" : "content omitted"
  },
  "collect_data_config" : {
    "_comment" : "content omitted"
  },
  "cl_step_config" : {
    "_comment" : "content omitted"
  },
  "_comment" : "all"
},
```


The configs for prepare training, run training, prepare exploration, run exploration, prepare fp, run fp, select configurations, collect data and concurrent learning steps are given correspondingly.

The readers are referred to [this page](#) for a full documentation of the step configs.

Any of the config in the `step_configs` can be omitted. If so, the configs of the step is set to the default step configs, which is provided by the following section, for example,

```
"default_step_config" : {  
  "template_config" : {  
    "image" : "dpgen2:x.x.x"  
  }  
},
```

The way of writing the `default_step_config` is the same as any step config in the `step_configs`. One may refer to [this page](#) for full documentation.

ARGUMENTS OF THE SUBMIT SCRIPT

fp:

type: dict

argument path: fp

The configuration for FP

Depending on the value of *type*, different sub args are accepted.

type:

type: str (flag key)

argument path: fp/type

possible choices: *vasp*

the type of the fp

When *type* is set to *vasp*:

config:

type: dict, optional, default: {'command': 'vasp', 'log': 'vasp.log',
'out': 'data'}

argument path: fp[vasp]/config

Configuration of vasp runs

command:

type: str, optional, default: vasp

argument path: fp[vasp]/config/command

The command of VASP

log:

type: str, optional, default: vasp.log

argument path: fp[vasp]/config/log

The log file name of VASP

out:

type: str, optional, default: data

argument path: fp[vasp]/config/out

The output dir name of labeled data. In *deepmd/npz* format provided by *dpdata*.

task_max:

type: int, optional, default: 10

argument path: `fp[vasp]/task_max`

Maximum number of vasp tasks for each iteration

pp_files:

type: `dict`

argument path: `fp[vasp]/pp_files`

The pseudopotential files set by a dict, e.g. `{"Al" : "path/to/the/al/pp/file", "Mg" : "path/to/the/mg/pp/file"}`

incar:

type: `str`

argument path: `fp[vasp]/incar`

The pseudopotential files set by a dict, e.g. `{"Al" : "path/to/the/al/pp/file", "Mg" : "path/to/the/mg/pp/file"}`

explore:

type: `dict`

argument path: `explore`

The configuration for exploration

Depending on the value of *type*, different sub args are accepted.

type:

type: `str` (flag key)

argument path: `explore/type`

possible choices: *lmp*

the type of the exploration

When *type* is set to *lmp*:

config:

type: `dict`, optional, default: `{'command': 'lmp'}`

argument path: `explore[lmp]/config`

Configuration of *lmp* exploration

command:

type: `str`, optional, default: *lmp*

argument path: `explore[lmp]/config/command`

The command of LAMMPS

max_numb_iter:

type: `int`, optional, default: `10`

argument path: `explore[lmp]/max_numb_iter`

Maximum number of iterations per stage

conv_accuracy:

type: `float`, optional, default: `0.9`

argument path: `explore[lmp]/conv_accuracy`

Convergence accuracy

fatal_at_max:

type: `bool`, optional, default: `True`

argument path: `explore[lmp]/fatal_at_max`

Fatal when the number of iteration per stage reaches the *max_numb_iter*

f_trust_lo:

type: `float`

argument path: `explore[lmp]/f_trust_lo`

Lower trust level of force model deviation

f_trust_hi:

type: `float`

argument path: `explore[lmp]/f_trust_hi`

Higher trust level of force model deviation

v_trust_lo:

type: `NoneType` | `float`, optional, default: `None`

argument path: `explore[lmp]/v_trust_lo`

Lower trust level of virial model deviation

v_trust_hi:

type: `NoneType` | `float`, optional, default: `None`

argument path: `explore[lmp]/v_trust_hi`

Higher trust level of virial model deviation

configuration_prefix:

type: `NoneType` | `str`, optional, default: `None`

argument path: `explore[lmp]/configuration_prefix`

The path prefix of lmp initial configurations

configurations:

type: `list`, alias: *configuration*

argument path: `explore[lmp]/configurations`

A list of initial configurations.

stages:

type: `list`

argument path: `explore[lmp]/stages`

A list of exploration stages.

train:

type: dict

argument path: train

The configuration for training

Depending on the value of *type*, different sub args are accepted.

type:

type: str (flag key)

argument path: train/type

possible choices: *dp*

the type of the training

When *type* is set to *dp*:

config:

type: dict, optional, default: {'init_model_policy': 'no',
'init_model_old_ratio': 0.9, 'init_model_num_steps': 400000,
'init_model_start_lr': 0.0001, 'init_model_start_pref_e':
0.1, 'init_model_start_pref_f': 100,
'init_model_start_pref_v': 0.0}

argument path: train[dp]/config

Number of models trained for evaluating the model deviation

init_model_policy:

type: str, optional, default: no

argument path: train[dp]/config/init_model_policy

The policy of init-model training. It can be

- 'no': No init-model training. Training from scratch.
- 'yes': Do init-model training.
- 'old_data_larger_than:XXX': Do init-model if the training data size of the previous model is larger than XXX. XXX is an int number.

init_model_old_ratio:

type: float, optional, default: 0.9

argument path: train[dp]/config/init_model_old_ratio

The frequency ratio of old data over new data

init_model_num_steps:

type: int, optional, default: 400000, alias: *init_model_stop_batch*

argument path: train[dp]/config/init_model_num_steps

The number of training steps when init-model

init_model_start_lr:

type: float, optional, default: 0.0001

argument path: train[dp]/config/init_model_start_lr

The start learning rate when init-model

init_model_start_pref_e:

type: float, optional, default: 0.1

argument path: train[dp]/config/init_model_start_pref_e

The start energy prefactor in loss when init-model

init_model_start_pref_f:

type: int | float, optional, default: 100

argument path: train[dp]/config/init_model_start_pref_f

The start force prefactor in loss when init-model

init_model_start_pref_v:

type: float, optional, default: 0.0

argument path: train[dp]/config/init_model_start_pref_v

The start virial prefactor in loss when init-model

numb_models:

type: int, optional, default: 4

argument path: train[dp]/numb_models

Number of models trained for evaluating the model deviation

template_script:

type: list | dict

argument path: train[dp]/template_script

Template training script. It can be a *List[Dict]*, the length of which is the same as *numb_models*. Each template script in the list is used to train a model. Can be a *Dict*, the models share the same template training script.

inputs:

type: dict

argument path: inputs

The input parameter and artifacts for dpgen2

type_map:

type: list

argument path: inputs/type_map

The type map. e.g. ["Al", "Mg"]. Al and Mg will have type 0 and 1, respectively.

mass_map:

type: list

argument path: inputs/mass_map

The mass map. e.g. [27., 24.]. Al and Mg will be set with mass 27. and 24. amu, respectively.

init_data_prefix:

type: NoneType | str, optional, default: None

argument path: inputs/init_data_prefix

The prefix of initial data systems

init_data_sys:

type: list
argument path: inputs/init_data_sys
The initial data systems

upload_python_packages:

type: list | NoneType | str, optional, default: None, alias: *upload_python_package*
argument path: upload_python_packages
Upload python package, for debug purpose

step_configs:

type: dict, optional, default: {}
argument path: step_configs
Configurations for executing dflow steps

prep_train_config:

type: dict, optional, default: {'template_config': {'image': 'dptechnology/dpgen2:latest', 'timeout': None, 'retry_on_transient_error': None, 'timeout_as_transient_error': False, 'envs': None}, 'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'parallelism': None, 'executor': None}
argument path: step_configs/prep_train_config

Configuration for prepare train

template_config:

type: dict, optional, default: {'image': 'dptechnology/dpgen2:latest'}
argument path:
step_configs/prep_train_config/template_config

The configs passed to the PythonOPTemplate.

image:

type: str, optional, default: dptechnology/dpgen2:latest
argument path: step_configs/prep_train_config/
template_config/image

The image to run the step.

timeout:

type: int | NoneType, optional, default: None
argument path: step_configs/prep_train_config/
template_config/timeout

The time limit of the OP. Unit is second.

retry_on_transient_error:

type: NoneType | bool, optional, default: None

argument path: `step_configs/prep_train_config/template_config/retry_on_transient_error`

Retry the step if a `TransientError` is raised.

timeout_as_transient_error:

type: `bool`, optional, default: `False`

argument path: `step_configs/prep_train_config/template_config/timeout_as_transient_error`

Treat the timeout as `TransientError`.

envs:

type: `dict | NoneType`, optional, default: `None`

argument path: `step_configs/prep_train_config/template_config/envs`

The environmental variables.

continue_on_failed:

type: `bool`, optional, default: `False`

argument path:

`step_configs/prep_train_config/continue_on_failed`

If continue the the step is failed (`FatalError`, `TransientError`, A certain number of retrial is reached...).

continue_on_num_success:

type: `int | NoneType`, optional, default: `None`

argument path: `step_configs/prep_train_config/continue_on_num_success`

Only in the sliced OP case. Continue the workflow if a certain number of the sliced jobs are successful.

continue_on_success_ratio:

type: `NoneType | float`, optional, default: `None`

argument path: `step_configs/prep_train_config/continue_on_success_ratio`

Only in the sliced OP case. Continue the workflow if a certain ratio of the sliced jobs are successful.

parallelism:

type: `int | NoneType`, optional, default: `None`

argument path:

`step_configs/prep_train_config/parallelism`

The parallelism for the step

executor:

type: `dict | NoneType`, optional, default: `None`

argument path: `step_configs/prep_train_config/executor`

The executor of the step.

Depending on the value of *type*, different sub args are accepted.

type:

type: str (flag key)
argument path:
step_configs/prep_train_config/executor/type
possible choices: *lebesgue_v2*, *dispatcher*

The type of the executor.

When *type* is set to *lebesgue_v2*:

extra:

type: dict, optional
argument path: step_configs/prep_train_config/
executor[lebesgue_v2]/extra

The 'extra' key in the lebesgue executor. Note that we do not check if 'the *dict* provided to the 'extra' key is valid or not.

scass_type:

type: str, optional
argument path:
step_configs/prep_train_config/
executor[lebesgue_v2]/extra/scass_type

The machine configuraiton.

program_id:

type: str, optional
argument path:
step_configs/prep_train_config/
executor[lebesgue_v2]/extra/program_id

The ID of the program.

job_type:

type: str, optional, default: container
argument path:
step_configs/prep_train_config/
executor[lebesgue_v2]/extra/job_type

The type of job.

template_cover_cmd_escape_bug:

type: bool, optional, default: True
argument path:
step_configs/prep_train_config/
executor[lebesgue_v2]/extra/
template_cover_cmd_escape_bug

The key for hacking around a bug in Lebesgue.

When *type* is set to *dispatcher*:

run_train_config:

type: dict, optional, default: {'template_config': {'image':
'dptechnology/dpgen2:latest', 'timeout': None,
'retry_on_transient_error': None,
'timeout_as_transient_error': False, 'envs': None},

'continue_on_failed': False, 'continue_on_num_success':
None, 'continue_on_success_ratio': None, 'parallelism':
None, 'executor': None}

argument path: step_configs/run_train_config

Configuration for run train

template_config:

type: dict, optional, default: {'image':
'dptechnology/dpugen2:latest'}

argument path:

step_configs/run_train_config/template_config

The configs passed to the PythonOPTemplate.

image:

type: str, optional, default:
dptechnology/dpugen2:latest

argument path:

step_configs/run_train_config/
template_config/image

The image to run the step.

timeout:

type: int | NoneType, optional, default: None

argument path:

step_configs/run_train_config/
template_config/timeout

The time limit of the OP. Unit is second.

retry_on_transient_error:

type: NoneType | bool, optional, default:
None

argument path: step_configs/
run_train_config/template_config/
retry_on_transient_error

Retry the step if a TransientError is raised.

timeout_as_transient_error:

type: bool, optional, default: False

argument path: step_configs/
run_train_config/template_config/
timeout_as_transient_error

Treat the timeout as TransientError.

envs:

type: dict | NoneType, optional, default:
None

argument path:

step_configs/run_train_config/
template_config/envs

The environmental variables.

continue_on_failed:

type: bool, optional, default: False
argument path: `step_configs/run_train_config/continue_on_failed`

If continue the the step is failed (FatalError, TransientError, A certain number of retrial is reached...).

continue_on_num_success:

type: int | NoneType, optional, default: None
argument path: `step_configs/run_train_config/continue_on_num_success`

Only in the sliced OP case. Continue the workflow if a certain number of the sliced jobs are successful.

continue_on_success_ratio:

type: NoneType | float, optional, default: None
argument path: `step_configs/run_train_config/continue_on_success_ratio`

Only in the sliced OP case. Continue the workflow if a certain ratio of the sliced jobs are successful.

parallelism:

type: int | NoneType, optional, default: None
argument path:
`step_configs/run_train_config/parallelism`

The parallelism for the step

executor:

type: dict | NoneType, optional, default: None
argument path:
`step_configs/run_train_config/executor`

The executor of the step.

Depending on the value of *type*, different sub args are accepted.

type:

type: str (flag key)
argument path: `step_configs/run_train_config/executor/type`
possible choices: *lebesgue_v2*,
dispatcher

The type of the executor.

When *type* is set to *lebesgue_v2*:

extra:

type: dict, optional
 argument path:
 step_configs/run_train_config/
 executor[lebesgue_v2]/extra

The 'extra' key in the lebesgue executor. Note that we do not check if 'the *dict* provided to the 'extra' key is valid or not.

scass_type:

type: str, optional
 argument path: step_configs/
 run_train_config/
 executor[lebesgue_v2]/extra/
 scass_type

The machine configuraiton.

program_id:

type: str, optional
 argument path: step_configs/
 run_train_config/
 executor[lebesgue_v2]/extra/
 program_id

The ID of the program.

job_type:

type: str, optional, default:
 container
 argument path: step_configs/
 run_train_config/
 executor[lebesgue_v2]/extra/
 job_type

The type of job.

template_cover_cmd_escape_bug:

type: bool, optional, default: True
 argument path: step_configs/
 run_train_config/
 executor[lebesgue_v2]/extra/
 template_cover_cmd_escape_bug

The key for hacking around a bug in Lebesgue.

When `type` is set to dispatcher:

prep_explore_config:

type: dict, optional, default: {'template_config': {'image': 'dptechnology/dpgen2:latest', 'timeout': None, 'retry_on_transient_error': None, 'timeout_as_transient_error': False, 'envs': None}, 'continue_on_failed': False, 'continue_on_num_success':

None, 'continue_on_success_ratio': None, 'parallelism':
None, 'executor': None}

argument path: step_configs/prepare_explore_config

Configuration for prepare exploration

template_config:

type: dict, optional, default: {'image':
'dptechnology/dpgen2:latest'}

argument path: step_configs/prepare_explore_config/
template_config

The configs passed to the PythonOPTemplate.

image:

type: str, optional, default:
dptechnology/dpgen2:latest

argument path:
step_configs/prepare_explore_config/
template_config/image

The image to run the step.

timeout:

type: int | NoneType, optional, default: None

argument path:
step_configs/prepare_explore_config/
template_config/timeout

The time limit of the OP. Unit is second.

retry_on_transient_error:

type: NoneType | bool, optional, default:
None

argument path:
step_configs/prepare_explore_config/
template_config/
retry_on_transient_error

Retry the step if a TransientError is raised.

timeout_as_transient_error:

type: bool, optional, default: False

argument path:
step_configs/prepare_explore_config/
template_config/
timeout_as_transient_error

Treat the timeout as TransientError.

envs:

type: dict | NoneType, optional, default:
None

argument path:
step_configs/prep_explore_config/
template_config/envs

The environmental variables.

continue_on_failed:

type: bool, optional, default: False
argument path: step_configs/prep_explore_config/
continue_on_failed

If continue the the step is failed (FatalError, TransientError, A certain number of retrial is reached...).

continue_on_num_success:

type: int | NoneType, optional, default: None
argument path: step_configs/prep_explore_config/
continue_on_num_success

Only in the sliced OP case. Continue the workflow if a certain number of the sliced jobs are successful.

continue_on_success_ratio:

type: NoneType | float, optional, default: None
argument path: step_configs/prep_explore_config/
continue_on_success_ratio

Only in the sliced OP case. Continue the workflow if a certain ratio of the sliced jobs are successful.

parallelism:

type: int | NoneType, optional, default: None
argument path:
step_configs/prep_explore_config/parallelism

The parallelism for the step

executor:

type: dict | NoneType, optional, default: None
argument path:
step_configs/prep_explore_config/executor

The executor of the step.

Depending on the value of *type*, different sub args are accepted.

type:

type: str (flag key)
argument path: step_configs/
prep_explore_config/executor/type
possible choices: *lebesgue_v2*,
dispatcher

The type of the executor.

When `type` is set to `lebesgue_v2`:

extra:

type: dict, optional
argument path:
step_configs/prep_explore_config/
executor[lebesgue_v2]/extra

The 'extra' key in the lebesgue executor. Note that we do not check if 'the *dict* provided to the 'extra' key is valid or not.

scass_type:

type: str, optional
argument path: step_configs/
prep_explore_config/
executor[lebesgue_v2]/extra/
scass_type

The machine configuraiton.

program_id:

type: str, optional
argument path: step_configs/
prep_explore_config/
executor[lebesgue_v2]/extra/
program_id

The ID of the program.

job_type:

type: str, optional, default:
container
argument path: step_configs/
prep_explore_config/
executor[lebesgue_v2]/extra/
job_type

The type of job.

template_cover_cmd_escape_bug:

type: bool, optional, default: True
argument path: step_configs/
prep_explore_config/
executor[lebesgue_v2]/extra/
template_cover_cmd_escape_bug

The key for hacking around a bug in Lebesgue.

When `type` is set to `dispatcher`:

run_explore_config:

type: dict, optional, default: {'template_config': {'image':
'dptechnology/dpgen2:latest', 'timeout': None,
'retry_on_transient_error': None,
'timeout_as_transient_error': False, 'envs': None},


```
'continue_on_failed': False, 'continue_on_num_success':  
None, 'continue_on_success_ratio': None, 'parallelism':  
None, 'executor': None}
```

argument path: step_configs/run_explore_config

Configuration for run exploration

template_config:

```
type: dict, optional, default: {'image':  
'dptechnology/dpgen2:latest'}
```

argument path: step_configs/run_explore_config/
template_config

The configs passed to the PythonOPTemplate.

image:

```
type: str, optional, default:  
dptechnology/dpgen2:latest
```

argument path:
step_configs/run_explore_config/
template_config/image

The image to run the step.

timeout:

```
type: int | NoneType, optional, default: None
```

argument path:
step_configs/run_explore_config/
template_config/timeout

The time limit of the OP. Unit is second.

retry_on_transient_error:

```
type: NoneType | bool, optional, default:  
None
```

argument path: step_configs/
run_explore_config/template_config/
retry_on_transient_error

Retry the step if a TransientError is raised.

timeout_as_transient_error:

```
type: bool, optional, default: False
```

argument path: step_configs/
run_explore_config/template_config/
timeout_as_transient_error

Treat the timeout as TransientError.

envs:

```
type: dict | NoneType, optional, default:  
None
```

argument path:
step_configs/run_explore_config/
template_config/envs

The environmental variables.

continue_on_failed:

type: bool, optional, default: False
argument path: `step_configs/run_explore_config/continue_on_failed`

If continue the the step is failed (FatalError, TransientError, A certain number of retrial is reached...).

continue_on_num_success:

type: int | NoneType, optional, default: None
argument path: `step_configs/run_explore_config/continue_on_num_success`

Only in the sliced OP case. Continue the workflow if a certain number of the sliced jobs are successful.

continue_on_success_ratio:

type: NoneType | float, optional, default: None
argument path: `step_configs/run_explore_config/continue_on_success_ratio`

Only in the sliced OP case. Continue the workflow if a certain ratio of the sliced jobs are successful.

parallelism:

type: int | NoneType, optional, default: None
argument path:
`step_configs/run_explore_config/parallelism`

The parallelism for the step

executor:

type: dict | NoneType, optional, default: None
argument path:
`step_configs/run_explore_config/executor`

The executor of the step.

Depending on the value of *type*, different sub args are accepted.

type:

type: str (flag key)
argument path: `step_configs/run_explore_config/executor/type`
possible choices: *lebesgue_v2*,
dispatcher

The type of the executor.

When *type* is set to *lebesgue_v2*:

extra:

type: dict, optional

argument path:

step_configs/run_explore_config/
executor[lebesgue_v2]/extra

The 'extra' key in the lebesgue executor. Note that we do not check if 'the *dict* provided to the 'extra' key is valid or not.

scass_type:

type: str, optional

argument path: step_configs/

run_explore_config/

executor[lebesgue_v2]/extra/

scass_type

The machine configuraiton.

program_id:

type: str, optional

argument path: step_configs/

run_explore_config/

executor[lebesgue_v2]/extra/

program_id

The ID of the program.

job_type:

type: str, optional, default:

container

argument path: step_configs/

run_explore_config/

executor[lebesgue_v2]/extra/

job_type

The type of job.

template_cover_cmd_escape_bug:

type: bool, optional, default: True

argument path: step_configs/

run_explore_config/

executor[lebesgue_v2]/extra/

template_cover_cmd_escape_bug

The key for hacking around a bug in Lebesgue.

When `type` is set to dispatcher:

prep_fp_config:

```
type: dict, optional, default: {'template_config': {'image':
'dptechnology/dpgen2:latest', 'timeout': None,
'retry_on_transient_error': None,
'timeout_as_transient_error': False, 'envs': None},
'continue_on_failed': False, 'continue_on_num_success':
```

None, 'continue_on_success_ratio': None, 'parallelism':
None, 'executor': None}

argument path: step_configs/prep_fp_config

Configuration for prepare fp

template_config:

type: dict, optional, default: {'image':
'dptechnology/dpgen2:latest'}

argument path:

step_configs/prep_fp_config/template_config

The configs passed to the PythonOPTemplate.

image:

type: str, optional, default:

dptechnology/dpgen2:latest

argument path:

step_configs/prep_fp_config/
template_config/image

The image to run the step.

timeout:

type: int | NoneType, optional, default: None

argument path:

step_configs/prep_fp_config/
template_config/timeout

The time limit of the OP. Unit is second.

retry_on_transient_error:

type: NoneType | bool, optional, default:
None

argument path: step_configs/
prep_fp_config/template_config/
retry_on_transient_error

Retry the step if a TransientError is raised.

timeout_as_transient_error:

type: bool, optional, default: False

argument path: step_configs/
prep_fp_config/template_config/
timeout_as_transient_error

Treat the timeout as TransientError.

envs:

type: dict | NoneType, optional, default:
None

argument path: step_configs/
prep_fp_config/template_config/envs

The environmental variables.

continue_on_failed:

type: bool, optional, default: False

argument path:

step_configs/prep_fp_config/continue_on_failed

If continue the the step is failed (FatalError, TransientError, A certain number of retrial is reached...).

continue_on_num_success:

type: int | NoneType, optional, default: None

argument path: step_configs/prep_fp_config/
continue_on_num_success

Only in the sliced OP case. Continue the workflow if a certain number of the sliced jobs are successful.

continue_on_success_ratio:

type: NoneType | float, optional, default: None

argument path: step_configs/prep_fp_config/
continue_on_success_ratio

Only in the sliced OP case. Continue the workflow if a certain ratio of the sliced jobs are successful.

parallelism:

type: int | NoneType, optional, default: None

argument path:

step_configs/prep_fp_config/parallelism

The parallelism for the step

executor:

type: dict | NoneType, optional, default: None

argument path:

step_configs/prep_fp_config/executor

The executor of the step.

Depending on the value of *type*, different sub args are accepted.

type:

type: str (flag key)

argument path: step_configs/
prep_fp_config/executor/type

possible choices: *lebesgue_v2*,
dispatcher

The type of the executor.

When *type* is set to *lebesgue_v2*:

extra:

type: dict, optional

argument path:
step_configs/prep_fp_config/
executor[lebesgue_v2]/extra

The 'extra' key in the lebesgue executor. Note that we do not check if 'the *dict* provided to the 'extra' key is valid or not.

scass_type:

type: str, optional
argument path:
step_configs/prep_fp_config/
executor[lebesgue_v2]/extra/
scass_type

The machine configuraiton.

program_id:

type: str, optional
argument path:
step_configs/prep_fp_config/
executor[lebesgue_v2]/extra/
program_id

The ID of the program.

job_type:

type: str, optional, default:
container
argument path:
step_configs/prep_fp_config/
executor[lebesgue_v2]/extra/
job_type

The type of job.

template_cover_cmd_escape_bug:

type: bool, optional, default: True
argument path:
step_configs/prep_fp_config/
executor[lebesgue_v2]/extra/
template_cover_cmd_escape_bug

The key for hacking around a bug in Lebesgue.

When `type` is set to dispatcher:

run_fp_config:

type: dict, optional, default: {'template_config': {'image': 'dptechnology/dpgen2:latest', 'timeout': None, 'retry_on_transient_error': None, 'timeout_as_transient_error': False, 'envs': None}, 'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'parallelism': None, 'executor': None}
argument path: step_configs/run_fp_config

Configuration for run fp

template_config:

type: dict, optional, default: {'image':
'dptechnology/dpgen2:latest'}
argument path:
step_configs/run_fp_config/template_config

The configs passed to the PythonOPTemplate.

image:

type: str, optional, default:
dptechnology/dpgen2:latest
argument path: step_configs/
run_fp_config/template_config/image

The image to run the step.

timeout:

type: int | NoneType, optional, default: None
argument path:
step_configs/run_fp_config/
template_config/timeout

The time limit of the OP. Unit is second.

retry_on_transient_error:

type: NoneType | bool, optional, default:
None
argument path: step_configs/
run_fp_config/template_config/
retry_on_transient_error

Retry the step if a TransientError is raised.

timeout_as_transient_error:

type: bool, optional, default: False
argument path: step_configs/
run_fp_config/template_config/
timeout_as_transient_error

Treat the timeout as TransientError.

envs:

type: dict | NoneType, optional, default:
None
argument path: step_configs/
run_fp_config/template_config/envs

The environmental variables.

continue_on_failed:

type: bool, optional, default: False

argument path:
step_configs/run_fp_config/continue_on_failed

If continue the the step is failed (FatalError, TransientError, A certain number of retrial is reached...).

continue_on_num_success:

type: int | NoneType, optional, default: None
argument path: step_configs/run_fp_config/
continue_on_num_success

Only in the sliced OP case. Continue the workflow if a certain number of the sliced jobs are successful.

continue_on_success_ratio:

type: NoneType | float, optional, default: None
argument path: step_configs/run_fp_config/
continue_on_success_ratio

Only in the sliced OP case. Continue the workflow if a certain ratio of the sliced jobs are successful.

parallelism:

type: int | NoneType, optional, default: None
argument path:
step_configs/run_fp_config/parallelism

The parallelism for the step

executor:

type: dict | NoneType, optional, default: None
argument path:
step_configs/run_fp_config/executor

The executor of the step.

Depending on the value of *type*, different sub args are accepted.

type:

type: str (flag key)
argument path: step_configs/
run_fp_config/executor/type
possible choices: *lebesgue_v2*,
dispatcher

The type of the executor.

When *type* is set to *lebesgue_v2*:

extra:

type: dict, optional
argument path:
step_configs/run_fp_config/
executor[lebesgue_v2]/extra

The 'extra' key in the lebesgue executor. Note that we do not check if 'the *dict* provided to the 'extra' key is valid or not.

scass_type:

type: str, optional
 argument path:
 step_configs/run_fp_config/
 executor[lebesgue_v2]/extra/
 scass_type

The machine configuraiton.

program_id:

type: str, optional
 argument path:
 step_configs/run_fp_config/
 executor[lebesgue_v2]/extra/
 program_id

The ID of the program.

job_type:

type: str, optional, default:
 container
 argument path:
 step_configs/run_fp_config/
 executor[lebesgue_v2]/extra/
 job_type

The type of job.

template_cover_cmd_escape_bug:

type: bool, optional, default: True
 argument path:
 step_configs/run_fp_config/
 executor[lebesgue_v2]/extra/
 template_cover_cmd_escape_bug

The key for hacking around a bug in Lebesgue.

When `type` is set to dispatcher:

select_confs_config:

type: dict, optional, default: {'template_config': {'image': 'dptechnology/dpgen2:latest', 'timeout': None, 'retry_on_transient_error': None, 'timeout_as_transient_error': False, 'envs': None}, 'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'parallelism': None, 'executor': None}
 argument path: step_configs/select_confs_config

Configuration for the select confs

template_config:

type: dict, optional, default: {'image':
'dptechnology/dpgen2:latest'}
argument path: step_configs/select_confs_config/
template_config

The configs passed to the PythonOPTemplate.

image:

type: str, optional, default:
dptechnology/dpgen2:latest
argument path:
step_configs/select_confs_config/
template_config/image

The image to run the step.

timeout:

type: int | NoneType, optional, default: None
argument path:
step_configs/select_confs_config/
template_config/timeout

The time limit of the OP. Unit is second.

retry_on_transient_error:

type: NoneType | bool, optional, default:
None
argument path:
step_configs/select_confs_config/
template_config/
retry_on_transient_error

Retry the step if a TransientError is raised.

timeout_as_transient_error:

type: bool, optional, default: False
argument path:
step_configs/select_confs_config/
template_config/
timeout_as_transient_error

Treat the timeout as TransientError.

envs:

type: dict | NoneType, optional, default:
None
argument path:
step_configs/select_confs_config/
template_config/envs

The environmental variables.

continue_on_failed:

type: bool, optional, default: False

argument path: `step_configs/select_confs_config/continue_on_failed`

If continue the the step is failed (FatalError, TransientError, A certain number of retrial is reached...).

continue_on_num_success:

type: `int | NoneType`, optional, default: `None`

argument path: `step_configs/select_confs_config/continue_on_num_success`

Only in the sliced OP case. Continue the workflow if a certain number of the sliced jobs are successful.

continue_on_success_ratio:

type: `NoneType | float`, optional, default: `None`

argument path: `step_configs/select_confs_config/continue_on_success_ratio`

Only in the sliced OP case. Continue the workflow if a certain ratio of the sliced jobs are successful.

parallelism:

type: `int | NoneType`, optional, default: `None`

argument path:
`step_configs/select_confs_config/parallelism`

The parallelism for the step

executor:

type: `dict | NoneType`, optional, default: `None`

argument path:
`step_configs/select_confs_config/executor`

The executor of the step.

Depending on the value of *type*, different sub args are accepted.

type:

type: `str` (flag key)

argument path: `step_configs/select_confs_config/executor/type`

possible choices: *lebesgue_v2*,
dispatcher

The type of the executor.

When *type* is set to *lebesgue_v2*:

extra:

type: `dict`, optional

argument path:
`step_configs/select_confs_config/executor[lebesgue_v2]/extra`

The 'extra' key in the lebesgue executor. Note that we do not check if 'the *dict* provided to the 'extra' key is valid or not.

scass_type:

type: str, optional
argument path: step_configs/
select_confs_config/
executor[lebesgue_v2]/extra/
scass_type

The machine configuraiton.

program_id:

type: str, optional
argument path: step_configs/
select_confs_config/
executor[lebesgue_v2]/extra/
program_id

The ID of the program.

job_type:

type: str, optional, default:
container
argument path: step_configs/
select_confs_config/
executor[lebesgue_v2]/extra/
job_type

The type of job.

template_cover_cmd_escape_bug:

type: bool, optional, default: True
argument path: step_configs/
select_confs_config/
executor[lebesgue_v2]/extra/
template_cover_cmd_escape_bug

The key for hacking around a bug in Lebesgue.

When `type` is set to dispatcher:

collect_data_config:

type: dict, optional, default: {'template_config': {'image':
'dptechnology/dpgen2:latest', 'timeout': None,
'retry_on_transient_error': None,
'timeout_as_transient_error': False, 'envs': None},
'continue_on_failed': False, 'continue_on_num_success':
None, 'continue_on_success_ratio': None, 'parallelism':
None, 'executor': None}
argument path: step_configs/collect_data_config

Configuration for the collect data

template_config:

type: dict, optional, default: {'image':
'dptechnology/dpgen2:latest'}
argument path: step_configs/collect_data_config/
template_config

The configs passed to the PythonOPTemplate.

image:

type: str, optional, default:
dptechnology/dpgen2:latest
argument path:
step_configs/collect_data_config/
template_config/image

The image to run the step.

timeout:

type: int | NoneType, optional, default: None
argument path:
step_configs/collect_data_config/
template_config/timeout

The time limit of the OP. Unit is second.

retry_on_transient_error:

type: NoneType | bool, optional, default:
None
argument path:
step_configs/collect_data_config/
template_config/
retry_on_transient_error

Retry the step if a TransientError is raised.

timeout_as_transient_error:

type: bool, optional, default: False
argument path:
step_configs/collect_data_config/
template_config/
timeout_as_transient_error

Treat the timeout as TransientError.

envs:

type: dict | NoneType, optional, default:
None
argument path:
step_configs/collect_data_config/
template_config/envs

The environmental variables.

continue_on_failed:

type: bool, optional, default: False

argument path: `step_configs/collect_data_config/continue_on_failed`

If continue the the step is failed (FatalError, TransientError, A certain number of retrial is reached...).

continue_on_num_success:

type: `int | NoneType`, optional, default: `None`

argument path: `step_configs/collect_data_config/continue_on_num_success`

Only in the sliced OP case. Continue the workflow if a certain number of the sliced jobs are successful.

continue_on_success_ratio:

type: `NoneType | float`, optional, default: `None`

argument path: `step_configs/collect_data_config/continue_on_success_ratio`

Only in the sliced OP case. Continue the workflow if a certain ratio of the sliced jobs are successful.

parallelism:

type: `int | NoneType`, optional, default: `None`

argument path:
`step_configs/collect_data_config/parallelism`

The parallelism for the step

executor:

type: `dict | NoneType`, optional, default: `None`

argument path:
`step_configs/collect_data_config/executor`

The executor of the step.

Depending on the value of *type*, different sub args are accepted.

type:

type: `str` (flag key)

argument path: `step_configs/collect_data_config/executor/type`

possible choices: *lebesgue_v2*,
dispatcher

The type of the executor.

When *type* is set to *lebesgue_v2*:

extra:

type: `dict`, optional

argument path:
`step_configs/collect_data_config/executor[lebesgue_v2]/extra`

The 'extra' key in the lebesgue executor. Note that we do not check if 'the *dict* provided to the 'extra' key is valid or not.

scass_type:

type: str, optional
 argument path: step_configs/
 collect_data_config/
 executor[lebesgue_v2]/extra/
 scass_type

The machine configuraiton.

program_id:

type: str, optional
 argument path: step_configs/
 collect_data_config/
 executor[lebesgue_v2]/extra/
 program_id

The ID of the program.

job_type:

type: str, optional, default:
 container
 argument path: step_configs/
 collect_data_config/
 executor[lebesgue_v2]/extra/
 job_type

The type of job.

template_cover_cmd_escape_bug:

type: bool, optional, default: True
 argument path: step_configs/
 collect_data_config/
 executor[lebesgue_v2]/extra/
 template_cover_cmd_escape_bug

The key for hacking around a bug in Lebesgue.

When `type` is set to dispatcher:

cl_step_config:

type: dict, optional, default: {'template_config': {'image': 'dptechnology/dpgen2:latest', 'timeout': None, 'retry_on_transient_error': None, 'timeout_as_transient_error': False, 'envs': None}, 'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'parallelism': None, 'executor': None}
 argument path: step_configs/cl_step_config

Configuration for the concurrent learning step

template_config:

type: dict, optional, default: {'image':
'dptechnology/dpgen2:latest'}
argument path:
step_configs/cl_step_config/template_config

The configs passed to the PythonOPTemplate.

image:

type: str, optional, default:
dptechnology/dpgen2:latest
argument path:
step_configs/cl_step_config/
template_config/image

The image to run the step.

timeout:

type: int | NoneType, optional, default: None
argument path:
step_configs/cl_step_config/
template_config/timeout

The time limit of the OP. Unit is second.

retry_on_transient_error:

type: NoneType | bool, optional, default:
None
argument path: step_configs/
cl_step_config/template_config/
retry_on_transient_error

Retry the step if a TransientError is raised.

timeout_as_transient_error:

type: bool, optional, default: False
argument path: step_configs/
cl_step_config/template_config/
timeout_as_transient_error

Treat the timeout as TransientError.

envs:

type: dict | NoneType, optional, default:
None
argument path: step_configs/
cl_step_config/template_config/envs

The environmental variables.

continue_on_failed:

type: bool, optional, default: False
argument path:
step_configs/cl_step_config/continue_on_failed

If continue the the step is failed (FatalError, TransientError, A certain number of retrial is reached...).

continue_on_num_success:

type: int | NoneType, optional, default: None
 argument path: step_configs/cl_step_config/
 continue_on_num_success

Only in the sliced OP case. Continue the workflow if a certain number of the sliced jobs are successful.

continue_on_success_ratio:

type: NoneType | float, optional, default: None
 argument path: step_configs/cl_step_config/
 continue_on_success_ratio

Only in the sliced OP case. Continue the workflow if a certain ratio of the sliced jobs are successful.

parallelism:

type: int | NoneType, optional, default: None
 argument path:
 step_configs/cl_step_config/parallelism

The parallelism for the step

executor:

type: dict | NoneType, optional, default: None
 argument path:
 step_configs/cl_step_config/executor

The executor of the step.

Depending on the value of *type*, different sub args are accepted.

type:

type: str (flag key)
 argument path: step_configs/
 cl_step_config/executor/type
 possible choices: *lebesgue_v2*,
dispatcher

The type of the executor.

When *type* is set to *lebesgue_v2*:

extra:

type: dict, optional
 argument path:
 step_configs/cl_step_config/
 executor[lebesgue_v2]/extra

The 'extra' key in the lebesgue executor. Note that we do not check if 'the dict provided to the 'extra' key is valid or not.

scass_type:

type: str, optional
argument path:
step_configs/cl_step_config/
executor[lebesgue_v2]/extra/
scass_type

The machine configuraiton.

program_id:

type: str, optional
argument path:
step_configs/cl_step_config/
executor[lebesgue_v2]/extra/
program_id

The ID of the program.

job_type:

type: str, optional, default:
container
argument path:
step_configs/cl_step_config/
executor[lebesgue_v2]/extra/
job_type

The type of job.

template_cover_cmd_escape_bug:

type: bool, optional, default: True
argument path:
step_configs/cl_step_config/
executor[lebesgue_v2]/extra/
template_cover_cmd_escape_bug

The key for hacking around a bug in
Lebesgue.

When `type` is set to dispatcher:

default_step_config:

type: dict, optional, default: {}
argument path: default_step_config

The default step configuration.

template_config:

type: dict, optional, default: {'image':
'dptechnology/dpgen2:latest'}
argument path: default_step_config/template_config

The configs passed to the PythonOPTemplate.

image:

type: str, optional, default:
dptechnology/dpgen2:latest

argument path:
default_step_config/template_config/image

The image to run the step.

timeout:

type: int | NoneType, optional, default: None

argument path:
default_step_config/template_config/timeout

The time limit of the OP. Unit is second.

retry_on_transient_error:

type: NoneType | bool, optional, default: None

argument path: default_step_config/
template_config/retry_on_transient_error

Retry the step if a TransientError is raised.

timeout_as_transient_error:

type: bool, optional, default: False

argument path: default_step_config/
template_config/timeout_as_transient_error

Treat the timeout as TransientError.

envs:

type: dict | NoneType, optional, default: None

argument path:
default_step_config/template_config/envs

The environmental variables.

continue_on_failed:

type: bool, optional, default: False

argument path: default_step_config/continue_on_failed

If continue the the step is failed (FatalError, TransientError, A certain number of retrial is reached...).

continue_on_num_success:

type: int | NoneType, optional, default: None

argument path: default_step_config/continue_on_num_success

Only in the sliced OP case. Continue the workflow if a certain number of the sliced jobs are successful.

continue_on_success_ratio:

type: NoneType | float, optional, default: None

argument path: default_step_config/continue_on_success_ratio

Only in the sliced OP case. Continue the workflow if a certain ratio of the sliced jobs are successful.

parallelism:

type: int | NoneType, optional, default: None

argument path: `default_step_config/parallelism`

The parallelism for the step

executor:

type: `dict | NoneType`, optional, default: `None`

argument path: `default_step_config/executor`

The executor of the step.

Depending on the value of *type*, different sub args are accepted.

type:

type: `str` (flag key)

argument path: `default_step_config/executor/type`

possible choices: *lebesgue_v2*, *dispatcher*

The type of the executor.

When *type* is set to *lebesgue_v2*:

extra:

type: `dict`, optional

argument path: `default_step_config/executor[lebesgue_v2]/extra`

The 'extra' key in the lebesgue executor. Note that we do not check if 'the *dict* provided to the 'extra' key is valid or not.

scass_type:

type: `str`, optional

argument path: `default_step_config/executor[lebesgue_v2]/extra/scass_type`

The machine configuraiton.

program_id:

type: `str`, optional

argument path: `default_step_config/executor[lebesgue_v2]/extra/program_id`

The ID of the program.

job_type:

type: `str`, optional, default: `container`

argument path: `default_step_config/executor[lebesgue_v2]/extra/job_type`

The type of job.

template_cover_cmd_escape_bug:

type: `bool`, optional, default: `True`

argument path: default_step_config/
executor[lebesgue_v2]/extra/
template_cover_cmd_escape_bug

The key for hacking around a bug in Lebesgue.

When `type` is set to `dispatcher`:

lebesgue_context_config:

type: dict | NoneType, optional, default: None
argument path: lebesgue_context_config

Configuration passed to dflow Lebesgue context

s3_config:

type: dict | NoneType, optional, default: None
argument path: s3_config

The S3 configuration passed to dflow

dflow_config:

type: dict | NoneType, optional, default: None
argument path: dflow_config

The configuration passed to dflow

DPGEN2 CONFIGURATIONS

5.1 Op configs

5.1.1 RunDPTrain

init_model_start_pref_v:

type: float, optional, default: 0.0
argument path: `init_model_start_pref_v`
The start virial prefactor in loss when init-model

init_model_start_pref_f:

type: int | float, optional, default: 100
argument path: `init_model_start_pref_f`
The start force prefactor in loss when init-model

init_model_start_pref_e:

type: float, optional, default: 0.1
argument path: `init_model_start_pref_e`
The start energy prefactor in loss when init-model

init_model_start_lr:

type: float, optional, default: 0.0001
argument path: `init_model_start_lr`
The start learning rate when init-model

init_model_numb_steps:

type: int, optional, default: 400000, alias: `init_model_stop_batch`
argument path: `init_model_numb_steps`
The number of training steps when init-model

init_model_old_ratio:

type: float, optional, default: 0.9
argument path: `init_model_old_ratio`
The frequency ratio of old data over new data

init_model_policy:

type: str, optional, default: no

argument path: `init_model_policy`

The policy of init-model training. It can be

- ‘no’: No init-model training. Traing from scratch.
- ‘yes’: Do init-model training.
- ‘old_data_larger_than:XXX’: Do init-model if the training data size of the previous model is larger than XXX. XXX is an int number.

5.1.2 RunLmp

command:

type: str, optional, default: `lmp`

argument path: `command`

The command of LAMMPS

5.1.3 RunVasp

out:

type: str, optional, default: `data`

argument path: `out`

The output dir name of labeled data. In *deepmd/npz* format provided by *dpdata*.

log:

type: str, optional, default: `vasp.log`

argument path: `log`

The log file name of VASP

command:

type: str, optional, default: `vasp`

argument path: `command`

The command of VASP

5.2 Alloy configs

fmt:

type: str, optional, default: `lammmps/lmp`

argument path: `fmt`

The format of file content

atom_pert_dist:

type: float, optional, default: `0.0`

argument path: `atom_pert_dist`

The distance of atomic position perturbation

cell_pert_frac:

type: float, optional, default: 0.0

argument path: cell_pert_frac

The fraction of cell perturbation

concentration:

type: list | NoneType, optional, default: None

argument path: concentration

The concentration of each element. If None all elements have the same concentration

numb_confs:

type: int, optional, default: 1

argument path: numb_confs

The number of configurations to generate

replicate:

type: list | NoneType, optional, default: None

argument path: replicate

The number of replicates in each direction

type_map:

type: list

argument path: type_map

The type map of the system

lattice:

type: list | tuple

argument path: lattice

The lattice. Should be a list providing ["lattice_type", lattice_const], or a list providing ["/path/to/dpdata/system", "fmt"]. The two styles are distinguished by the type of the second element.

5.3 Task group configs

task_group_configs:

type: dict

argument path: task_group_configs

Depending on the value of *type*, different sub args are accepted.

type:

type: str (flag key)

argument path: task_group_configs/type

possible choices: *lmp-md*, *lmp-template*

the type of the task group

When *type* is set to *lmp-md* (or its alias *lmp-npt*):

temps:

type: list, alias: *Ts*
argument path: task_group_configs[lmp-md]/temps
A list of temperatures in K. Also used to initialize the temperature

press:

type: list, optional, alias: *Ps*
argument path: task_group_configs[lmp-md]/press
A list of pressures in bar.

ens:

type: str, optional, default: nve, alias: *ensemble*
argument path: task_group_configs[lmp-md]/ens
The ensemble. Allowed options are 'nve', 'nvt', 'npt', 'npt-a', 'npt-t'. 'npt-a' stands for anisotropic box sampling and 'npt-t' stands for triclinic box sampling.

dt:

type: float, optional, default: 0.001
argument path: task_group_configs[lmp-md]/dt
The time step

nsteps:

type: int, optional, default: 100
argument path: task_group_configs[lmp-md]/nsteps
The number of steps

trj_freq:

type: int, optional, default: 10, aliases: *t_freq*, *trj_freq*, *traj_freq*
argument path: task_group_configs[lmp-md]/trj_freq
The number of steps

tau_t:

type: float, optional, default: 0.05
argument path: task_group_configs[lmp-md]/tau_t
The time scale of thermostat

tau_p:

type: float, optional, default: 0.5
argument path: task_group_configs[lmp-md]/tau_p
The time scale of barostat

pka_e:

type: NoneType | float, optional, default: None
argument path: task_group_configs[lmp-md]/pka_e
The energy of primary knock-on atom

neidelay:

type: int | NoneType, optional, default: None
argument path: task_group_configs[lmp-md]/neidelay
The delay of updating the neighbor list

no_pbc:

type: bool, optional, default: False
 argument path: task_group_configs[lmp-md]/no_pbc
 Not using the periodic boundary condition

use_clusters:

type: bool, optional, default: False
 argument path: task_group_configs[lmp-md]/use_clusters
 Calculate atomic model deviation

relative_f_epsilon:

type: NoneType | float, optional, default: None
 argument path: task_group_configs[lmp-md]/relative_f_epsilon
 Calculate relative force model deviation

relative_v_epsilon:

type: NoneType | float, optional, default: None
 argument path: task_group_configs[lmp-md]/relative_v_epsilon
 Calculate relative virial model deviation

When `type` is set to `lmp-template`:

lmp_template_fname:

type: str, aliases: *lmp_template*, *lmp*
 argument path:
 task_group_configs[lmp-template]/lmp_template_fname
 The file name of lammmps input template

plm_template_fname:

type: NoneType | str, optional, default: None, aliases: *plm_template*, *plm*
 argument path:
 task_group_configs[lmp-template]/plm_template_fname
 The file name of plumed input template

revisions:

type: dict, optional, default: {}
 argument path: task_group_configs[lmp-template]/revisions

traj_freq:

type: int, optional, default: 10, aliases: *t_freq*, *trj_freq*, *trj_freq*
 argument path: task_group_configs[lmp-template]/traj_freq
 The frequency of dumping configurations and thermodynamic states

5.4 Step configs

executor:

type: dict | NoneType, optional, default: None

argument path: `executor`

The executor of the step.

Depending on the value of *type*, different sub args are accepted.

type:

type: str (flag key)

argument path: `executor/type`

possible choices: *lebesgue_v2*, *dispatcher*

The type of the executor.

When *type* is set to *lebesgue_v2*:

extra:

type: dict, optional

argument path: `executor[lebesgue_v2]/extra`

The 'extra' key in the lebesgue executor. Note that we do not check if 'the *dict* provided to the 'extra' key is valid or not.

scass_type:

type: str, optional

argument path:

`executor[lebesgue_v2]/extra/scass_type`

The machine configuraiton.

program_id:

type: str, optional

argument path:

`executor[lebesgue_v2]/extra/program_id`

The ID of the program.

job_type:

type: str, optional, default: container

argument path:

`executor[lebesgue_v2]/extra/job_type`

The type of job.

template_cover_cmd_escape_bug:

type: bool, optional, default: True

argument path: `executor[lebesgue_v2]/extra/`

`template_cover_cmd_escape_bug`

The key for hacking around a bug in Lebesgue.

When *type* is set to *dispatcher*:

parallelism:

type: int | NoneType, optional, default: None
 argument path: parallelism

The parallelism for the step

continue_on_success_ratio:

type: NoneType | float, optional, default: None
 argument path: continue_on_success_ratio

Only in the sliced OP case. Continue the workflow if a certain ratio of the sliced jobs are successful.

continue_on_num_success:

type: int | NoneType, optional, default: None
 argument path: continue_on_num_success

Only in the sliced OP case. Continue the workflow if a certain number of the sliced jobs are successful.

continue_on_failed:

type: bool, optional, default: False
 argument path: continue_on_failed

If continue the the step is failed (FatalError, TransientError, A certain number of retrial is reached...).

template_config:

type: dict, optional, default: {'image': 'dptechnology/dpgen2:latest'}
 argument path: template_config

The configs passed to the PythonOPTemplate.

image:

type: str, optional, default: dptechnology/dpgen2:latest
 argument path: template_config/image

The image to run the step.

timeout:

type: int | NoneType, optional, default: None
 argument path: template_config/timeout

The time limit of the OP. Unit is second.

retry_on_transient_error:

type: NoneType | bool, optional, default: None
 argument path: template_config/retry_on_transient_error

Retry the step if a TransientError is raised.

timeout_as_transient_error:

type: bool, optional, default: False
 argument path: template_config/timeout_as_transient_error

Treat the timeout as TransientError.

envs:

type: dict | NoneType, optional, default: None

argument path: `template_config/envs`
The environmental variables.

DEVELOPERS' GUIDE

- The concurrent learning algorithm
- Overview of the DPGEN2 implementation
- The DPGEN2 workflow
- How to contribute

6.1 The concurrent learning algorithm

DPGEN2 implements the concurrent learning algorithm named DP-GEN, described in [this paper](#). It is noted that other types of workflows, like active learning, should be easily implemented within the infrastructure of DPGEN2.

The DP-GEN algorithm is iterative. In each iteration, four steps are consecutively executed: training, exploration, selection, and labeling.

1. **Training.** A set of DP models are trained with the same dataset and the same hyperparameters. The only difference is the random seed initializing the model parameters.
2. **Exploration.** One of the DP models is used to explore the configuration space. The strategy of exploration highly depends on the purpose of the application case of the model. The simulation technique for exploration can be molecular dynamics, Monte Carlo, structure search/optimization, enhanced sampling, or any combination of them. Current DPGEN2 only supports exploration based on molecular simulation platform [LAMMPS](#).
3. **Selection.** Not all the explored configurations are labeled, rather, the model prediction errors on the configurations are estimated by the *model deviation*, which is defined as the standard deviation in predictions of the set of the models. The critical configurations with large and not-that-large errors are selected for labeling. The configurations with very large errors are not selected because the large error is usually caused by non-physical configurations, e.g. overlapping atoms.
4. **Labeling.** The selected configurations are labeled with energy, forces, and virial calculated by a method of first-principles accuracy. The usually used method is the [density functional theory](#) implemented in [VASP](#), [Quantum Espresso](#), [CP2K](#), and etc.. The labeled data are finally added to the training dataset to start the next iteration.

In each iteration, the quality of the model is improved by selecting and labeling more critical data and adding them to the training dataset. The DP-GEN iteration is converged when no more critical data can be selected.

6.2 Overview of the DPGEN2 Implementation

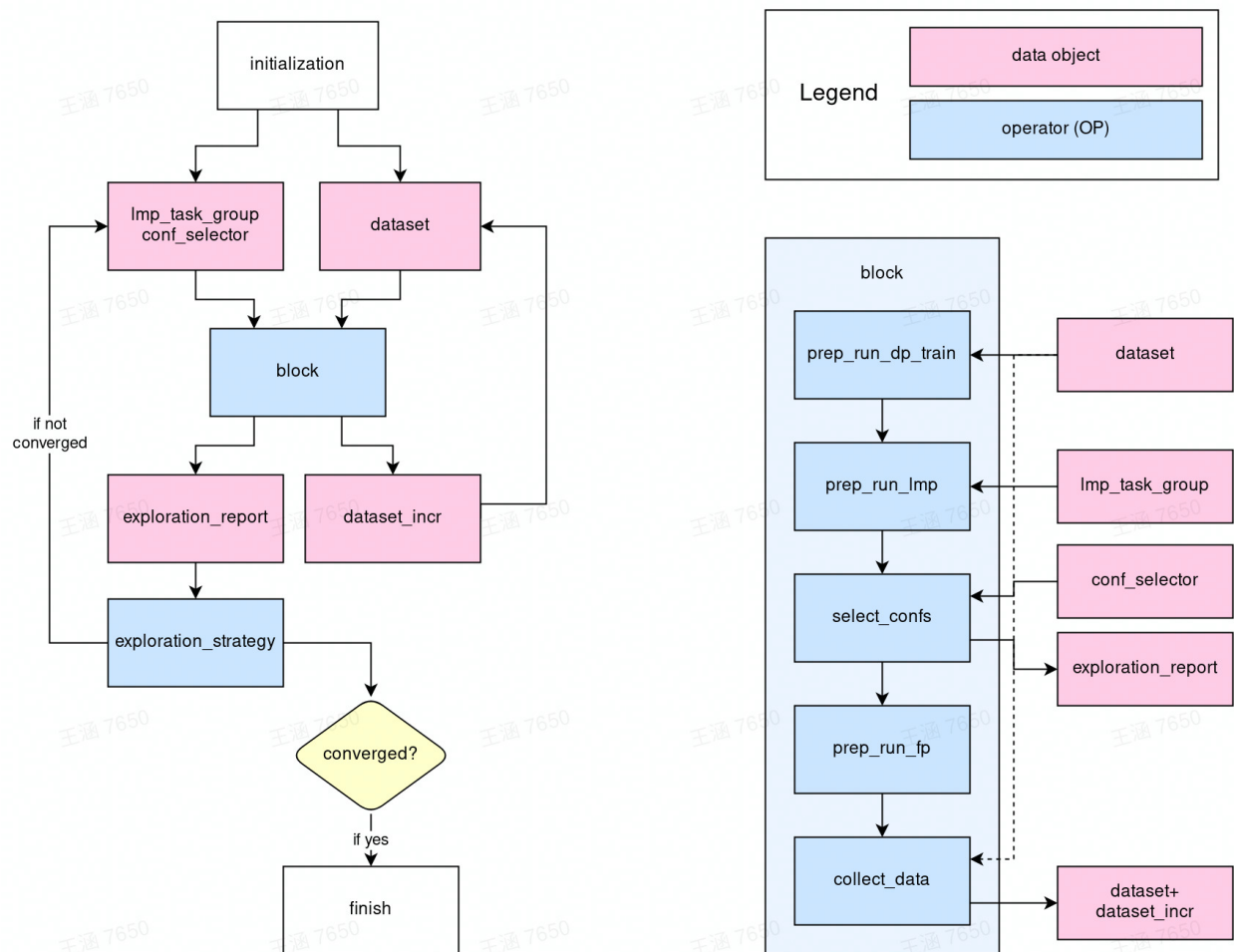
The implementation DPGEN2 is based on the workflow platform `dflow`, which is a python wrapper of the `Argo Workflows`, an open-source container-native workflow engine on `Kubernetes`.

The DP-GEN algorithm is conceptually modeled as a computational graph. The implementation is then considered as two lines: the operators and the workflow.

1. **Operators.** Operators are implemented in Python v3. The operators should be implemented and tested *without* the workflow.
2. **Workflow.** Workflow is implemented on `dflow`. Ideally, the workflow is implemented and tested with all operators mocked.

6.3 The DPGEN2 workflow

The workflow of DPGEN2 is illustrated in the following figure



In the center is the `block` operator, which is a super-OP (an OP composed by several OPs) for one DP-GEN iteration, i.e. the super-OP of the training, exploration, selection, and labeling steps. The inputs of the `block` OP are `Imp_task_group`, `conf_selector` and `dataset`.

- `Imp_task_group`: definition of a group of LAMMPS tasks that explore the configuration space.

- `conf_selector`: defines the rule by which the configurations are selected for labeling.
- `dataset`: the training dataset.

The outputs of the block OP are

- `exploration_report`: a report recording the result of the exploration. For example, how many configurations are accurate enough and how many are selected as candidates for labeling.
- `dataset_incr`: the increment of the training dataset.

The `dataset_incr` is added to the training dataset.

The `exploration_report` is passed to the `exploration_strategy` OP. The `exploration_strategy` implements the strategy of exploration. It reads the `exploration_report` generated by each iteration (`block`), then tells if the iteration is converged. If not, it generates a group of LAMMPS tasks (`lmp_task_group`) and the criteria of selecting configurations (`conf_selector`). The `lmp_task_group` and `conf_selector` are then used by `block` of the next iteration. The iteration closes.

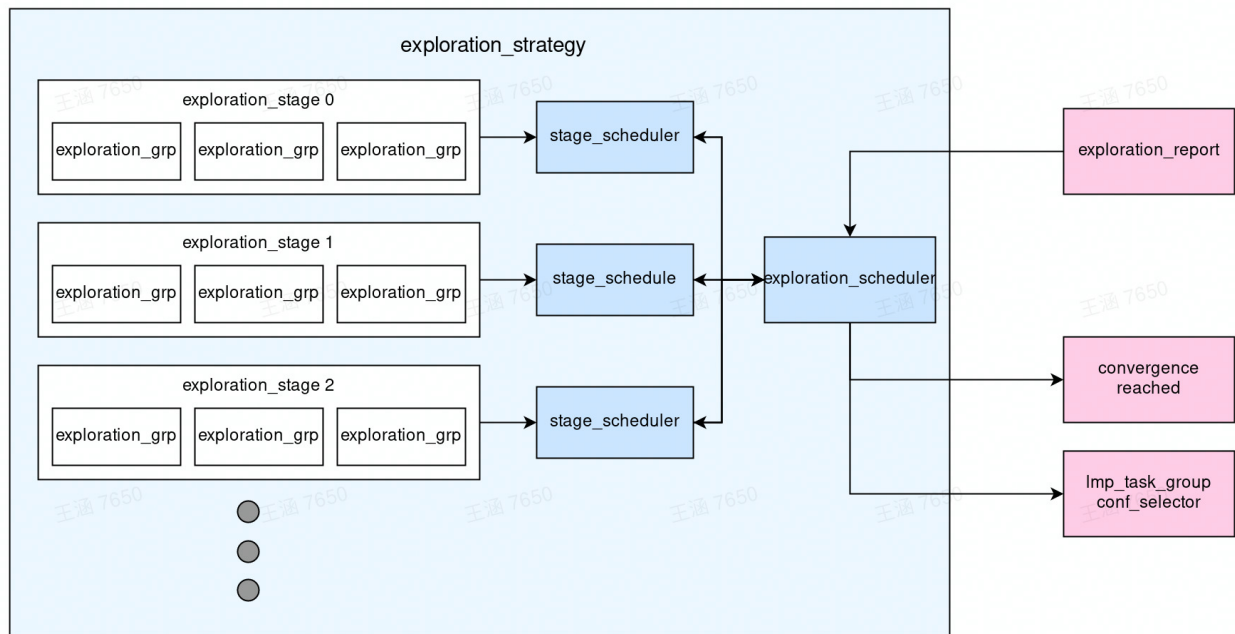
6.3.1 Inside the block operator

The inside of the super-OP block is displayed on the right-hand side of the figure. It contains the following steps to finish one DPGEN iteration

- `prep_run_dp_train`: prepares training tasks of DP models and runs them.
- `prep_run_lmp`: prepares the LAMMPS exploration tasks and runs them.
- `select_confs`: selects configurations for labeling from the explored configurations.
- `prep_run_fp`: prepares and runs first-principles tasks.
- `collect_data`: collects the `dataset_incr` and adds it to the dataset.

6.3.2 The exploration strategy

The exploration strategy defines how the configuration space is explored by the concurrent learning algorithm. The design of the exploration strategy is graphically illustrated in the following figure. The exploration is composed of stages. Only the DP-GEN exploration is converged at one stage (no configuration with a large error is explored), the exploration goes to the next iteration. The whole procedure is controlled by `exploration_scheduler`. Each stage has its schedule, which talks to the `exploration_scheduler` to generate the schedule for the DP-GEN algorithm.



Some concepts are explained below:

- **Exploration group.** A group of LAMMPS tasks shares similar settings. For example, a group of NPT MD simulations in a certain thermodynamic space.
- **Exploration stage.** The `exploration_stage` contains a list of exploration groups. It contains all information needed to define the `lmp_task_group` used by the block in the DP-GEN iteration.
- **Stage scheduler.** It guarantees the convergence of the DP-GEN algorithm in each `exploration_stage`. If the exploration is not converged, the `stage_scheduler` generates `lmp_task_group` and `conf_selector` from the `exploration_stage` for the next iteration (probably with a different initial condition, i.e. different initial configurations and randomly generated initial velocity).
- **Exploration scheduler.** The scheduler for the DP-GEN algorithm. When DP-GEN is converged in one of the stages, it goes to the next stage until all planned stages are used.

6.4 How to contribute

Anyone interested in the DPGEN2 project may contribute OPs, workflows, and exploration strategies.

- To contribute OPs, one may check the *guide on writing operators*
- To contribute workflows, one may take the DP-GEN workflow as an example. It is implemented in `dp-gen2/flow/dp-gen_loop.py` and tested with all operators mocked in `test/test_dp-gen_loop.py`
- To contribute the exploration strategy, one may check the *guide on writing exploration strategies*

OPERATORS

There are two types of OPs in DPGEN2

- OP. An execution unit the the workflow. It can be roughly viewed as a piece of Python script taking some input and gives some outputs. An OP cannot be used in the `dflow` until it is embedded in a super-OP.
- Super-OP. An execution unite that is composed by one or more OP and/or super-OPs.

Technically, OP is a Python class derived from `dflow.python.OP`. It serves as the `PythonOPTemplate` of `dflow.Step`.

The super-OP is a Python class derived from `dflow.Steps`. It contains `dflow.Steps` as building blocks, and can be used as OP template to generate a `dflow.Step`. The explanation of the concepts `dflow.Step` and `dflow.Steps`, one may refer to the [manual of dflow](#).

7.1 The super-OP `PrepRunDPTrain`

In the following we will take the `PrepRunDPTrain` super-OP as an example to illustrate how to write OPs in DPGEN2.

`PrepRunDPTrain` is a super-OP that prepares several DeePMD-kit training tasks, and submit all of them. This super-OP is composed by two `dflow.Steps` building from `dflow.python.OPs` `PrepDPTrain` and `RunDPTrain`.

```
from dflow import (
    Step,
    Steps,
)
from dflow.python import(
    PythonOPTemplate,
    OP,
    Slices,
)

class PrepRunDPTrain(Steps):
    def __init__(
        self,
        name : str,
        prep_train_op : OP,
        run_train_op : OP,
        prep_train_image : str = "dflow:v1.0",
        run_train_image : str = "dflow:v1.0",
    ):
        ...
```

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```

self = _prep_run_dp_train(
    self,
    self.step_keys,
    prep_train_op,
    run_train_op,
    prep_train_image = prep_train_image,
    run_train_image = run_train_image,
)

```

The construction of the `PrepRunDPTrain` takes prepare-training OP and run-training OP and their docker images as input, and implemented in internal method `_prep_run_dp_train`.

```

def _prep_run_dp_train(
    train_steps,
    step_keys,
    prep_train_op : OP = PrepDPTrain,
    run_train_op : OP = RunDPTrain,
    prep_train_image : str = "dflow:v1.0",
    run_train_image : str = "dflow:v1.0",
):
    prep_train = Step(
        ...
        template=PythonOPTemplate(
            prep_train_op,
            image=prep_train_image,
            ...
        ),
        ...
    )
    train_steps.add(prepare_train)

    run_train = Step(
        ...
        template=PythonOPTemplate(
            run_train_op,
            image=run_train_image,
            ...
        ),
        ...
    )
    train_steps.add(run_train)

    train_steps.outputs.artifacts["scripts"]._from = run_train.outputs.artifacts["script
↪"]
    train_steps.outputs.artifacts["models"]._from = run_train.outputs.artifacts["model"]
    train_steps.outputs.artifacts["logs"]._from = run_train.outputs.artifacts["log"]
    train_steps.outputs.artifacts["lcurves"]._from = run_train.outputs.artifacts["lcurve
↪"]

    return train_steps

```

In `_prep_run_dp_train`, two instances of `dflow.Step`, i.e. `prep_train` and `run_train`, generated from `prep_train_op` and `run_train_op`, respectively, are added to `train_steps`. Both of `prep_train_op` and

`run_train_op` are OPs (python classes derived from `dflow.python.OPs`) that will be illustrated later. `train_steps` is an instance of `dflow.Steps`. The outputs of the second OP `run_train` are assigned to the outputs of the `train_steps`.

The `prep_train` prepares a list of paths, each of which contains all necessary files to start a DeePMD-kit training tasks.

The `run_train` slices the list of paths, and assign each item in the list to a DeePMD-kit task. The task is executed by `run_train_op`. This is a very nice feature of `dflow`, because the developer only needs to implement how one DeePMD-kit task is executed, and then all the items in the task list will be executed **in parallel**. See the following code to see how it works

```
run_train = Step(
    'run-train',
    template=PythonOPTemplate(
        run_train_op,
        image=run_train_image,
        slices = Slices(
            "int('{{item}}')",
            input_parameter = ["task_name"],
            input_artifact = ["task_path", "init_model"],
            output_artifact = ["model", "lcurve", "log", "script"],
        ),
    ),
    parameters={
        "config" : train_steps.inputs.parameters["train_config"],
        "task_name" : prep_train.outputs.parameters["task_names"],
    },
    artifacts={
        'task_path' : prep_train.outputs.artifacts['task_paths'],
        "init_model" : train_steps.inputs.artifacts['init_models'],
        "init_data": train_steps.inputs.artifacts['init_data'],
        "iter_data": train_steps.inputs.artifacts['iter_data'],
    },
    with_sequence=argo_sequence(argo_len(prep_train.outputs.parameters["task_names
↪"]), format=train_index_pattern),
    key = step_keys['run-train'],
)
```

The input parameter "task_names" and artifacts "task_paths" and "init_model" are sliced and supplied to each DeePMD-kit task. The output artifacts of the tasks ("model", "lcurve", "log" and "script") are stacked in the same order as the input lists. These lists are assigned as the outputs of `train_steps` by

```
train_steps.outputs.artifacts["scripts"]._from = run_train.outputs.artifacts["script
↪"]
train_steps.outputs.artifacts["models"]._from = run_train.outputs.artifacts["model"]
train_steps.outputs.artifacts["logs"]._from = run_train.outputs.artifacts["log"]
train_steps.outputs.artifacts["lcurves"]._from = run_train.outputs.artifacts["lcurve
↪"]
```

7.2 The OP RunDPTrain

We will take RunDPTrain as an example to illustrate how to implement an OP in DPGEN2. The source code of this OP is found [here](#)

Firstly of all, an OP should be implemented as a derived class of `dflow.python.OP`.

The `dflow.python.OP` requires static type define for the input and output variables, i.e. the signatures of an OP. The input and output signatures of the `dflow.python.OP` are given by classmethods `get_input_sign` and `get_output_sign`.

```

from dflow.python import (
    OP,
    OPIO,
    OPIOSign,
    Artifact,
)
class RunDPTrain(OP):
    @classmethod
    def get_input_sign(cls):
        return OPIOSign({
            "config" : dict,
            "task_name" : str,
            "task_path" : Artifact(Path),
            "init_model" : Artifact(Path),
            "init_data" : Artifact(List[Path]),
            "iter_data" : Artifact(List[Path]),
        })

    @classmethod
    def get_output_sign(cls):
        return OPIOSign({
            "script" : Artifact(Path),
            "model" : Artifact(Path),
            "lcurve" : Artifact(Path),
            "log" : Artifact(Path),
        })

```

All items not defined as `Artifact` are treated as parameters of the OP. The concept of parameter and artifact are explained in the [dflow document](#). To be short, the artifacts can be `pathlib.Path` or a list of `pathlib.Path`. The artifacts are passed by the file system. Other data structures are treated as parameters, they are passed as variables encoded in `str`. Therefore, a large amount of information should be stored in artifacts, otherwise they can be considered as parameters.

The operation of the OP is implemented in method `execute`, and are run in docker containers. Again taking the `execute` method of `RunDPTrain` as an example

```

@OP.exec_sign_check
def execute(
    self,
    ip : OPIO,
) -> OPIO:
    ...
    task_name = ip['task_name']

```

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```

task_path = ip['task_path']
init_model = ip['init_model']
init_data = ip['init_data']
iter_data = ip['iter_data']
...
work_dir = Path(task_name)
...
# here copy all files in task_path to work_dir
...
with set_directory(work_dir):
    fplog = open('train.log', 'w')
    def clean_before_quit():
        fplog.close()
    # train model
    command = ['dp', 'train', train_script_name]
    ret, out, err = run_command(command)
    if ret != 0:
        clean_before_quit()
        raise FatalError('dp train failed')
    fplog.write(out)
    # freeze model
    ret, out, err = run_command(['dp', 'freeze', '-o', 'frozen_model.pb'])
    if ret != 0:
        clean_before_quit()
        raise FatalError('dp freeze failed')
    fplog.write(out)
    clean_before_quit()

return OPIO({
    "script" : work_dir / train_script_name,
    "model" : work_dir / "frozen_model.pb",
    "lcurve" : work_dir / "lcurve.out",
    "log" : work_dir / "train.log",
})

```

The inputs and outputs variables are recorded in data structure `dflow.python.OPIO`, which is initialized by a Python dict. The keys in the input/output dict, and the types of the input/output variables will be checked against their signatures by decorator `OP.exec_sign_check`. If any key or type does not match, an exception will be raised.

It is noted that all input artifacts of the OP are read-only, therefore, the first step of the `RunDPTrain.execute` is to copy all necessary input files from the directory `task_path` prepared by `PrepDPTrain` to the working directory `work_dir`.

`with_directory` method creates the `work_dir` and swithes to the directory before the execution, and then exits the directoy when the task finishes or an error is raised.

In what follows, the training and model frozen bash commands are executed consecutively. The return code is check and a `FatalError` is raised if a non-zero code is detected.

Finally the trained model file, input script, learning curve file and the log file are recored in a `dflow.python.OPIO` and returned.

EXPLORATION

DPGEN2 allows developers to contribute exploration strategies. The exploration strategy defines how the configuration space is explored by molecular simulations in each DPGEN iteration. Notice that we are not restricted to molecular dynamics, any molecular simulation is, in principle, allowed. For example, Monte Carlo, enhanced sampling, structure optimization, and so on.

An exploration strategy takes the history of exploration as input, and gives back DPGEN the exploration tasks (we call it **task group**) and the rule to select configurations from the trajectories generated by the tasks (we call it **configuration selector**).

One can contribute from three aspects:

- The stage scheduler
- The exploration task groups
- Configuration selector

8.1 Stage scheduler

The stage scheduler takes an exploration report passed from the exploration scheduler as input, and tells the exploration scheduler if the exploration in the stage is converged, if not, returns a group of exploration tasks and a configuration selector that are used in the next DPGEN iteration.

Detailed explanation of the concepts are found here.

All the stage schedulers are derived from the abstract base class `StageScheduler`. The only interface to be implemented is `StageScheduler.plan_next_iteration`. One may check the doc string for the explanation of the interface.

```
class StageScheduler(ABC):
    """
    The scheduler for an exploration stage.
    """

    @abstractmethod
    def plan_next_iteration(
        self,
        hist_reports : List[ExplorationReport],
        report : ExplorationReport,
        confs : List[Path],
    ) -> Tuple[bool, ExplorationTaskGroup, ConfSelector] :
        """
```

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```

    Make the plan for the next iteration of the stage.

    It checks the report of the current and all historical iterations of the stage,
    and tells if the iterations are converged.
    If not converged, it will plan the next iteration for the stage.

    Parameters
    -----
    hist_reports: List[ExplorationReport]
        The historical exploration report of the stage. If this is the first
        ↪ iteration of the stage, this list is empty.
    report : ExplorationReport
        The exploration report of this iteration.
    confs: List[Path]
        A list of configurations generated during the exploration. May be used to
        ↪ generate new configurations for the next iteration.

    Returns
    -----
    converged: bool
        If the stage converged.
    task: ExplorationTaskGroup
        A `ExplorationTaskGroup` defining the exploration of the next iteration.
        ↪ Should be `None` if the stage is converged.
    conf_selector: ConfSelector
        The configuration selector for the next iteration. Should be `None` if the
        ↪ stage is converged.

    """

```

One may check more details on the exploration task group and the configuration selector.

8.2 Exploration task groups

DPGEN2 defines a python class `ExplorationTask` to manage all necessary files needed to run an exploration task. It can be used as the example provided in the doc string.

```

class ExplorationTask():
    """Define the files needed by an exploration task.

    Examples
    -----
    >>> # this example dumps all files needed by the task.
    >>> files = exploration_task.files()
    ... for file_name, file_content in files.items():
    ...     with open(file_name, 'w') as fp:
    ...         fp.write(file_content)

    """

```

A collection of the exploration tasks is called exploration task group. All task groups are derived from the base class

ExplorationTaskGroup. The exploration task group can be viewed as a list of ExplorationTasks, one may get the list by using property ExplorationTaskGroup.task_list. One may add tasks, or ExplorationTaskGroup to the group by methods ExplorationTaskGroup.add_task and ExplorationTaskGroup.add_group, respectively.

```
class ExplorationTaskGroup(Sequence):
    @property
    def task_list(self) -> List[ExplorationTask]:
        """Get the `list` of `ExplorationTask`"""
        ...

    def add_task(self, task: ExplorationTask):
        """Add one task to the group."""
        ...

    def add_group(
        self,
        group : 'ExplorationTaskGroup',
    ):
        """Add another group to the group."""
        ...
```

An example of generating a group of NPT MD simulations may illustrate how to implement the ExplorationTaskGroups.

8.3 Configuration selector

The configuration selectors are derived from the abstract base class ConfSelector

```
class ConfSelector(ABC):
    """Select configurations from trajectory and model deviation files.
    """
    @abstractmethod
    def select (
        self,
        trajs : List[Path],
        model_devis : List[Path],
        traj_fmt : str = 'deepmd/npz',
        type_map : List[str] = None,
    ) -> Tuple[List[ Path ], ExplorationReport]:
```

The abstractmethod to implement is ConfSelector.select. trajs and model_devis are lists of files that recording the simulations trajectories and model deviations respectively. traj_fmt and type_map are parameters that may be needed for loading the trajectories by dpdata.

The ConfSelector.select returns a Path, each of which can be treated as a dpdata.MultiSystems, and a ExplorationReport.

An example of selecting configurations from LAMMPS trajectories may illustrate how to implement the ConfSelectors.

9.1 dpngen2 package

9.1.1 Subpackages

dpngen2.entrypoint package

Submodules

dpngen2.entrypoint.download module

`dpngen2.entrypoint.download.download`(*workflow_id*, *wf_config*: *Optional*[*Dict*] = {}, *wf_keys*: *Optional*[*List*] = *None*, *prefix*: *Optional*[*str*] = *None*)

dpngen2.entrypoint.main module

`dpngen2.entrypoint.main.main`()

`dpngen2.entrypoint.main.main_parser`() → *ArgumentParser*

DPGEN2 commandline options argument parser.

Returns

`argparse.ArgumentParser`

the argument parser

Notes

This function is used by documentation.

`dpngen2.entrypoint.main.parse_args`(*args*: *Optional*[*List*[*str*]] = *None*)

DPGEN2 commandline options argument parsing.

Parameters

`args`: **`List`[*str*]**

list of command line arguments, main purpose is testing default option `None` takes arguments from `sys.argv`

dpgen2.entrypoint.showkey module

`dpgen2.entrypoint.showkey.showkey(wf_id, wf_config)`

dpgen2.entrypoint.status module

`dpgen2.entrypoint.status.status(workflow_id, wf_config: Optional[Dict] = {})`

dpgen2.entrypoint.submit module

`dpgen2.entrypoint.submit.expand_idx(in_list)`

`dpgen2.entrypoint.submit.expand_sys_str(root_dir: Union[str, Path]) → List[str]`

`dpgen2.entrypoint.submit.get_kspacing_kgamma_from_incar(fname)`

`dpgen2.entrypoint.submit.get_resubmit_keys(wf)`

```

dpgen2.entrypoint.submit.make_concurrent_learning_op(train_style: str = 'dp', explore_style: str =
'imp', fp_style: str = 'vasp', prep_train_config:
dict = {'continue_on_failed': False,
'continue_on_num_success': None,
'continue_on_success_ratio': None, 'executor':
None, 'parallelism': None, 'template_config':
{'envs': None, 'image':
'dptechnology/dpgen2:latest',
'retry_on_transient_error': None, 'timeout':
None, 'timeout_as_transient_error': False}},
run_train_config: dict = {'continue_on_failed':
False, 'continue_on_num_success': None,
'continue_on_success_ratio': None, 'executor':
None, 'parallelism': None, 'template_config':
{'envs': None, 'image':
'dptechnology/dpgen2:latest',
'retry_on_transient_error': None, 'timeout':
None, 'timeout_as_transient_error': False}},
prep_explore_config: dict =
{'continue_on_failed': False,
'continue_on_num_success': None,
'continue_on_success_ratio': None, 'executor':
None, 'parallelism': None, 'template_config':
{'envs': None, 'image':
'dptechnology/dpgen2:latest',
'retry_on_transient_error': None, 'timeout':
None, 'timeout_as_transient_error': False}},
run_explore_config: dict =
{'continue_on_failed': False,
'continue_on_num_success': None,
'continue_on_success_ratio': None, 'executor':
None, 'parallelism': None, 'template_config':
{'envs': None, 'image':
'dptechnology/dpgen2:latest',
'retry_on_transient_error': None, 'timeout':
None, 'timeout_as_transient_error': False}},
prep_fp_config: dict = {'continue_on_failed':
False, 'continue_on_num_success': None,
'continue_on_success_ratio': None, 'executor':
None, 'parallelism': None, 'template_config':
{'envs': None, 'image':
'dptechnology/dpgen2:latest',
'retry_on_transient_error': None, 'timeout':
None, 'timeout_as_transient_error': False}},
run_fp_config: dict = {'continue_on_failed':
False, 'continue_on_num_success': None,
'continue_on_success_ratio': None, 'executor':
None, 'parallelism': None, 'template_config':
{'envs': None, 'image':
'dptechnology/dpgen2:latest',
'retry_on_transient_error': None, 'timeout':
None, 'timeout_as_transient_error': False}},
select_confs_config: dict =
{'continue_on_failed': False,
'continue_on_num_success': None,
'continue_on_success_ratio': None, 'executor':
None, 'parallelism': None, 'template_config':
{'envs': None, 'image':
'dptechnology/dpgen2:latest',
'retry_on_transient_error': None, 'timeout':

```

```
dpngen2.entrypoint.submit.make_conf_list(conf_list, type_map, fmt='vasp/poscar')
dpngen2.entrypoint.submit.make_naive_exploration_scheduler(config, old_style=False)
dpngen2.entrypoint.submit.print_list_steps(steps)
dpngen2.entrypoint.submit.resubmit_concurrent_learning(wf_config, wfid, list_steps=False,
                                                       reuse=None, old_style=False)
dpngen2.entrypoint.submit.submit_concurrent_learning(wf_config, reuse_step=None, old_style=False)
dpngen2.entrypoint.submit.successful_step_keys(wf)
dpngen2.entrypoint.submit.wf_global_workflow(wf_config)
dpngen2.entrypoint.submit.workflow_concurrent_learning(config: Dict, old_style: bool = False)
```

dpngen2.entrypoint.submit_args module

```
dpngen2.entrypoint.submit_args.default_step_config_args()
dpngen2.entrypoint.submit_args.dflow_conf_args()
dpngen2.entrypoint.submit_args.dp_train_args()
dpngen2.entrypoint.submit_args.dpngen_step_config_args(default_config)
dpngen2.entrypoint.submit_args.gen_doc(*, make_anchor=True, make_link=True, **kwargs)
dpngen2.entrypoint.submit_args.input_args()
dpngen2.entrypoint.submit_args.lebesgue_conf_args()
dpngen2.entrypoint.submit_args.lmp_args()
dpngen2.entrypoint.submit_args.normalize(data)
dpngen2.entrypoint.submit_args.submit_args(default_step_config={'continue_on_failed': False,
                                                                'continue_on_num_success': None,
                                                                'continue_on_success_ratio': None, 'executor': None,
                                                                'parallelism': None, 'template_config': {'envs': None, 'image':
                                                                'dptechnology/dpugen2:latest', 'retry_on_transient_error':
                                                                None, 'timeout': None, 'timeout_as_transient_error': False}})
dpngen2.entrypoint.submit_args.variant_explore()
dpngen2.entrypoint.submit_args.variant_fp()
dpngen2.entrypoint.submit_args.variant_train()
dpngen2.entrypoint.submit_args.vasp_args()
```


dpngen2.entrypoint.watch module

`dpngen2.entrypoint.watch.update_finished_steps`(*wf*, *finished_keys*: *Optional[List[str]] = None*,
download: *Optional[bool] = False*, *watching_keys*:
Optional[List[str]] = None, *prefix*: *Optional[str] = None*)

`dpngen2.entrypoint.watch.watch`(*workflow_id*, *wf_config*: *Optional[Dict] = {}*, *watching_keys*: *Optional[List]*
= ['prep-run-train', 'prep-run-lmp', 'prep-run-fp', 'collect-data'], *frequency*:
float = 600.0, *download*: *Optional[bool] = False*, *prefix*: *Optional[str] = None*)

dpngen2.exploration package**Subpackages****dpngen2.exploration.report package****Submodules****dpngen2.exploration.report.naive_report module**

`class dpngen2.exploration.report.naive_report.NaiveExplorationReport`(*counter_f*, *counter_v*)
Bases: *ExplorationReport*

Methods

accurate_ratio	
calculate_ratio	
candidate_ratio	
failed_ratio	
ratio	

accurate_ratio(*tag=None*) → float

static calculate_ratio(*cc*, *ca*, *cf*)

candidate_ratio(*tag=None*) → float

failed_ratio(*tag=None*) → float

ratio(*quantity: str*, *item: str*) → float

dpgen2.exploration.report.report module

class dpgen2.exploration.report.report.**ExplorationReport**

Bases: *ABC*

Methods

accurate_ratio	
candidate_ratio	
failed_ratio	

abstract `accurate_ratio(tag=None)` → float

abstract `candidate_ratio(tag=None)` → float

abstract `failed_ratio(tag=None)` → float

dpgen2.exploration.report.trajs_report module

class dpgen2.exploration.report.trajs_report.**TrajsExplorationReport**

Bases: *ExplorationReport*

Methods

<code>get_candidates([max_nframes])</code>	Get candidates.
<code>record_traj(id_f_accu, id_f_cand, id_f_fail, ...)</code>	Record one trajectory.

accurate_ratio	
candidate_ratio	
clear	
failed_ratio	

accurate_ratio(*tag=None*)

candidate_ratio(*tag=None*)

clear()

failed_ratio(*tag=None*)

get_candidates(*max_nframes: Optional[int] = None*) → List[Tuple[int, int]]

Get candidates. If number of candidates is larger than *max_nframes*, then randomly pick *max_nframes* frames from the candidates.

Parameters

max_nframes int

The maximal number of frames of candidates.

Returns

cand_frames List[Tuple[int,int]]

Candidate frames. A list of tuples: [(traj_idx, frame_idx), ...]

record_traj(*id_f_accu, id_f_cand, id_f_fail, id_v_accu, id_v_cand, id_v_fail*)

Record one trajectory. inputs are the indexes of candidate, accurate and failed frames.

dpgen2.exploration.scheduler package

Submodules

dpgen2.exploration.scheduler.convergence_check_stage_scheduler module

class dpgen2.exploration.scheduler.convergence_check_stage_scheduler.**ConvergenceCheckStageScheduler**(*stage*)

Ex-
plo-
ratio
se-
lec-
tor:
Con
f-
S-
e-
lec-
tor,
conv
float
=
0.9,
max.
Op-
tion
=
Non
fa-
tal_e
bool
=
True

Bases: *StageScheduler*

Methods

<i>converged</i> ()	Tell if the stage is converged
<i>plan_next_iteration</i> ([report, trajs])	Make the plan for the next iteration of the stage.

complete	
reached_max_iteration	

complete()

converged()

Tell if the stage is converged

Returns

converged bool
the convergence

plan_next_iteration(*report: Optional[ExplorationReport] = None, trajs: Optional[List[Path]] = None*)
→ Tuple[bool, Optional[ExplorationTaskGroup], Optional[ConfSelector]]

Make the plan for the next iteration of the stage.

It checks the report of the current and all historical iterations of the stage, and tells if the iterations are converged. If not converged, it will plan the next iteration for the stage.

Parameters**hist_reports: List[ExplorationReport]**

The historical exploration report of the stage. If this is the first iteration of the stage, this list is empty.

report

[ExplorationReport] The exploration report of this iteration.

confs: List[Path]

A list of configurations generated during the exploration. May be used to generate new configurations for the next iteration.

Returns**stg_complete: bool**

If the stage completed. Two cases may happen: 1. converged. 2. when not fatal_at_max, not converged but reached max number of iterations.

task: ExplorationTaskGroup

A *ExplorationTaskGroup* defining the exploration of the next iteration. Should be *None* if the stage is converged.

conf_selector: ConfSelector

The configuration selector for the next iteration. Should be *None* if the stage is converged.

reached_max_iteration()**dpgen2.exploration.scheduler.scheduler module****class dpgen2.exploration.scheduler.scheduler.ExplorationScheduler**

Bases: `object`

The exploration scheduler.

Methods

<code>add_stage_scheduler(stage_scheduler)</code>	Add stage scheduler.
<code>complete()</code>	Tell if all stages are converged.
<code>get_convergence_ratio()</code>	Get the accurate, candidate and failed ratios of the iterations
<code>get_iteration()</code>	Get the index of the current iteration.
<code>get_stage()</code>	Get the index of current stage.
<code>get_stage_of_iterations()</code>	Get the stage index and the index in the stage of iterations.
<code>plan_next_iteration([report, trajs])</code>	Make the plan for the next DPGEN iteration.

print_convergence	
-------------------	--

add_stage_scheduler(*stage_scheduler*: StageScheduler)

Add stage scheduler.

All added schedulers can be treated as a *list* (order matters). Only one stage is converged, the iteration goes to the next iteration.

Parameters

stage_scheduler: StageScheduler
The added stage scheduler

complete()

Tell if all stages are converged.

get_convergence_ratio()

Get the accurate, candidate and failed ratios of the iterations

Returns

accu np.ndarray

The accurate ratio. length of array the same as # iterations.

cand np.ndarray

The candidate ratio. length of array the same as # iterations.

fail np.ndarray

The failed ration. length of array the same as # iterations.

get_iteration()

Get the index of the current iteration.

Iteration index increase when *self.plan_next_iteration* returns valid *lmp_task_grp* and *conf_selector* for the next iteration.

get_stage()

Get the index of current stage.

Stage index increases when the previous stage converges. Usually called after *self.plan_next_iteration*.

get_stage_of_iterations()

Get the stage index and the index in the stage of iterations.

plan_next_iteration(*report*: Optional[ExplorationReport] = None, *trajs*: Optional[List[Path]] = None)
→ Tuple[bool, Optional[ExplorationTaskGroup], Optional[ConfSelector]]

Make the plan for the next DPGEN iteration.

Parameters

report

[ExplorationReport] The exploration report of this iteration.

confs: List[Path]

A list of configurations generated during the exploration. May be used to generate new configurations for the next iteration.

Returns

complete: bool

If all the DPGEN stages complete.

task: ExplorationTaskGroup

A *ExplorationTaskGroup* defining the exploration of the next iteration. Should be *None* if converged.

conf_selector: ConfSelector

The configuration selector for the next iteration. Should be *None* if converged.

```
print_convergence()
```

dpgen2.exploration.scheduler.stage_scheduler module

```
class dpgen2.exploration.scheduler.stage_scheduler.StageScheduler
```

Bases: `ABC`

The scheduler for an exploration stage.

Methods

<code>converged()</code>	Tell if the stage is converged
<code>plan_next_iteration(report, trajs)</code>	Make the plan for the next iteration of the stage.

```
abstract converged()
```

Tell if the stage is converged

Returns

converged bool
the convergence

```
abstract plan_next_iteration(report: ExplorationReport, trajs: List[Path]) → Tuple[bool,
    ExplorationTaskGroup, ConfSelector]
```

Make the plan for the next iteration of the stage.

It checks the report of the current and all historical iterations of the stage, and tells if the iterations are converged. If not converged, it will plan the next iteration for the stage.

Parameters

hist_reports: List[ExplorationReport]

The historical exploration report of the stage. If this is the first iteration of the stage, this list is empty.

report

[ExplorationReport] The exploration report of this iteration.

confs: List[Path]

A list of configurations generated during the exploration. May be used to generate new configurations for the next iteration.

Returns

stg_complete: bool

If the stage completed. Two cases may happen: 1. converged. 2. when not fatal_at_max, not converged but reached max number of iterations.

task: ExplorationTaskGroup

A *ExplorationTaskGroup* defining the exploration of the next iteration. Should be *None* if the stage is converged.

conf_selector: ConfSelector

The configuration selector for the next iteration. Should be *None* if the stage is converged.

dpngen2.exploration.selector package**Submodules****dpngen2.exploration.selector.conf_filter module****class** dpngen2.exploration.selector.conf_filter.**ConfFilter**Bases: `ABC`**Methods**

<code>check</code> (coords, cell, atom_types, nopbc)	Check if the configuration is valid.
--	--------------------------------------

abstract check(coords: `ndarray`, cell: `ndarray`, atom_types: `ndarray`, nopbc: `bool`) → `bool`

Check if the configuration is valid.

Parameters**coords**[`numpy.array`] The coordinates, numpy array of shape natoms x 3**cell**[`numpy.array`] The cell tensor. numpy array of shape 3 x 3**atom_types**[`numpy.array`] The atom types. numpy array of shape natoms**nopbc**[`bool`] If no periodic boundary condition.**Returns****valid**[`bool`] *True* if the configuration is a valid configuration, else *False*.**class** dpngen2.exploration.selector.conf_filter.**ConfFilters**Bases: `object`**Methods**

add	
check	

add(conf_filter: `ConfFilter`) → `ConfFilters`**check**(conf: `System`) → `bool`

dpngen2.exploration.selector.conf_selector module**class** dpngen2.exploration.selector.conf_selector.**ConfSelector**Bases: *ABC*

Select configurations from trajectory and model deviation files.

Methods**select**

abstract select(trajs: *List[Path]*, model_devis: *List[Path]*, traj_fmt: *str* = 'deepmd/npz', type_map: *Optional[List[str]]* = *None*) → *Tuple[List[Path], ExplorationReport]*

dpngen2.exploration.selector.conf_selector_frame module

class dpngen2.exploration.selector.conf_selector_frame.**ConfSelectorLammpsFrames**(trust_level, max_num_sel: *Optional[int]* = *None*, conf_filters: *Optional[ConfFilters]* = *None*)

Bases: *ConfSelector*

Select frames from trajectories as confs.

Parameters: trust_level: *TrustLevel*
The trust level**conf_filter: ConfFilters**
The configuration filter**Methods**

select(trajs, model_devis[, traj_fmt, type_map]) Select configurations

record_one_traj**record_one_traj**(traj, model_devi, traj_fmt, type_map) → *None*

select(trajs: *List[Path]*, model_devis: *List[Path]*, traj_fmt: *str* = 'lammps/dump', type_map: *Optional[List[str]]* = *None*) → *Tuple[List[Path], ExplorationReport]*

Select configurations

Parameters**trajs***[List[Path]]* A list of *Path* to trajectory files generated by LAMMPS

model_devis

[List[Path]] A *list* of *Path* to model deviation files generated by LAMMPS. Format: each line has 7 numbers they are used as # frame_id md_v_max md_v_min md_v_mean md_f_max md_f_min md_f_mean where *md* stands for model deviation, *v* for virial and *f* for force

traj_fmt

[str] Format of the trajectory, by default it is the dump file of LAMMPS

type_map

[List[str]] The *type_map* of the systems

Returns**confs**

[List[Path]] The selected configurations, stored in a folder in deepmd/npv format, can be parsed as dpdata.MultiSystems. The *list* only has one item.

report

[ExplorationReport] The exploration report recoding the status of the exploration.

dpngen2.exploration.selector.trust_level module

```
class dpngen2.exploration.selector.trust_level.TrustLevel(level_f_lo, level_f_hi, level_v_lo=None,
                                                         level_v_hi=None)
```

Bases: `object`

Attributes

`level_f_hi`

`level_f_lo`

`level_v_hi`

`level_v_lo`

property `level_f_hi`

property `level_f_lo`

property `level_v_hi`

property `level_v_lo`

dpngen2.exploration.task package**Subpackages****dpngen2.exploration.task.lmp package****Submodules****dpngen2.exploration.task.lmp.lmp_input module**

```

dpgen2.exploration.task.lmp.lmp_input.make_lmp_input(conf_file: str, ensemble: str, graphs: List[str],
                                                    nsteps: int, dt: float, neidelay: Optional[int],
                                                    trj_freq: int, mass_map: List[float], temp:
                                                    float, tau_t: float = 0.1, pres: Optional[float] =
                                                    None, tau_p: float = 0.5, use_clusters: bool =
                                                    False, relative_f_epsilon: Optional[float] =
                                                    None, relative_v_epsilon: Optional[float] =
                                                    None, pka_e: Optional[float] = None,
                                                    ele_temp_f: Optional[float] = None,
                                                    ele_temp_a: Optional[float] = None, nopbc:
                                                    bool = False, max_seed: int = 1000000,
                                                    deepmd_version='2.0',
                                                    trj_seperate_files=True)

```

Submodules

dpgen2.exploration.task.conf_sampling_task_group module

```
class dpgen2.exploration.task.conf_sampling_task_group.ConfSamplingTaskGroup
```

Bases: *ExplorationTaskGroup*

Attributes

task_list

Get the list of *ExplorationTask*

Methods

<code>add_group(group)</code>	Add another group to the group.
<code>add_task(task)</code>	Add one task to the group.
<code>count(value)</code>	
<code>index(value, [start, [stop]])</code>	Raises <i>ValueError</i> if the value is not present.
<code>set_conf(conf_list[, n_sample, random_sample])</code>	Set the configurations of exploration

clear

```
set_conf(conf_list: List[str], n_sample: Optional[int] = None, random_sample: bool = False)
```

Set the configurations of exploration

Parameters

conf_list str

A list of file contents

n_sample int

Number of samples drawn from the conf list each time *make_task* is called. If set to *None*, *n_sample* is set to length of the *conf_list*.

random_sample bool

If true the confs are randomly sampled, otherwise are consecutively sampled from the *conf_list*

dpgen2.exploration.task.lmp_template_task_group module

class dpgen2.exploration.task.lmp_template_task_group.LmpTemplateTaskGroup

Bases: *ConfSamplingTaskGroup*

Attributes

task_list

Get the *list* of *ExplorationTask*

Methods

add_group(group)	Add another group to the group.
add_task(task)	Add one task to the group.
count(value)	
index(value, [start, [stop]])	Raises ValueError if the value is not present.
set_conf(conf_list[, n_sample, random_sample])	Set the configurations of exploration

clear	
make_cont	
make_task	
set_lmp	

make_cont(*templates: list, revisions: dict*)

make_task() → *ExplorationTaskGroup*

set_lmp(*numb_models: int, lmp_template_fname: str, plm_template_fname: Optional[str] = None, revisions: dict = {}, traj_freq: int = 10*) → *None*

dpgen2.exploration.task.lmp_template_task_group.**find_only_one_key**(*lmp_lines, key*)

dpgen2.exploration.task.lmp_template_task_group.**revise_by_keys**(*lmp_lines, keys, values*)

dpgen2.exploration.task.lmp_template_task_group.**revise_lmp_input_dump**(*lmp_lines, trj_freq*)

dpgen2.exploration.task.lmp_template_task_group.**revise_lmp_input_model**(*lmp_lines, task_model_list, trj_freq, deepmd_version='I'*)

dpgen2.exploration.task.lmp_template_task_group.**revise_lmp_input_plm**(*lmp_lines, in_plm, out_plm='output.plumed'*)

dpgen2.exploration.task.make_task_group_from_config module

dpgen2.exploration.task.make_task_group_from_config.lmp_template_task_group_args()

dpgen2.exploration.task.make_task_group_from_config.make_task_group_from_config(*numb_models*,
mass_map,
config)

dpgen2.exploration.task.make_task_group_from_config.normalize(*data*)

dpgen2.exploration.task.make_task_group_from_config.npt_task_group_args()

dpgen2.exploration.task.make_task_group_from_config.task_group_args()

dpgen2.exploration.task.make_task_group_from_config.variant_task_group()

dpgen2.exploration.task.npt_task_group module

class dpgen2.exploration.task.npt_task_group.NPTTaskGroup

Bases: *ConfSamplingTaskGroup*

Attributes

task_list

Get the list of *ExplorationTask*

Methods

add_group(group)	Add another group to the group.
add_task(task)	Add one task to the group.
count(value)	
index(value, [start, [stop]])	Raises ValueError if the value is not present.
make_task()	Make the LAMMPS task group.
set_conf(conf_list[, n_sample, random_sample])	Set the configurations of exploration
set_md(numb_models, mass_map, temps[, ...])	Set MD parameters

clear

make_task() → *ExplorationTaskGroup*

Make the LAMMPS task group.

Returns

task_grp: ExplorationTaskGroup

The returned lammps task group. The number of tasks is $nconf \cdot nT \cdot nP$. *nconf* is set by *n_sample* parameter of *set_conf*. *nT* and *nP* are lengths of the *temps* and *press* parameters of *set_md*.

set_md(*numb_models*, *mass_map*, *temps*: *List[float]*, *press*: *Optional[List[float]]* = *None*, *ens*: *str* = 'npt', *dt*: *float* = 0.001, *nsteps*: *int* = 1000, *trj_freq*: *int* = 10, *tau_t*: *float* = 0.1, *tau_p*: *float* = 0.5, *pka_e*: *Optional[float]* = *None*, *neidelay*: *Optional[int]* = *None*, *no_pbc*: *bool* = *False*, *use_clusters*: *bool* = *False*, *relative_f_epsilon*: *Optional[float]* = *None*, *relative_v_epsilon*: *Optional[float]* = *None*, *ele_temp_f*: *Optional[float]* = *None*, *ele_temp_a*: *Optional[float]* = *None*)

Set MD parameters

dpgen2.exploration.task.stage module

class dpgen2.exploration.task.stage.**ExplorationStage**

Bases: `object`

The exploration stage.

Methods

<code>add_task_group(grp)</code>	Add an exploration group
<code>clear()</code>	Clear all exploration group.
<code>make_task()</code>	Make the LAMMPS task group.

add_task_group(*grp*: `ExplorationTaskGroup`)

Add an exploration group

Parameters

grp: `ExplorationTaskGroup`

The added exploration task group

clear()

Clear all exploration group.

make_task() → `ExplorationTaskGroup`

Make the LAMMPS task group.

Returns

task_grp: `ExplorationTaskGroup`

The returned lammps task group. The number of tasks is equal to the summation of task groups defined by all the exploration groups added to the stage.

dpgen2.exploration.task.task module

class dpgen2.exploration.task.task.**ExplorationTask**

Bases: `object`

Define the files needed by an exploration task.

Examples

```
>>> # this example dumps all files needed by the task.
>>> files = exploration_task.files()
... for file_name, file_content in files.items():
...     with open(file_name, 'w') as fp:
...         fp.write(file_content)
```

Methods

<code>add_file(fname, fcont)</code>	Add file to the task
<code>files()</code>	Get all files for the task.

add_file(*fname: str, fcont: str*)

Add file to the task

Parameters

fname

[str] The name of the file

fcont

[str] The content of the file.

files() → Dict

Get all files for the task.

Returns

files

[dict] The dict storing all files for the task. The file name is a key of the dict, and the file content is the corresponding value.

class dpgen2.exploration.task.task.**ExplorationTaskGroup**

Bases: Sequence

A group of exploration tasks. Implemented as a *list* of *ExplorationTask*.

Attributes

task_list

Get the *list* of *ExplorationTask*

Methods

<code>add_group(group)</code>	Add another group to the group.
<code>add_task(task)</code>	Add one task to the group.
<code>count(value)</code>	
<code>index(value, [start, [stop]])</code>	Raises ValueError if the value is not present.

clear

add_group(*group: ExplorationTaskGroup*)

Add another group to the group.

add_task(*task: ExplorationTask*)

Add one task to the group.

clear() → None

property *task_list*: List[ExplorationTask]

Get the *list* of *ExplorationTask*

class dpgen2.exploration.task.task.**FootTask**(*conf_name='conf.lmp', conf_cont='',
inpu_name='in.lammps', inpu_cont=''*)

Bases: *ExplorationTask*

Methods

<code>add_file(fname, fcont)</code>	Add file to the task
<code>files()</code>	Get all files for the task.

class `dpngen2.exploration.task.task.FooTaskGroup`(*numb_task*)

Bases: *ExplorationTaskGroup*

Attributes

task_list

Get the list of *ExplorationTask*

Methods

<code>add_group(group)</code>	Add another group to the group.
<code>add_task(task)</code>	Add one task to the group.
<code>count(value)</code>	
<code>index(value, [start, [stop]])</code>	Raises <i>ValueError</i> if the value is not present.

clear

property `task_list`

Get the list of *ExplorationTask*

dpngen2.flow package**Submodules****dpngen2.flow.dpngen_loop module**

class `dpngen2.flow.dpngen_loop.ConcurrentLearning`(*name: str, block_op: OPTemplate, step_config: dict = {'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'executor': None, 'parallelism': None, 'template_config': {'envs': None, 'image': 'dpotechnology/dpugen2:latest', 'retry_on_transient_error': None, 'timeout': None, 'timeout_as_transient_error': False}}, upload_python_packages: Optional[List[PathLike]] = None)*

Bases: *Steps*

Attributes

`init_keys`

`input_artifacts`

`input_parameters`

`loop_keys`

`output_artifacts`

`output_parameters`

Methods

add(step)	Add a step or a list of parallel steps to the steps
-----------	---

convert_to_argo	
handle_key	
run	

property `init_keys`
 property `input_artifacts`
 property `input_parameters`
 property `loop_keys`
 property `output_artifacts`
 property `output_parameters`

```
class dpngen2.flow.dpgen_loop.ConcurrentLearningLoop(name: str, block_op: OPTemplate, step_config: dict = {'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'executor': None, 'parallelism': None, 'template_config': {'envs': None, 'image': 'dptechnology/dpgen2:latest', 'retry_on_transient_error': None, 'timeout': None, 'timeout_as_transient_error': False}}, upload_python_packages: Optional[List[PathLike]] = None)
```

Bases: `Steps`

Attributes

`input_artifacts`
`input_parameters`
`keys`
`output_artifacts`
`output_parameters`

Methods

add(step)	Add a step or a list of parallel steps to the steps
-----------	---

convert_to_argo	
handle_key	
run	

property `input_artifacts`
 property `input_parameters`

property keys

property output_artifacts

property output_parameters

class `dpgen2.flow.dpgen_loop.MakeBlockId(*args, **kwargs)`

Bases: `OP`

Methods

<code>execute(ip)</code>	Run the OP
<code>get_input_sign()</code>	Get the signature of the inputs
<code>get_output_sign()</code>	Get the signature of the outputs

<code>exec_sign_check</code>	
<code>function</code>	
<code>get_info</code>	
<code>get_input_artifact_link</code>	
<code>get_input_artifact_storage_key</code>	
<code>get_opio_info</code>	
<code>get_output_artifact_link</code>	
<code>get_output_artifact_storage_key</code>	

execute(*ip*: `OPIO`) → `OPIO`

Run the OP

classmethod `get_input_sign()`

Get the signature of the inputs

classmethod `get_output_sign()`

Get the signature of the outputs

class `dpgen2.flow.dpgen_loop.SchedulerWrapper(*args, **kwargs)`

Bases: `OP`

Methods

<code>execute(ip)</code>	Run the OP
<code>get_input_sign()</code>	Get the signature of the inputs
<code>get_output_sign()</code>	Get the signature of the outputs

<code>exec_sign_check</code>	
<code>function</code>	
<code>get_info</code>	
<code>get_input_artifact_link</code>	
<code>get_input_artifact_storage_key</code>	
<code>get_opio_info</code>	
<code>get_output_artifact_link</code>	
<code>get_output_artifact_storage_key</code>	

execute(*ip*: *OPIO*) → *OPIO*

Run the OP

classmethod **get_input_sign**()

Get the signature of the inputs

classmethod **get_output_sign**()

Get the signature of the outputs

dpgen2.fp package

Submodules

dpgen2.fp.vasp module

class `dpgen2.fp.vasp.VaspInputs`(*kspacing*: *Union[float, List[float]]*, *incar_template_name*: *str*,
potcar_names: *Dict[str, str]*, *kgamma*: *bool = True*)

Bases: `object`

Attributes

incar_template

potcars

Methods

incar_from_file	
make_kpoints	
make_potcar	
potcars_from_file	

incar_from_file(*fname*: *str*)

property **incar_template**

make_kpoints(*box*: *ndarray*) → *str*

make_potcar(*atom_names*) → *str*

property **potcars**

potcars_from_file(*dict_fnames*: *Dict[str, str]*)

`dpgen2.fp.vasp.make_kspacing_kpoints`(*box*, *kspacing*, *kgamma*)

dpngen2.op package

Submodules

dpngen2.op.collect_data module

class dpngen2.op.collect_data.CollectData(*args, **kwargs)

Bases: OP

Collect labeled data and add to the iteration dataset.

After running FP tasks, the labeled data are scattered in task directories. This OP collect the labeled data in one data directory and add it to the iteration data. The data generated by this iteration will be place in *ip["name"]* subdirectory of the iteration data directory.

Methods

<i>execute</i> (ip)	Execute the OP.
<i>get_input_sign</i> ()	Get the signature of the inputs
<i>get_output_sign</i> ()	Get the signature of the outputs

exec_sign_check	
function	
get_info	
get_input_artifact_link	
get_input_artifact_storage_key	
get_opio_info	
get_output_artifact_link	
get_output_artifact_storage_key	

execute(*ip*: OPIO) → OPIO

Execute the OP. This OP collect data scattered in directories given by *ip['labeled_data']* in to one *dp-data.Multisystems* and store it in a directory named *name*. This directory is appended to the list *iter_data*.

Parameters

ip

[dict] Input dict with components:

- *name*: (*str*) The name of this iteration. The data generated by this iteration will be place in a sub-directory of *name*.
- *labeled_data*: (*Artifact(List[Path])*) The paths of labeled data generated by FP tasks of the current iteration.
- *iter_data*: (*Artifact(List[Path])*) The data paths previous iterations.

Returns

Output dict with components:

- *iter_data*: (*Artifact(List[Path])*) The data paths of previous and the current iteration data.

classmethod *get_input_sign*()

Get the signature of the inputs

classmethod `get_output_sign()`

Get the signature of the outputs

dpngen2.op.md_settings module

```
class dpngen2.op.md_settings.MDSettings(ens: str, dt: float, nsteps: int, trj_freq: int, temps:
Optional[List[float]] = None, press: Optional[List[float]] =
None, tau_t: float = 0.1, tau_p: float = 0.5, pka_e:
Optional[float] = None, neidelay: Optional[int] = None, no_pbc:
bool = False, use_clusters: bool = False, relative_epsilon:
Optional[float] = None, relative_v_epsilon: Optional[float] =
None, ele_temp_f: Optional[float] = None, ele_temp_a:
Optional[float] = None)
```

Bases: `object`

Methods

<code>to_str</code>	
---------------------	--

`to_str()` → `str`

dpngen2.op.prep_dp_train module

```
class dpngen2.op.prep_dp_train.PrepDPTrain(*args, **kwargs)
```

Bases: `OP`

Prepares the working directories for DP training tasks.

A list of (*numb_models*) working directories containing all files needed to start training tasks will be created. The paths of the directories will be returned as `op["task_paths"]`. The identities of the tasks are returned as `op["task_names"]`.

Methods

<code>execute(ip)</code>	Execute the OP.
<code>get_input_sign()</code>	Get the signature of the inputs
<code>get_output_sign()</code>	Get the signature of the outputs

<code>exec_sign_check</code>	
function	
<code>get_info</code>	
<code>get_input_artifact_link</code>	
<code>get_input_artifact_storage_key</code>	
<code>get_opio_info</code>	
<code>get_output_artifact_link</code>	
<code>get_output_artifact_storage_key</code>	

execute(*ip*: *OPIO*) → *OPIO*

Execute the OP.

Parameters

ip

[dict] Input dict with components:

- *template_script*: (*str* or *List[str]*) A template of the training script. Can be a *str* or *List[str]*. In the case of *str*, all training tasks share the same training input template, the only difference is the random number used to initialize the network parameters. In the case of *List[str]*, one training task uses one template from the list. The random numbers used to initialize the network parameters are different. The length of the list should be the same as *numb_models*.
- *numb_models*: (*int*) Number of DP models to train.

Returns

op

[dict] Output dict with components:

- *task_names*: (*List[str]*) The name of tasks. Will be used as the identities of the tasks. The names of different tasks are different.
- *task_paths*: (*Artifact(List[Path])*) The prepared working paths of the tasks. The order of the Paths should be consistent with *op["task_names"]*

classmethod get_input_sign()

Get the signature of the inputs

classmethod get_output_sign()

Get the signature of the outputs

dpngen2.op.prep_lmp module

`dpngen2.op.prep_lmp.PrepExplorationTaskGroup`

alias of *PrepLmp*

class `dpngen2.op.prep_lmp.PrepLmp(*args, **kwargs)`

Bases: *OP*

Prepare the working directories for LAMMPS tasks.

A list of working directories (defined by *ip["task"]*) containing all files needed to start LAMMPS tasks will be created. The paths of the directories will be returned as *op["task_paths"]*. The identities of the tasks are returned as *op["task_names"]*.

Methods

<code>execute(ip)</code>	Execute the OP.
<code>get_input_sign()</code>	Get the signature of the inputs
<code>get_output_sign()</code>	Get the signature of the outputs

<code>exec_sign_check</code>	
<code>function</code>	
<code>get_info</code>	
<code>get_input_artifact_link</code>	
<code>get_input_artifact_storage_key</code>	
<code>get_opio_info</code>	
<code>get_output_artifact_link</code>	
<code>get_output_artifact_storage_key</code>	

execute(*ip*: *OPIO*) → *OPIO*

Execute the OP.

Parameters

ip

[dict] Input dict with components: - *Imp_task_grp* : (*Artifact(Path)*) Can be pickle loaded as a ExplorationTaskGroup. Definitions for LAMMPS tasks

Returns

op

[dict] Output dict with components:

- *task_names*: (*List[str]*) The name of tasks. Will be used as the identities of the tasks. The names of different tasks are different.
- *task_paths*: (*Artifact(List[Path])*) The prepared working paths of the tasks. Contains all input files needed to start the LAMMPS simulation. The order fo the Paths should be consistent with *op["task_names"]*

classmethod `get_input_sign()`

Get the signature of the inputs

classmethod `get_output_sign()`

Get the signature of the outputs

dpgen2.op.prep_vasp module

class `dpgen2.op.prep_vasp.PrepVasp(*args, **kwargs)`

Bases: *OP*

Prepares the working directories for VASP tasks.

A list of (same length as *ip["confs"]*) working directories containing all files needed to start VASP tasks will be created. The paths of the directories will be returned as *op["task_paths"]*. The identities of the tasks are returned as *op["task_names"]*.

Methods

<code>execute(ip)</code>	Execute the OP.
<code>get_input_sign()</code>	Get the signature of the inputs
<code>get_output_sign()</code>	Get the signature of the outputs

<code>exec_sign_check</code>	
<code>function</code>	
<code>get_info</code>	
<code>get_input_artifact_link</code>	
<code>get_input_artifact_storage_key</code>	
<code>get_opio_info</code>	
<code>get_output_artifact_link</code>	
<code>get_output_artifact_storage_key</code>	

execute(*ip*: *OPIO*) → *OPIO*

Execute the OP.

Parameters

ip

[dict] Input dict with components:

- *config* : (*dict*) Should have *config*['inputs'], which is of type *VaspInputs* and defines the VASP inputs
- *confs* : (*Artifact(List[Path])*) Configurations for the VASP tasks. Stored in folders as deepmd/npz format. Can be parsed as *dpdata.MultiSystems*.

Returns

op

[dict] Output dict with components:

- *task_names*: (*List[str]*) The name of tasks. Will be used as the identities of the tasks. The names of different tasks are different.
- *task_paths*: (*Artifact(List[Path])*) The prepared working paths of the tasks. Contains all input files needed to start the VASP. The order of the Paths should be consistent with *op*["task_names"]

classmethod `get_input_sign()`

Get the signature of the inputs

classmethod `get_output_sign()`

Get the signature of the outputs

dpngen2.op.run_dp_train module

class `dpngen2.op.run_dp_train.RunDPTrain(*args, **kwargs)`

Bases: *OP*

Execute a DP training task. Train and freeze a DP model.

A working directory named *task_name* is created. All input files are copied or symbol linked to directory *task_name*. The DeepMD-kit training and freezing commands are executed from directory *task_name*.

Methods

<code>execute(ip)</code>	Execute the OP.
<code>get_input_sign()</code>	Get the signature of the inputs
<code>get_output_sign()</code>	Get the signature of the outputs

<code>decide_init_model</code>	
<code>exec_sign_check</code>	
<code>function</code>	
<code>get_info</code>	
<code>get_input_artifact_link</code>	
<code>get_input_artifact_storage_key</code>	
<code>get_opio_info</code>	
<code>get_output_artifact_link</code>	
<code>get_output_artifact_storage_key</code>	
<code>normalize_config</code>	
<code>training_args</code>	
<code>write_data_to_input_script</code>	
<code>write_other_to_input_script</code>	

`static decide_init_model(config, init_model, init_data, iter_data)`

`execute(ip: OPIO) → OPIO`

Execute the OP.

Parameters

ip

[dict] Input dict with components:

- *config*: (*dict*) The config of training task. Check *RunDPTrain.training_args* for definitions.
- *task_name*: (*str*) The name of training task.
- *task_path*: (*Artifact(Path)*) The path that contains all input files prepared by *PrepDPTrain*.
- *init_model*: (*Artifact(Path)*) A frozen model to initialize the training.
- *init_data*: (*Artifact(List[Path])*) Initial training data.
- *iter_data*: (*Artifact(List[Path])*) Training data generated in the DPGEN iterations.

Returns

Output dict with components:

- *script*: (*Artifact(Path)*) The training script.
- *model*: (*Artifact(Path)*) The trained frozen model.
- *lcurve*: (*Artifact(Path)*) The learning curve file.
- *log*: (*Artifact(Path)*) The log file of training.

`classmethod get_input_sign()`

Get the signature of the inputs

`classmethod get_output_sign()`

Get the signature of the outputs


```

static normalize_config(data={})

static training_args()

static write_data_to_input_script(idict: dict, init_data: List[Path], iter_data: List[Path],
                                  auto_prob_str: str = 'prob_sys_size', major_version: str = '1')

static write_other_to_input_script(idict, config, do_init_model, major_version: str = '1')

```

```
dpngen2.op.run_dp_train.config_args()
```

dpngen2.op.run_lmp module

```
class dpngen2.op.run_lmp.RunLmp(*args, **kwargs)
```

Bases: `OP`

Execute a LAMMPS task.

A working directory named *task_name* is created. All input files are copied or symbol linked to directory *task_name*. The LAMMPS command is executed from directory *task_name*. The trajectory and the model deviation will be stored in files *op["traj"]* and *op["model_devi"]*, respectively.

Methods

<code>execute(ip)</code>	Execute the OP.
<code>get_input_sign()</code>	Get the signature of the inputs
<code>get_output_sign()</code>	Get the signature of the outputs

<code>exec_sign_check</code>	
<code>function</code>	
<code>get_info</code>	
<code>get_input_artifact_link</code>	
<code>get_input_artifact_storage_key</code>	
<code>get_opio_info</code>	
<code>get_output_artifact_link</code>	
<code>get_output_artifact_storage_key</code>	
<code>lmp_args</code>	
<code>normalize_config</code>	

`execute(ip: OPIO) → OPIO`

Execute the OP.

Parameters

ip

[dict] Input dict with components:

- *config*: (dict) The config of lmp task. Check *RunLmp.lmp_args* for definitions.
- *task_name*: (str) The name of the task.
- *task_path*: (Artifact(Path)) The path that contains all input files prepared by *PrepLmp*.

- *models*: (*Artifact(List[Path])*) The frozen model to estimate the model deviation. The first model will be used to drive molecular dynamics simulation.

Returns

Output dict with components:

- *log*: (*Artifact(Path)*) The log file of LAMMPS.
- *traj*: (*Artifact(Path)*) The output trajectory.
- *model_devi*: (*Artifact(Path)*) The model deviation. The order of recorded model deviations should be consistent with the order of frames in *traj*.

classmethod `get_input_sign()`

Get the signature of the inputs

classmethod `get_output_sign()`

Get the signature of the outputs

static `lmp_args()`

static `normalize_config(data={})`

`dpngen2.op.run_lmp.config_args()`

dpngen2.op.run_vasp module

class `dpngen2.op.run_vasp.RunVasp(*args, **kwargs)`

Bases: `OP`

Execute a VASP task.

A working directory named *task_name* is created. All input files are copied or symbol linked to directory *task_name*. The VASP command is executed from directory *task_name*. The *op*["*labeled_data*"] in "*deepmd/npz*" format (HF5 in the future) provided by *dpdata* will be created.

Methods

<code>execute(ip)</code>	Execute the OP.
<code>get_input_sign()</code>	Get the signature of the inputs
<code>get_output_sign()</code>	Get the signature of the outputs

<code>exec_sign_check</code>	
<code>function</code>	
<code>get_info</code>	
<code>get_input_artifact_link</code>	
<code>get_input_artifact_storage_key</code>	
<code>get_opio_info</code>	
<code>get_output_artifact_link</code>	
<code>get_output_artifact_storage_key</code>	
<code>normalize_config</code>	
<code>vasp_args</code>	

execute(*ip*: *OPIO*) → *OPIO*

Execute the OP.

Parameters

ip

[dict] Input dict with components:

- *config*: (*dict*) The config of vasp task. Check *RunVasp.vasp_args* for definitions.
- *task_name*: (*str*) The name of task.
- *task_path*: (*Artifact(Path)*) The path that contains all input files prepared by *PrepVasp*.

Returns

Output dict with components:

- *log*: (*Artifact(Path)*) The log file of VASP.
- *labeled_data*: (*Artifact(Path)*) The path to the labeled data in “*deepmd/npz*” format provided by *dpdata*.

classmethod `get_input_sign()`

Get the signature of the inputs

classmethod `get_output_sign()`

Get the signature of the outputs

static `normalize_config(data={}, strict=True)`

static `vasp_args()`

`dpngen2.op.run_vasp.config_args()`

dpngen2.op.select_confs module

class `dpngen2.op.select_confs.SelectConfs(*args, **kwargs)`

Bases: *OP*

Select configurations from exploration trajectories for labeling.

Methods

<code>execute(ip)</code>	Execute the OP.
<code>get_input_sign()</code>	Get the signature of the inputs
<code>get_output_sign()</code>	Get the signature of the outputs

<code>exec_sign_check</code>	
<code>function</code>	
<code>get_info</code>	
<code>get_input_artifact_link</code>	
<code>get_input_artifact_storage_key</code>	
<code>get_opio_info</code>	
<code>get_output_artifact_link</code>	
<code>get_output_artifact_storage_key</code>	

execute(*ip*: *OPIO*) → *OPIO*

Execute the OP.

Parameters

ip

[dict] Input dict with components:

- *conf_selector*: (*ConfSelector*) Configuration selector.
- *traj_fmt*: (*str*) The format of trajectory.
- *type_map*: (*List[str]*) The type map.
- *trajs*: (*Artifact(List[Path])*) The trajectories generated in the exploration.
- *model_devis*: (*Artifact(List[Path])*) The file storing the model deviation of the trajectory. The order of model deviation storage is consistent with that of the trajectories. The order of frames of one model deviation storage is also consistent with that of the corresponding trajectory.

Returns

Output dict with components:

- *report*: (*ExplorationReport*) **The report on the exploration.**
- *conf*: (*Artifact(List[Path])*) **The selected configurations.**

classmethod `get_input_sign()`

Get the signature of the inputs

classmethod `get_output_sign()`

Get the signature of the outputs

dpgen2.superop package

Submodules

dpgen2.superop.block module

```

class dpngen2.superop.block.ConcurrentLearningBlock(name: str, prep_run_dp_train_op: OPTemplate,
                                                    prep_run_lmp_op: OPTemplate, select_confs_op:
                                                    OP, prep_run_fp_op: OPTemplate,
                                                    collect_data_op: OP, select_confs_config: dict =
                                                    {'continue_on_failed': False,
                                                    'continue_on_num_success': None,
                                                    'continue_on_success_ratio': None, 'executor':
                                                    None, 'parallelism': None, 'template_config':
                                                    {'envs': None, 'image':
                                                    'dptechnology/dpugen2:latest',
                                                    'retry_on_transient_error': None, 'timeout': None,
                                                    'timeout_as_transient_error': False}},
                                                    collect_data_config: dict = {'continue_on_failed':
                                                    False, 'continue_on_num_success': None,
                                                    'continue_on_success_ratio': None, 'executor':
                                                    None, 'parallelism': None, 'template_config':
                                                    {'envs': None, 'image':
                                                    'dptechnology/dpugen2:latest',
                                                    'retry_on_transient_error': None, 'timeout': None,
                                                    'timeout_as_transient_error': False}},
                                                    upload_python_packages:
                                                    Optional[List[PathLike]] = None)

```

Bases: [Steps](#)

Attributes

input_artifacts
input_parameters
keys
output_artifacts
output_parameters

Methods

add(step)	Add a step or a list of parallel steps to the steps
-----------	---

convert_to_argo	
handle_key	
run	

property input_artifacts
property input_parameters
property keys
property output_artifacts
property output_parameters

dpgen2.superop.prep_run_dp_train module

```
class dpgen2.superop.prep_run_dp_train.PrepRunDPTrain(name: str, prep_train_op: OP, run_train_op:
    OP, prep_config: dict =
        {'continue_on_failed': False,
         'continue_on_num_success': None,
         'continue_on_success_ratio': None,
         'executor': None, 'parallelism': None,
         'template_config': {'envs': None, 'image':
            'dptechnology/dpgen2:latest',
            'retry_on_transient_error': None, 'timeout':
            None, 'timeout_as_transient_error': False}},
    run_config: dict = {'continue_on_failed':
        False, 'continue_on_num_success': None,
        'continue_on_success_ratio': None,
        'executor': None, 'parallelism': None,
        'template_config': {'envs': None, 'image':
            'dptechnology/dpgen2:latest',
            'retry_on_transient_error': None, 'timeout':
            None, 'timeout_as_transient_error': False}},
    upload_python_packages:
        Optional[List[PathLike]] = None)
```

Bases: Steps

Attributes

- input_artifacts**
- input_parameters**
- keys**
- output_artifacts**
- output_parameters**

Methods

add(step)	Add a step or a list of parallel steps to the steps
-----------	---

convert_to_argo	
handle_key	
run	

- property **input_artifacts**
- property **input_parameters**
- property **keys**
- property **output_artifacts**
- property **output_parameters**

dpngen2.superop.prep_run_fp module

```
class dpngen2.superop.prep_run_fp.PrepRunFp(name: str, prep_op: OP, run_op: OP, prep_config: dict =
    {'continue_on_failed': False, 'continue_on_num_success':
    None, 'continue_on_success_ratio': None, 'executor': None,
    'parallelism': None, 'template_config': {'envs': None,
    'image': 'dptechnology/dpugen2:latest',
    'retry_on_transient_error': None, 'timeout': None,
    'timeout_as_transient_error': False}}, run_config: dict =
    {'continue_on_failed': False, 'continue_on_num_success':
    None, 'continue_on_success_ratio': None, 'executor': None,
    'parallelism': None, 'template_config': {'envs': None,
    'image': 'dptechnology/dpugen2:latest',
    'retry_on_transient_error': None, 'timeout': None,
    'timeout_as_transient_error': False}},
    upload_python_packages: Optional[List[PathLike]] =
    None)
```

Bases: `Steps`**Attributes**

`input_artifacts`
`input_parameters`
`keys`
`output_artifacts`
`output_parameters`

Methods

<code>add(step)</code>	Add a step or a list of parallel steps to the steps
------------------------	---

<code>convert_to_argo</code>	
<code>handle_key</code>	
<code>run</code>	

`property input_artifacts`
`property input_parameters`
`property keys`
`property output_artifacts`
`property output_parameters`

dpngen2.superop.prep_run_lmp module

```
class dpngen2.superop.prep_run_lmp.PrepRunLmp(name: str, prep_op: OP, run_op: OP, prep_config: dict =
    {'continue_on_failed': False, 'continue_on_num_success':
    None, 'continue_on_success_ratio': None, 'executor':
    None, 'parallelism': None, 'template_config': {'envs':
    None, 'image': 'dptechnology/dpugen2:latest',
    'retry_on_transient_error': None, 'timeout': None,
    'timeout_as_transient_error': False}}, run_config: dict =
    {'continue_on_failed': False, 'continue_on_num_success':
    None, 'continue_on_success_ratio': None, 'executor':
    None, 'parallelism': None, 'template_config': {'envs':
    None, 'image': 'dptechnology/dpugen2:latest',
    'retry_on_transient_error': None, 'timeout': None,
    'timeout_as_transient_error': False}},
    upload_python_packages: Optional[List[PathLike]] =
    None)
```

Bases: Steps

Attributes

- input_artifacts**
- input_parameters**
- keys**
- output_artifacts**
- output_parameters**

Methods

add(step)	Add a step or a list of parallel steps to the steps
-----------	---

convert_to_argo	
handle_key	
run	

- property **input_artifacts**
- property **input_parameters**
- property **keys**
- property **output_artifacts**
- property **output_parameters**

dpngen2.utils package

Submodules

dpngen2.utils.alloy_conf module

```
class dpngen2.utils.alloy_conf.AlloyConf(lattice: Union[System, Tuple[str, float]], type_map: List[str],
                                         replicate: Optional[Union[List[int], Tuple[int], int]] = None)
```

Bases: `object`

Parameters

lattice Union[`dpdata.System`, `Tuple[str, float]`]

Lattice of the alloy confs. can be `dpdata.System`: lattice in `dpdata.System Tuple[str, float]`: pair of lattice type and lattice constant. lattice type can be “bcc”, “fcc”, “hcp”, “sc” or “diamond”

replicate Union[`List[int]`, `Tuple[int], int]`

replicate of the lattice

type_map `List[str]`

The type map

Methods

```
generate_file_content(numb_confs[, ...])
```

Parameters

```
generate_systems(numb_confs[, ...])
```

Parameters

```
generate_file_content(numb_confs, concentration: Optional[Union[List[List[float]], List[float]]] = None, cell_pert_frac: float = 0.0, atom_pert_dist: float = 0.0, fmt: str = 'lammps/lmp') → List[str]
```

Parameters

numb_confs `int`

Number of configurations to generate

concentration `List[List[float]]` or `List[float]` or `None`

If `List[float]`, the concentrations of each element. The length of the list should be the same as the `type_map`. If `List[List[float]]`, a list of concentrations (`List[float]`) is randomly picked from the List. If `None`, the elements are assumed to be of equal concentration.

cell_pert_frac `float`

fraction of cell perturbation

atom_pert_dist `float`

the atom perturbation distance (unit angstrom).

fmt `str`

the format of the returned conf strings. Should be one of the formats supported by `dpdata`

Returns

conf_list `List[str]`

A list of file content of configurations.

generate_systems(*numb_confs*, *concentration*: *Optional[Union[List[List[float]], List[float]]] = None*,
cell_pert_frac: *float = 0.0*, *atom_pert_dist*: *float = 0.0*) → List[str]

Parameters**numb_confs** int

Number of configurations to generate

concentration List[List[float]] or List[float] or NoneIf *List[float]*, the concentrations of each element. The length of the list should be the same as the *type_map*. If *List[List[float]]*, a list of concentrations (*List[float]*) is randomly picked from the List. If *None*, the elements are assumed to be of equal concentration.**cell_pert_frac** float

fraction of cell perturbation

atom_pert_dist float

the atom perturbation distance (unit angstrom).

Returns**conf_list** List[dpdata.System]A list of generated confs in *dpdata.System*.

dpgen2.utils.alloy_conf.**gen_doc**(**make_anchor=True*, *make_link=True*, ***kwargs*)

dpgen2.utils.alloy_conf.**generate_alloy_conf_args**()

dpgen2.utils.alloy_conf.**generate_alloy_conf_file_content**(*lattice*: *Union[System, Tuple[str, float]]*,
type_map: *List[str]*, *numb_confs*,
replicate: *Optional[Union[List[int],
Tuple[int], int]] = None*, *concentration*:
*Optional[Union[List[List[float]],
List[float]]] = None*, *cell_pert_frac*: *float
= 0.0*, *atom_pert_dist*: *float = 0.0*, *fmt*: *str
= 'lammps/lmp'*)

dpgen2.utils.alloy_conf.**normalize**(*data*)

dpgen2.utils.chdir module

dpgen2.utils.chdir.**chdir**(*path_key*: *str*)

Returns a decorator that can change the current working path.

Parameters**path_key**

[str] key to OPIO

Examples

```
>>> class SomeOP(OP):
...     @chdir("path")
...     def execute(self, ip: OPIO):
...         do_something()
```

dpgen2.utils.chdir.**set_directory**(*path*: *Path*)

Sets the current working path within the context.

Parameters

path
 [Path] The path to the cwd
Yields
 None

Examples

```
>>> with set_directory("some_path"):
...     do_something()
```

dpngen2.utils.dflow_config module

`dpngen2.utils.dflow_config.dflow_config(config_data)`

set the dflow config by *config_data*

the keys starting with “s3_” will be treated as s3_config keys, other keys are treated as config keys.

`dpngen2.utils.dflow_config.dflow_config_lower(dflow_config)`

`dpngen2.utils.dflow_config.dflow_s3_config(config_data)`

set the s3 config by *config_data*

`dpngen2.utils.dflow_config.dflow_s3_config_lower(dflow_s3_config_data)`

`dpngen2.utils.dflow_config.workflow_config_from_dict(wf_config)`

dpngen2.utils.dflow_query module

`dpngen2.utils.dflow_query.find_slice_ranges(keys: List[str], sliced_subkey: str)`

find range of sliced OPs that matches the pattern ‘iter-[0-9]*-*{sliced_subkey}*-[0-9]*’

`dpngen2.utils.dflow_query.get_iteration(key: str)`

`dpngen2.utils.dflow_query.get_last_iteration(keys: List[str])`

get the index of the last interaction from a list of step keys.

`dpngen2.utils.dflow_query.get_last_scheduler(wf: Any, keys: List[str])`

get the output Scheduler of the last successful iteration

`dpngen2.utils.dflow_query.get_subkey(key: str, idx: int = -1)`

`dpngen2.utils.dflow_query.matched_step_key(all_keys: List[str], step_keys: Optional[List[str]] = None)`

returns the keys in *all_keys* that matches any of the *step_keys*

`dpngen2.utils.dflow_query.print_keys_in_nice_format(keys: List[str], sliced_subkey: List[str],
 idx_fmt_len: int = 8)`

`dpngen2.utils.dflow_query.sort_slice_ops(keys: List[str], sliced_subkey: List[str])`

sort the keys of the sliced ops. the keys of the sliced ops contains *sliced_subkey*

dpgen2.utils.download_dpgen2_artifacts module

class dpgen2.utils.download_dpgen2_artifacts.**DownloadDefinition**

Bases: `object`

Methods

add_def	
add_input	
add_output	

add_def(*tdict*, *key*, *suffix=None*)

add_input(*input_key*, *suffix=None*)

add_output(*output_key*, *suffix=None*)

dpgen2.utils.download_dpgen2_artifacts.download_dpgen2_artifacts(*wf*, *key*, *prefix=None*)

download the artifacts of a step. the key should be of format 'iter-xxxxxx-subkey-of-step-xxxxxx' the input and output artifacts will be downloaded to prefix/iter-xxxxxx/key-of-step/inputs/ and prefix/iter-xxxxxx/key-of-step/outputs/

the downloaded input and output artifacts of steps are defined by *op_download_setting*

dpgen2.utils.obj_artifact module

dpgen2.utils.obj_artifact.dump_object_to_file(*obj*, *fname*)

pickle dump object to a file

dpgen2.utils.obj_artifact.load_object_from_file(*fname*)

pickle load object from a file

dpgen2.utils.run_command module

dpgen2.utils.run_command.run_command(*cmd*, *shell: bool = False*)

dpgen2.utils.step_config module

dpgen2.utils.step_config.dispatcher_args()

free style dispatcher args

dpgen2.utils.step_config.gen_doc(***, *make_anchor=True*, *make_link=True*, ***kwargs*)

dpgen2.utils.step_config.init_executor(*executor_dict*)

dpgen2.utils.step_config.lebesgue_executor_args()

dpgen2.utils.step_config.lebesgue_extra_args()

dpgen2.utils.step_config.normalize(*data*)

```

dpgen2.utils.step_config.step_conf_args()
dpgen2.utils.step_config.template_conf_args()
dpgen2.utils.step_config.variant_executor()

```

dpgen2.utils.unit_cells module

```

class dpgen2.utils.unit_cells.BCC
    Bases: object

```

Methods

gen_box	
numb_atoms	
poscar_unit	

```

gen_box()
numb_atoms()
poscar_unit(latt)

```

```

class dpgen2.utils.unit_cells.DIAMOND
    Bases: object

```

Methods

gen_box	
numb_atoms	
poscar_unit	

```

gen_box()
numb_atoms()
poscar_unit(latt)

```

```

class dpgen2.utils.unit_cells.FCC
    Bases: object

```

Methods

gen_box	
numb_atoms	
poscar_unit	

```

gen_box()

```

`numb_atoms()`

`poscar_unit(latt)`

`class dpgen2.utils.unit_cells.HCP`

Bases: `object`

Methods

<code>gen_box</code>	
<code>numb_atoms</code>	
<code>poscar_unit</code>	

`gen_box()`

`numb_atoms()`

`poscar_unit(latt)`

`class dpgen2.utils.unit_cells.SC`

Bases: `object`

Methods

<code>gen_box</code>	
<code>numb_atoms</code>	
<code>poscar_unit</code>	

`gen_box()`

`numb_atoms()`

`poscar_unit(latt)`

`dpgen2.utils.unit_cells.generate_unit_cell(crystal: str, latt: float = 1.0) → System`

9.1.2 Submodules

9.1.3 dpgen2.constants module

- `genindex`
- `modindex`
- `search`

PYTHON MODULE INDEX

d

dpngen2, 73
dpngen2.constants, 114
dpngen2.entrypoint, 73
dpngen2.entrypoint.download, 73
dpngen2.entrypoint.main, 73
dpngen2.entrypoint.showkey, 74
dpngen2.entrypoint.status, 74
dpngen2.entrypoint.submit, 74
dpngen2.entrypoint.submit_args, 76
dpngen2.entrypoint.watch, 77
dpngen2.exploration, 77
dpngen2.exploration.report, 77
dpngen2.exploration.report.naive_report, 77
dpngen2.exploration.report.report, 78
dpngen2.exploration.report.trajs_report, 78
dpngen2.exploration.scheduler, 79
dpngen2.exploration.scheduler.convergence_check_stage_scheduler, 79
dpngen2.exploration.scheduler.scheduler, 80
dpngen2.exploration.scheduler.stage_scheduler, 82
dpngen2.exploration.selector, 83
dpngen2.exploration.selector.conf_filter, 83
dpngen2.exploration.selector.conf_selector, 84
dpngen2.exploration.selector.conf_selector_frame, 84
dpngen2.exploration.selector.trust_level, 85
dpngen2.exploration.task, 85
dpngen2.exploration.task.conf_sampling_task_group, 86
dpngen2.exploration.task.lmp, 85
dpngen2.exploration.task.lmp.lmp_input, 85
dpngen2.exploration.task.lmp_template_task_group, 87
dpngen2.exploration.task.make_task_group_from_config, 88
dpngen2.exploration.task.npt_task_group, 88
dpngen2.exploration.task.stage, 89
dpngen2.exploration.task.task, 89
dpngen2.flow, 91
dpngen2.flow.dpngen_loop, 91
dpngen2.fp, 94
dpngen2.fp.vasp, 94
dpngen2.op, 95
dpngen2.op.collect_data, 95
dpngen2.op.md_settings, 96
dpngen2.op.prep_dp_train, 96
dpngen2.op.prep_lmp, 97
dpngen2.op.prep_vasp, 98
dpngen2.op.run_dp_train, 99
dpngen2.op.run_lmp, 101
dpngen2.op.run_vasp, 102
dpngen2.op.select_confs, 103
dpngen2.superop, 104
dpngen2.superop.block, 104
dpngen2.superop.prep_run_dp_train, 106
dpngen2.superop.prep_run_fp, 107
dpngen2.superop.prep_run_lmp, 108
dpngen2.utils, 109
dpngen2.utils.alloy_conf, 109
dpngen2.utils.chdir, 110
dpngen2.utils.dflow_config, 111
dpngen2.utils.dflow_query, 111
dpngen2.utils.download_dpngen2_artifacts, 112
dpngen2.utils.obj_artifact, 112
dpngen2.utils.run_command, 112
dpngen2.utils.step_config, 112
dpngen2.utils.unit_cells, 113

INDEX

A

- `accurate_ratio()` (*dp-gen2.exploration.report.naive_report.NaiveExplorationReport* method), 77
`accurate_ratio()` (*dp-gen2.exploration.report.report.ExplorationReport* method), 78
`accurate_ratio()` (*dp-gen2.exploration.report.trajs_report.TrajsExplorationReport* method), 78
`add()` (*dp-gen2.exploration.selector.conf_filter.ConfFilters* method), 83
`add_def()` (*dp-gen2.utils.download_dpgen2_artifacts.DownloadDefinition* method), 112
`add_file()` (*dp-gen2.exploration.task.task.ExplorationTask* method), 90
`add_group()` (*dp-gen2.exploration.task.task.ExplorationTaskGroup* method), 90
`add_input()` (*dp-gen2.utils.download_dpgen2_artifacts.DownloadDefinition* method), 112
`add_output()` (*dp-gen2.utils.download_dpgen2_artifacts.DownloadDefinition* method), 112
`add_stage_scheduler()` (*dp-gen2.exploration.scheduler.scheduler.ExplorationScheduler* method), 81
`add_task()` (*dp-gen2.exploration.task.task.ExplorationTaskGroup* method), 90
`add_task_group()` (*dp-gen2.exploration.task.stage.ExplorationStage* method), 89
`AlloyConf` (class in *dp-gen2.utils.alloy_conf*), 109
`atom_pert_dist` (Argument)
 `atom_pert_dist:`, 52
`atom_pert_dist:`
 `atom_pert_dist` (Argument), 52
- ### B
- `BCC` (class in *dp-gen2.utils.unit_cells*), 113
- ### C
- `calculate_ratio()` (*dp-gen2.exploration.report.naive_report.NaiveExplorationReport* static method), 77
`candidate_ratio()` (*dp-gen2.exploration.report.naive_report.NaiveExplorationReport* method), 77
`candidate_ratio()` (*dp-gen2.exploration.report.report.ExplorationReport* method), 78
`candidate_ratio()` (*dp-gen2.exploration.report.trajs_report.TrajsExplorationReport* method), 78
`cell_pert_frac` (Argument)
 `cell_pert_frac:`, 52
`cell_pert_frac:`
 `cell_pert_frac` (Argument), 52
`chdir()` (in module *dp-gen2.utils.chdir*), 110
`check()` (*dp-gen2.exploration.selector.conf_filter.ConfFilter* method), 83
`check()` (*dp-gen2.exploration.selector.conf_filter.ConfFilters* method), 83
`cl_step_config:`
 `step_configs/cl_step_config` (Argument), 43
`clear()` (*dp-gen2.exploration.report.trajs_report.TrajsExplorationReport* method), 78
`clear()` (*dp-gen2.exploration.task.stage.ExplorationStage* method), 89
`clear()` (*dp-gen2.exploration.task.task.ExplorationTaskGroup* method), 90
`collect_data_config:`
 `step_configs/collect_data_config` (Argument), 40
`CollectData` (class in *dp-gen2.op.collect_data*), 95
`command` (Argument)
 `command:`, 52
`command:`
 `command` (Argument), 52
 `explore[lmp]/config/command` (Argument), 16
 `fp[vasp]/config/command` (Argument), 15
`complete()` (*dp-gen2.exploration.scheduler.convergence_check_stage_scheduler* method), 79
`complete()` (*dp-gen2.exploration.scheduler.scheduler.ExplorationScheduler* method), 81
`concentration` (Argument)

concentration:, **53**
 concentration:
 concentration (*Argument*), **53**
 ConcurrentLearning (class in *dp-gen2.flow.dpgen_loop*), **91**
 ConcurrentLearningBlock (class in *dp-gen2.superop.block*), **104**
 ConcurrentLearningLoop (class in *dp-gen2.flow.dpgen_loop*), **92**
 ConfFilter (class in *dp-gen2.exploration.selector.conf_filter*), **83**
 ConfFilters (class in *dp-gen2.exploration.selector.conf_filter*), **83**
 config:
 explore[lmp]/config (*Argument*), **16**
 fp[vasp]/config (*Argument*), **15**
 train[dp]/config (*Argument*), **18**
 config_args() (in module *dpgen2.op.run_dp_train*), **101**
 config_args() (in module *dpgen2.op.run_lmp*), **102**
 config_args() (in module *dpgen2.op.run_vasp*), **103**
 configuration_prefix:
 explore[lmp]/configuration_prefix (*Argument*), **17**
 configurations:
 explore[lmp]/configurations (*Argument*), **17**
 ConfSamplingTaskGroup (class in *dp-gen2.exploration.task.conf_sampling_task_group*), **86**
 ConfSelector (class in *dp-gen2.exploration.selector.conf_selector*), **84**
 ConfSelectorLammpsFrames (class in *dp-gen2.exploration.selector.conf_selector_frame*), **84**
 continue_on_failed (*Argument*)
 continue_on_failed:, **57**
 continue_on_failed:
 continue_on_failed (*Argument*), **57**
 default_step_config/continue_on_failed (*Argument*), **47**
 step_configs/cl_step_config/continue_on_failed (*Argument*), **44**
 step_configs/collect_data_config/continue_on_failed (*Argument*), **41**
 step_configs/prepare_explore_config/continue_on_failed (*Argument*), **27**
 step_configs/prepare_fp_config/continue_on_failed (*Argument*), **32**
 step_configs/prepare_train_config/continue_on_failed (*Argument*), **21**
 step_configs/run_explore_config/continue_on_failed (*Argument*), **30**
 step_configs/run_fp_config/continue_on_failed (*Argument*), **36**
 step_configs/run_train_config/continue_on_failed (*Argument*), **24**
 step_configs/select_confs_config/continue_on_failed (*Argument*), **39**
 div_accuracy:
 step_configs/run_train_config/continue_on_failed (*Argument*), **24**
 step_configs/select_confs_config/continue_on_failed (*Argument*), **39**
 step_configs/collect_data_config/continue_on_failed (*Argument*), **41**
 step_configs/prepare_explore_config/continue_on_failed (*Argument*), **27**
 step_configs/prepare_fp_config/continue_on_failed (*Argument*), **32**
 step_configs/prepare_train_config/continue_on_failed (*Argument*), **21**
 step_configs/run_explore_config/continue_on_failed (*Argument*), **30**
 step_configs/run_fp_config/continue_on_failed (*Argument*), **36**
 step_configs/run_train_config/continue_on_failed (*Argument*), **24**
 step_configs/select_confs_config/continue_on_failed (*Argument*), **39**
 continue_on_success_ratio (*Argument*)
 continue_on_success_ratio:, **57**
 continue_on_success_ratio:
 continue_on_success_ratio (*Argument*), **57**
 default_step_config/continue_on_success_ratio (*Argument*), **47**
 step_configs/cl_step_config/continue_on_success_ratio (*Argument*), **45**
 step_configs/collect_data_config/continue_on_success_ratio (*Argument*), **42**
 step_configs/prepare_explore_config/continue_on_success_ratio (*Argument*), **27**
 step_configs/prepare_fp_config/continue_on_success_ratio (*Argument*), **33**
 step_configs/prepare_train_config/continue_on_success_ratio (*Argument*), **21**
 step_configs/run_explore_config/continue_on_success_ratio (*Argument*), **30**
 step_configs/run_fp_config/continue_on_success_ratio (*Argument*), **36**
 step_configs/run_train_config/continue_on_success_ratio (*Argument*), **24**
 step_configs/select_confs_config/continue_on_success_ratio (*Argument*), **39**

explore[*lmp*]/conv_accuracy (*Argument*), **16**
 converged() (*dp*gen2.exploration.scheduler.convergence_check_stage_scheduler.
ConvergenceCheckStageScheduler method), **79**
 converged() (*dp*gen2.exploration.scheduler.stage_scheduler.
StageScheduler method), **82**
 ConvergenceCheckStageScheduler (*class* in *dp*-
 gen2.exploration.scheduler.convergence_check_stage_scheduler), **79**

D

decide_init_model() (*dp*-gen2.op.run_dp_train.RunDPTrain
static method), **100**
 default_step_config (*Argument*)
 default_step_config:, **46**
 default_step_config/continue_on_failed (*Argument*)
 continue_on_failed:, **47**
 default_step_config/continue_on_num_success
 (*Argument*)
 continue_on_num_success:, **47**
 default_step_config/continue_on_success_ratio
 (*Argument*)
 continue_on_success_ratio:, **47**
 default_step_config/executor (*Argument*)
 executor:, **48**
 default_step_config/executor/type (*Argument*)
 type:, **48**
 default_step_config/executor[lebesgue_v2]/extra
 (*Argument*)
 extra:, **48**
 default_step_config/executor[lebesgue_v2]/extra/job_type
 (*Argument*)
 job_type:, **48**
 default_step_config/executor[lebesgue_v2]/extra/program_id
 (*Argument*)
 program_id:, **48**
 default_step_config/executor[lebesgue_v2]/extra/scass_type
 (*Argument*)
 scass_type:, **48**
 default_step_config/executor[lebesgue_v2]/extra/template_cover
 (*Argument*)
 template_cover_cmd_escape_bug:, **48**
 default_step_config/parallelism (*Argument*)
 parallelism:, **47**
 default_step_config/template_config (*Argument*)
 template_config:, **46**
 default_step_config/template_config/envs (*Argument*)
 envs:, **47**
 default_step_config/template_config/image
 (*Argument*)
 image:, **46**
 default_step_config/template_config/retry_on_transient_error
 (*Argument*)
 retry_on_transient_error:, **47**
 default_step_config/template_config/timeout
 (*Argument*)
 timeout:, **47**
 default_step_config/template_config/timeout_as_transient_error
 (*Argument*)
 timeout_as_transient_error:, **47**
 default_step_config:
 default_step_config (*Argument*), **46**
 default_step_config_args() (*in* module *dp*-
 gen2.entrypoint.submit_args), **76**
 dflow_conf_args() (*in* module *dp*-
 gen2.entrypoint.submit_args), **76**
 dflow_config (*Argument*)
 dflow_config:, **49**
 dflow_config() (*in* module *dp*gen2.utils.dflow_config),
111
 dflow_config:
 dflow_config (*Argument*), **49**
 dflow_config_lower() (*in* module *dp*-
 gen2.utils.dflow_config), **111**
 dflow_s3_config() (*in* module *dp*-
 gen2.utils.dflow_config), **111**
 dflow_s3_config_lower() (*in* module *dp*-
 gen2.utils.dflow_config), **111**
 DIAMOND (*class* in *dp*gen2.utils.unit_cells), **113**
 dispatcher_args() (*in* module *dp*-
 gen2.utils.step_config), **112**
 download() (*in* module *dp*gen2.entrypoint.download),
76
 download_dpgen2_artifacts() (*in* module *dp*-
 gen2.utils.download_dpgen2_artifacts), **112**
 DownloadDefinition (*class* in *dp*-
 gen2.utils.download_dpgen2_artifacts), **112**
 dp_train_args() (*in* module *dp*-
 gen2.entrypoint.submit_args), **76**
 dpgen2
 module, **73**
 dpgen2.constants
 module, **114**
 dpgen2.entrypoint
 module, **73**
 dpgen2.entrypoint.download
 module, **73**
 dpgen2.entrypoint.main
 module, **73**
 dpgen2.entrypoint.showkey
 module, **74**
 dpgen2.entrypoint.status
 module, **74**
 dpgen2.entrypoint.submit
 module, **74**

dpngen2.entrypoint.submit_args	dpngen2.fp
module, 76	module, 94
dpngen2.entrypoint.watch	dpngen2.fp.vasp
module, 77	module, 94
dpngen2.exploration	dpngen2.op
module, 77	module, 95
dpngen2.exploration.report	dpngen2.op.collect_data
module, 77	module, 95
dpngen2.exploration.report.naive_report	dpngen2.op.md_settings
module, 77	module, 96
dpngen2.exploration.report.report	dpngen2.op.prep_dp_train
module, 78	module, 96
dpngen2.exploration.report.trajs_report	dpngen2.op.prep_lmp
module, 78	module, 97
dpngen2.exploration.scheduler	dpngen2.op.prep_vasp
module, 79	module, 98
dpngen2.exploration.scheduler.convergence_checker	dpngen2.op.scheduler_train
module, 79	module, 99
dpngen2.exploration.scheduler.scheduler	dpngen2.op.run_lmp
module, 80	module, 101
dpngen2.exploration.scheduler.stage_scheduler	dpngen2.op.run_vasp
module, 82	module, 102
dpngen2.exploration.selector	dpngen2.op.select_confs
module, 83	module, 103
dpngen2.exploration.selector.conf_filter	dpngen2.superop
module, 83	module, 104
dpngen2.exploration.selector.conf_selector	dpngen2.superop.block
module, 84	module, 104
dpngen2.exploration.selector.conf_selector_framework	dpngen2.superop.prep_run_dp_train
module, 84	module, 106
dpngen2.exploration.selector.trust_level	dpngen2.superop.prep_run_fp
module, 85	module, 107
dpngen2.exploration.task	dpngen2.superop.prep_run_lmp
module, 85	module, 108
dpngen2.exploration.task.conf_sampling_task_group	dpngen2.utils
module, 86	module, 109
dpngen2.exploration.task.lmp	dpngen2.utils.alloy_conf
module, 85	module, 109
dpngen2.exploration.task.lmp.lmp_input	dpngen2.utils.chdir
module, 85	module, 110
dpngen2.exploration.task.lmp_template_task_group	dpngen2.utils.dflow_config
module, 87	module, 111
dpngen2.exploration.task.make_task_group_from_configs	dpngen2.utils.dflow_query
module, 88	module, 111
dpngen2.exploration.task.npt_task_group	dpngen2.utils.download_dpngen2_artifacts
module, 88	module, 112
dpngen2.exploration.task.stage	dpngen2.utils.obj_artifact
module, 89	module, 112
dpngen2.exploration.task.task	dpngen2.utils.run_command
module, 89	module, 112
dpngen2.flow	dpngen2.utils.step_config
module, 91	module, 112
dpngen2.flow.dpngen_loop	dpngen2.utils.unit_cells
module, 91	module, 113

dpgen_step_config_args() (in module *dp-
gen2.entrypoint.submit_args*), 76

dt:
 task_group_configs[lmp-md]/dt (Argument),
 54

dump_object_to_file() (in module *dp-
gen2.utils.obj_artifact*), 112

E

ens:
 task_group_configs[lmp-md]/ens (Argument),
 54

envs:
 default_step_config/template_config/envs
 (Argument), 47
 step_configs/cl_step_config/template_config/envs
 (Argument), 44
 step_configs/collect_data_config/template_config/envs
 (Argument), 41
 step_configs/prepare_explore_config/template_config/envs
 (Argument), 26
 step_configs/prepare_fp_config/template_config/envs
 (Argument), 32
 step_configs/prepare_train_config/template_config/envs
 (Argument), 21
 step_configs/run_explore_config/template_config/envs
 (Argument), 29
 step_configs/run_fp_config/template_config/envs
 (Argument), 35
 step_configs/run_train_config/template_config/envs
 (Argument), 23
 step_configs/select_confs_config/template_config/envs
 (Argument), 38
 template_config/envs (Argument), 57

execute() (*dpgen2.flow.dpgen_loop.MakeBlockId*
method), 93

execute() (*dpgen2.flow.dpgen_loop.SchedulerWrapper*
method), 94

execute() (*dpgen2.op.collect_data.CollectData*
method), 95

execute() (*dpgen2.op.prepare_dp_train.PrepareDPTrain*
method), 96

execute() (*dpgen2.op.prepare_lmp.PrepareLmp* *method*), 98

execute() (*dpgen2.op.prepare_vasp.PrepareVasp* *method*), 99

execute() (*dpgen2.op.run_dp_train.RunDPTrain*
method), 100

execute() (*dpgen2.op.run_lmp.RunLmp* *method*), 101

execute() (*dpgen2.op.run_vasp.RunVasp* *method*), 102

execute() (*dpgen2.op.select_confs.SelectConfs*
method), 103

executor (Argument)
 executor:, 56

executor/type (Argument)
 type:, 56

executor:
 default_step_config/executor (Argument), 48
 executor (Argument), 56
 step_configs/cl_step_config/executor (Ar-
 gument), 45
 step_configs/collect_data_config/executor
 (Argument), 42
 step_configs/prepare_explore_config/executor
 (Argument), 27
 step_configs/prepare_fp_config/executor (Ar-
 gument), 33
 step_configs/prepare_train_config/executor
 (Argument), 21
 step_configs/run_explore_config/executor
 (Argument), 30
 step_configs/run_fp_config/executor
 (Argument), 36
 step_configs/run_train_config/executor
 (Argument), 24
 step_configs/select_confs_config/executor
 (Argument), 39

executor[lebesgue_v2]/extra (Argument)
 extra:, 56

executor[lebesgue_v2]/extra/job_type (Argu-
 ment)
 job_type:, 56

executor[lebesgue_v2]/extra/program_id (Argu-
 ment)
 program_id:, 56

executor[lebesgue_v2]/extra/scass_type (Argu-
 ment)
 scass_type:, 56

executor[lebesgue_v2]/extra/template_cover_cmd_escape_bug
 (Argument)
 template_cover_cmd_escape_bug:, 56

expand_idx() (in module *dpgen2.entrypoint.submit*), 74

expand_sys_str() (in module *dp-
gen2.entrypoint.submit*), 74

ExplorationReport (class in *dp-
gen2.exploration.report.report*), 78

ExplorationScheduler (class in *dp-
gen2.exploration.scheduler.scheduler*), 80

ExplorationStage (class in *dp-
gen2.exploration.task.stage*), 89

ExplorationTask (class in *dp-
gen2.exploration.task.task*), 89

ExplorationTaskGroup (class in *dp-
gen2.exploration.task.task*), 90

explore (Argument)
 explore:, 16

explore/type (Argument)
 type:, 16

explore:
 explore (Argument), 16

explore[lmp]/config (*Argument*)
 config:, 16
 explore[lmp]/config/command (*Argument*)
 command:, 16
 explore[lmp]/configuration_prefix (*Argument*)
 configuration_prefix:, 17
 explore[lmp]/configurations (*Argument*)
 configurations:, 17
 explore[lmp]/conv_accuracy (*Argument*)
 conv_accuracy:, 16
 explore[lmp]/f_trust_hi (*Argument*)
 f_trust_hi:, 17
 explore[lmp]/f_trust_lo (*Argument*)
 f_trust_lo:, 17
 explore[lmp]/fatal_at_max (*Argument*)
 fatal_at_max:, 17
 explore[lmp]/max_numb_iter (*Argument*)
 max_numb_iter:, 16
 explore[lmp]/stages (*Argument*)
 stages:, 17
 explore[lmp]/v_trust_hi (*Argument*)
 v_trust_hi:, 17
 explore[lmp]/v_trust_lo (*Argument*)
 v_trust_lo:, 17
 extra:
 default_step_config/executor[lebesgue_v2]/extra
 (*Argument*), 48
 executor[lebesgue_v2]/extra (*Argument*), 56
 step_configs/cl_step_config/executor[lebesgue_v2]/extra
 (*Argument*), 45
 step_configs/collect_data_config/executor[lebesgue_v2]/extra
 (*Argument*), 42
 step_configs/prep_explore_config/executor[lebesgue_v2]/extra
 (*Argument*), 28
 step_configs/prep_fp_config/executor[lebesgue_v2]/extra
 (*Argument*), 33
 step_configs/prep_train_config/executor[lebesgue_v2]/extra
 (*Argument*), 22
 step_configs/run_explore_config/executor[lebesgue_v2]/extra
 (*Argument*), 30
 step_configs/run_fp_config/executor[lebesgue_v2]/extra
 (*Argument*), 36
 step_configs/run_train_config/executor[lebesgue_v2]/extra
 (*Argument*), 24
 step_configs/select_confs_config/executor[lebesgue_v2]/extra
 (*Argument*), 39
 failed_ratio() (*dpgen2.exploration.report.naive_report.NaiveReport*
 method), 77
 failed_ratio() (*dpgen2.exploration.report.report.ExplorationReport*
 method), 78
 failed_ratio() (*dpgen2.exploration.report.trajs_report.TrajsExploration*
 method), 78
 fatal_at_max:
 explore[lmp]/fatal_at_max (*Argument*), 17
 FCC (*class in dpgen2.util.unit_cells*), 113
 files() (*dpgen2.exploration.task.task.ExplorationTask*
 method), 90
 find_only_one_key() (*in module dp-*
 gen2.exploration.task.lmp_template_task_group),
 87
 find_slice_ranges() (*in module dp-*
 gen2.util.dflow_query), 111
 fmt (*Argument*)
 fmt:, 52
 fmt:
 fmt (*Argument*), 52
 FooTask (*class in dpgen2.exploration.task.task*), 90
 FooTaskGroup (*class in dpgen2.exploration.task.task*),
 91
 fp (*Argument*)
 fp:, 15
 fp/type (*Argument*)
 type:, 15
 fp (*Argument*), 15
 fp[vasp]/config (*Argument*)
 fp[vasp]/config/command (*Argument*)
 fp[vasp]/config/log (*Argument*)
 fp[vasp]/config/out (*Argument*)
 fp[vasp]/incar (*Argument*)
 fp[vasp]/pp_files (*Argument*)
 fp[vasp]/task_max (*Argument*)
 fp[vasp]/task_max:, 15
 G
 gen_box() (*dpgen2.util.unit_cells.BCC* method), 113
 gen_box() (*dpgen2.util.unit_cells.DIAMOND* method),
 113
 gen_box() (*dpgen2.util.unit_cells.FCC* method), 113
 gen_box() (*dpgen2.util.unit_cells.HCP* method), 114
 gen_box() (*dpgen2.util.unit_cells.SC* method), 114
 gen_doc() (*in module dpgen2.entrypoint.submit_args*),
 76
 gen_doc() (*in module dpgen2.util.alloy_conf*), 110
 gen_doc() (*in module dpgen2.util.step_config*), 112

`generate_alloy_conf_args()` (in module `dp-gen2.utils.alloy_conf`), 110
`generate_alloy_conf_file_content()` (in module `dp-gen2.utils.alloy_conf`), 110
`generate_file_content()` (`dp-gen2.utils.alloy_conf.AlloyConf` method), 109
`generate_systems()` (`dp-gen2.utils.alloy_conf.AlloyConf` method), 109
`generate_unit_cell()` (in module `dp-gen2.utils.unit_cells`), 114
`get_candidates()` (`dp-gen2.exploration.report.trajs_report.TrajsExplorationReport` method), 78
`get_convergence_ratio()` (`dp-gen2.exploration.scheduler.scheduler.ExplorationScheduler` class method), 81
`get_input_sign()` (`dp-gen2.flow.dpgen_loop.MakeBlockId` class method), 93
`get_input_sign()` (`dp-gen2.flow.dpgen_loop.SchedulerWrapper` class method), 94
`get_input_sign()` (`dp-gen2.op.collect_data.CollectData` class method), 95
`get_input_sign()` (`dp-gen2.op.prep_dp_train.PrepareDPTrain` class method), 97
`get_input_sign()` (`dp-gen2.op.prep_lmp.PrepareLmp` class method), 98
`get_input_sign()` (`dp-gen2.op.prep_vasp.PrepareVasp` class method), 99
`get_input_sign()` (`dp-gen2.op.run_dp_train.RunDPTrain` class method), 100
`get_input_sign()` (`dp-gen2.op.run_lmp.RunLmp` class method), 102
`get_input_sign()` (`dp-gen2.op.run_vasp.RunVasp` class method), 103
`get_input_sign()` (`dp-gen2.op.select_confs.SelectConfs` class method), 104
`get_input_sign()` (`dp-gen2.op.prep_dp_train.PrepareDPTrain` class method), 97
`get_input_sign()` (`dp-gen2.op.prep_lmp.PrepareLmp` class method), 98
`get_input_sign()` (`dp-gen2.op.prep_vasp.PrepareVasp` class method), 99
`get_input_sign()` (`dp-gen2.op.run_dp_train.RunDPTrain` class method), 100
`get_input_sign()` (`dp-gen2.op.run_lmp.RunLmp` class method), 102
`get_input_sign()` (`dp-gen2.op.run_vasp.RunVasp` class method), 103
`get_input_sign()` (`dp-gen2.op.select_confs.SelectConfs` class method), 104
`get_iteration()` (`dp-gen2.exploration.scheduler.scheduler.ExplorationScheduler` method), 81
`get_iteration()` (in module `dp-gen2.utils.dflow_query`), 111
`get_kspacing_kgamma_from_incar()` (in module `dp-gen2.entrypoint.submit`), 74
`get_last_iteration()` (in module `dp-gen2.utils.dflow_query`), 111
`get_last_scheduler()` (in module `dp-gen2.utils.dflow_query`), 111
`get_output_sign()` (`dp-gen2.flow.dpgen_loop.MakeBlockId` class method), 93
`get_output_sign()` (`dp-gen2.flow.dpgen_loop.SchedulerWrapper` class method), 94
`get_output_sign()` (`dp-gen2.op.collect_data.CollectData` class method), 95
`get_output_sign()` (`dp-gen2.op.prep_dp_train.PrepareDPTrain` class method), 97
`get_output_sign()` (`dp-gen2.op.prep_lmp.PrepareLmp` class method), 98
`get_output_sign()` (`dp-gen2.op.prep_vasp.PrepareVasp` class method), 99
`get_output_sign()` (`dp-gen2.op.run_dp_train.RunDPTrain` class method), 100
`get_output_sign()` (`dp-gen2.op.run_lmp.RunLmp` class method), 102
`get_output_sign()` (`dp-gen2.op.run_vasp.RunVasp` class method), 103
`get_output_sign()` (`dp-gen2.op.select_confs.SelectConfs` class method), 104
`get_resubmit_keys()` (in module `dp-gen2.entrypoint.submit`), 74
`get_stage()` (`dp-gen2.exploration.scheduler.scheduler.ExplorationScheduler` method), 81
`get_stage_of_iterations()` (`dp-gen2.exploration.scheduler.scheduler.ExplorationScheduler` method), 81
`get_subkey()` (in module `dp-gen2.utils.dflow_query`), 111

H

HCP (class in `dp-gen2.utils.unit_cells`), 114

I

image:

- `default_step_config/template_config/image` (Argument), 46
- `step_configs/cl_step_config/template_config/image` (Argument), 44
- `step_configs/collect_data_config/template_config/image` (Argument), 41
- `step_configs/prepare_explore_config/template_config/image` (Argument), 26
- `step_configs/prepare_fp_config/template_config/image` (Argument), 32
- `step_configs/prepare_train_config/template_config/image` (Argument), 20

step_configs/run_explore_config/template_config/image/init_model_start_pref_f: **51**
 (Argument), **29** init_model_start_pref_f:
 step_configs/run_fp_config/template_config/image/init_model_start_pref_f (Argument), **51**
 (Argument), **35** train[dp]/config/init_model_start_pref_f
 step_configs/run_train_config/template_config/image (Argument), **19**
 (Argument), **23** init_model_start_pref_v (Argument)
 step_configs/select_confs_config/template_config/image/init_model_start_pref_v: **51**
 (Argument), **38** init_model_start_pref_v:
 template_config/image (Argument), **57** init_model_start_pref_v (Argument), **51**
 train[dp]/config/init_model_start_pref_v
 incar: (Argument), **19**
 fp[vasp]/incar (Argument), **16**
 incar_from_file() (dpgen2.fp.vasp.VaspInputs input_args() (in module dp-
 method), **94** gen2.entrypoint.submit_args), **76**
 incar_template (dpgen2.fp.vasp.VaspInputs property), input_artifacts (dp-
94 gen2.flow.dpgen_loop.ConcurrentLearning
 property), **92**
 init_data_prefix: input_artifacts (dp-
 inputs/init_data_prefix (Argument), **19** gen2.flow.dpgen_loop.ConcurrentLearningLoop
 property), **92**
 init_data_sys: inputs/init_data_sys (Argument), **19**
 init_executor() (in module dpgen2.utils.step_config), input_artifacts (dp-
112 gen2.superop.block.ConcurrentLearningBlock
 property), **105**
 init_keys (dpgen2.flow.dpgen_loop.ConcurrentLearning input_artifacts (dp-
 property), **92** gen2.superop.prep_run_dp_train.PrepareRunDPTrain
 property), **106**
 init_model_numb_steps (Argument) input_artifacts (dp-
 init_model_numb_steps: **51** gen2.superop.prep_run_fp.PrepareRunFp prop-
 erty), **107**
 init_model_numb_steps: input_artifacts (dp-
 init_model_numb_steps (Argument), **51** gen2.superop.prep_run_imp.PrepareRunImp
 train[dp]/config/init_model_numb_steps property), **108**
 (Argument), **18**
 init_model_old_ratio (Argument) input_parameters (dp-
 init_model_old_ratio: **51** gen2.flow.dpgen_loop.ConcurrentLearning
 property), **92**
 init_model_old_ratio: input_parameters (dp-
 init_model_old_ratio (Argument), **51** gen2.flow.dpgen_loop.ConcurrentLearningLoop
 train[dp]/config/init_model_old_ratio property), **92**
 (Argument), **18**
 init_model_policy (Argument) input_parameters (dp-
 init_model_policy: **51** gen2.superop.block.ConcurrentLearningBlock
 property), **105**
 init_model_policy: input_parameters (dp-
 init_model_policy (Argument), **51** gen2.superop.prep_run_dp_train.PrepareRunDPTrain
 train[dp]/config/init_model_policy (Argu- property), **106**
 ment), **18**
 input_parameters (dp-
 gen2.superop.prep_run_fp.PrepareRunFp prop-
 erty), **107**
 input_parameters (dp-
 gen2.superop.prep_run_imp.PrepareRunImp
 property), **108**
 inputs (Argument) inputs: **19**
 inputs/init_data_prefix (Argument) inputs/init_data_prefix: **19**
 init_data_prefix: **19**
 inputs/init_data_sys (Argument)

- init_data_sys:, 19
 inputs/mass_map (Argument)
 mass_map:, 19
 inputs/type_map (Argument)
 type_map:, 19
 inputs:
 inputs (Argument), 19
- ## J
- job_type:
 default_step_config/executor[lebesgue_v2]/extra/job_type (Argument), 48
 executor[lebesgue_v2]/extra/job_type (Argument), 56
 step_configs/cl_step_config/executor[lebesgue_v2]/extra/job_type (Argument), 46
 step_configs/collect_data_config/executor[lebesgue_v2]/extra/job_type (Argument), 43
 step_configs/prep_explore_config/executor[lebesgue_v2]/extra/job_type (Argument), 28
 step_configs/prep_fp_config/executor[lebesgue_v2]/extra/job_type (Argument), 34
 step_configs/prep_train_config/executor[lebesgue_v2]/extra/job_type (Argument), 22
 step_configs/run_explore_config/executor[lebesgue_v2]/extra/job_type (Argument), 31
 step_configs/run_fp_config/executor[lebesgue_v2]/extra/job_type (Argument), 37
 step_configs/run_train_config/executor[lebesgue_v2]/extra/job_type (Argument), 25
 step_configs/select_confs_config/executor[lebesgue_v2]/extra/job_type (Argument), 40
- ## K
- keys (dpngen2.flow.dpngen_loop.ConcurrentLearningLoop property), 92
 keys (dpngen2.superop.block.ConcurrentLearningBlock property), 105
 keys (dpngen2.superop.prep_run_dp_train.PrepRunDPTrain property), 106
 keys (dpngen2.superop.prep_run_fp.PrepRunFp property), 107
 keys (dpngen2.superop.prep_run_lmp.PrepRunLmp property), 108
- ## L
- lattice (Argument)
 lattice:, 53
 lattice:
 lattice (Argument), 53
 lebesgue_conf_args() (in module dp-
 gen2.entrystate.submit_args), 76
 lebesgue_context_config (Argument)
 lebesgue_context_config:, 49
 lebesgue_context_config (Argument), 49
 lebesgue_executor_args() (in module dp-
 gen2.utils.step_config), 112
 lebesgue_extra_args() (in module dp-
 gen2.utils.step_config), 112
 level_f_hi (dpngen2.exploration.selector.trust_level.TrustLevel
 property), 85
 level_f_lo (dpngen2.exploration.selector.trust_level.TrustLevel
 property), 85
 level_v_hi (dpngen2.exploration.selector.trust_level.TrustLevel
 property), 85
 level_v_lo (dpngen2.exploration.selector.trust_level.TrustLevel
 property), 85
 lmp_args() (dpngen2.op.run_lmp.RunLmp static
 method), 102
 lmp_args() (in module dpngen2.entrystate.submit_args),
 76
 lmp_template_fname:
 task_group_configs[lmp_template]/lmp_template_fname
 (Argument), 55
 lmp_template_task_group_args() (in module dp-
 gen2.exploration.task.make_task_group_from_config),
 88
 LmpTemplateTaskGroup (class in dp-
 gen2.exploration.task.lmp_template_task_group),
 87
 load_object_from_file() (in module dp-
 gen2.utils.obj_artifact), 112
 log (Argument)
 log:, 52
 log:
 fp[vasp]/config/log (Argument), 15
 log (Argument), 52
 loop_keys (dpngen2.flow.dpngen_loop.ConcurrentLearning
 property), 92
- ## M
- main() (in module dpngen2.entrystate.main), 73
 main_parser() (in module dpngen2.entrystate.main), 73
 make_concurrent_learning_op() (in module dp-
 gen2.entrystate.submit), 74
 make_conf_list() (in module dp-
 gen2.entrystate.submit), 76
 make_cont() (dpngen2.exploration.task.lmp_template_task_group.LmpTem-
 plateTaskGroup method), 87
 make_kpoints() (dpngen2.fp.vasp.VaspInputs method),
 94
 make_kspacing_kpoints() (in module dp-
 gen2.fp.vasp), 94
 make_lmp_input() (in module dp-
 gen2.exploration.task.lmp.lmp_input), 85

make_naive_exploration_scheduler() (in module *dp-
 gen2.entrypoint.submit*), 76
 make_potcar() (*dpgen2.fp.vasp.VaspInputs* method), 94
 make_task() (*dpgen2.exploration.task.lmp_template_task_group*
 method), 87
 make_task() (*dpgen2.exploration.task.npt_task_group.NPTTask*
 method), 88
 make_task() (*dpgen2.exploration.task.stage.ExplorationStage*
 method), 89
 make_task_group_from_config() (in module *dp-
 gen2.exploration.task.make_task_group_from_config*),
 88
 MakeBlockId (class in *dpgen2.flow.dpgen_loop*), 93
 mass_map:
 inputs/mass_map (Argument), 19
 matched_step_key() (in module *dp-
 gen2.utils.dflow_query*), 111
 max_numb_iter:
 explore[lmp]/max_numb_iter (Argument), 16
 MDSettings (class in *dpgen2.op.md_settings*), 96
 module
 dpgen2, 73
 dpgen2.constants, 114
 dpgen2.entrypoint, 73
 dpgen2.entrypoint.download, 73
 dpgen2.entrypoint.main, 73
 dpgen2.entrypoint.showkey, 74
 dpgen2.entrypoint.status, 74
 dpgen2.entrypoint.submit, 74
 dpgen2.entrypoint.submit_args, 76
 dpgen2.entrypoint.watch, 77
 dpgen2.exploration, 77
 dpgen2.exploration.report, 77
 dpgen2.exploration.report.naive_report,
 77
 dpgen2.exploration.report.report, 78
 dpgen2.exploration.report.trajs_report,
 78
 dpgen2.exploration.scheduler, 79
 dpgen2.exploration.scheduler.convergence_checker,
 79
 dpgen2.exploration.scheduler.scheduler,
 80
 dpgen2.exploration.scheduler.stage_scheduler,
 82
 dpgen2.exploration.selector, 83
 dpgen2.exploration.selector.conf_filter,
 83
 dpgen2.exploration.selector.conf_selector,
 84
 dpgen2.exploration.selector.conf_selector_frame,
 84
 dpgen2.exploration.selector.trust_level,
 85
 dpgen2.exploration.task, 85
 dpgen2.exploration.task.conf_sampling_task_group,
 86
 dpgen2.exploration.task.conf_sampling_task_group.
 lmp, 85
 dpgen2.exploration.task.lmp.lmp_input, 85
 dpgen2.exploration.task.lmp_template_task_group,
 87
 dpgen2.exploration.task.make_task_group_from_config,
 88
 dpgen2.exploration.task.npt_task_group,
 88
 dpgen2.exploration.task.stage, 89
 dpgen2.exploration.task.task, 89
 dpgen2.flow, 91
 dpgen2.flow.dpgen_loop, 91
 dpgen2.fp, 94
 dpgen2.fp.vasp, 94
 dpgen2.op, 95
 dpgen2.op.collect_data, 95
 dpgen2.op.md_settings, 96
 dpgen2.op.prep_dp_train, 96
 dpgen2.op.prep_lmp, 97
 dpgen2.op.prep_vasp, 98
 dpgen2.op.run_dp_train, 99
 dpgen2.op.run_lmp, 101
 dpgen2.op.run_vasp, 102
 dpgen2.op.select_confs, 103
 dpgen2.superop, 104
 dpgen2.superop.block, 104
 dpgen2.superop.prep_run_dp_train, 106
 dpgen2.superop.prep_run_fp, 107
 dpgen2.superop.prep_run_lmp, 108
 dpgen2.utils, 109
 dpgen2.utils.alloy_conf, 109
 dpgen2.utils.chdir, 110
 dpgen2.utils.dflow_config, 111
 dpgen2.utils.dflow_query, 111
 dpgen2.utils.download_dpgen2_artifacts,
 112
 dpgen2.utils.schedule,
 112
 dpgen2.utils.run_command, 112
 dpgen2.utils.step_config, 112
 dpgen2.utils.unit_cells, 113
 NaiveExplorationReport (class in *dp-
 gen2.exploration.report.naive_report*), 77
 neidelay:
 task_group_configs[lmp-md]/neidelay
 (Argument), 54
 no_pbc:
 task_group_configs[lmp-md]/no_pbc (Argu-
 ment), 55

normalize() (in module *dp-gen2.entrypoint.submit_args*), 76
 normalize() (in module *dp-gen2.exploration.task.make_task_group_from_config*), 88
 normalize() (in module *dp-gen2.utils.alloy_conf*), 110
 normalize() (in module *dp-gen2.utils.step_config*), 112
 normalize_config() (*dp-gen2.op.run_dp_train.RunDPTrain* static method), 100
 normalize_config() (*dp-gen2.op.run_imp.RunImp* static method), 102
 normalize_config() (*dp-gen2.op.run_vasp.RunVasp* static method), 103
 npt_task_group_args() (in module *dp-gen2.exploration.task.make_task_group_from_config*), 88
 NPTTaskGroup (class in *dp-gen2.exploration.task.npt_task_group*), 88
 nsteps:
 task_group_configs[*lmp-md*]/nsteps (Argument), 54
 numb_atoms() (*dp-gen2.utils.unit_cells.BCC* method), 113
 numb_atoms() (*dp-gen2.utils.unit_cells.DIAMOND* method), 113
 numb_atoms() (*dp-gen2.utils.unit_cells.FCC* method), 113
 numb_atoms() (*dp-gen2.utils.unit_cells.HCP* method), 114
 numb_atoms() (*dp-gen2.utils.unit_cells.SC* method), 114
 numb_confs (Argument)
 numb_confs:, 53
 numb_confs:
 numb_confs (Argument), 53
 numb_models:
 train[*dp*]/numb_models (Argument), 19
O
 out (Argument)
 out:, 52
 out:
 fp[*vasp*]/config/out (Argument), 15
 out (Argument), 52
 output_artifacts (dp-gen2.flow.dp-gen2_loop.ConcurrentLearning property), 92
 output_artifacts (dp-gen2.flow.dp-gen2_loop.ConcurrentLearningLoop property), 93
 output_artifacts (dp-gen2.superop.block.ConcurrentLearningBlock property), 105
 output_artifacts (dp-gen2.superop.prep_run_dp_train.PrepRunDPTrain property), 106
 output_artifacts (dp-gen2.superop.prep_run_fp.PrepRunFp property), 107
 output_artifacts (dp-gen2.superop.prep_run_imp.PrepRunImp property), 108
 output_parameters (dp-gen2.flow.dp-gen2_loop.ConcurrentLearning property), 92
 output_parameters (dp-gen2.flow.dp-gen2_loop.ConcurrentLearningLoop property), 93
 output_parameters (dp-gen2.superop.block.ConcurrentLearningBlock property), 105
 output_parameters (dp-gen2.superop.prep_run_dp_train.PrepRunDPTrain property), 106
 output_parameters (dp-gen2.superop.prep_run_fp.PrepRunFp property), 107
 output_parameters (dp-gen2.superop.prep_run_imp.PrepRunImp property), 108
P
 parallelism (Argument)
 parallelism:, 56
 parallelism:
 default_step_config/parallelism (Argument), 47
 parallelism (Argument), 56
 step_configs/cl_step_config/parallelism (Argument), 45
 step_configs/collect_data_config/parallelism (Argument), 42
 step_configs/prep_explore_config/parallelism (Argument), 27
 step_configs/prep_fp_config/parallelism (Argument), 33
 step_configs/prep_train_config/parallelism (Argument), 21
 step_configs/run_explore_config/parallelism (Argument), 30
 step_configs/run_fp_config/parallelism (Argument), 36
 step_configs/run_train_config/parallelism (Argument), 24
 step_configs/select_confs_config/parallelism (Argument), 39
 parse_args() (in module *dp-gen2.entrypoint.main*), 73

pka_e:
 task_group_configs[lmp-md]/pka_e (Argument), **54**
 plan_next_iteration() (dp-gen2.exploration.scheduler.convergence_check_stage_scheduler.ConvergenceCheckStageScheduler method), **80**
 plan_next_iteration() (dp-gen2.exploration.scheduler.scheduler.ExplorationScheduler method), **81**
 plan_next_iteration() (dp-gen2.exploration.scheduler.stage_scheduler.StageScheduler method), **82**
 plm_template_fname:
 task_group_configs[lmp-template]/plm_template_fname (Argument), **55**
 poscar_unit() (dp-gen2.utils.unit_cells.BCC method), **113**
 poscar_unit() (dp-gen2.utils.unit_cells.DIAMOND method), **113**
 poscar_unit() (dp-gen2.utils.unit_cells.FCC method), **114**
 poscar_unit() (dp-gen2.utils.unit_cells.HCP method), **114**
 poscar_unit() (dp-gen2.utils.unit_cells.SC method), **114**
 potcars (dp-gen2.fp.vasp.VaspInputs property), **94**
 potcars_from_file() (dp-gen2.fp.vasp.VaspInputs method), **94**
 pp_files:
 fp[vasp]/pp_files (Argument), **16**
 prep_explore_config:
 step_configs/prep_explore_config (Argument), **25**
 prep_fp_config:
 step_configs/prep_fp_config (Argument), **31**
 prep_train_config:
 step_configs/prep_train_config (Argument), **20**
 PrepDPTrain (class in dp-gen2.op.prep_dp_train), **96**
 PrepExplorationTaskGroup (in module dp-gen2.op.prep_lmp), **97**
 PrepLmp (class in dp-gen2.op.prep_lmp), **97**
 PrepRunDPTrain (class in dp-gen2.superop.prep_run_dp_train), **106**
 PrepRunFp (class in dp-gen2.superop.prep_run_fp), **107**
 PrepRunLmp (class in dp-gen2.superop.prep_run_lmp), **108**
 PrepVasp (class in dp-gen2.op.prep_vasp), **98**
 press:
 task_group_configs[lmp-md]/press (Argument), **54**
 print_convergence() (dp-gen2.exploration.scheduler.scheduler.ExplorationScheduler method), **81**
 print_keys_in_nice_format() (in module dp-gen2.utils.dflow_query), **111**
 print_list_steps() (in module dp-gen2.entrypoint.submit), **76**
 program_id: ConvergenceCheckStageScheduler
 default_step_config/executor[lebesgue_v2]/extra/program_id (Argument), **48**
 executor[lebesgue_v2]/extra/program_id (Argument), **56**
 step_configs/cl_step_config/executor[lebesgue_v2]/extra/program_id (Argument), **46**
 step_configs/collect_data_config/executor[lebesgue_v2]/extra/program_id (Argument), **43**
 step_configs/prepare_config/executor[lebesgue_v2]/extra/program_id (Argument), **28**
 step_configs/prep_fp_config/executor[lebesgue_v2]/extra/program_id (Argument), **34**
 step_configs/prep_train_config/executor[lebesgue_v2]/extra/program_id (Argument), **22**
 step_configs/run_explore_config/executor[lebesgue_v2]/extra/program_id (Argument), **31**
 step_configs/run_fp_config/executor[lebesgue_v2]/extra/program_id (Argument), **37**
 step_configs/run_train_config/executor[lebesgue_v2]/extra/program_id (Argument), **25**
 step_configs/select_confs_config/executor[lebesgue_v2]/extra/program_id (Argument), **40**
R
 ratio() (dp-gen2.exploration.report.naive_report.NaiveExplorationReport method), **77**
 reached_max_iteration() (dp-gen2.exploration.scheduler.convergence_check_stage_scheduler.ConvergenceCheckStageScheduler method), **80**
 record_one_traj() (dp-gen2.exploration.selector.conf_selector_frame.ConfSelectorLammps method), **84**
 record_traj() (dp-gen2.exploration.report.trajs_report.TrajsExplorationReport method), **78**
 relative_f_epsilon:
 task_group_configs[lmp-md]/relative_f_epsilon (Argument), **55**
 relative_v_epsilon:
 task_group_configs[lmp-md]/relative_v_epsilon (Argument), **55**
 replicate (Argument)
 replicate:, **53**
 replicate:
 replicate (Argument), **53**
 resubmit_concurrent_learning() (in module dp-gen2.entrypoint.submit), **76**
 retry_on_transient_error:
 default_step_config/template_config/retry_on_transient_error (Argument), **47**

step_configs/cl_step_config/template_config(retry_on_transient_error), 114
 (Argument), 44 scass_type:
 step_configs/collect_data_config/template_config/default_step_config/executor[lebesgue_v2]/extra/scass_type
 (Argument), 41 (Argument), 48
 step_configs/prepare_explore_config/template_config/extra/scass_type
 (Argument), 26 (Argument), 56
 step_configs/prepare_fp_config/template_config/retry_on_transient_error/executor[lebesgue_v2]/extra/scass_type
 (Argument), 32 (Argument), 45
 step_configs/prepare_train_config/template_config/retry_on_transient_error/executor[lebesgue_v2]/extra/scass_type
 (Argument), 20 (Argument), 43
 step_configs/run_explore_config/template_config/retry_on_transient_error/executor[lebesgue_v2]/extra/scass_type
 (Argument), 29 (Argument), 28
 step_configs/run_fp_config/template_config/retry_on_transient_error/executor[lebesgue_v2]/extra/scass_type
 (Argument), 35 (Argument), 34
 step_configs/run_train_config/template_config/retry_on_transient_error/executor[lebesgue_v2]/extra/scass_type
 (Argument), 23 (Argument), 22
 step_configs/select_confs_config/template_config/retry_on_transient_error/executor[lebesgue_v2]/extra/scass_type
 (Argument), 38 (Argument), 31
 template_config/retry_on_transient_error step_configs/run_fp_config/executor[lebesgue_v2]/extra/scass_type
 (Argument), 57 (Argument), 37
 revise_by_keys() (in module dp- step_configs/run_train_config/executor[lebesgue_v2]/extra/scass_type
 gen2.exploration.task.lmp_template_task_group), (Argument), 25
 87 step_configs/select_confs_config/executor[lebesgue_v2]/extra/scass_type
 (Argument), 40
 revise_lmp_input_dump() (in module dp- SchedulerWrapper (class in dp- gen2.flow.dpgen_loop),
 gen2.exploration.task.lmp_template_task_group), 93
 87
 revise_lmp_input_model() (in module dp- select() (dp- gen2.exploration.selector.conf_selector.ConfSelector
 gen2.exploration.task.lmp_template_task_group), method), 84
 87 select() (dp- gen2.exploration.selector.conf_selector_frame.ConfSelectorL
 method), 84
 revise_lmp_input_plm() (in module dp- select_confs_config:
 gen2.exploration.task.lmp_template_task_group), 87
 87 step_configs/select_confs_config (Argu-
 ment), 37
 revisions:
 task_group_configs[lmp-template]/revisionsSelectConfs (class in dp- gen2.op.select_confs), 103
 (Argument), 55 set_conf() (dp- gen2.exploration.task.conf_sampling_task_group.ConfSam-
 plingTaskGroup), 86
 run_command() (in module dp- gen2.utils.run_command), 112 set_directory() (in module dp- gen2.utils.chdir), 110
 run_explore_config: set_lmp() (dp- gen2.exploration.task.lmp_template_task_group.LmpTempla-
 step_configs/run_explore_config (Argu- method), 87
 ment), 28 set_md() (dp- gen2.exploration.task.npt_task_group.NPTTaskGroup
 method), 88
 run_fp_config: showkey() (in module dp- gen2.entrypoint.showkey), 74
 step_configs/run_fp_config (Argument), 34 sort_slice_ops() (in module dp- gen2.utils.dflow_query), 111
 run_train_config: stages:
 step_configs/run_train_config (Argument), 22 explore[lmp]/stages (Argument), 17
 StageScheduler (class in dp- gen2.exploration.scheduler.stage_scheduler),
 82
 RunDPTrain (class in dp- gen2.op.run_dp_train), 99 status() (in module dp- gen2.entrypoint.status), 74
 RunLmp (class in dp- gen2.op.run_lmp), 101 step_conf_args() (in module dp- gen2.utils.step_config), 112
 RunVasp (class in dp- gen2.op.run_vasp), 102 step_configs (Argument)
 step_configs:, 20
S
 s3_config (Argument)
 s3_config:, 49
 s3_config:
 s3_config (Argument), 49

step_configs/cl_step_config (*Argument*)
 cl_step_config:, 43
 step_configs/cl_step_config/continue_on_failed (*Argument*)
 continue_on_failed:, 44
 step_configs/cl_step_config/continue_on_num_success (*Argument*)
 continue_on_num_success:, 45
 step_configs/cl_step_config/continue_on_success_ratio (*Argument*)
 continue_on_success_ratio:, 45
 step_configs/cl_step_config/executor (*Argument*)
 executor:, 45
 step_configs/cl_step_config/executor/type (*Argument*)
 type:, 45
 step_configs/cl_step_config/executor[lebesgue_v2]/extra (*Argument*)
 extra:, 45
 step_configs/cl_step_config/executor[lebesgue_v2]/extra/job_type (*Argument*)
 job_type:, 46
 step_configs/cl_step_config/executor[lebesgue_v2]/extra/program_id (*Argument*)
 program_id:, 46
 step_configs/cl_step_config/executor[lebesgue_v2]/extra/scass_type (*Argument*)
 scass_type:, 45
 step_configs/cl_step_config/executor[lebesgue_v2]/extra/template_cover_cmd_escape_bug (*Argument*)
 template_cover_cmd_escape_bug:, 46
 step_configs/cl_step_config/parallelism (*Argument*)
 parallelism:, 45
 step_configs/cl_step_config/template_config (*Argument*)
 template_config:, 43
 step_configs/cl_step_config/template_config/envs (*Argument*)
 envs:, 44
 step_configs/cl_step_config/template_config/image (*Argument*)
 image:, 44
 step_configs/cl_step_config/template_config/retry_on_transient_error (*Argument*)
 retry_on_transient_error:, 44
 step_configs/cl_step_config/template_config/timeout (*Argument*)
 timeout:, 44
 step_configs/cl_step_config/template_config/timeout_as_transient_error (*Argument*)
 timeout_as_transient_error:, 44
 step_configs/collect_data_config (*Argument*)
 collect_data_config:, 40
 step_configs/collect_data_config/continue_on_failed (*Argument*)
 continue_on_failed:, 41
 step_configs/collect_data_config/continue_on_num_success (*Argument*)
 continue_on_num_success:, 42
 step_configs/collect_data_config/continue_on_success_ratio (*Argument*)
 continue_on_success_ratio:, 42
 step_configs/collect_data_config/executor (*Argument*)
 executor:, 42
 step_configs/collect_data_config/executor/type (*Argument*)
 type:, 42
 step_configs/collect_data_config/executor[lebesgue_v2]/extra (*Argument*)
 extra:, 42
 step_configs/collect_data_config/executor[lebesgue_v2]/extra/job_type (*Argument*)
 job_type:, 43
 step_configs/collect_data_config/executor[lebesgue_v2]/extra/program_id (*Argument*)
 program_id:, 43
 step_configs/collect_data_config/executor[lebesgue_v2]/extra/scass_type (*Argument*)
 scass_type:, 43
 step_configs/collect_data_config/executor[lebesgue_v2]/extra/template_cover_cmd_escape_bug (*Argument*)
 template_cover_cmd_escape_bug:, 43
 step_configs/collect_data_config/parallelism (*Argument*)
 parallelism:, 42
 step_configs/collect_data_config/template_config (*Argument*)
 template_config:, 40
 step_configs/collect_data_config/template_config/envs (*Argument*)
 envs:, 41
 step_configs/collect_data_config/template_config/image (*Argument*)
 image:, 41
 step_configs/collect_data_config/template_config/retry_on_transient_error (*Argument*)
 retry_on_transient_error:, 41
 step_configs/collect_data_config/template_config/timeout (*Argument*)
 timeout:, 41
 step_configs/collect_data_config/template_config/timeout_as_transient_error (*Argument*)
 timeout_as_transient_error:, 41
 step_configs/prepare_explore_config (*Argument*)
 prep_explore_config:, 25

step_configs/prepare_explore_config/continue_on_failed (Argument)
 continue_on_failed:, 27
 step_configs/prepare_explore_config/continue_on_num_success (Argument)
 continue_on_num_success:, 27
 step_configs/prepare_explore_config/continue_on_success_ratio (Argument)
 continue_on_success_ratio:, 27
 step_configs/prepare_explore_config/executor (Argument)
 executor:, 27
 step_configs/prepare_explore_config/executor/type (Argument)
 type:, 27
 step_configs/prepare_explore_config/executor[lebesgue_v2] (Argument)
 extra:, 28
 step_configs/prepare_explore_config/executor[lebesgue_v2] (Argument)
 job_type:, 28
 step_configs/prepare_explore_config/executor[lebesgue_v2] (Argument)
 program_id:, 28
 step_configs/prepare_explore_config/executor[lebesgue_v2] (Argument)
 scass_type:, 28
 step_configs/prepare_explore_config/executor[lebesgue_v2] (Argument)
 template_cover_cmd_escape_bug:, 28
 step_configs/prepare_explore_config/parallelism (Argument)
 parallelism:, 27
 step_configs/prepare_explore_config/template_config (Argument)
 template_config:, 26
 step_configs/prepare_explore_config/template_config/envs (Argument)
 envs:, 26
 step_configs/prepare_explore_config/template_config/image (Argument)
 image:, 26
 step_configs/prepare_explore_config/template_config/retry_on_transient_error (Argument)
 retry_on_transient_error:, 26
 step_configs/prepare_explore_config/template_config/timeout (Argument)
 timeout:, 26
 step_configs/prepare_explore_config/template_config/timeout_as_transient_error (Argument)
 timeout_as_transient_error:, 26
 step_configs/prepare_fp_config (Argument)
 prepare_fp_config:, 31
 step_configs/prepare_fp_config/continue_on_failed (Argument)
 continue_on_failed:, 32
 step_configs/prepare_fp_config/continue_on_num_success (Argument)
 continue_on_num_success:, 33
 step_configs/prepare_fp_config/continue_on_success_ratio (Argument)
 continue_on_success_ratio:, 33
 step_configs/prepare_fp_config/executor (Argument)
 executor:, 33
 step_configs/prepare_fp_config/executor/type (Argument)
 type:, 33
 step_configs/prepare_fp_config/executor[lebesgue_v2]/extra (Argument)
 extra:, 33
 step_configs/prepare_fp_config/executor[lebesgue_v2]/extra/job_type (Argument)
 job_type:, 34
 step_configs/prepare_fp_config/executor[lebesgue_v2]/extra/program_id (Argument)
 program_id:, 34
 step_configs/prepare_fp_config/executor[lebesgue_v2]/extra/scass_type (Argument)
 scass_type:, 34
 step_configs/prepare_fp_config/executor[lebesgue_v2]/extra/template_cover_cmd_escape_bug (Argument)
 template_cover_cmd_escape_bug:, 34
 step_configs/prepare_fp_config/parallelism (Argument)
 parallelism:, 33
 step_configs/prepare_fp_config/template_config (Argument)
 template_config:, 32
 step_configs/prepare_fp_config/template_config/envs (Argument)
 envs:, 32
 step_configs/prepare_fp_config/template_config/image (Argument)
 image:, 32
 step_configs/prepare_fp_config/template_config/retry_on_transient_error (Argument)
 retry_on_transient_error:, 32
 step_configs/prepare_fp_config/template_config/timeout (Argument)
 timeout:, 32
 step_configs/prepare_fp_config/template_config/timeout_as_transient_error (Argument)
 timeout_as_transient_error:, 32
 step_configs/prepare_train_config (Argument)
 prepare_train_config:, 20
 step_configs/prepare_train_config/continue_on_failed (Argument)

continue_on_failed:, 21
 step_configs/prep_train_config/continue_on_num_success (Argument)
 (Argument)
 continue_on_num_success:, 21
 step_configs/prep_train_config/continue_on_success_ratio (Argument)
 (Argument)
 continue_on_success_ratio:, 21
 step_configs/prep_train_config/executor (Argument)
 (Argument)
 executor:, 21
 step_configs/prep_train_config/executor/type (Argument)
 (Argument)
 type:, 21
 step_configs/prep_train_config/executor[lebesgue_v2] (Argument)
 (Argument)
 extra:, 22
 step_configs/prep_train_config/executor[lebesgue_v2] (Argument)
 (Argument)
 job_type:, 22
 step_configs/prep_train_config/executor[lebesgue_v2] (Argument)
 (Argument)
 program_id:, 22
 step_configs/prep_train_config/executor[lebesgue_v2] (Argument)
 (Argument)
 scass_type:, 22
 step_configs/prep_train_config/executor[lebesgue_v2] (Argument)
 (Argument)
 template_cover_cmd_escape_bug:, 22
 step_configs/prep_train_config/parallelism (Argument)
 (Argument)
 parallelism:, 21
 step_configs/prep_train_config/template_config (Argument)
 (Argument)
 template_config:, 20
 step_configs/prep_train_config/template_config/envs (Argument)
 (Argument)
 envs:, 21
 step_configs/prep_train_config/template_config/image (Argument)
 (Argument)
 image:, 20
 step_configs/prep_train_config/template_config/retry_on_transient_error (Argument)
 (Argument)
 retry_on_transient_error:, 20
 step_configs/prep_train_config/template_config/timeout (Argument)
 (Argument)
 timeout:, 20
 step_configs/prep_train_config/template_config/timeout_as_transient_error (Argument)
 (Argument)
 timeout_as_transient_error:, 21
 step_configs/run_explore_config (Argument)
 (Argument)
 run_explore_config:, 28
 step_configs/run_explore_config/continue_on_failed (Argument)
 (Argument)
 continue_on_failed:, 30
 step_configs/run_explore_config/continue_on_num_success (Argument)
 (Argument)
 continue_on_num_success:, 30
 step_configs/run_explore_config/continue_on_success_ratio (Argument)
 (Argument)
 continue_on_success_ratio:, 30
 step_configs/run_explore_config/executor (Argument)
 (Argument)
 executor:, 30
 step_configs/run_explore_config/executor/type (Argument)
 (Argument)
 type:, 30
 step_configs/run_explore_config/executor[lebesgue_v2] (Argument)
 (Argument)
 extra:, 30
 step_configs/run_explore_config/executor[lebesgue_v2] (Argument)
 (Argument)
 job_type:, 31
 step_configs/run_explore_config/executor[lebesgue_v2] (Argument)
 (Argument)
 program_id:, 31
 step_configs/run_explore_config/executor[lebesgue_v2] (Argument)
 (Argument)
 scass_type:, 31
 step_configs/run_explore_config/executor[lebesgue_v2] (Argument)
 (Argument)
 template_cover_cmd_escape_bug:, 31
 step_configs/run_explore_config/parallelism (Argument)
 (Argument)
 parallelism:, 30
 step_configs/run_explore_config/template_config (Argument)
 (Argument)
 template_config:, 29
 step_configs/run_explore_config/template_config/envs (Argument)
 (Argument)
 envs:, 29
 step_configs/run_explore_config/template_config/image (Argument)
 (Argument)
 image:, 29
 step_configs/run_explore_config/template_config/retry_on_transient_error (Argument)
 (Argument)
 retry_on_transient_error:, 29
 step_configs/run_explore_config/template_config/timeout (Argument)
 (Argument)
 timeout:, 29
 step_configs/run_explore_config/template_config/timeout_as_transient_error (Argument)
 (Argument)
 timeout_as_transient_error:, 29
 step_configs/run_fp_config (Argument)
 (Argument)
 run_fp_config:, 34
 step_configs/run_fp_config/continue_on_failed (Argument)
 (Argument)
 continue_on_failed:, 35
 step_configs/run_fp_config/continue_on_num_success (Argument)
 (Argument)

(Argument)
 continue_on_num_success:, 36
 step_configs/run_fp_config/continue_on_success_ratio (Argument)
 (Argument)
 continue_on_success_ratio:, 36
 step_configs/run_fp_config/executor (Argument)
 (Argument)
 executor:, 36
 step_configs/run_fp_config/executor/type (Argument)
 (Argument)
 type:, 36
 step_configs/run_fp_config/executor[lebesgue_v2]/extra (Argument)
 (Argument)
 extra:, 36
 step_configs/run_fp_config/executor[lebesgue_v2]/extra/job_type (Argument)
 (Argument)
 job_type:, 37
 step_configs/run_fp_config/executor[lebesgue_v2]/extra/program_id (Argument)
 (Argument)
 program_id:, 37
 step_configs/run_fp_config/executor[lebesgue_v2]/extra/scass_type (Argument)
 (Argument)
 scass_type:, 37
 step_configs/run_fp_config/executor[lebesgue_v2]/extra/template_cover_cmd_escape_bug (Argument)
 (Argument)
 template_cover_cmd_escape_bug:, 37
 step_configs/run_fp_config/parallelism (Argument)
 (Argument)
 parallelism:, 36
 step_configs/run_fp_config/template_config (Argument)
 (Argument)
 template_config:, 35
 step_configs/run_fp_config/template_config/envs (Argument)
 (Argument)
 envs:, 35
 step_configs/run_fp_config/template_config/image (Argument)
 (Argument)
 image:, 35
 step_configs/run_fp_config/template_config/retry_on_transient_error (Argument)
 (Argument)
 retry_on_transient_error:, 35
 step_configs/run_fp_config/template_config/timeout (Argument)
 (Argument)
 timeout:, 35
 step_configs/run_fp_config/template_config/timeout_as_transient_error (Argument)
 (Argument)
 timeout_as_transient_error:, 35
 step_configs/run_train_config (Argument)
 (Argument)
 run_train_config:, 22
 step_configs/run_train_config/continue_on_failed (Argument)
 (Argument)
 continue_on_failed:, 24
 step_configs/run_train_config/continue_on_num_success (Argument)
 (Argument)
 continue_on_num_success:, 24
 step_configs/run_train_config/continue_on_success_ratio (Argument)
 (Argument)
 continue_on_success_ratio:, 24
 step_configs/run_train_config/executor (Argument)
 (Argument)
 executor:, 24
 step_configs/run_train_config/executor/type (Argument)
 (Argument)
 type:, 24
 step_configs/run_train_config/executor[lebesgue_v2]/extra (Argument)
 (Argument)
 extra:, 24
 step_configs/run_train_config/executor[lebesgue_v2]/extra/job_type (Argument)
 (Argument)
 job_type:, 25
 step_configs/run_train_config/executor[lebesgue_v2]/extra/program_id (Argument)
 (Argument)
 program_id:, 25
 step_configs/run_train_config/executor[lebesgue_v2]/extra/scass_type (Argument)
 (Argument)
 scass_type:, 25
 step_configs/run_train_config/executor[lebesgue_v2]/extra/template_cover_cmd_escape_bug (Argument)
 (Argument)
 template_cover_cmd_escape_bug:, 25
 step_configs/run_train_config/parallelism (Argument)
 (Argument)
 parallelism:, 24
 step_configs/run_train_config/template_config (Argument)
 (Argument)
 template_config:, 23
 step_configs/run_train_config/template_config/envs (Argument)
 (Argument)
 envs:, 23
 step_configs/run_train_config/template_config/image (Argument)
 (Argument)
 image:, 23
 step_configs/run_train_config/template_config/retry_on_transient_error (Argument)
 (Argument)
 retry_on_transient_error:, 23
 step_configs/run_train_config/template_config/timeout (Argument)
 (Argument)
 timeout:, 23
 step_configs/run_train_config/template_config/timeout_as_transient_error (Argument)
 (Argument)
 timeout_as_transient_error:, 23
 step_configs/select_confs_config (Argument)
 (Argument)
 select_confs_config:, 37
 step_configs/select_confs_config/continue_on_failed (Argument)
 (Argument)
 continue_on_failed:, 38
 step_configs/select_confs_config/continue_on_num_success (Argument)
 (Argument)
 continue_on_num_success:, 39

step_configs/select_confs_config/continue_on_success_ratio
 (Argument) **continue_on_success_ratio**:, 39
 step_configs/select_confs_config/executor
 (Argument) **executor**:, 39
 step_configs/select_confs_config/executor/type
 (Argument) **type**:, 39
 step_configs/select_confs_config/executor[lebesgue_v2]/extra
 (Argument) **extra**:, 39
 step_configs/select_confs_config/executor[lebesgue_v2]/extra/job_type
 (Argument) **job_type**:, 40
 step_configs/select_confs_config/executor[lebesgue_v2]/extra/program_id
 (Argument) **program_id**:, 40
 step_configs/select_confs_config/executor[lebesgue_v2]/extra/scass_type
 (Argument) **scass_type**:, 40
 step_configs/select_confs_config/executor[lebesgue_v2]/extra/template_cover_cmd_escape_bug
 (Argument) **template_cover_cmd_escape_bug**:, 40
 step_configs/select_confs_config/parallelism
 (Argument) **parallelism**:, 39
 step_configs/select_confs_config/template_config
 (Argument) **template_config**:, 37
 step_configs/select_confs_config/template_config/envs
 (Argument) **envs**:, 38
 step_configs/select_confs_config/template_config/image
 (Argument) **image**:, 38
 step_configs/select_confs_config/template_config/retry_on_transient_error
 (Argument) **retry_on_transient_error**:, 38
 step_configs/select_confs_config/template_config/timeout
 (Argument) **timeout**:, 38
 step_configs/select_confs_config/template_config/timeout_as_transient_error
 (Argument) **timeout_as_transient_error**:, 38
 step_configs:
 step_configs (Argument), 20
 submit_args() (in module dp-
 gen2.entrypoint.submit_args), 76
 submit_concurrent_learning() (in module dp-
 gen2.entrypoint.submit), 76
 successful_step_keys() (in module dp-
 gen2.entrypoint.submit), 76

Success_ratio
 task_group_args() (in module dp-
 gen2.exploration.task.make_task_group_from_config),
 88
 task_group_configs (Argument)
 task_group_configs:, 53
 task_group_configs/type (Argument)
 type:, 53
 task_group_configs:
 task_group_configs (Argument), 53
 task_group_configs[lmp-md]/dt (Argument)
 dt:, 54
 task_group_configs[lmp-md]/ens (Argument)
 ens:, 54
 task_group_configs[lmp-md]/neidelay (Argu-
 ment)
 neidelay:, 54
 task_group_configs[lmp-md]/no_pbc (Argument)
 no_pbc:, 55
 task_group_configs[lmp-md]/nsteps (Argument)
 nsteps:, 54
 task_group_configs[lmp-md]/pka_e (Argument)
 pka_e:, 54
 task_group_configs[lmp-md]/press (Argument)
 press:, 54
 task_group_configs[lmp-md]/relative_f_epsilon
 (Argument)
 relative_f_epsilon:, 55
 task_group_configs[lmp-md]/relative_v_epsilon
 (Argument)
 relative_v_epsilon:, 55
 task_group_configs[lmp-md]/tau_p (Argument)
 tau_p:, 54
 task_group_configs[lmp-md]/tau_t (Argument)
 tau_t:, 54
 task_group_configs[lmp-md]/temps (Argument)
 temps:, 53
 task_group_configs[lmp-md]/trj_freq (Argu-
 ment)
 trj_freq:, 54
 task_group_configs[lmp-md]/use_clusters
 (Argument)
 use_clusters:, 55
 task_group_configs[lmp-template]/lmp_template_fname
 (Argument)
 lmp_template_fname:, 55
 task_group_configs[lmp-template]/plm_template_fname
 (Argument)
 plm_template_fname:, 55
 task_group_configs[lmp-template]/revisions
 (Argument)
 revisions:, 55
 task_group_configs[lmp-template]/traj_freq
 (Argument)

traj_freq:, 55
 task_list (*dpngen2.exploration.task.task.ExplorationTaskGroup* property), 90
 task_list (*dpngen2.exploration.task.task.FooTaskGroup* property), 91
 task_max:
 fp[vasp]/task_max (*Argument*), 15
 tau_p:
 task_group_configs[lmp-md]/tau_p (*Argument*), 54
 tau_t:
 task_group_configs[lmp-md]/tau_t (*Argument*), 54
 template_conf_args() (*in module dpngen2.utils.step_config*), 113
 template_config (*Argument*)
 template_config:, 57
 template_config/envs (*Argument*)
 envs:, 57
 template_config/image (*Argument*)
 image:, 57
 template_config/retry_on_transient_error (*Argument*)
 retry_on_transient_error:, 57
 template_config/timeout (*Argument*)
 timeout:, 57
 template_config/timeout_as_transient_error (*Argument*)
 timeout_as_transient_error:, 57
 template_config:
 default_step_config/template_config (*Argument*), 46
 step_configs/cl_step_config/template_config (*Argument*), 43
 step_configs/collect_data_config/template_config (*Argument*), 40
 step_configs/prep_explore_config/template_config (*Argument*), 26
 step_configs/prep_fp_config/template_config (*Argument*), 32
 step_configs/prep_train_config/template_config (*Argument*), 20
 step_configs/run_explore_config/template_config (*Argument*), 29
 step_configs/run_fp_config/template_config (*Argument*), 35
 step_configs/run_train_config/template_config (*Argument*), 23
 step_configs/select_confs_config/template_config (*Argument*), 37
 template_config (*Argument*), 57
 template_cover_cmd_escape_bug:
 default_step_config/executor[lebesgue_v2]/extra/template_cover_cmd_escape (*Argument*), 48
 step_configs/cl_step_config/executor[lebesgue_v2]/extra/template_cover_cmd_escape (*Argument*), 46
 step_configs/collect_data_config/executor[lebesgue_v2]/extra/template_cover_cmd_escape (*Argument*), 43
 step_configs/prep_explore_config/executor[lebesgue_v2]/extra/template_cover_cmd_escape (*Argument*), 28
 step_configs/prep_fp_config/executor[lebesgue_v2]/extra/template_cover_cmd_escape (*Argument*), 34
 step_configs/prep_train_config/executor[lebesgue_v2]/extra/template_cover_cmd_escape (*Argument*), 22
 step_configs/run_explore_config/executor[lebesgue_v2]/extra/template_cover_cmd_escape (*Argument*), 31
 step_configs/run_fp_config/executor[lebesgue_v2]/extra/template_cover_cmd_escape (*Argument*), 37
 step_configs/run_train_config/executor[lebesgue_v2]/extra/template_cover_cmd_escape (*Argument*), 25
 step_configs/select_confs_config/executor[lebesgue_v2]/extra/template_cover_cmd_escape (*Argument*), 40
 template_script:
 train[dp]/template_script (*Argument*), 19
 temps:
 task_group_configs[lmp-md]/temps (*Argument*), 53
 timeout:
 default_step_config/template_config/timeout (*Argument*), 47
 step_configs/cl_step_config/template_config/timeout (*Argument*), 44
 step_configs/collect_data_config/template_config/timeout (*Argument*), 41
 step_configs/prep_explore_config/template_config/timeout (*Argument*), 26
 step_configs/prep_fp_config/template_config/timeout (*Argument*), 32
 step_configs/prep_train_config/template_config/timeout (*Argument*), 20
 step_configs/run_explore_config/template_config/timeout (*Argument*), 29
 step_configs/run_fp_config/template_config/timeout (*Argument*), 35
 step_configs/run_train_config/template_config/timeout (*Argument*), 23
 step_configs/select_confs_config/template_config/timeout (*Argument*), 38
 template_config/timeout (*Argument*), 57
 timeout_as_transient_error:
 default_step_config/template_config/timeout_as_transient_error (*Argument*), 47
 step_configs/cl_step_config/template_config/timeout_as_transient_error (*Argument*), 44
 step_configs/collect_data_config/template_config/timeout_as_transient_error (*Argument*), 41
 step_configs/prep_explore_config/template_config/timeout_as_transient_error (*Argument*), 26
 step_configs/prep_fp_config/template_config/timeout_as_transient_error (*Argument*), 32
 step_configs/prep_train_config/template_config/timeout_as_transient_error (*Argument*), 20
 step_configs/run_explore_config/template_config/timeout_as_transient_error (*Argument*), 29
 step_configs/run_fp_config/template_config/timeout_as_transient_error (*Argument*), 35
 step_configs/run_train_config/template_config/timeout_as_transient_error (*Argument*), 23
 step_configs/select_confs_config/template_config/timeout_as_transient_error (*Argument*), 38

step_configs/prepare_explore_config/template_config/timeout_as_transient_error (Argument), 26
 step_configs/prepare_explore_config/template_config/traj_explore_as_transient_error (Argument), 55
 step_configs/prepare_fp_config/template_config/traj_explore_as_transient_error (class in *dp-gen2.exploration.report.trajs_report*), 78
 step_configs/prepare_train_config/template_config/timeout_as_transient_error (Argument), 21
 step_configs/run_explore_config/template_config/timeout_as_transient_error (Argument), 29
 step_configs/run_fp_config/template_config/timeout_as_transient_error (Argument), 35
 step_configs/run_train_config/template_config/timeout_as_transient_error (Argument), 23
 step_configs/select_confs_config/template_config/timeout_as_transient_error (Argument), 38
 template_config/timeout_as_transient_error (Argument), 57
 to_str() (*dp-gen2.op.md_settings.MDSettings* method), 96
 train (Argument)
 train:, 17
 train/type (Argument)
 type:, 18
 train:
 train (Argument), 17
 training_args() (*dp-gen2.op.run_dp_train.RunDPTrain* static method), 101
 train[dp]/config (Argument)
 config:, 18
 train[dp]/config/init_model_num_steps (Argument)
 init_model_num_steps:, 18
 train[dp]/config/init_model_old_ratio (Argument)
 init_model_old_ratio:, 18
 train[dp]/config/init_model_policy (Argument)
 init_model_policy:, 18
 train[dp]/config/init_model_start_lr (Argument)
 init_model_start_lr:, 18
 train[dp]/config/init_model_start_pref_e (Argument)
 init_model_start_pref_e:, 18
 train[dp]/config/init_model_start_pref_f (Argument)
 init_model_start_pref_f:, 19
 train[dp]/config/init_model_start_pref_v (Argument)
 init_model_start_pref_v:, 19
 train[dp]/num_models (Argument)
 num_models:, 19
 train[dp]/template_script (Argument)
 template_script:, 19
 traj_freq:

task_group_configs[*lmp-md*]/trj_freq (Argument), 55
 TrustLevel (class in *dp-gen2.exploration.report.trajs_report*), 85
 type:
 default_step_config_executor/type (Argument), 48
 explore/type (Argument), 16
 fp/type (Argument), 15
 step_configs/cl_step_config/executor/type (Argument), 45
 step_configs/collect_data_config/executor/type (Argument), 42
 step_configs/prepare_explore_config/executor/type (Argument), 27
 step_configs/prepare_fp_config/executor/type (Argument), 33
 step_configs/prepare_train_config/executor/type (Argument), 21
 step_configs/run_explore_config/executor/type (Argument), 30
 step_configs/run_fp_config/executor/type (Argument), 36
 step_configs/run_train_config/executor/type (Argument), 24
 step_configs/select_confs_config/executor/type (Argument), 39
 task_group_configs/type (Argument), 53
 train/type (Argument), 18
 type_map (Argument)
 type_map:, 53
 type_map:
 inputs/type_map (Argument), 19
 type_map (Argument), 53

U

update_finished_steps() (in module *dp-gen2.entrypoint.watch*), 77
 upload_python_packages (Argument)
 upload_python_packages:, 20
 upload_python_packages:
 upload_python_packages (Argument), 20
 use_clusters:
 task_group_configs[*lmp-md*]/use_clusters (Argument), 55

V

v_trust_hi:

explore[*lmp*]/v_trust_hi (*Argument*), 17
 v_trust_lo:
 explore[*lmp*]/v_trust_lo (*Argument*), 17
 variant_executor() (in module *dp-
 gen2.utils.step_config*), 113
 variant_explore() (in module *dp-
 gen2.entrypoint.submit_args*), 76
 variant_fp() (in module *dp-
 gen2.entrypoint.submit_args*), 76
 variant_task_group() (in module *dp-
 gen2.exploration.task.make_task_group_from_config*),
 88
 variant_train() (in module *dp-
 gen2.entrypoint.submit_args*), 76
 vasp_args() (*dpgen2.op.run_vasp.RunVasp* static
 method), 103
 vasp_args() (in module *dp-
 gen2.entrypoint.submit_args*), 76
 VaspInputs (class in *dpgen2.fp.vasp*), 94

W

watch() (in module *dpgen2.entrypoint.watch*), 77
 wf_global_workflow() (in module *dp-
 gen2.entrypoint.submit*), 76
 workflow_concurrent_learning() (in module *dp-
 gen2.entrypoint.submit*), 76
 workflow_config_from_dict() (in module *dp-
 gen2.utils.dflow_config*), 111
 write_data_to_input_script() (*dp-
 gen2.op.run_dp_train.RunDPTrain* static
 method), 101
 write_other_to_input_script() (*dp-
 gen2.op.run_dp_train.RunDPTrain* static
 method), 101