
DPGEN2

DeepModeling

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DPGEN2 is the 2nd generation of the Deep Potential GENERator.

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GUIDE ON DPGEN2 COMMANDS

One may use `dpgen2` through command line interface. A full documentation of the cli is found [here](#)

1.1 Submit a workflow

The `dpgen2` workflow can be submitted via the `submit` command

```
dpgen2 submit input.json
```

where `input.json` is the input script. A guide of writing the script is found [here](#). When a workflow is submitted, a ID (WFID) of the workflow will be printed for later reference.

1.2 Check the convergence of a workflow

The convergence of stages of the workflow can be checked by the `status` command. It prints the indexes of the finished stages, iterations, and the accurate, candidate and failed ratio of explored configurations of each iteration.

```
$ dpgen2 status input.json WFID
# stage id_stg. iter.   accu.   cand.   fail.
# Stage  0  -----
#         0      0      0      0.8333  0.1667  0.0000
#         0      1      1      0.7593  0.2407  0.0000
#         0      2      2      0.7778  0.2222  0.0000
#         0      3      3      1.0000  0.0000  0.0000
# Stage  0 converged YES reached max numb iterations NO
# All stages converged
```

1.3 Watch the progress of a workflow

The progress of a workflow can be watched on-the-fly

```
$ dpgen2 watch input.json WFID
INFO:root:steps iter-000000--prep-run-train----- finished
INFO:root:steps iter-000000--prep-run-lmp----- finished
INFO:root:steps iter-000000--prep-run-fp----- finished
INFO:root:steps iter-000000--collect-data----- finished
```

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```
INFO:root:steps iter-000001--prep-run-train----- finished
INFO:root:steps iter-000001--prep-run-lmp----- finished
...
```

The artifacts can be downloaded on-the-fly with `-d` flag. Note that the existing files are automatically skipped if one sets `dflow_config["archive_mode"] = None`.

1.4 Show the keys of steps

Each `dpgen2` step is assigned a unique key. The keys of the finished steps can be checked with `showkey` command

```

    0 : iter-000000--prep-train
    1 -> 4 : iter-000000--run-train-0000 -> iter-000000--run-train-0003
    5 : iter-000000--prep-lmp
    6 -> 14 : iter-000000--run-lmp-000000 -> iter-000000--run-lmp-000008
    15 : iter-000000--select-confs
    16 : iter-000000--prep-fp
   17 -> 20 : iter-000000--run-fp-000000 -> iter-000000--run-fp-000003
    21 : iter-000000--collect-data
    22 : iter-000000--scheduler
    23 : iter-000000--id
    24 : iter-000001--prep-train
   25 -> 28 : iter-000001--run-train-0000 -> iter-000001--run-train-0003
    29 : iter-000001--prep-lmp
   30 -> 38 : iter-000001--run-lmp-000000 -> iter-000001--run-lmp-000008
    39 : iter-000001--select-confs
    40 : iter-000001--prep-fp
   41 -> 44 : iter-000001--run-fp-000000 -> iter-000001--run-fp-000003
    45 : iter-000001--collect-data
    46 : iter-000001--scheduler
    47 : iter-000001--id
```

1.5 Resubmit a workflow

If a workflow stopped abnormally, one may submit a new workflow with some steps of the old workflow reused.

```
dpgen2 resubmit input.json WFID --reuse 0-41
```

The steps of workflow `WDID 0-41` ($0 \leq id < 41$, note that 41 is not included) will be reused in the new workflow. The indexes of the steps are printed by `dpgen2 showkey`. In the example, all the steps before the `iter-000001--run-fp-000000` will be used in the new workflow.

COMMAND LINE INTERFACE

DPGEN2: concurrent learning workflow generating the machine learning potential energy models.

```
usage: dpgen2 [-h] [-v]
             {submit, resubmit, showkey, status, download, watch, terminate, stop, suspend,
             ↪ delete, retry, resume}
             ...
```

2.1 Named Arguments

-v, --version show program's version number and exit

2.2 Valid subcommands

command Possible choices: submit, resubmit, showkey, status, download, watch, terminate, stop, suspend, delete, retry, resume

2.3 Sub-commands

2.3.1 submit

Submit DPGEN2 workflow

```
dpgen2 submit [-h] [-o] CONFIG
```

Positional Arguments

CONFIG the config file in json format defining the workflow.

Named Arguments

-o, --old-compatible compatible with old-style input script used in dpgen2 < 0.0.6.
Default: False

2.3.2 resubmit

Submit DPGEN2 workflow resuing steps from an existing workflow

```
dpgen2 resubmit [-h] [-l] [-u REUSE [REUSE ...]] [-k] [-o] CONFIG ID
```

Positional Arguments

CONFIG the config file in json format defining the workflow.

ID the ID of the existing workflow.

Named Arguments

-l, --list list the Steps of the existing workflow.
Default: False

-u, --reuse specify which Steps to reuse.

-k, --keep-schedule if set then keep schedule of the old workflow. otherwise use the schedule defined in the input file
Default: False

-o, --old-compatible compatible with old-style input script used in dpgen2 < 0.0.6.
Default: False

2.3.3 showkey

Print the keys of the successful DPGEN2 steps

```
dpgen2 showkey [-h] CONFIG ID
```

Positional Arguments

CONFIG	the config file in json format.
ID	the ID of the existing workflow.

2.3.4 status

Print the status (stage, iteration, convergence) of the DPGEN2 workflow

```
dpgen2 status [-h] CONFIG ID
```

Positional Arguments

CONFIG	the config file in json format.
ID	the ID of the existing workflow.

2.3.5 download

Download the artifacts of DPGEN2 steps

```
dpgen2 download [-h] [-k KEYS [KEYS ...]] [-p PREFIX] [-n] CONFIG ID
```

Positional Arguments

CONFIG	the config file in json format.
ID	the ID of the existing workflow.

Named Arguments

-k, --keys	the keys of the downloaded steps. If not provided download all artifacts
-p, --prefix	the prefix of the path storing the download artifacts
-n, --no-check-point	if specified, download regardless whether check points exist. Default: True

2.3.6 watch

Watch a DPGEN2 workflow

```
dpgen2 watch [-h] [-k KEYS [KEYS ...]] [-f FREQUENCY] [-d] [-p PREFIX] [-n]
             CONFIG ID
```

Positional Arguments

CONFIG	the config file in json format.
ID	the ID of the existing workflow.

Named Arguments

-k, --keys	the subkey to watch. For example, 'prep-run-train' 'prep-run-lmp' Default: ['prep-run-train', 'prep-run-lmp', 'prep-run-fp', 'collect-data']
-f, --frequency	the frequency of workflow status query. In unit of second Default: 600.0
-d, --download	whether to download artifacts of a step when it finishes Default: False
-p, --prefix	the prefix of the path storing the download artifacts
-n, --no-check-point	if specified, download regardless whether check points exist. Default: True

2.3.7 terminate

Terminate a DPGEN2 workflow.

```
dpngen2 terminate [-h] CONFIG ID
```

Positional Arguments

CONFIG	the config file in json format.
ID	the ID of the workflow.

2.3.8 stop

Stop a DPGEN2 workflow.

```
dpngen2 stop [-h] CONFIG ID
```

Positional Arguments

CONFIG	the config file in json format.
ID	the ID of the workflow.

2.3.9 suspend

Suspend a DPGEN2 workflow.

```
dpgen2 suspend [-h] CONFIG ID
```

Positional Arguments

CONFIG	the config file in json format.
ID	the ID of the workflow.

2.3.10 delete

Delete a DPGEN2 workflow.

```
dpgen2 delete [-h] CONFIG ID
```

Positional Arguments

CONFIG	the config file in json format.
ID	the ID of the workflow.

2.3.11 retry

Retry a DPGEN2 workflow.

```
dpgen2 retry [-h] CONFIG ID
```

Positional Arguments

CONFIG	the config file in json format.
ID	the ID of the workflow.

2.3.12 resume

Resume a DPGEN2 workflow.

```
dpgen2 resume [-h] CONFIG ID
```

Positional Arguments

CONFIG the config file in json format.
ID the ID of the workflow.

GUIDE ON WRITING INPUT SCRIPTS FOR DPGEN2 COMMANDS

3.1 Preliminaries

The reader of this doc is assumed to be familiar with the concurrent learning algorithm that the `dpgen2` implements. If not, one may check [this paper](#).

3.2 The input script for all `dpgen2` commands

For all the `dpgen2` commands, one need to provide `dflow2` global configurations. For example,

```
"dflow_config" : {
  "host" : "http://address.of.the.host:port"
},
"dflow_s3_config" : {
  "endpoint" : "address.of.the.s3.sever:port"
},
```

The `dpgen` simply pass all keys of `"dflow_config"` to `dflow.config` and all keys of `"dflow_s3_config"` to `dflow.s3_config`.

3.3 The input script for `submit` and `resubmit`

The full documentation of the `submit` and `resubmit` script can be [found here](#). This documentation provides a fast guide on how to write the input script.

In the input script of `dpgen2 submit` and `dpgen2 resubmit`, one needs to provide the definition of the workflow and how they are executed in the input script. One may find an example input script in the `dpgen2 Al-Mg alloy` example.

The definition of the workflow can be provided by the following sections:

3.3.1 Inputs

This section provides the inputs to start a dpgen2 workflow. An example for the Al-Mg alloy

```
"inputs": {
  "type_map":          ["Al", "Mg"],
  "mass_map":          [27, 24],
  "init_data_sys":    [
    "path/to/init/data/system/0",
    "path/to/init/data/system/1"
  ],
}
```

The key "init_data_sys" provides the initial training data to kick-off the training of deep potential (DP) models.

3.3.2 Training

This section defines how a model is trained.

```
"train" : {
  "type" : "dp",
  "numb_models" : 4,
  "config" : {},
  "template_script" : {
    "_comment" : "omitted content of template script"
  },
  "_comment" : "all"
}
```

The "type" : "dp" tell the training method is "dp", i.e. calling [DeePMD-kit](#) to train DP models. The "config" key defines the training configs, see *the full documentation*. The "template_script" provides the template training script in json format.

3.3.3 Exploration

This section defines how the configuration space is explored.

```
"explore" : {
  "type" : "lmp",
  "config" : {
    "command": "lmp -var restart 0"
  },
  "max_numb_iter" : 5,
  "conv_accuracy" : 0.9,
  "fatal_at_max" : false,
  "f_trust_lo": 0.05,
  "f_trust_hi": 0.50,
  "configurations": [
    {
      "lattice" : ["fcc", 4.57],
      "replicate" : [2, 2, 2],
      "numb_confs" : 30,
    }
  ]
}
```

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```

        "concentration" : [[1.0, 0.0], [0.5, 0.5], [0.0, 1.0]]
    }
    {
        "lattice" : ["fcc", 4.57],
        "replicate" : [3, 3, 3],
        "numb_confs" : 30,
        "concentration" : [[1.0, 0.0], [0.5, 0.5], [0.0, 1.0]]
    }
],
"stages": [
    [
        {
            "_comment" : "stage 0, task group 0",
            "type" : "lmp-md",
            "ensemble": "nvt", "nsteps": 50, "temps": [50, 100], "trj_freq": 10,
            "conf_idx": [0], "n_sample" : 3
        },
        {
            "_comment" : "stage 1, task group 0",
            "type" : "lmp-template",
            "lmp" : "template.lammps", "plm" : "template.plumed",
            "trj_freq" : 10, "revisions" : {"V_NSTEPS" : [40], "V_TEMP" : [150, ↵
↵200]},
            "conf_idx": [0], "n_sample" : 3
        }
    ],
    [
        {
            "_comment" : "stage 1, task group 0",
            "type" : "lmp-md",
            "ensemble": "npt", "nsteps": 50, "press": [1e0], "temps": [50, 100, ↵
↵200], "trj_freq": 10,
            "conf_idx": [1], "n_sample" : 3
        }
    ],
],
}

```

The "type" : "lmp" means that configurations are explored by LAMMPS DPMD runs. The "config" key defines the lmp configs, see [the full documentation](#). The "configurations" provides the initial configurations (coordinates of atoms and the simulation cell) of the DPMD simulations. It is a list. The elements of the list can be

- list[str]: The strings provides the path to the configuration files.
- dict: Automatic alloy configuration generator. See the detailed doc of the allowed keys.

The "stages" defines the exploration stages. It is of type list[list[dict]]. The outer list enumerate the exploration stages, the inner list enumerate the task groups of the stage. Each dict defines a stage. See [the full documentation of the target group](#) for writing task groups.

"n_sample" tells the number of configurations randomly sampled from the set picked by "conf_idx" from configurations for each exploration task. All configurations has the equal possibility to be sampled. The default value of "n_sample" is null, in this case all picked configurations are sampled. In the example, we have 3 samples for stage 0 task group 0 and 2 thermodynamic states (NVT, T=50 and 100K), then the task group has 3x2=6 NVT DPMD tasks.

3.3.4 FP

This section defines the first-principle (FP) calculation .

```
"fp" : {
  "type" :      "vasp",
  "config" : {
    "command": "source /opt/intel/oneapi/setvars.sh && mpirun -n 16 vasp_std"
  },
  "task_max":   2,
  "pp_files":   {"Al" : "vasp/POTCAR.Al", "Mg" : "vasp/POTCAR.Mg"},
  "incar":      "vasp/INCAR",
  "_comment" : "all"
}
```

The "type" : "vasp" means that first-principles are VASP calculations. The "config" key defines the vasp configs, see *the full documentation*. The "task_max" key defines the maximal number of vasp calculations in each dpgen2 iteration. The "pp_files" and "incar" keys provides the pseudopotential files and the template incar file.

3.3.5 Configuration of dflow step

The execution units of the dpgen2 are the dflow Steps. How each step is executed is defined by the "step_configs".

```
"step_configs":{
  "prep_train_config" : {
    "_comment" : "content omitted"
  },
  "run_train_config" : {
    "_comment" : "content omitted"
  },
  "prep_explore_config" : {
    "_comment" : "content omitted"
  },
  "run_explore_config" : {
    "_comment" : "content omitted"
  },
  "prep_fp_config" : {
    "_comment" : "content omitted"
  },
  "run_fp_config" : {
    "_comment" : "content omitted"
  },
  "select_confs_config" : {
    "_comment" : "content omitted"
  },
  "collect_data_config" : {
    "_comment" : "content omitted"
  },
  "cl_step_config" : {
    "_comment" : "content omitted"
  },
  "_comment" : "all"
},
```

The configs for prepare training, run training, prepare exploration, run exploration, prepare fp, run fp, select configurations, collect data and concurrent learning steps are given correspondingly.

The readers are referred to [this page](#) for a full documentation of the step configs.

Any of the config in the `step_configs` can be omitted. If so, the configs of the step is set to the default step configs, which is provided by the following section, for example,

```
"default_step_config" : {  
  "template_config" : {  
    "image" : "dpgen2:x.x.x"  
  }  
},
```

The way of writing the `default_step_config` is the same as any step config in the `step_configs`. One may refer to [this page](#) for full documentation.

ARGUMENTS OF THE SUBMIT SCRIPT

DPGEN2 CONFIGURATIONS

5.1 Op configs

5.1.1 RunDPTrain

init_model_policy:

type: str, optional, default: no

argument path: `init_model_policy`

The policy of init-model training. It can be

- ‘no’: No init-model training. Traing from scratch.
- ‘yes’: Do init-model training.
- ‘old_data_larger_than:XXX’: Do init-model if the training data size of the previous model is larger than XXX. XXX is an int number.

init_model_old_ratio:

type: float, optional, default: 0.9

argument path: `init_model_old_ratio`

The frequency ratio of old data over new data

init_model_numb_steps:

type: int, optional, default: 400000, alias: *init_model_stop_batch*

argument path: `init_model_numb_steps`

The number of training steps when init-model

init_model_start_lr:

type: float, optional, default: 0.0001

argument path: `init_model_start_lr`

The start learning rate when init-model

init_model_start_pref_e:

type: float, optional, default: 0.1

argument path: `init_model_start_pref_e`

The start energy prefactor in loss when init-model

init_model_start_pref_f:

type: int | float, optional, default: 100

argument path: `init_model_start_pref_f`

The start force prefactor in loss when init-model

init_model_start_pref_v:

type: float, optional, default: 0.0

argument path: `init_model_start_pref_v`

The start virial prefactor in loss when init-model

5.1.2 RunLmp

command:

type: str, optional, default: `lmp`

argument path: `command`

The command of LAMMPS

5.1.3 RunVasp

5.2 Alloy configs

5.3 Task group configs

task_group_configs:

type: dict

argument path: `task_group_configs`

Depending on the value of *type*, different sub args are accepted.

type:

type: str (flag key)

argument path: `task_group_configs/type`

possible choices: *lmp-md*, *lmp-template*

the type of the task group

When *type* is set to *lmp-md* (or its alias *lmp-npt*):

temps:

type: list, alias: *Ts*

argument path: `task_group_configs[lmp-md]/temps`

A list of temperatures in K. Also used to initialize the temperature

press:

type: list, optional, alias: *Ps*

argument path: `task_group_configs[lmp-md]/press`

A list of pressures in bar.

ens:

type: `str`, optional, default: `nve`, alias: *ensemble*

argument path: `task_group_configs[lmp-md]/ens`

The ensemble. Allowed options are ‘nve’, ‘nvt’, ‘npt’, ‘npt-a’, ‘npt-t’. ‘npt-a’ stands for anisotropic box sampling and ‘npt-t’ stands for triclinic box sampling.

dt:

type: `float`, optional, default: `0.001`

argument path: `task_group_configs[lmp-md]/dt`

The time step

nsteps:

type: `int`, optional, default: `100`

argument path: `task_group_configs[lmp-md]/nsteps`

The number of steps

trj_freq:

type: `int`, optional, default: `10`, aliases: *t_freq*, *trj_freq*, *traj_freq*

argument path: `task_group_configs[lmp-md]/trj_freq`

The number of steps

tau_t:

type: `float`, optional, default: `0.05`

argument path: `task_group_configs[lmp-md]/tau_t`

The time scale of thermostat

tau_p:

type: `float`, optional, default: `0.5`

argument path: `task_group_configs[lmp-md]/tau_p`

The time scale of barostat

pka_e:

type: `NoneType` | `float`, optional, default: `None`

argument path: `task_group_configs[lmp-md]/pka_e`

The energy of primary knock-on atom

neidelay:

type: `int` | `NoneType`, optional, default: `None`

argument path: `task_group_configs[lmp-md]/neidelay`

The delay of updating the neighbor list

no_pbc:

type: `bool`, optional, default: `False`

argument path: `task_group_configs[lmp-md]/no_pbc`

Not using the periodic boundary condition

use_clusters:

type: bool, optional, default: False
argument path: `task_group_configs[lmp-md]/use_clusters`
Calculate atomic model deviation

relative_f_epsilon:

type: NoneType | float, optional, default: None
argument path: `task_group_configs[lmp-md]/relative_f_epsilon`
Calculate relative force model deviation

relative_v_epsilon:

type: NoneType | float, optional, default: None
argument path: `task_group_configs[lmp-md]/relative_v_epsilon`
Calculate relative virial model deviation

When `type` is set to `lmp-template`:

lmp_template_fname:

type: str, aliases: *lmp_template*, *lmp*
argument path: `task_group_configs[lmp-template]/lmp_template_fname`
The file name of lammmps input template

plm_template_fname:

type: NoneType | str, optional, default: None, aliases: *plm_template*, *plm*
argument path: `task_group_configs[lmp-template]/plm_template_fname`
The file name of plumed input template

revisions:

type: dict, optional, default: {}
argument path: `task_group_configs[lmp-template]/revisions`

traj_freq:

type: int, optional, default: 10, aliases: *t_freq*, *trj_freq*, *trj_freq*
argument path: `task_group_configs[lmp-template]/traj_freq`
The frequency of dumping configurations and thermodynamic states

5.4 Step configs

template_config:

type: dict, optional, default: {'image': 'dptechnology/dpgen2:latest'}
argument path: `template_config`

The configs passed to the PythonOPTemplate.

image:

type: str, optional, default: `dptechnology/dpgen2:latest`
argument path: `template_config/image`

The image to run the step.

timeout:

type: `int | NoneType`, optional, default: `None`
 argument path: `template_config/timeout`

The time limit of the OP. Unit is second.

retry_on_transient_error:

type: `int | NoneType`, optional, default: `None`
 argument path: `template_config/retry_on_transient_error`

The number of retry times if a `TransientError` is raised.

timeout_as_transient_error:

type: `bool`, optional, default: `False`
 argument path: `template_config/timeout_as_transient_error`

Treat the timeout as `TransientError`.

envs:

type: `dict | NoneType`, optional, default: `None`
 argument path: `template_config/envs`

The environmental variables.

continue_on_failed:

type: `bool`, optional, default: `False`
 argument path: `continue_on_failed`

If continue the the step is failed (`FatalError`, `TransientError`, A certain number of retrial is reached...).

continue_on_num_success:

type: `int | NoneType`, optional, default: `None`
 argument path: `continue_on_num_success`

Only in the sliced OP case. Continue the workflow if a certain number of the sliced jobs are successful.

continue_on_success_ratio:

type: `NoneType | float`, optional, default: `None`
 argument path: `continue_on_success_ratio`

Only in the sliced OP case. Continue the workflow if a certain ratio of the sliced jobs are successful.

parallelism:

type: `int | NoneType`, optional, default: `None`
 argument path: `parallelism`

The parallelism for the step

executor:

type: `dict | NoneType`, optional, default: `None`
 argument path: `executor`

The executor of the step.

Depending on the value of *type*, different sub args are accepted.

type:

type: str (flag key)
argument path: `executor/type`
possible choices: `lebesgue_v2`, `dispatcher`

The type of the executor.

When `type` is set to `lebesgue_v2`:

extra:

type: dict, optional
argument path: `executor[lebesgue_v2]/extra`

The 'extra' key in the lebesgue executor. Note that we do not check if 'the *dict* provided to the 'extra' key is valid or not.

scass_type:

type: str, optional
argument path: `executor[lebesgue_v2]/extra/scass_type`

The machine configuraiton.

program_id:

type: str, optional
argument path: `executor[lebesgue_v2]/extra/program_id`

The ID of the program.

job_type:

type: str, optional, default: `container`
argument path: `executor[lebesgue_v2]/extra/job_type`

The type of job.

template_cover_cmd_escape_bug:

type: bool, optional, default: `True`
argument path:
`executor[lebesgue_v2]/extra/template_cover_cmd_escape_bug`

The key for hacking around a bug in Lebesgue.

When `type` is set to `dispatcher`:

DEVELOPERS' GUIDE

- The concurrent learning algorithm
- Overview of the DPGEN2 implementation
- The DPGEN2 workflow
- How to contribute

6.1 The concurrent learning algorithm

DPGEN2 implements the concurrent learning algorithm named DP-GEN, described in [this paper](#). It is noted that other types of workflows, like active learning, should be easily implemented within the infrastructure of DPGEN2.

The DP-GEN algorithm is iterative. In each iteration, four steps are consecutively executed: training, exploration, selection, and labeling.

1. **Training.** A set of DP models are trained with the same dataset and the same hyperparameters. The only difference is the random seed initializing the model parameters.
2. **Exploration.** One of the DP models is used to explore the configuration space. The strategy of exploration highly depends on the purpose of the application case of the model. The simulation technique for exploration can be molecular dynamics, Monte Carlo, structure search/optimization, enhanced sampling, or any combination of them. Current DPGEN2 only supports exploration based on molecular simulation platform [LAMMPS](#).
3. **Selection.** Not all the explored configurations are labeled, rather, the model prediction errors on the configurations are estimated by the *model deviation*, which is defined as the standard deviation in predictions of the set of the models. The critical configurations with large and not-that-large errors are selected for labeling. The configurations with very large errors are not selected because the large error is usually caused by non-physical configurations, e.g. overlapping atoms.
4. **Labeling.** The selected configurations are labeled with energy, forces, and virial calculated by a method of first-principles accuracy. The usually used method is the [density functional theory](#) implemented in [VASP](#), [Quantum Espresso](#), [CP2K](#), and etc.. The labeled data are finally added to the training dataset to start the next iteration.

In each iteration, the quality of the model is improved by selecting and labeling more critical data and adding them to the training dataset. The DP-GEN iteration is converged when no more critical data can be selected.

6.2 Overview of the DPGEN2 Implementation

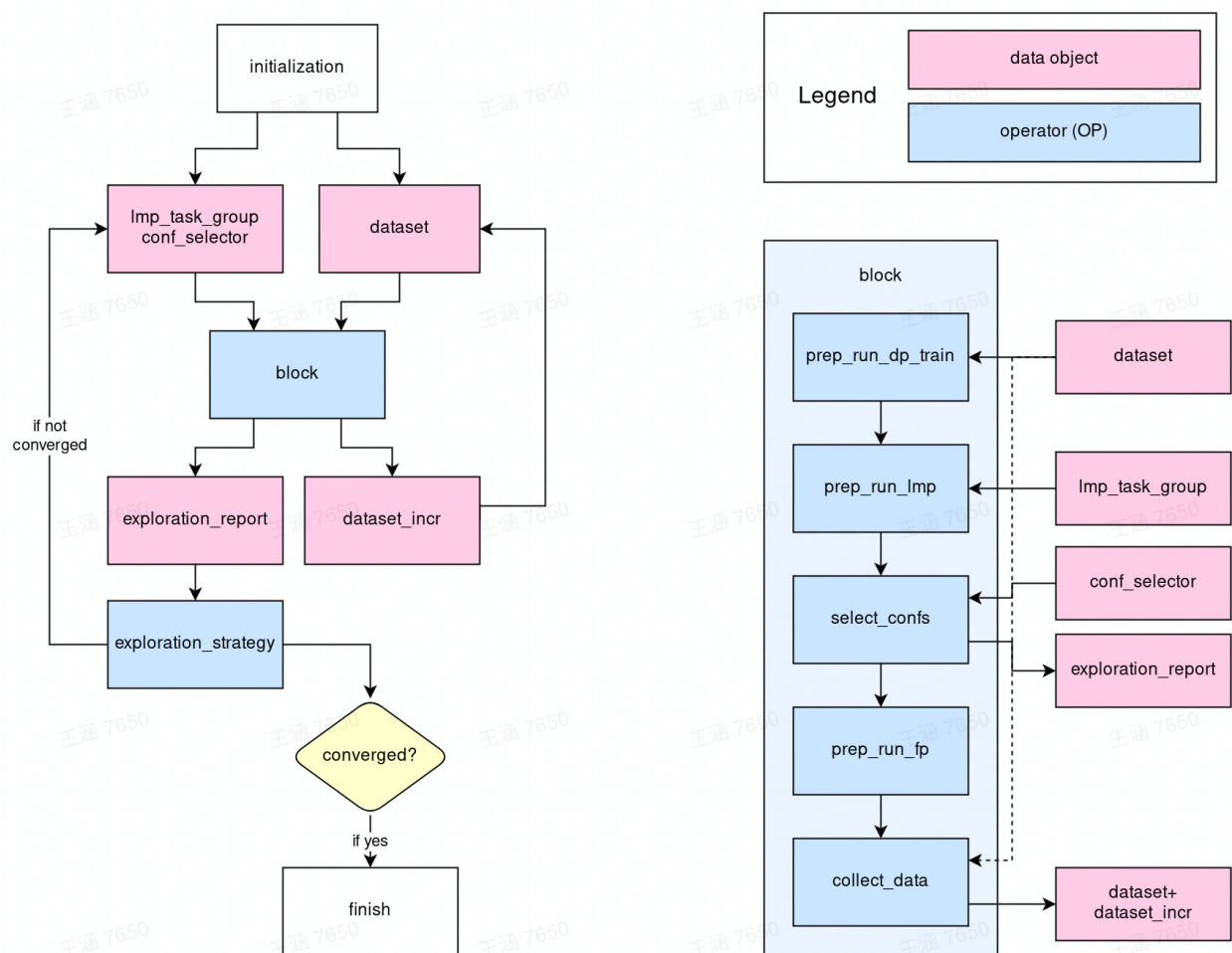
The implementation DPGEN2 is based on the workflow platform `dflow`, which is a python wrapper of the `Argo Workflows`, an open-source container-native workflow engine on `Kubernetes`.

The DP-GEN algorithm is conceptually modeled as a computational graph. The implementation is then considered as two lines: the operators and the workflow.

1. **Operators.** Operators are implemented in Python v3. The operators should be implemented and tested *without* the workflow.
2. **Workflow.** Workflow is implemented on `dflow`. Ideally, the workflow is implemented and tested with all operators mocked.

6.3 The DPGEN2 workflow

The workflow of DPGEN2 is illustrated in the following figure



In the center is the **block** operator, which is a super-OP (an OP composed by several OPs) for one DP-GEN iteration, i.e. the super-OP of the training, exploration, selection, and labeling steps. The inputs of the **block** OP are **Imp_task_group**, **conf_selector** and **dataset**.

- **Imp_task_group**: definition of a group of LAMMPS tasks that explore the configuration space.

- `conf_selector`: defines the rule by which the configurations are selected for labeling.
- `dataset`: the training dataset.

The outputs of the block OP are

- `exploration_report`: a report recording the result of the exploration. For example, how many configurations are accurate enough and how many are selected as candidates for labeling.
- `dataset_incr`: the increment of the training dataset.

The `dataset_incr` is added to the training dataset.

The `exploration_report` is passed to the `exploration_strategy` OP. The `exploration_strategy` implements the strategy of exploration. It reads the `exploration_report` generated by each iteration (`block`), then tells if the iteration is converged. If not, it generates a group of LAMMPS tasks (`lmp_task_group`) and the criteria of selecting configurations (`conf_selector`). The `lmp_task_group` and `conf_selector` are then used by `block` of the next iteration. The iteration closes.

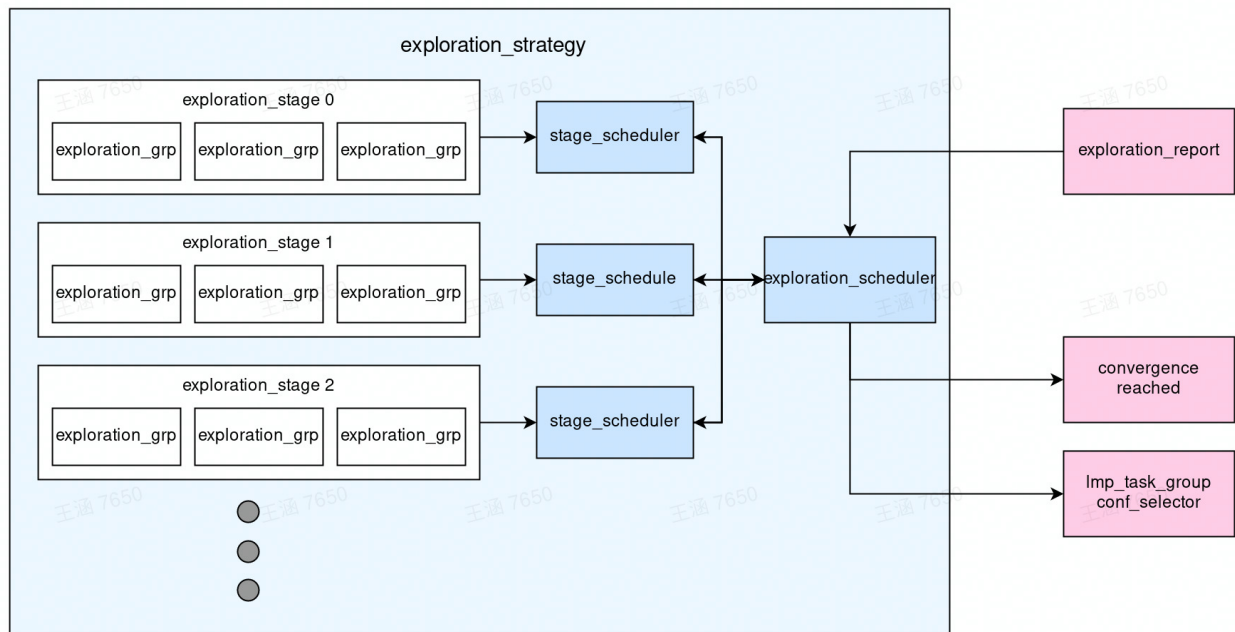
6.3.1 Inside the block operator

The inside of the super-OP block is displayed on the right-hand side of the figure. It contains the following steps to finish one DPGEN iteration

- `prep_run_dp_train`: prepares training tasks of DP models and runs them.
- `prep_run_lmp`: prepares the LAMMPS exploration tasks and runs them.
- `select_confs`: selects configurations for labeling from the explored configurations.
- `prep_run_fp`: prepares and runs first-principles tasks.
- `collect_data`: collects the `dataset_incr` and adds it to the dataset.

6.3.2 The exploration strategy

The exploration strategy defines how the configuration space is explored by the concurrent learning algorithm. The design of the exploration strategy is graphically illustrated in the following figure. The exploration is composed of stages. Only the DP-GEN exploration is converged at one stage (no configuration with a large error is explored), the exploration goes to the next iteration. The whole procedure is controlled by `exploration_scheduler`. Each stage has its schedule, which talks to the `exploration_scheduler` to generate the schedule for the DP-GEN algorithm.



Some concepts are explained below:

- **Exploration group.** A group of LAMMPS tasks shares similar settings. For example, a group of NPT MD simulations in a certain thermodynamic space.
- **Exploration stage.** The `exploration_stage` contains a list of exploration groups. It contains all information needed to define the `lmp_task_group` used by the block in the DP-GEN iteration.
- **Stage scheduler.** It guarantees the convergence of the DP-GEN algorithm in each `exploration_stage`. If the exploration is not converged, the `stage_scheduler` generates `lmp_task_group` and `conf_selector` from the `exploration_stage` for the next iteration (probably with a different initial condition, i.e. different initial configurations and randomly generated initial velocity).
- **Exploration scheduler.** The scheduler for the DP-GEN algorithm. When DP-GEN is converged in one of the stages, it goes to the next stage until all planned stages are used.

6.4 How to contribute

Anyone interested in the DPGEN2 project may contribute OPs, workflows, and exploration strategies.

- To contribute OPs, one may check the *guide on writing operators*
- To contribute workflows, one may take the DP-GEN workflow as an example. It is implemented in `dp-gen2/flow/dp-gen_loop.py` and tested with all operators mocked in `test/test_dp-gen_loop.py`
- To contribute the exploration strategy, one may check the *guide on writing exploration strategies*

OPERATORS

There are two types of OPs in DPGEN2

- OP. An execution unit the the workflow. It can be roughly viewed as a piece of Python script taking some input and gives some outputs. An OP cannot be used in the `dflow` until it is embedded in a super-OP.
- Super-OP. An execution unite that is composed by one or more OP and/or super-OPs.

Technically, OP is a Python class derived from `dflow.python.OP`. It serves as the `PythonOPTemplate` of `dflow.Step`.

The super-OP is a Python class derived from `dflow.Steps`. It contains `dflow.Steps` as building blocks, and can be used as OP template to generate a `dflow.Step`. The explanation of the concepts `dflow.Step` and `dflow.Steps`, one may refer to the [manual of dflow](#).

7.1 The super-OP `PrepRunDPTrain`

In the following we will take the `PrepRunDPTrain` super-OP as an example to illustrate how to write OPs in DPGEN2.

`PrepRunDPTrain` is a super-OP that prepares several DeePMD-kit training tasks, and submit all of them. This super-OP is composed by two `dflow.Steps` building from `dflow.python.OPs` `PrepDPTrain` and `RunDPTrain`.

```
from dflow import (
    Step,
    Steps,
)
from dflow.python import(
    PythonOPTemplate,
    OP,
    Slices,
)

class PrepRunDPTrain(Steps):
    def __init__(
        self,
        name : str,
        prep_train_op : OP,
        run_train_op : OP,
        prep_train_image : str = "dflow:v1.0",
        run_train_image : str = "dflow:v1.0",
    ):
        ...
```

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```

self = _prep_run_dp_train(
    self,
    self.step_keys,
    prep_train_op,
    run_train_op,
    prep_train_image = prep_train_image,
    run_train_image = run_train_image,
)

```

The construction of the `PrepRunDPTrain` takes prepare-training OP and run-training OP and their docker images as input, and implemented in internal method `_prep_run_dp_train`.

```

def _prep_run_dp_train(
    train_steps,
    step_keys,
    prep_train_op : OP = PrepDPTrain,
    run_train_op : OP = RunDPTrain,
    prep_train_image : str = "dflow:v1.0",
    run_train_image : str = "dflow:v1.0",
):
    prep_train = Step(
        ...
        template=PythonOPTemplate(
            prep_train_op,
            image=prep_train_image,
            ...
        ),
        ...
    )
    train_steps.add(prepare_train)

    run_train = Step(
        ...
        template=PythonOPTemplate(
            run_train_op,
            image=run_train_image,
            ...
        ),
        ...
    )
    train_steps.add(run_train)

    train_steps.outputs.artifacts["scripts"]._from = run_train.outputs.artifacts["script
↪"]
    train_steps.outputs.artifacts["models"]._from = run_train.outputs.artifacts["model"]
    train_steps.outputs.artifacts["logs"]._from = run_train.outputs.artifacts["log"]
    train_steps.outputs.artifacts["lcurves"]._from = run_train.outputs.artifacts["lcurve
↪"]

    return train_steps

```

In `_prep_run_dp_train`, two instances of `dflow.Step`, i.e. `prep_train` and `run_train`, generated from `prep_train_op` and `run_train_op`, respectively, are added to `train_steps`. Both of `prep_train_op` and

`run_train_op` are OPs (python classes derived from `dflow.python.OPs`) that will be illustrated later. `train_steps` is an instance of `dflow.Steps`. The outputs of the second OP `run_train` are assigned to the outputs of the `train_steps`.

The `prep_train` prepares a list of paths, each of which contains all necessary files to start a DeePMD-kit training tasks.

The `run_train` slices the list of paths, and assign each item in the list to a DeePMD-kit task. The task is executed by `run_train_op`. This is a very nice feature of `dflow`, because the developer only needs to implement how one DeePMD-kit task is executed, and then all the items in the task list will be executed **in parallel**. See the following code to see how it works

```
run_train = Step(
    'run-train',
    template=PythonOPTemplate(
        run_train_op,
        image=run_train_image,
        slices = Slices(
            "int('{{item}}')",
            input_parameter = ["task_name"],
            input_artifact = ["task_path", "init_model"],
            output_artifact = ["model", "lcurve", "log", "script"],
        ),
    ),
    parameters={
        "config" : train_steps.inputs.parameters["train_config"],
        "task_name" : prep_train.outputs.parameters["task_names"],
    },
    artifacts={
        'task_path' : prep_train.outputs.artifacts['task_paths'],
        "init_model" : train_steps.inputs.artifacts['init_models'],
        "init_data": train_steps.inputs.artifacts['init_data'],
        "iter_data": train_steps.inputs.artifacts['iter_data'],
    },
    with_sequence=argo_sequence(argo_len(prep_train.outputs.parameters["task_names
↪"]), format=train_index_pattern),
    key = step_keys['run-train'],
)
```

The input parameter "task_names" and artifacts "task_paths" and "init_model" are sliced and supplied to each DeePMD-kit task. The output artifacts of the tasks ("model", "lcurve", "log" and "script") are stacked in the same order as the input lists. These lists are assigned as the outputs of `train_steps` by

```
train_steps.outputs.artifacts["scripts"]._from = run_train.outputs.artifacts["script
↪"]
train_steps.outputs.artifacts["models"]._from = run_train.outputs.artifacts["model"]
train_steps.outputs.artifacts["logs"]._from = run_train.outputs.artifacts["log"]
train_steps.outputs.artifacts["lcurves"]._from = run_train.outputs.artifacts["lcurve
↪"]
```

7.2 The OP RunDPTrain

We will take RunDPTrain as an example to illustrate how to implement an OP in DPGEN2. The source code of this OP is found [here](#)

Firstly of all, an OP should be implemented as a derived class of `dflow.python.OP`.

The `dflow.python.OP` requires static type define for the input and output variables, i.e. the signatures of an OP. The input and output signatures of the `dflow.python.OP` are given by classmethods `get_input_sign` and `get_output_sign`.

```

from dflow.python import (
    OP,
    OPIO,
    OPIOSign,
    Artifact,
)
class RunDPTrain(OP):
    @classmethod
    def get_input_sign(cls):
        return OPIOSign({
            "config" : dict,
            "task_name" : str,
            "task_path" : Artifact(Path),
            "init_model" : Artifact(Path),
            "init_data" : Artifact(List[Path]),
            "iter_data" : Artifact(List[Path]),
        })

    @classmethod
    def get_output_sign(cls):
        return OPIOSign({
            "script" : Artifact(Path),
            "model" : Artifact(Path),
            "lcurve" : Artifact(Path),
            "log" : Artifact(Path),
        })

```

All items not defined as `Artifact` are treated as parameters of the OP. The concept of parameter and artifact are explained in the [dflow document](#). To be short, the artifacts can be `pathlib.Path` or a list of `pathlib.Path`. The artifacts are passed by the file system. Other data structures are treated as parameters, they are passed as variables encoded in `str`. Therefore, a large amount of information should be stored in artifacts, otherwise they can be considered as parameters.

The operation of the OP is implemented in method `execute`, and are run in docker containers. Again taking the `execute` method of `RunDPTrain` as an example

```

@OP.exec_sign_check
def execute(
    self,
    ip : OPIO,
) -> OPIO:
    ...
    task_name = ip['task_name']

```

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```

task_path = ip['task_path']
init_model = ip['init_model']
init_data = ip['init_data']
iter_data = ip['iter_data']
...
work_dir = Path(task_name)
...
# here copy all files in task_path to work_dir
...
with set_directory(work_dir):
    fplog = open('train.log', 'w')
    def clean_before_quit():
        fplog.close()
    # train model
    command = ['dp', 'train', train_script_name]
    ret, out, err = run_command(command)
    if ret != 0:
        clean_before_quit()
        raise FatalError('dp train failed')
    fplog.write(out)
    # freeze model
    ret, out, err = run_command(['dp', 'freeze', '-o', 'frozen_model.pb'])
    if ret != 0:
        clean_before_quit()
        raise FatalError('dp freeze failed')
    fplog.write(out)
    clean_before_quit()

return OPIO({
    "script" : work_dir / train_script_name,
    "model" : work_dir / "frozen_model.pb",
    "lcurve" : work_dir / "lcurve.out",
    "log" : work_dir / "train.log",
})

```

The inputs and outputs variables are recorded in data structure `dflow.python.OPIO`, which is initialized by a Python dict. The keys in the input/output dict, and the types of the input/output variables will be checked against their signatures by decorator `OP.exec_sign_check`. If any key or type does not match, an exception will be raised.

It is noted that all input artifacts of the OP are read-only, therefore, the first step of the `RunDPTrain.execute` is to copy all necessary input files from the directory `task_path` prepared by `PrepDPTrain` to the working directory `work_dir`.

`with_directory` method creates the `work_dir` and swithes to the directory before the execution, and then exits the directoy when the task finishes or an error is raised.

In what follows, the training and model frozen bash commands are executed consecutively. The return code is check and a `FatalError` is raised if a non-zero code is detected.

Finally the trained model file, input script, learning curve file and the log file are recored in a `dflow.python.OPIO` and returned.

EXPLORATION

DPGEN2 allows developers to contribute exploration strategies. The exploration strategy defines how the configuration space is explored by molecular simulations in each DPGEN iteration. Notice that we are not restricted to molecular dynamics, any molecular simulation is, in principle, allowed. For example, Monte Carlo, enhanced sampling, structure optimization, and so on.

An exploration strategy takes the history of exploration as input, and gives back DPGEN the exploration tasks (we call it **task group**) and the rule to select configurations from the trajectories generated by the tasks (we call it **configuration selector**).

One can contribute from three aspects:

- The stage scheduler
- The exploration task groups
- Configuration selector

8.1 Stage scheduler

The stage scheduler takes an exploration report passed from the exploration scheduler as input, and tells the exploration scheduler if the exploration in the stage is converged, if not, returns a group of exploration tasks and a configuration selector that are used in the next DPGEN iteration.

Detailed explanation of the concepts are found here.

All the stage schedulers are derived from the abstract base class `StageScheduler`. The only interface to be implemented is `StageScheduler.plan_next_iteration`. One may check the doc string for the explanation of the interface.

```
class StageScheduler(ABC):
    """
    The scheduler for an exploration stage.
    """

    @abstractmethod
    def plan_next_iteration(
        self,
        hist_reports : List[ExplorationReport],
        report : ExplorationReport,
        confs : List[Path],
    ) -> Tuple[bool, ExplorationTaskGroup, ConfSelector] :
        """
```

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```

    Make the plan for the next iteration of the stage.

    It checks the report of the current and all historical iterations of the stage,
    and tells if the iterations are converged.
    If not converged, it will plan the next iteration for the stage.

    Parameters
    -----
    hist_reports: List[ExplorationReport]
        The historical exploration report of the stage. If this is the first
        ↪ iteration of the stage, this list is empty.
    report : ExplorationReport
        The exploration report of this iteration.
    confs: List[Path]
        A list of configurations generated during the exploration. May be used to
        ↪ generate new configurations for the next iteration.

    Returns
    -----
    converged: bool
        If the stage converged.
    task: ExplorationTaskGroup
        A `ExplorationTaskGroup` defining the exploration of the next iteration.
        ↪ Should be `None` if the stage is converged.
    conf_selector: ConfSelector
        The configuration selector for the next iteration. Should be `None` if the
        ↪ stage is converged.

    """

```

One may check more details on the exploration task group and the configuration selector.

8.2 Exploration task groups

DPGEN2 defines a python class `ExplorationTask` to manage all necessary files needed to run an exploration task. It can be used as the example provided in the doc string.

```

class ExplorationTask():
    """Define the files needed by an exploration task.

    Examples
    -----
    >>> # this example dumps all files needed by the task.
    >>> files = exploration_task.files()
    ... for file_name, file_content in files.items():
    ...     with open(file_name, 'w') as fp:
    ...         fp.write(file_content)

    """

```

A collection of the exploration tasks is called exploration task group. All task groups are derived from the base class

ExplorationTaskGroup. The exploration task group can be viewed as a list of ExplorationTasks, one may get the list by using property ExplorationTaskGroup.task_list. One may add tasks, or ExplorationTaskGroup to the group by methods ExplorationTaskGroup.add_task and ExplorationTaskGroup.add_group, respectively.

```
class ExplorationTaskGroup(Sequence):
    @property
    def task_list(self) -> List[ExplorationTask]:
        """Get the `list` of `ExplorationTask`"""
        ...

    def add_task(self, task: ExplorationTask):
        """Add one task to the group."""
        ...

    def add_group(
        self,
        group : 'ExplorationTaskGroup',
    ):
        """Add another group to the group."""
        ...
```

An example of generating a group of NPT MD simulations may illustrate how to implement the ExplorationTaskGroups.

8.3 Configuration selector

The configuration selectors are derived from the abstract base class ConfSelector

```
class ConfSelector(ABC):
    """Select configurations from trajectory and model deviation files.
    """
    @abstractmethod
    def select (
        self,
        trajs : List[Path],
        model_devis : List[Path],
        traj_fmt : str = 'deepmd/npz',
        type_map : List[str] = None,
    ) -> Tuple[List[ Path ], ExplorationReport]:
```

The abstractmethod to implement is ConfSelector.select. trajs and model_devis are lists of files that recording the simulations trajectories and model deviations respectively. traj_fmt and type_map are parameters that may be needed for loading the trajectories by dpdata.

The ConfSelector.select returns a Path, each of which can be treated as a dpdata.MultiSystems, and a ExplorationReport.

An example of selecting configurations from LAMMPS trajectories may illustrate how to implement the ConfSelectors.

DPGEN2 API

9.1 dpngen2 package

9.1.1 Subpackages

dpngen2.conf package

Submodules

dpngen2.conf.alloy_conf module

```
class dpngen2.conf.alloy_conf.AlloyConf(lattice: Union[System, Tuple[str, float]], type_map: List[str],
                                         replicate: Optional[Union[List[int], Tuple[int], int]] = None)
```

Bases: `object`

Parameters

lattice `Union[dpdata.System, Tuple[str, float]]`

Lattice of the alloy confs. can be `dpdata.System`: lattice in `dpdata.System Tuple[str, float]`: pair of lattice type and lattice constant. lattice type can be “bcc”, “fcc”, “hcp”, “sc” or “diamond”

replicate `Union[List[int], Tuple[int], int]`

replicate of the lattice

type_map `List[str]`

The type map

Methods

```
generate_file_content(numb_confs[, ...])
```

Parameters

```
generate_systems(numb_confs[, ...])
```

Parameters

```
generate_file_content(numb_confs, concentration: Optional[Union[List[List[float]], List[float]]] = None, cell_pert_frac: float = 0.0, atom_pert_dist: float = 0.0, fmt: str = 'lammps/lmp') → List[str]
```

Parameters**numb_confs int**

Number of configurations to generate

concentration List[List[float]] or List[float] or None

If *List[float]*, the concentrations of each element. The length of the list should be the same as the *type_map*. If *List[List[float]]*, a list of concentrations (*List[float]*) is randomly picked from the List. If *None*, the elements are assumed to be of equal concentration.

cell_pert_frac float

fraction of cell perturbation

atom_pert_dist float

the atom perturbation distance (unit angstrom).

fmt str

the format of the returned conf strings. Should be one of the formats supported by *dpdata*

Returns**conf_list List[str]**

A list of file content of configurations.

generate_systems (*numb_confs*, *concentration*: *Optional[Union[List[List[float]], List[float]] = None*, *cell_pert_frac*: *float = 0.0*, *atom_pert_dist*: *float = 0.0*) → *List[str]*

Parameters**numb_confs int**

Number of configurations to generate

concentration List[List[float]] or List[float] or None

If *List[float]*, the concentrations of each element. The length of the list should be the same as the *type_map*. If *List[List[float]]*, a list of concentrations (*List[float]*) is randomly picked from the List. If *None*, the elements are assumed to be of equal concentration.

cell_pert_frac float

fraction of cell perturbation

atom_pert_dist float

the atom perturbation distance (unit angstrom).

Returns**conf_list List[dpdata.System]**

A list of generated confs in *dpdata.System*.

class `dpgen2.conf.alloy_conf.AlloyConfGenerator` (*numb_confs*, *lattice*: *Union[System, Tuple[str, float]]*, *replicate*: *Optional[Union[List[int], Tuple[int], int]] = None*, *concentration*: *Optional[Union[List[List[float]], List[float]] = None*, *cell_pert_frac*: *float = 0.0*, *atom_pert_dist*: *float = 0.0*)

Bases: *ConfGenerator*

Parameters

numb_confs int

Number of configurations to generate

lattice Union[dpdata.System, Tuple[str,float]]

Lattice of the alloy confs. can be *dpdata.System*: lattice in *dpdata.System Tuple[str, float]*: pair of lattice type and lattice constant. lattice type can be “bcc”, “fcc”, “hcp”, “sc” or “diamond”

replicate Union[List[int], Tuple[int], int]

replicate of the lattice

concentration List[List[float]] or List[float] or None

If *List[float]*, the concentrations of each element. The length of the list should be the same as the *type_map*. If *List[List[float]]*, a list of concentrations (*List[float]*) is randomly picked from the List. If *None*, the elements are assumed to be of equal concentration.

cell_pert_frac float

fraction of cell perturbation

atom_pert_dist float

the atom perturbation distance (unit angstrom).

Methods

<code>generate(type_map)</code>	Method of generating configurations.
<code>get_file_content(type_map[, fmt])</code>	Get the file content of configurations
<code>normalize_config([data, strict])</code>	Normalized the argument.

args	
-------------	--

static args() → *List[Argument]*

generate(type_map) → *MultiSystems*

Method of generating configurations.

Parameters

type_map: List[str]

The type map.

Returns

confs: dpdata.MultiSystems

The returned configurations in *dpdata.MultiSystems* format

`dpgen2.conf.alloy_conf.gen_doc(*, make_anchor=True, make_link=True, **kwargs)`

`dpgen2.conf.alloy_conf.generate_alloy_conf_args()`

`dpgen2.conf.alloy_conf.generate_alloy_conf_file_content(lattice: Union[System, Tuple[str, float]], type_map: List[str], numb_confs, replicate: Optional[Union[List[int], Tuple[int], int]] = None, concentration: Optional[Union[List[List[float]], List[float]]) = None, cell_pert_frac: float = 0.0, atom_pert_dist: float = 0.0, fmt: str = 'lammps/lmp')`

`dpgen2.conf.alloy_conf.normalize(data)`

dpgen2.conf.conf_generator module

class `dpgen2.conf.conf_generator.ConfGenerator`

Bases: `ABC`

Methods

<code>generate(type_map)</code>	Method of generating configurations.
<code>get_file_content(type_map[, fmt])</code>	Get the file content of configurations
<code>normalize_config([data, strict])</code>	Normalized the argument.

args

abstract static `args()` → `List[Argument]`

abstract `generate(type_map)` → `MultiSystems`

Method of generating configurations.

Parameters

type_map: List[str]
The type map.

Returns

confs: dpdata.MultiSystems
The returned configurations in `dpdata.MultiSystems` format

get_file_content(`type_map`, `fmt='lammps/lmp'`) → `List[str]`

Get the file content of configurations

Parameters

type_map: List[str]
The type map.

Returns

conf_list: List[str]
A list of file content of configurations.

classmethod `normalize_config`(`data: Dict = {}`, `strict: bool = True`) → `Dict`

Normalized the argument.

Parameters

data: Dict
The input dict of arguments.

strict: bool
Strictly check the arguments.

Returns

data: Dict
The normalized arguments.

dpngen2.conf.file_conf module

class dpngen2.conf.file_conf.**FileConfGenerator**(files: Union[str, List[str]], fmt: str = 'auto', prefix: Optional[str] = None, remove_pbc: Optional[bool] = False)

Bases: *ConfGenerator*

Methods

<i>generate</i> (type_map)	Method of generating configurations.
<i>get_file_content</i> (type_map[, fmt])	Get the file content of configurations
<i>normalize_config</i> ([data, strict])	Normalized the argument.

args	
-------------	--

static args() → List[Argument]

generate(type_map) → MultiSystems

Method of generating configurations.

Parameters

type_map: List[str]
The type map.

Returns

confs: dpdata.MultiSystems
The returned configurations in *dpdata.MultiSystems* format

dpngen2.conf.unit_cells module

class dpngen2.conf.unit_cells.**BCC**

Bases: *object*

Methods

gen_box	
numb_atoms	
poscar_unit	

gen_box()

numb_atoms()

`poscar_unit(latt)`

`class dpngen2.conf.unit_cells.DIAMOND`

Bases: `object`

Methods

<code>gen_box</code>	
<code>numb_atoms</code>	
<code>poscar_unit</code>	

`gen_box()`

`numb_atoms()`

`poscar_unit(latt)`

`class dpngen2.conf.unit_cells.FCC`

Bases: `object`

Methods

<code>gen_box</code>	
<code>numb_atoms</code>	
<code>poscar_unit</code>	

`gen_box()`

`numb_atoms()`

`poscar_unit(latt)`

`class dpngen2.conf.unit_cells.HCP`

Bases: `object`

Methods

<code>gen_box</code>	
<code>numb_atoms</code>	
<code>poscar_unit</code>	

`gen_box()`

`numb_atoms()`

`poscar_unit(latt)`

`class dpngen2.conf.unit_cells.SC`

Bases: `object`

Methods

<code>gen_box</code>	
<code>numb_atoms</code>	
<code>poscar_unit</code>	

`gen_box()`

`numb_atoms()`

`poscar_unit(latt)`

`dpngen2.conf.unit_cells.generate_unit_cell(crystal: str, latt: float = 1.0) → System`

dpngen2.entrypoint package

Submodules

dpngen2.entrypoint.args module

`dpngen2.entrypoint.args.bohrium_conf_args()`

`dpngen2.entrypoint.args.default_step_config_args()`

`dpngen2.entrypoint.args.dflow_conf_args()`

`dpngen2.entrypoint.args.dp_train_args()`

`dpngen2.entrypoint.args.dpngen_step_config_args(default_config)`

`dpngen2.entrypoint.args.fp_args(inputs, run)`

`dpngen2.entrypoint.args.gen_doc(*, make_anchor=True, make_link=True, **kwargs)`

`dpngen2.entrypoint.args.input_args()`

`dpngen2.entrypoint.args.lebesgue_conf_args()`

`dpngen2.entrypoint.args.lmp_args()`

`dpngen2.entrypoint.args.normalize(data)`

`dpngen2.entrypoint.args.submit_args(default_step_config={'continue_on_failed': False, 'continue_on_num_success': None, 'continue_on_success_ratio': None, 'executor': None, 'parallelism': None, 'template_config': {'envs': None, 'image': 'dpotechnology/dpugen2:latest', 'retry_on_transient_error': None, 'timeout': None, 'timeout_as_transient_error': False}})`

`dpngen2.entrypoint.args.variant_conf()`

`dpngen2.entrypoint.args.variant_explore()`

`dpngen2.entrypoint.args.variant_fp()`

`dpngen2.entrypoint.args.variant_train()`

dpgen2.entrypoint.common module

`dpgen2.entrypoint.common.expand_idx(in_list)`

`dpgen2.entrypoint.common.expand_sys_str(root_dir: Union[str, Path]) → List[str]`

`dpgen2.entrypoint.common.global_config_workflow(wf_config, do_lebesgue: bool = False)`

dpgen2.entrypoint.download module

`dpgen2.entrypoint.download.download(workflow_id, wf_config: Optional[Dict] = {}, wf_keys: Optional[List] = None, prefix: Optional[str] = None, chk_pnt: bool = False)`

dpgen2.entrypoint.main module

`dpgen2.entrypoint.main.main()`

`dpgen2.entrypoint.main.main_parser() → ArgumentParser`

DPGEN2 commandline options argument parser.

Returns

argparse.ArgumentParser
the argument parser

Notes

This function is used by documentation.

`dpgen2.entrypoint.main.parse_args(args: Optional[List[str]] = None)`

DPGEN2 commandline options argument parsing.

Parameters

args: List[str]
list of command line arguments, main purpose is testing default option None takes arguments from `sys.argv`

dpgen2.entrypoint.showkey module

`dpgen2.entrypoint.showkey.showkey(wf_id, wf_config)`

dpgen2.entrypoint.status module

`dpgen2.entrypoint.status.status(workflow_id, wf_config: Optional[Dict] = {})`

dpgen2.entrypoint.submit module

`dpgen2.entrypoint.submit.copy_scheduler_plans(scheduler_new, scheduler_old)`

`dpgen2.entrypoint.submit.get_kspacing_kgamma_from_incar(fname)`

`dpgen2.entrypoint.submit.get_resubmit_keys(wf)`

`dpgen2.entrypoint.submit.get_scheduler_ids(reuse_step)`

```

dpgen2.entrypoint.submit.make_concurrent_learning_op(train_style: str = 'dp', explore_style: str =
'imp', fp_style: str = 'vasp', prep_train_config:
dict = {'continue_on_failed': False,
'continue_on_num_success': None,
'continue_on_success_ratio': None, 'executor':
None, 'parallelism': None, 'template_config':
{'envs': None, 'image':
'dptechnology/dpgen2:latest',
'retry_on_transient_error': None, 'timeout':
None, 'timeout_as_transient_error': False}},
run_train_config: dict = {'continue_on_failed':
False, 'continue_on_num_success': None,
'continue_on_success_ratio': None, 'executor':
None, 'parallelism': None, 'template_config':
{'envs': None, 'image':
'dptechnology/dpgen2:latest',
'retry_on_transient_error': None, 'timeout':
None, 'timeout_as_transient_error': False}},
prep_explore_config: dict =
{'continue_on_failed': False,
'continue_on_num_success': None,
'continue_on_success_ratio': None, 'executor':
None, 'parallelism': None, 'template_config':
{'envs': None, 'image':
'dptechnology/dpgen2:latest',
'retry_on_transient_error': None, 'timeout':
None, 'timeout_as_transient_error': False}},
run_explore_config: dict =
{'continue_on_failed': False,
'continue_on_num_success': None,
'continue_on_success_ratio': None, 'executor':
None, 'parallelism': None, 'template_config':
{'envs': None, 'image':
'dptechnology/dpgen2:latest',
'retry_on_transient_error': None, 'timeout':
None, 'timeout_as_transient_error': False}},
prep_fp_config: dict = {'continue_on_failed':
False, 'continue_on_num_success': None,
'continue_on_success_ratio': None, 'executor':
None, 'parallelism': None, 'template_config':
{'envs': None, 'image':
'dptechnology/dpgen2:latest',
'retry_on_transient_error': None, 'timeout':
None, 'timeout_as_transient_error': False}},
run_fp_config: dict = {'continue_on_failed':
False, 'continue_on_num_success': None,
'continue_on_success_ratio': None, 'executor':
None, 'parallelism': None, 'template_config':
{'envs': None, 'image':
'dptechnology/dpgen2:latest',
'retry_on_transient_error': None, 'timeout':
None, 'timeout_as_transient_error': False}},
select_confs_config: dict =
{'continue_on_failed': False,
'continue_on_num_success': None,
'continue_on_success_ratio': None, 'executor':
None, 'parallelism': None, 'template_config':
{'envs': None, 'image':
'dptechnology/dpgen2:latest',
'retry_on_transient_error': None, 'timeout':

```

```

dpngen2.entrypoint.submit.make_naive_exploration_scheduler(config, old_style=False)
dpngen2.entrypoint.submit.print_list_steps(steps)
dpngen2.entrypoint.submit.resubmit_concurrent_learning(wf_config, wfid, list_steps=False,
                                                       reuse=None, old_style=False,
                                                       replace_scheduler=False)
dpngen2.entrypoint.submit.submit_concurrent_learning(wf_config, reuse_step: Optional[List[Step]] =
                                                       None, old_style: bool = False,
                                                       replace_scheduler: bool = False)
dpngen2.entrypoint.submit.successful_step_keys(wf)
dpngen2.entrypoint.submit.update_reuse_step_scheduler(reuse_step, scheduler_new)
dpngen2.entrypoint.submit.workflow_concurrent_learning(config: Dict, old_style: bool = False)

```

dpngen2.entrypoint.watch module

```

dpngen2.entrypoint.watch.update_finished_steps(wf, finished_keys: Optional[List[str]] = None,
                                               download: Optional[bool] = False, watching_keys:
                                               Optional[List[str]] = None, prefix: Optional[str] =
                                               None, chk_pnt: bool = False)
dpngen2.entrypoint.watch.watch(workflow_id, wf_config: Optional[Dict] = {}, watching_keys: Optional[List]
                               = ['prep-run-train', 'prep-run-lmp', 'prep-run-fp', 'collect-data'], frequency:
                               float = 600.0, download: bool = False, prefix: Optional[str] = None,
                               chk_pnt: bool = False)

```

dpngen2.entrypoint.workflow module

```

dpngen2.entrypoint.workflow.add_subparser_workflow_subcommand(subparsers, command: str)
dpngen2.entrypoint.workflow.execute_workflow_subcommand(command: str, wfid: str, wf_config:
                                                         Optional[dict] = {})

```

dpngen2.exploration package

Subpackages

dpngen2.exploration.render package

Submodules

dpngen2.exploration.render.traj_render module

```
class dpngen2.exploration.render.traj_render.TrajRender
```

Bases: [ABC](#)

Methods

<code>get_confs(traj, id_selected[, type_map, ...])</code>	Get configurations from trajectory by selection.
<code>get_model_devi(files)</code>	Get model deviations from recording files.

abstract `get_confs`(*traj*: *List*[*Path*], *id_selected*: *List*[*List*[*int*]], *type_map*: *Optional*[*List*[*str*]] = *None*, *conf_filters*: *Optional*[*ConfFilters*] = *None*) → *MultiSystems*

Get configurations from trajectory by selection.

Parameters

traj: *List*[*Path*]

Trajectory files

id_selected: *List*[*List*[*int*]]

The selected frames. `id_selected[ii][jj]` is the `jj`-th selected frame from the `ii`-th trajectory. `id_selected[ii]` may be an empty list.

type_map: *List*[*str*]

The type map.

Returns

ms: *dpdata.MultiSystems*

The configurations in *dpdata.MultiSystems* format

abstract `get_model_devi`(*files*: *List*[*Path*]) → *Tuple*[*List*[*ndarray*], *Optional*[*List*[*ndarray*]]]

Get model deviations from recording files.

Parameters

files: *List*[*Path*]

The paths to the model deviation recording files

Returns

model_devis: *Tuple*[*List*[*np.array*], *Union*[*List*[*np.array*],*None*]]

A tuple. `model_devis[0]` is the force model deviations, `model_devis[1]` is the virial model deviations. The `model_devis[1]` can be *None*. If not *None*, `model_devis[i]` is *List*[*np.array*], where *np.array* is a one-dimensional array. The first dimension of `model_devis[i]` is the trajectory (same size as `len(files)`), while the second dimension is the frame.

`dpngen2.exploration.render.traj_render_lammps` module

class `dpngen2.exploration.render.traj_render_lammps.TrajRenderLammps`(*nopbc*: *bool* = *False*)

Bases: *TrajRender*

Methods

<code>get_confs(trajs, id_selected[, type_map, ...])</code>	Get configurations from trajectory by selection.
<code>get_model_devi(files)</code>	Get model deviations from recording files.

get_confs(trajs: *List[Path]*, id_selected: *List[List[int]]*, type_map: *Optional[List[str]] = None*, conf_filters: *Optional[ConfFilters] = None*) → *MultiSystems*

Get configurations from trajectory by selection.

Parameters

traj: *List[Path]*

Trajectory files

id_selected: *List[List[int]]*

The selected frames. `id_selected[ii][jj]` is the `jj`-th selected frame from the `ii`-th trajectory. `id_selected[ii]` may be an empty list.

type_map: *List[str]*

The type map.

Returns

ms: *dpdata.MultiSystems*

The configurations in `dpdata.MultiSystems` format

get_model_devi(files: *List[Path]*) → *Tuple[List[ndarray], Optional[List[ndarray]]]*

Get model deviations from recording files.

Parameters

files: *List[Path]*

The paths to the model deviation recording files

Returns

model_devis: *Tuple[List[np.array], Union[List[np.array],None]]*

A tuple. `model_devis[0]` is the force model deviations, `model_devis[1]` is the virial model deviations. The `model_devis[1]` can be `None`. If not `None`, `model_devis[i]` is `List[np.array]`, where `np.array` is a one-dimensional array. The first dimension of `model_devis[i]` is the trajectory (same size as `len(files)`), while the second dimension is the frame.

dpngen2.exploration.report package

Submodules

dpngen2.exploration.report.report module

class `dpngen2.exploration.report.report.ExplorationReport`

Bases: `ABC`

Methods

<code>clear()</code>	Clear the report
<code>converged()</code>	If the exploration is converged
<code>get_candidate_ids([max_nframes])</code>	Get indexes of candidate configurations
<code>no_candidate()</code>	If no candidate configuration is found
<code>print(stage_idx, idx_in_stage, iter_idx)</code>	Print the report
<code>print_header()</code>	Print the header of report
<code>record(md_f[, md_v])</code>	Record the model deviations of the trajectories

abstract clear()

Clear the report

abstract converged() → bool

If the exploration is converged

abstract get_candidate_ids(max_nframes: Optional[int] = None) → List[List[int]]

Get indexes of candidate configurations

Parameters

max_nframes int

The maximal number of frames of candidates.

Returns

idx: List[List[int]]

The frame indices of candidate configurations. `idx[ii][jj]` is the frame index of the `jj`-th candidate of the `ii`-th trajectory.

no_candidate() → bool

If no candidate configuration is found

abstract print(stage_idx: int, idx_in_stage: int, iter_idx: int) → str

Print the report

abstract print_header() → str

Print the header of report

abstract record(md_f: List[ndarray], md_v: Optional[List[ndarray]] = None)

Record the model deviations of the trajectories

Parameters

mdf

[List[np.ndarray]] The force model deviations. `mdf[ii][jj]` is the force model deviation of the `jj`-th frame of the `ii`-th trajectory.

mdv

[Optional[List[np.ndarray]]] The virial model deviations. `mdv[ii][jj]` is the virial model deviation of the `jj`-th frame of the `ii`-th trajectory.

dpgen2.exploration.report.report_trust_levels module

class dpgen2.exploration.report.report_trust_levels.**ExplorationReportTrustLevels**(*trust_level*,
conv_accuracy)

Bases: *ExplorationReport*

Methods

<i>clear</i> ()	Clear the report
<i>converged</i> ()	If the exploration is converged
<i>get_candidate_ids</i> ([<i>max_nframes</i>])	Get indexes of candidate configurations
<i>no_candidate</i> ()	If no candidate configuration is found
<i>print</i> (<i>stage_idx</i> , <i>idx_in_stage</i> , <i>iter_idx</i>)	Print the report
<i>print_header</i> ()	Print the header of report
<i>record</i> (<i>md_f</i> [], <i>md_v</i> [])	Record the model deviations of the trajectories

accurate_ratio	
candidate_ratio	
failed_ratio	

accurate_ratio(*tag=None*)

candidate_ratio(*tag=None*)

clear()

Clear the report

converged()

If the exploration is converged

failed_ratio(*tag=None*)

get_candidate_ids(*max_nframes: Optional[int] = None*) → List[List[int]]

Get indexes of candidate configurations

Parameters

max_nframes int

The maximal number of frames of candidates.

Returns

idx: List[List[int]]

The frame indices of candidate configurations. `idx[ii][jj]` is the frame index of the `jj`-th candidate of the `ii`-th trajectory.

print(*stage_idx: int*, *idx_in_stage: int*, *iter_idx: int*) → str

Print the report

print_header() → str

Print the header of report

record(*md_f*: List[ndarray], *md_v_*: Optional[List[ndarray]] = None)

Record the model deviations of the trajectories

Parameters

mdf

[List[np.ndarray]] The force model deviations. `mdf[ii][jj]` is the force model deviation of the `jj`-th frame of the `ii`-th trajectory.

mdv

[Optional[List[np.ndarray]]] The virial model deviations. `mdv[ii][jj]` is the virial model deviation of the `jj`-th frame of the `ii`-th trajectory.

dpgen2.exploration.scheduler package

Submodules

dpgen2.exploration.scheduler.convergence_check_stage_scheduler module

class `dpgen2.exploration.scheduler.convergence_check_stage_scheduler.ConvergenceCheckStageScheduler` (*StageScheduler*)

Ex-
plo-
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tor:
Con
f-
S-
e-
lec-
tor,
max
Op-
tion
=
Non
fa-
tal_e
bool
=
True

Bases: *StageScheduler*

Methods

<code>complete()</code>	Tell if the stage is complete
<code>converged()</code>	Tell if the stage is converged
<code>force_complete()</code>	For complete the stage
<code>get_reports()</code>	Return all exploration reports
<code>next_iteration()</code>	Return the index of the next iteration
<code>plan_next_iteration([report, trajs])</code>	Make the plan for the next iteration of the stage.

<code>reached_max_iteration</code>

`complete()`

Tell if the stage is complete

Returns

converged bool
if the stage is complete

`converged()`

Tell if the stage is converged

Returns

converged bool
the convergence

`force_complete()`

For complete the stage

`get_reports()`

Return all exploration reports

Returns

reports List[ExplorationReport]
the reports

`next_iteration()`

Return the index of the next iteration

Returns

index int
the index of the next iteration

plan_next_iteration(*report: Optional[ExplorationReport] = None, trajs: Optional[List[Path]] = None*)
→ Tuple[bool, Optional[ExplorationTaskGroup], Optional[ConfSelector]]

Make the plan for the next iteration of the stage.

It checks the report of the current and all historical iterations of the stage, and tells if the iterations are converged. If not converged, it will plan the next iteration for the stage.

Parameters

hist_reports: List[ExplorationReport]
The historical exploration report of the stage. If this is the first iteration of the stage, this list is empty.

report

[ExplorationReport] The exploration report of this iteration.

confs: List[Path]

A list of configurations generated during the exploration. May be used to generate new configurations for the next iteration.

Returns**stg_complete: bool**

If the stage completed. Two cases may happen: 1. converged. 2. when not fatal_at_max, not converged but reached max number of iterations.

task: ExplorationTaskGroup

A *ExplorationTaskGroup* defining the exploration of the next iteration. Should be *None* if the stage is converged.

conf_selector: ConfSelector

The configuration selector for the next iteration. Should be *None* if the stage is converged.

reached_max_iteration()

dpgen2.exploration.scheduler.scheduler module**class dpgen2.exploration.scheduler.scheduler.ExplorationScheduler**

Bases: `object`

The exploration scheduler.

Methods

<code>add_stage_scheduler(stage_scheduler)</code>	Add stage scheduler.
<code>complete()</code>	Tell if all stages are converged.
<code>force_stage_complete()</code>	Force complete the current stage
<code>get_convergence_ratio()</code>	Get the accurate, candidate and failed ratios of the iterations
<code>get_iteration()</code>	Get the index of the current iteration.
<code>get_stage()</code>	Get the index of current stage.
<code>get_stage_of_iterations()</code>	Get the stage index and the index in the stage of iterations.
<code>plan_next_iteration([report, trajs])</code>	Make the plan for the next DPGEN iteration.

print_convergence	
--------------------------	--

print_last_iteration	
-----------------------------	--

add_stage_scheduler(stage_scheduler: StageScheduler)

Add stage scheduler.

All added schedulers can be treated as a *list* (order matters). Only one stage is converged, the iteration goes to the next iteration.

Parameters

stage_scheduler: StageScheduler

The added stage scheduler

complete()

Tell if all stages are converged.

force_stage_complete()

Force complete the current stage

get_convergence_ratio()

Get the accurate, candidate and failed ratios of the iterations

Returns**accu np.ndarray**

The accurate ratio. length of array the same as # iterations.

cand np.ndarray

The candidate ratio. length of array the same as # iterations.

fail np.ndarray

The failed ration. length of array the same as # iterations.

get_iteration()

Get the index of the current iteration.

Iteration index increase when *self.plan_next_iteration* returns valid *lmp_task_grp* and *conf_selector* for the next iteration.**get_stage()**

Get the index of current stage.

Stage index increases when the previous stage converges. Usually called after *self.plan_next_iteration*.**get_stage_of_iterations()**

Get the stage index and the index in the stage of iterations.

plan_next_iteration(*report: Optional[ExplorationReport] = None, trajs: Optional[List[Path]] = None*)
 → Tuple[bool, Optional[ExplorationTaskGroup], Optional[ConfSelector]]

Make the plan for the next DPGEN iteration.

Parameters**report**

[ExplorationReport] The exploration report of this iteration.

confs: List[Path]

A list of configurations generated during the exploration. May be used to generate new configurations for the next iteration.

Returns**complete: bool**

If all the DPGEN stages complete.

task: ExplorationTaskGroupA *ExplorationTaskGroup* defining the exploration of the next iteration. Should be *None* if converged.**conf_selector: ConfSelector**The configuration selector for the next iteration. Should be *None* if converged.

```
print_convergence()  
print_last_iteration(print_header=False)
```

dpgen2.exploration.scheduler.stage_scheduler module

```
class dpgen2.exploration.scheduler.stage_scheduler.StageScheduler
```

Bases: ABC

The scheduler for an exploration stage.

Methods

<code>complete()</code>	Tell if the stage is complete
<code>converged()</code>	Tell if the stage is converged
<code>force_complete()</code>	For complete the stage
<code>get_reports()</code>	Return all exploration reports
<code>next_iteration()</code>	Return the index of the next iteration
<code>plan_next_iteration(report, trajs)</code>	Make the plan for the next iteration of the stage.

```
abstract complete() → bool
```

Tell if the stage is complete

Returns

converged bool
if the stage is complete

```
abstract converged() → bool
```

Tell if the stage is converged

Returns

converged bool
the convergence

```
abstract force_complete()
```

For complete the stage

```
abstract get_reports() → List[ExplorationReport]
```

Return all exploration reports

Returns

reports List[ExplorationReport]
the reports

```
abstract next_iteration() → int
```

Return the index of the next iteration

Returns

index int
the index of the next iteration

abstract plan_next_iteration(*report*: ExplorationReport, *trajs*: List[Path]) → Tuple[bool, ExplorationTaskGroup, ConfSelector]

Make the plan for the next iteration of the stage.

It checks the report of the current and all historical iterations of the stage, and tells if the iterations are converged. If not converged, it will plan the next iteration for the stage.

Parameters

hist_reports: List[ExplorationReport]

The historical exploration report of the stage. If this is the first iteration of the stage, this list is empty.

report

[ExplorationReport] The exploration report of this iteration.

confs: List[Path]

A list of configurations generated during the exploration. May be used to generate new configurations for the next iteration.

Returns

stg_complete: bool

If the stage completed. Two cases may happen: 1. converged. 2. when not fatal_at_max, not converged but reached max number of iterations.

task: ExplorationTaskGroup

A *ExplorationTaskGroup* defining the exploration of the next iteration. Should be *None* if the stage is converged.

conf_selector: ConfSelector

The configuration selector for the next iteration. Should be *None* if the stage is converged.

dpgen2.exploration.selector package

Submodules

dpgen2.exploration.selector.conf_filter module

class dpgen2.exploration.selector.conf_filter.**ConfFilter**

Bases: ABC

Methods

<i>check</i> (coords, cell, atom_types, nopbc)	Check if the configuration is valid.
--	--------------------------------------

abstract check(*coords*: ndarray, *cell*: ndarray, *atom_types*: ndarray, *nopbc*: bool) → bool

Check if the configuration is valid.

Parameters

coords

[numpy.array] The coordinates, numpy array of shape natoms x 3

cell

[numpy.array] The cell tensor. numpy array of shape 3 x 3

atom_types

[numpy.array] The atom types. numpy array of shape natoms

nopbc

[bool] If no periodic boundary condition.

Returns**valid**

[bool] *True* if the configuration is a valid configuration, else *False*.

class `dpngen2.exploration.selector.conf_filter.ConfFilters`

Bases: `object`

Methods

add	
check	

add(*conf_filter*: `ConfFilter`) → `ConfFilters`

check(*conf*: `System`) → `bool`

dpngen2.exploration.selector.conf_selector module

class `dpngen2.exploration.selector.conf_selector.ConfSelector`

Bases: `ABC`

Select configurations from trajectory and model deviation files.

Methods

select	
---------------	--

abstract select(*trajs*: `List[Path]`, *model_devis*: `List[Path]`, *type_map*: `Optional[List[str]] = None`) → `Tuple[List[Path], ExplorationReport]`

dpngen2.exploration.selector.conf_selector_frame module

class `dpngen2.exploration.selector.conf_selector_frame.ConfSelectorFrames`(*traj_render*: `TrajRender`, *report*: `ExplorationReport`, *max_numb_sel*: `Optional[int] = None`, *conf_filters*: `Optional[ConfFilters] = None`)

Bases: *ConfSelector*

Select frames from trajectories as confs.

Parameters: `trust_level`: `TrustLevel`

The trust level

conf_filter: `ConfFilters`

The configuration filter

Methods

<code>select</code> (<code>trajs</code> , <code>model_devis</code> [, <code>type_map</code>])	Select configurations
---	-----------------------

select(*trajs*: `List[Path]`, *model_devis*: `List[Path]`, *type_map*: `Optional[List[str]] = None`) → `Tuple[List[Path], ExplorationReport]`

Select configurations

Parameters

trajs

`[List[Path]]` A *list* of *Path* to trajectory files generated by LAMMPS

model_devis

`[List[Path]]` A *list* of *Path* to model deviation files generated by LAMMPS. Format: each line has 7 numbers they are used as # `frame_id md_v_max md_v_min md_v_mean md_f_max md_f_min md_f_mean` where *md* stands for model deviation, *v* for virial and *f* for force

type_map

`[List[str]]` The *type_map* of the systems

Returns

confs

`[List[Path]]` The selected configurations, stored in a folder in `deepmd/npz` format, can be parsed as `dpdata.MultiSystems`. The *list* only has one item.

report

`[ExplorationReport]` The exploration report recoding the status of the exploration.

dpngen2.exploration.selector.trust_level module

class `dpngen2.exploration.selector.trust_level.TrustLevel`(*level_f_lo*, *level_f_hi*, *level_v_lo*=None, *level_v_hi*=None)

Bases: `object`

Attributes

`level_f_hi`

`level_f_lo`

`level_v_hi`

`level_v_lo`

```
property level_f_hi
property level_f_lo
property level_v_hi
property level_v_lo
```

dpgen2.exploration.task package

Subpackages

dpgen2.exploration.task.lmp package

Submodules

dpgen2.exploration.task.lmp.lmp_input module

```
dpgen2.exploration.task.lmp.lmp_input.make_lmp_input(conf_file: str, ensemble: str, graphs: List[str],
nsteps: int, dt: float, neidelay: Optional[int],
trj_freq: int, mass_map: List[float], temp:
float, tau_t: float = 0.1, pres: Optional[float] =
None, tau_p: float = 0.5, use_clusters: bool =
False, relative_f_epsilon: Optional[float] =
None, relative_v_epsilon: Optional[float] =
None, pka_e: Optional[float] = None,
ele_temp_f: Optional[float] = None,
ele_temp_a: Optional[float] = None, nopbc:
bool = False, max_seed: int = 1000000,
deepmd_version='2.0',
trj_seperate_files=True)
```

Submodules

dpgen2.exploration.task.conf_sampling_task_group module

```
class dpgen2.exploration.task.conf_sampling_task_group.ConfSamplingTaskGroup
```

```
    Bases: ExplorationTaskGroup
```

```
    Attributes
```

```
        task_list
```

```
            Get the list of ExplorationTask
```

Methods

<code>add_group(group)</code>	Add another group to the group.
<code>add_task(task)</code>	Add one task to the group.
<code>count(value)</code>	
<code>index(value, [start, [stop]])</code>	Raises <code>ValueError</code> if the value is not present.
<code>set_conf(conf_list[, n_sample, random_sample])</code>	Set the configurations of exploration

clear	
--------------	--

set_conf(*conf_list*: *List[str]*, *n_sample*: *Optional[int] = None*, *random_sample*: *bool = False*)

Set the configurations of exploration

Parameters

conf_list *str*

A list of file contents

n_sample *int*

Number of samples drawn from the conf list each time *make_task* is called. If set to *None*, *n_sample* is set to length of the *conf_list*.

random_sample *bool*

If true the confs are randomly sampled, otherwise are consecutively sampled from the *conf_list*

dpgen2.exploration.task.lmp_template_task_group module

class `dpgen2.exploration.task.lmp_template_task_group.LmpTemplateTaskGroup`

Bases: *ConfSamplingTaskGroup*

Attributes

task_list

Get the *list* of *ExplorationTask*

Methods

<code>add_group(group)</code>	Add another group to the group.
<code>add_task(task)</code>	Add one task to the group.
<code>count(value)</code>	
<code>index(value, [start, [stop]])</code>	Raises <code>ValueError</code> if the value is not present.
<code>set_conf(conf_list[, n_sample, random_sample])</code>	Set the configurations of exploration

clear	
make_conf	
make_task	
set_lmp	

make_cont(*templates: list, revisions: dict*)

make_task() → *ExplorationTaskGroup*

set_lmp(*numb_models: int, lmp_template_fname: str, plm_template_fname: Optional[str] = None, revisions: dict = {}, traj_freq: int = 10*) → *None*

`dpngen2.exploration.task.lmp_template_task_group.find_only_one_key(lmp_lines, key)`

`dpngen2.exploration.task.lmp_template_task_group.revise_by_keys(lmp_lines, keys, values)`

`dpngen2.exploration.task.lmp_template_task_group.revise_lmp_input_dump(lmp_lines, trj_freq)`

`dpngen2.exploration.task.lmp_template_task_group.revise_lmp_input_model(lmp_lines, task_model_list, trj_freq, deepmd_version='I')`

`dpngen2.exploration.task.lmp_template_task_group.revise_lmp_input_plm(lmp_lines, in_plm, out_plm='output.plumed')`

dpngen2.exploration.task.make_task_group_from_config module

`dpngen2.exploration.task.make_task_group_from_config.lmp_template_task_group_args()`

`dpngen2.exploration.task.make_task_group_from_config.make_task_group_from_config(numb_models, mass_map, config)`

`dpngen2.exploration.task.make_task_group_from_config.normalize(data)`

`dpngen2.exploration.task.make_task_group_from_config.npt_task_group_args()`

`dpngen2.exploration.task.make_task_group_from_config.task_group_args()`

`dpngen2.exploration.task.make_task_group_from_config.variant_task_group()`

dpngen2.exploration.task.npt_task_group module

class `dpngen2.exploration.task.npt_task_group.NPTTaskGroup`

Bases: *ConfSamplingTaskGroup*

Attributes

task_list

Get the *list* of *ExplorationTask*

Methods

<code>add_group(group)</code>	Add another group to the group.
<code>add_task(task)</code>	Add one task to the group.
<code>count(value)</code>	
<code>index(value, [start, [stop]])</code>	Raises ValueError if the value is not present.
<code>make_task()</code>	Make the LAMMPS task group.
<code>set_conf(conf_list[, n_sample, random_sample])</code>	Set the configurations of exploration
<code>set_md(numb_models, mass_map, temps[, ...])</code>	Set MD parameters

clear

`make_task()` → *ExplorationTaskGroup*

Make the LAMMPS task group.

Returns

task_grp: ExplorationTaskGroup

The returned lammmps task group. The number of tasks is $nconf * nT * nP$. $nconf$ is set by *n_sample* parameter of *set_conf*. nT and nP are lengths of the *temps* and *press* parameters of *set_md*.

`set_md(numb_models, mass_map, temps: List[float], press: Optional[List[float]] = None, ens: str = 'npt', dt: float = 0.001, nsteps: int = 1000, trj_freq: int = 10, tau_t: float = 0.1, tau_p: float = 0.5, pka_e: Optional[float] = None, neidelay: Optional[int] = None, no_pbc: bool = False, use_clusters: bool = False, relative_f_epsilon: Optional[float] = None, relative_v_epsilon: Optional[float] = None, ele_temp_f: Optional[float] = None, ele_temp_a: Optional[float] = None)`

Set MD parameters

dpgen2.exploration.task.stage module

`class dpgen2.exploration.task.stage.ExplorationStage`

Bases: `object`

The exploration stage.

Methods

<code>add_task_group(grp)</code>	Add an exploration group
<code>clear()</code>	Clear all exploration group.
<code>make_task()</code>	Make the LAMMPS task group.

`add_task_group(grp: ExplorationTaskGroup)`

Add an exploration group

Parameters

grp: ExplorationTaskGroup

The added exploration task group

clear()

Clear all exploration group.

make_task() → *ExplorationTaskGroup*

Make the LAMMPS task group.

Returns**task_grp: ExplorationTaskGroup**

The returned lammmps task group. The number of tasks is equal to the summation of task groups defined by all the exploration groups added to the stage.

dpngen2.exploration.task.task module**class dpngen2.exploration.task.task.ExplorationTask**

Bases: *object*

Define the files needed by an exploration task.

Examples

```
>>> # this example dumps all files needed by the task.
>>> files = exploration_task.files()
... for file_name, file_content in files.items():
...     with open(file_name, 'w') as fp:
...         fp.write(file_content)
```

Methods

<code>add_file(fname, fcont)</code>	Add file to the task
<code>files()</code>	Get all files for the task.

add_file(*fname: str, fcont: str*)

Add file to the task

Parameters**fname**

[str] The name of the file

fcont

[str] The content of the file.

files() → *Dict*

Get all files for the task.

Returns**files**

[dict] The dict storing all files for the task. The file name is a key of the dict, and the file content is the corresponding value.

```
class dpngen2.exploration.task.task.ExplorationTaskGroup
```

```
    Bases: Sequence
```

```
    A group of exploration tasks. Implemented as a list of ExplorationTask.
```

Attributes

```
    task_list
```

```
        Get the list of ExplorationTask
```

Methods

<code>add_group(group)</code>	Add another group to the group.
<code>add_task(task)</code>	Add one task to the group.
<code>count(value)</code>	
<code>index(value, [start, [stop]])</code>	Raises ValueError if the value is not present.

clear	
--------------	--

```
add_group(group: ExplorationTaskGroup)
```

```
    Add another group to the group.
```

```
add_task(task: ExplorationTask)
```

```
    Add one task to the group.
```

```
clear() → None
```

```
property task_list: List[ExplorationTask]
```

```
    Get the list of ExplorationTask
```

```
class dpngen2.exploration.task.task.FooTask(conf_name='conf.lmp', conf_cont="",
                                             inpu_name='in.lammps', inpu_cont="")
```

```
    Bases: ExplorationTask
```

Methods

<code>add_file(fname, fcont)</code>	Add file to the task
<code>files()</code>	Get all files for the task.

```
class dpngen2.exploration.task.task.FooTaskGroup(numb_task)
```

```
    Bases: ExplorationTaskGroup
```

Attributes

```
    task_list
```

```
        Get the list of ExplorationTask
```

Methods

<code>add_group(group)</code>	Add another group to the group.
<code>add_task(task)</code>	Add one task to the group.
<code>count(value)</code>	
<code>index(value, [start, [stop]])</code>	Raises ValueError if the value is not present.

<code>clear</code>	
--------------------	--

property task_list

Get the list of *ExplorationTask*

dpgen2.flow package

Submodules

dpgen2.flow.dpgen_loop module

```
class dpgen2.flow.dpgen_loop.ConcurrentLearning(name: str, block_op: OPTemplate, step_config: dict =
    {'continue_on_failed': False,
     'continue_on_num_success': None,
     'continue_on_success_ratio': None, 'executor': None,
     'parallelism': None, 'template_config': {'envs': None,
     'image': 'dptechnology/dpgen2:latest',
     'retry_on_transient_error': None, 'timeout': None,
     'timeout_as_transient_error': False}},
    upload_python_packages: Optional[List[PathLike]]
    = None)
```

Bases: [Steps](#)

Attributes

- `init_keys`
- `input_artifacts`
- `input_parameters`
- `loop_keys`
- `output_artifacts`
- `output_parameters`

Methods

<code>add(step)</code>	Add a step or a list of parallel steps to the steps
------------------------	---

<code>convert_to_argo</code>	
<code>handle_key</code>	
<code>run</code>	


```

property init_keys
property input_artifacts
property input_parameters
property loop_keys
property output_artifacts
property output_parameters

```

```

class dpngen2.flow.dpngen_loop.ConcurrentLearningLoop(name: str, block_op: OPTemplate, step_config:
    dict = {'continue_on_failed': False,
            'continue_on_num_success': None,
            'continue_on_success_ratio': None, 'executor':
            None, 'parallelism': None, 'template_config':
            {'envs': None, 'image':
            'dptechnology/dpngen2:latest',
            'retry_on_transient_error': None, 'timeout':
            None, 'timeout_as_transient_error': False}},
            upload_python_packages:
            Optional[List[PathLike]] = None)

```

Bases: `Steps`

Attributes

```

input_artifacts
input_parameters
keys
output_artifacts
output_parameters

```

Methods

add(step)	Add a step or a list of parallel steps to the steps
-----------	---

convert_to_argo	
handle_key	
run	

```

property input_artifacts
property input_parameters
property keys
property output_artifacts
property output_parameters

```

```

class dpngen2.flow.dpngen_loop.MakeBlockId(*args, **kwargs)

```

Bases: `OP`

Methods

<code>execute(ip)</code>	Run the OP
<code>get_input_sign()</code>	Get the signature of the inputs
<code>get_output_sign()</code>	Get the signature of the outputs

<code>exec_sign_check</code>	
<code>function</code>	
<code>get_info</code>	
<code>get_input_artifact_link</code>	
<code>get_input_artifact_storage_key</code>	
<code>get_opio_info</code>	
<code>get_output_artifact_link</code>	
<code>get_output_artifact_storage_key</code>	

`execute(ip: OPIO) → OPIO`

Run the OP

`classmethod get_input_sign()`

Get the signature of the inputs

`classmethod get_output_sign()`

Get the signature of the outputs

`class dpgen2.flow.dpgen_loop.SchedulerWrapper(*args, **kwargs)`

Bases: `OP`

Methods

<code>execute(ip)</code>	Run the OP
<code>get_input_sign()</code>	Get the signature of the inputs
<code>get_output_sign()</code>	Get the signature of the outputs

<code>exec_sign_check</code>	
<code>function</code>	
<code>get_info</code>	
<code>get_input_artifact_link</code>	
<code>get_input_artifact_storage_key</code>	
<code>get_opio_info</code>	
<code>get_output_artifact_link</code>	
<code>get_output_artifact_storage_key</code>	

`execute(ip: OPIO) → OPIO`

Run the OP

`classmethod get_input_sign()`

Get the signature of the inputs

`classmethod get_output_sign()`

Get the signature of the outputs

dpngen2.fp package

Submodules

dpngen2.fp.gaussian module

Prep and Run Gaussian tasks.

```
class dpngen2.fp.gaussian.GaussianInputs(**kwargs: Any)
```

Bases: `object`

Methods

<code>args()</code>	The arguments of the GaussianInputs class.
---------------------	--

```
static args() → List[Argument]
```

The arguments of the GaussianInputs class.

```
class dpngen2.fp.gaussian.PrepGaussian(*args, **kwargs)
```

Bases: `PrepFp`

Methods

<code>execute(ip)</code>	Execute the OP.
<code>get_input_sign()</code>	Get the signature of the inputs
<code>get_output_sign()</code>	Get the signature of the outputs
<code>prep_task(conf_frame, inputs)</code>	Define how one Gaussian task is prepared.

<code>exec_sign_check</code>	
<code>function</code>	
<code>get_info</code>	
<code>get_input_artifact_link</code>	
<code>get_input_artifact_storage_key</code>	
<code>get_opio_info</code>	
<code>get_output_artifact_link</code>	
<code>get_output_artifact_storage_key</code>	

```
prep_task(conf_frame: System, inputs: GaussianInputs)
```

Define how one Gaussian task is prepared.

Parameters

`conf_frame`

[dpdata.System] One frame of configuration in the dpdata format.

`inputs: GaussianInputs`

The GaussianInputs object handels all other input files of the task.

```
class dpngen2.fp.gaussian.RunGaussian(*args, **kwargs)
```

Bases: `RunFp`

Methods

<code>args()</code>	The argument definition of the <code>run_task</code> method.
<code>execute(ip)</code>	Execute the OP.
<code>get_input_sign()</code>	Get the signature of the inputs
<code>get_output_sign()</code>	Get the signature of the outputs
<code>input_files()</code>	The mandatory input files to run a Gaussian task.
<code>normalize_config([data, strict])</code>	Normalized the argument.
<code>optional_input_files()</code>	The optional input files to run a Gaussian task.
<code>run_task(command, out)</code>	Defines how one FP task runs

<code>exec_sign_check</code>	
<code>function</code>	
<code>get_info</code>	
<code>get_input_artifact_link</code>	
<code>get_input_artifact_storage_key</code>	
<code>get_opio_info</code>	
<code>get_output_artifact_link</code>	
<code>get_output_artifact_storage_key</code>	

static args() → List[Argument]

The argument definition of the `run_task` method.

Returns

arguments: List[dargs.Argument]

List of dargs.Argument defines the arguments of `run_task` method.

input_files() → List[str]

The mandatory input files to run a Gaussian task.

Returns

files: List[str]

A list of madatory input files names.

optional_input_files() → List[str]

The optional input files to run a Gaussian task.

Returns

files: List[str]

A list of optional input files names.

run_task(command: str, out: str) → Tuple[str, str]

Defines how one FP task runs

Parameters

command: str

The command of running gaussian task

out: str

The name of the output data file.

Returns

out_name: str

The file name of the output data in the dpdata.LabeledSystem format.

log_name: str

The file name of the log.

dpngen2.fp.prep_fp module

class dpngen2.fp.prep_fp.PrepFp(*args, **kwargs)

Bases: OP, ABC

Prepares the working directories for first-principles (FP) tasks.

A list of (same length as ip["confs"]) working directories containing all files needed to start FP tasks will be created. The paths of the directories will be returned as *op["task_paths"]*. The identities of the tasks are returned as *op["task_names"]*.

Methods

<i>execute</i> (ip)	Execute the OP.
<i>get_input_sign</i> ()	Get the signature of the inputs
<i>get_output_sign</i> ()	Get the signature of the outputs
<i>prep_task</i> (conf_frame, inputs)	Define how one FP task is prepared.

exec_sign_check	
function	
get_info	
get_input_artifact_link	
get_input_artifact_storage_key	
get_opio_info	
get_output_artifact_link	
get_output_artifact_storage_key	

execute(ip: OPIO) → OPIO

Execute the OP.

Parameters**ip**

[dict] Input dict with components:

- *config*: (dict) Should have *config['inputs']*, which defines the input files of the FP task.
- *confs*: (Artifact(List[Path])) Configurations for the FP tasks. Stored in folders as deepmd/npz format. Can be parsed as dpdata.MultiSystems.

Returns**op**

[dict] Output dict with components:

- *task_names*: (List[str]) The name of tasks. Will be used as the identities of the tasks. The names of different tasks are different.

- *task_paths*: (*Artifact(List[Path])*) The prepared working paths of the tasks. Contains all input files needed to start the FP. The order for the Paths should be consistent with *op["task_names"]*

classmethod `get_input_sign()`

Get the signature of the inputs

classmethod `get_output_sign()`

Get the signature of the outputs

abstract prep_task(*conf_frame*: *System*, *inputs*: *Any*)

Define how one FP task is prepared.

Parameters

conf_frame

[dpdata.System] One frame of configuration in the dpdata format.

inputs: Any

The class object handles all other input files of the task. For example, pseudopotential file, k-point file and so on.

dpngen2.fp.run_fp module

class `dpngen2.fp.run_fp.RunFp(*args, **kwargs)`

Bases: *OP*, *ABC*

Execute a first-principles (FP) task.

A working directory named *task_name* is created. All input files are copied or symbol linked to directory *task_name*. The FP command is executed from directory *task_name*. The *op["labeled_data"]* in “*deepmd/npz*” format (HF5 in the future) provided by *dpdata* will be created.

Methods

<code>args()</code>	The argument definition of the <i>run_task</i> method.
<code>execute(ip)</code>	Execute the OP.
<code>get_input_sign()</code>	Get the signature of the inputs
<code>get_output_sign()</code>	Get the signature of the outputs
<code>input_files()</code>	The mandatory input files to run a FP task.
<code>normalize_config([data, strict])</code>	Normalized the argument.
<code>optional_input_files()</code>	The optional input files to run a FP task.
<code>run_task(**kwargs)</code>	Defines how one FP task runs

<code>exec_sign_check</code>	
<code>function</code>	
<code>get_info</code>	
<code>get_input_artifact_link</code>	
<code>get_input_artifact_storage_key</code>	
<code>get_opio_info</code>	
<code>get_output_artifact_link</code>	
<code>get_output_artifact_storage_key</code>	

abstract static args() → List[Argument]

The argument definition of the *run_task* method.

Returns

arguments: List[dargs.Argument]

List of dargs.Argument defines the arguments of *run_task* method.

execute(ip: OPIO) → OPIO

Execute the OP.

Parameters

ip

[dict] Input dict with components:

- *config*: (dict) The config of FP task. Should have *config['run']*, which defines the runtime configuration of the FP task.
- *task_name*: (str) The name of task.
- *task_path*: (Artifact(Path)) The path that contains all input files prepared by *PrepFp*.

Returns

Output dict with components:

- *log*: (Artifact(Path)) **The log file of FP.**
- *labeled_data*: (Artifact(Path)) **The path to the labeled data in “deepmd/npz” format provided by *dpdata*.**

classmethod get_input_sign()

Get the signature of the inputs

classmethod get_output_sign()

Get the signature of the outputs

abstract input_files() → List[str]

The mandatory input files to run a FP task.

Returns

files: List[str]

A list of madatory input files names.

classmethod normalize_config(data: Dict = {}, strict: bool = True) → Dict

Normalized the argument.

Parameters

data: Dict

The input dict of arguments.

strict: bool

Strictly check the arguments.

Returns

data: Dict

The normalized arguments.

abstract optional_input_files() → List[str]

The optional input files to run a FP task.

Returns

files: List[str]

A list of optional input files names.

abstract run_task(kwargs)** → Tuple[str, str]

Defines how one FP task runs

Parameters

kwargs

Keyword args defined by the developer. The fp/run_config session of the input file will be passed to this function.

Returns

out_name: str

The file name of the output data. Should be in dpdata.LabeledSystem format.

log_name: str

The file name of the log.

dpngen2.fp.vasp module

class dpngen2.fp.vasp.PrepVasp(*args, **kwargs)

Bases: *PrepFp*

Methods

<code>execute(ip)</code>	Execute the OP.
<code>get_input_sign()</code>	Get the signature of the inputs
<code>get_output_sign()</code>	Get the signature of the outputs
<code>prep_task(conf_frame, vasp_inputs)</code>	Define how one Vasp task is prepared.

<code>exec_sign_check</code>	
<code>function</code>	
<code>get_info</code>	
<code>get_input_artifact_link</code>	
<code>get_input_artifact_storage_key</code>	
<code>get_opio_info</code>	
<code>get_output_artifact_link</code>	
<code>get_output_artifact_storage_key</code>	

prep_task(conf_frame: System, vasp_inputs: VaspInputs)

Define how one Vasp task is prepared.

Parameters

conf_frame

[dpdata.System] One frame of configuration in the dpdata format.

inputs: VaspInputs

The VaspInputs object handels all other input files of the task.

```
class dpngen2.fp.vasp.RunVasp(*args, **kwargs)
```

Bases: *RunFp*

Methods

<i>args</i> ()	The argument definition of the <i>run_task</i> method.
<i>execute</i> (ip)	Execute the OP.
<i>get_input_sign</i> ()	Get the signature of the inputs
<i>get_output_sign</i> ()	Get the signature of the outputs
<i>input_files</i> ()	The mandatory input files to run a vasp task.
<i>normalize_config</i> ([data, strict])	Normalized the argument.
<i>optional_input_files</i> ()	The optional input files to run a vasp task.
<i>run_task</i> (command, out, log)	Defines how one FP task runs

exec_sign_check	
function	
get_info	
get_input_artifact_link	
get_input_artifact_storage_key	
get_opio_info	
get_output_artifact_link	
get_output_artifact_storage_key	

static args()

The argument definition of the *run_task* method.

Returns

arguments: List[dargs.Argument]

List of dargs.Argument defines the arguments of *run_task* method.

input_files() → List[str]

The mandatory input files to run a vasp task.

Returns

files: List[str]

A list of madatory input files names.

optional_input_files() → List[str]

The optional input files to run a vasp task.

Returns

files: List[str]

A list of optional input files names.

run_task(command: str, out: str, log: str) → Tuple[str, str]

Defines how one FP task runs

Parameters

command: str
The command of running vasp task

out: str
The name of the output data file.

log: str
The name of the log file

Returns

out_name: str
The file name of the output data in the dpdata.LabeledSystem format.

log_name: str
The file name of the log.

dpngen2.fp.vasp_input module

```
class dpngen2.fp.vasp_input.VaspInputs(kspacing: Union[float, List[float]], incar: str, pp_files: Dict[str, str], kgamma: bool = True)
```

Bases: `object`

Attributes

incar_template
potcars

Methods

args	
incar_from_file	
make_kpoints	
make_potcar	
normalize_config	
potcars_from_file	

```
static args()
```

```
incar_from_file(fname: str)
```

```
property incar_template
```

```
make_kpoints(box: ndarray) → str
```

```
make_potcar(atom_names) → str
```

```
static normalize_config(data={}, strict=True)
```

```
property potcars
```

```
potcars_from_file(dict_fnames: Dict[str, str])
```

```
dpngen2.fp.vasp_input.make_kspacing_kpoints(box, kspacing, kgamma)
```

dpngen2.op package

Submodules

dpngen2.op.collect_data module

class dpngen2.op.collect_data.CollectData(*args, **kwargs)

Bases: OP

Collect labeled data and add to the iteration dataset.

After running FP tasks, the labeled data are scattered in task directories. This OP collect the labeled data in one data directory and add it to the iteration data. The data generated by this iteration will be place in *ip["name"]* subdirectory of the iteration data directory.

Methods

<i>execute(ip)</i>	Execute the OP.
<i>get_input_sign()</i>	Get the signature of the inputs
<i>get_output_sign()</i>	Get the signature of the outputs

exec_sign_check	
function	
get_info	
get_input_artifact_link	
get_input_artifact_storage_key	
get_opio_info	
get_output_artifact_link	
get_output_artifact_storage_key	

execute(*ip: OPIO*) → OPIO

Execute the OP. This OP collect data scattered in directories given by *ip['labeled_data']* in to one *dp-data.Multisystems* and store it in a directory named *name*. This directory is appended to the list *iter_data*.

Parameters

ip

[dict] Input dict with components:

- *name*: (*str*) The name of this iteration. The data generated by this iteration will be place in a sub-directory of *name*.
- *labeled_data*: (*Artifact(List[Path])*) The paths of labeled data generated by FP tasks of the current iteration.
- *iter_data*: (*Artifact(List[Path])*) The data paths previous iterations.

Returns

Output dict with components:

- *iter_data*: (*Artifact(List[Path])*) The data paths of previous and the current iteration data.

classmethod `get_input_sign()`

Get the signature of the inputs

classmethod `get_output_sign()`

Get the signature of the outputs

dpgen2.op.md_settings module

class `dpgen2.op.md_settings.MDSettings`(*ens: str, dt: float, nsteps: int, trj_freq: int, temps: Optional[List[float]] = None, press: Optional[List[float]] = None, tau_t: float = 0.1, tau_p: float = 0.5, pka_e: Optional[float] = None, neidelay: Optional[int] = None, no_pbc: bool = False, use_clusters: bool = False, relative_epsilon: Optional[float] = None, relative_v_epsilon: Optional[float] = None, ele_temp_f: Optional[float] = None, ele_temp_a: Optional[float] = None*)

Bases: `object`

Methods

<code>to_str</code>	
---------------------	--

`to_str()` → `str`

dpgen2.op.prep_dp_train module

class `dpgen2.op.prep_dp_train.PrepDPTrain`(*args, **kwargs)

Bases: `OP`

Prepares the working directories for DP training tasks.

A list of (*numb_models*) working directories containing all files needed to start training tasks will be created. The paths of the directories will be returned as `op["task_paths"]`. The identities of the tasks are returned as `op["task_names"]`.

Methods

<code>execute(ip)</code>	Execute the OP.
<code>get_input_sign()</code>	Get the signature of the inputs
<code>get_output_sign()</code>	Get the signature of the outputs

<code>exec_sign_check</code>	
function	
<code>get_info</code>	
<code>get_input_artifact_link</code>	
<code>get_input_artifact_storage_key</code>	
<code>get_opio_info</code>	
<code>get_output_artifact_link</code>	
<code>get_output_artifact_storage_key</code>	

execute(*ip*: *OPIO*) → *OPIO*

Execute the OP.

Parameters

ip

[dict] Input dict with components:

- *template_script*: (*str* or *List[str]*) A template of the training script. Can be a *str* or *List[str]*. In the case of *str*, all training tasks share the same training input template, the only difference is the random number used to initialize the network parameters. In the case of *List[str]*, one training task uses one template from the list. The random numbers used to initialize the network parameters are different. The length of the list should be the same as *numb_models*.
- *numb_models*: (*int*) Number of DP models to train.

Returns

op

[dict] Output dict with components:

- *task_names*: (*List[str]*) The name of tasks. Will be used as the identities of the tasks. The names of different tasks are different.
- *task_paths*: (*Artifact(List[Path])*) The prepared working paths of the tasks. The order for the Paths should be consistent with *op["task_names"]*

classmethod `get_input_sign()`

Get the signature of the inputs

classmethod `get_output_sign()`

Get the signature of the outputs

dpngen2.op.prep_lmp module

`dpngen2.op.prep_lmp.PrepExplorationTaskGroup`

alias of *PrepLmp*

class `dpngen2.op.prep_lmp.PrepLmp(*args, **kwargs)`

Bases: *OP*

Prepare the working directories for LAMMPS tasks.

A list of working directories (defined by *ip["task"]*) containing all files needed to start LAMMPS tasks will be created. The paths of the directories will be returned as *op["task_paths"]*. The identities of the tasks are returned as *op["task_names"]*.

Methods

<code>execute(ip)</code>	Execute the OP.
<code>get_input_sign()</code>	Get the signature of the inputs
<code>get_output_sign()</code>	Get the signature of the outputs

<code>exec_sign_check</code>	
<code>function</code>	
<code>get_info</code>	
<code>get_input_artifact_link</code>	
<code>get_input_artifact_storage_key</code>	
<code>get_opio_info</code>	
<code>get_output_artifact_link</code>	
<code>get_output_artifact_storage_key</code>	

execute(*ip*: *OPIO*) → *OPIO*

Execute the OP.

Parameters

ip

[dict] Input dict with components: - *Imp_task_grp* : (*Artifact(Path)*) Can be pickle loaded as a ExplorationTaskGroup. Definitions for LAMMPS tasks

Returns

op

[dict] Output dict with components:

- *task_names*: (*List[str]*) The name of tasks. Will be used as the identities of the tasks. The names of different tasks are different.
- *task_paths*: (*Artifact(List[Path])*) The prepared working paths of the tasks. Contains all input files needed to start the LAMMPS simulation. The order of the Paths should be consistent with *op*["*task_names*"]

classmethod `get_input_sign()`

Get the signature of the inputs

classmethod `get_output_sign()`

Get the signature of the outputs

dpgen2.op.run_dp_train module

class `dpgen2.op.run_dp_train.RunDPTrain(*args, **kwargs)`

Bases: *OP*

Execute a DP training task. Train and freeze a DP model.

A working directory named *task_name* is created. All input files are copied or symbol linked to directory *task_name*. The DeePMD-kit training and freezing commands are executed from directory *task_name*.

Methods

<code>execute(ip)</code>	Execute the OP.
<code>get_input_sign()</code>	Get the signature of the inputs
<code>get_output_sign()</code>	Get the signature of the outputs

<code>decide_init_model</code>	
<code>exec_sign_check</code>	
<code>function</code>	
<code>get_info</code>	
<code>get_input_artifact_link</code>	
<code>get_input_artifact_storage_key</code>	
<code>get_opio_info</code>	
<code>get_output_artifact_link</code>	
<code>get_output_artifact_storage_key</code>	
<code>normalize_config</code>	
<code>skip_training</code>	
<code>training_args</code>	
<code>write_data_to_input_script</code>	
<code>write_other_to_input_script</code>	

`static decide_init_model(config, init_model, init_data, iter_data)`

`execute(ip: OPIO) → OPIO`

Execute the OP.

Parameters

ip

[dict] Input dict with components:

- *config*: (*dict*) The config of training task. Check *RunDPTrain.training_args* for definitions.
- *task_name*: (*str*) The name of training task.
- *task_path*: (*Artifact(Path)*) The path that contains all input files prepared by *PrepDPTrain*.
- *init_model*: (*Artifact(Path)*) A frozen model to initialize the training.
- *init_data*: (*Artifact(List[Path])*) Initial training data.
- *iter_data*: (*Artifact(List[Path])*) Training data generated in the DPGEN iterations.

Returns

Output dict with components:

- *script*: (*Artifact(Path)*) The training script.
- *model*: (*Artifact(Path)*) The trained frozen model.
- *lcurve*: (*Artifact(Path)*) The learning curve file.
- *log*: (*Artifact(Path)*) The log file of training.

```

classmethod get_input_sign()
    Get the signature of the inputs
classmethod get_output_sign()
    Get the signature of the outputs
static normalize_config(data={})
static skip_training(work_dir, train_dict, init_model, iter_data)
static training_args()
static write_data_to_input_script(idict: dict, init_data: List[Path], iter_data: List[Path],
    auto_prob_str: str = 'prob_sys_size', major_version: str = '1')
static write_other_to_input_script(idict, config, do_init_model, major_version: str = '1')
dpgen2.op.run_dp_train.config_args()

```

dpgen2.op.run_lmp module

```
class dpgen2.op.run_lmp.RunLmp(*args, **kwargs)
```

Bases: *OP*

Execute a LAMMPS task.

A working directory named *task_name* is created. All input files are copied or symbol linked to directory *task_name*. The LAMMPS command is executed from directory *task_name*. The trajectory and the model deviation will be stored in files *op["traj"]* and *op["model_devi"]*, respectively.

Methods

<i>execute</i>(ip)	Execute the OP.
<i>get_input_sign</i>()	Get the signature of the inputs
<i>get_output_sign</i>()	Get the signature of the outputs

exec_sign_check	
function	
get_info	
get_input_artifact_link	
get_input_artifact_storage_key	
get_opio_info	
get_output_artifact_link	
get_output_artifact_storage_key	
lmp_args	
normalize_config	

execute(ip: *OPIO*) → *OPIO*

Execute the OP.

Parameters

ip

[dict] Input dict with components:

- *config*: (*dict*) The config of lmp task. Check *RunLmp.lmp_args* for definitions.
- *task_name*: (*str*) The name of the task.
- *task_path*: (*Artifact(Path)*) The path that contains all input files prepared by *PrepLmp*.
- *models*: (*Artifact(List[Path])*) The frozen model to estimate the model deviation. The first model with be used to drive molecular dynamics simulation.

Returns

Output dict with components:

- *log*: (*Artifact(Path)*) **The log file of LAMMPS.**
- *traj*: (*Artifact(Path)*) **The output trajectory.**
- *model_devi*: (*Artifact(Path)*) **The model deviation. The order of recorded model deviations should be consistent with the order of frames in *traj*.**

classmethod `get_input_sign()`

Get the signature of the inputs

classmethod `get_output_sign()`

Get the signature of the outputs

static `lmp_args()`

static `normalize_config(data={})`

`dpngen2.op.run_lmp.config_args()`

dpngen2.op.select_confs module

class `dpngen2.op.select_confs.SelectConfs(*args, **kwargs)`

Bases: `OP`

Select configurations from exploration trajectories for labeling.

Methods

<code>execute(ip)</code>	Execute the OP.
<code>get_input_sign()</code>	Get the signature of the inputs
<code>get_output_sign()</code>	Get the signature of the outputs

<code>exec_sign_check</code>	
<code>function</code>	
<code>get_info</code>	
<code>get_input_artifact_link</code>	
<code>get_input_artifact_storage_key</code>	
<code>get_opio_info</code>	
<code>get_output_artifact_link</code>	
<code>get_output_artifact_storage_key</code>	

`execute(ip: OPIO) → OPIO`

Execute the OP.

Parameters

ip

[dict] Input dict with components:

- `conf_selector`: (*ConfSelector*) Configuration selector.
- `type_map`: (*List[str]*) The type map.
- `trajs`: (*Artifact(List[Path])*) The trajectories generated in the exploration.
- `model_devis`: (*Artifact(List[Path])*) The file storing the model deviation of the trajectory. The order of model deviation storage is consistent with that of the trajectories. The order of frames of one model deviation storage is also consistent with that of the corresponding trajectory.

Returns

Output dict with components:

- `report`: (*ExplorationReport*) The report on the exploration.
- `conf`: (*Artifact(List[Path])*) The selected configurations.

`classmethod get_input_sign()`

Get the signature of the inputs

`classmethod get_output_sign()`

Get the signature of the outputs

[dpgen2.superop package](#)

[Submodules](#)

[dpgen2.superop.block module](#)

```

class dpngen2.superop.block.ConcurrentLearningBlock(name: str, prep_run_dp_train_op: OPTemplate,
                                                    prep_run_lmp_op: OPTemplate, select_confs_op:
                                                    OP, prep_run_fp_op: OPTemplate,
                                                    collect_data_op: OP, select_confs_config: dict =
                                                    {'continue_on_failed': False,
                                                    'continue_on_num_success': None,
                                                    'continue_on_success_ratio': None, 'executor':
                                                    None, 'parallelism': None, 'template_config':
                                                    {'envs': None, 'image':
                                                    'dptechnology/dpugen2:latest',
                                                    'retry_on_transient_error': None, 'timeout': None,
                                                    'timeout_as_transient_error': False}},
                                                    collect_data_config: dict = {'continue_on_failed':
                                                    False, 'continue_on_num_success': None,
                                                    'continue_on_success_ratio': None, 'executor':
                                                    None, 'parallelism': None, 'template_config':
                                                    {'envs': None, 'image':
                                                    'dptechnology/dpugen2:latest',
                                                    'retry_on_transient_error': None, 'timeout': None,
                                                    'timeout_as_transient_error': False}},
                                                    upload_python_packages:
                                                    Optional[List[PathLike]] = None)

```

Bases: `Steps`

Attributes

input_artifacts
input_parameters
keys
output_artifacts
output_parameters

Methods

add(step)	Add a step or a list of parallel steps to the steps
-----------	---

convert_to_argo	
handle_key	
run	

property input_artifacts
property input_parameters
property keys
property output_artifacts
property output_parameters

dpngen2.superop.prep_run_dp_train module

```

class dpngen2.superop.prep_run_dp_train.PrepRunDPTrain(name: str, prep_train_op: OP, run_train_op:
    OP, prep_config: dict =
        {'continue_on_failed': False,
         'continue_on_num_success': None,
         'continue_on_success_ratio': None,
         'executor': None, 'parallelism': None,
         'template_config': {'envs': None, 'image':
            'dptechnology/dpugen2:latest',
            'retry_on_transient_error': None, 'timeout':
            None, 'timeout_as_transient_error': False}},
    run_config: dict = {'continue_on_failed':
        False, 'continue_on_num_success': None,
        'continue_on_success_ratio': None,
        'executor': None, 'parallelism': None,
        'template_config': {'envs': None, 'image':
            'dptechnology/dpugen2:latest',
            'retry_on_transient_error': None, 'timeout':
            None, 'timeout_as_transient_error': False}},
    upload_python_packages:
        Optional[List[PathLike]] = None)

```

Bases: `Steps`**Attributes**

input_artifacts
input_parameters
keys
output_artifacts
output_parameters

Methods

<code>add(step)</code>	Add a step or a list of parallel steps to the steps
------------------------	---

convert_to_argo	
handle_key	
run	

property `input_artifacts`
property `input_parameters`
property `keys`
property `output_artifacts`
property `output_parameters`

dpngen2.superop.prep_run_fp module

```
class dpngen2.superop.prep_run_fp.PrepRunFp(name: str, prep_op: OP, run_op: OP, prep_config: dict =
    {'continue_on_failed': False, 'continue_on_num_success':
    None, 'continue_on_success_ratio': None, 'executor': None,
    'parallelism': None, 'template_config': {'envs': None,
    'image': 'dptechnology/dpugen2:latest',
    'retry_on_transient_error': None, 'timeout': None,
    'timeout_as_transient_error': False}}, run_config: dict =
    {'continue_on_failed': False, 'continue_on_num_success':
    None, 'continue_on_success_ratio': None, 'executor': None,
    'parallelism': None, 'template_config': {'envs': None,
    'image': 'dptechnology/dpugen2:latest',
    'retry_on_transient_error': None, 'timeout': None,
    'timeout_as_transient_error': False}},
    upload_python_packages: Optional[List[PathLike]] =
    None)
```

Bases: `Steps`**Attributes**

`input_artifacts`
`input_parameters`
`keys`
`output_artifacts`
`output_parameters`

Methods

<code>add(step)</code>	Add a step or a list of parallel steps to the steps
------------------------	---

<code>convert_to_argo</code>	
<code>handle_key</code>	
<code>run</code>	

`property input_artifacts`
`property input_parameters`
`property keys`
`property output_artifacts`
`property output_parameters`

dpngen2.superop.prep_run_lmp module

```
class dpngen2.superop.prep_run_lmp.PrepRunLmp(name: str, prep_op: OP, run_op: OP, prep_config: dict =
    {'continue_on_failed': False, 'continue_on_num_success':
    None, 'continue_on_success_ratio': None, 'executor':
    None, 'parallelism': None, 'template_config': {'envs':
    None, 'image': 'dptechnology/dpugen2:latest',
    'retry_on_transient_error': None, 'timeout': None,
    'timeout_as_transient_error': False}}, run_config: dict =
    {'continue_on_failed': False, 'continue_on_num_success':
    None, 'continue_on_success_ratio': None, 'executor':
    None, 'parallelism': None, 'template_config': {'envs':
    None, 'image': 'dptechnology/dpugen2:latest',
    'retry_on_transient_error': None, 'timeout': None,
    'timeout_as_transient_error': False}},
    upload_python_packages: Optional[List[PathLike]] =
    None)
```

Bases: Steps

Attributes

- input_artifacts**
- input_parameters**
- keys**
- output_artifacts**
- output_parameters**

Methods

add(step)	Add a step or a list of parallel steps to the steps
-----------	---

convert_to_argo	
handle_key	
run	

- property **input_artifacts**
- property **input_parameters**
- property **keys**
- property **output_artifacts**
- property **output_parameters**

dpgen2.utils package

Submodules

dpgen2.utils.bohrium_config module

dpgen2.utils.bohrium_config.**bohrium_config_from_dict**(*bohrium_config*)

dpgen2.utils.chdir module

dpgen2.utils.chdir.**chdir**(*path_key: str*)

Returns a decorator that can change the current working path.

Parameters

path_key
[str] key to OPIO

Examples

```

>>> class SomeOP(OP):
...     @chdir("path")
...     def execute(self, ip: OPIO):
...         do_something()

```

dpgen2.utils.chdir.**set_directory**(*path: Path*)

Sets the current working path within the context.

Parameters

path
[Path] The path to the cwd

Yields

None

Examples

```

>>> with set_directory("some_path"):
...     do_something()

```

dpgen2.utils.dflow_config module

dpgen2.utils.dflow_config.**dflow_config**(*config_data*)

set the dflow config by *config_data*

the keys starting with “s3_” will be treated as s3_config keys, other keys are treated as config keys.

dpgen2.utils.dflow_config.**dflow_config_lower**(*dflow_config*)

`dpngen2.utils.dflow_config.dflow_s3_config(config_data)`

set the s3 config by `config_data`

`dpngen2.utils.dflow_config.dflow_s3_config_lower(dflow_s3_config_data)`

`dpngen2.utils.dflow_config.workflow_config_from_dict(wf_config)`

dpngen2.utils.dflow_query module

`dpngen2.utils.dflow_query.find_slice_ranges(keys: List[str], sliced_subkey: str)`

find range of sliced OPs that matches the pattern `'iter-[0-9]*-{sliced_subkey}-[0-9]*'`

`dpngen2.utils.dflow_query.get_all_schedulers(wf: Any, keys: List[str])`

get the output Scheduler of the all the iterations

`dpngen2.utils.dflow_query.get_iteration(key: str)`

`dpngen2.utils.dflow_query.get_last_iteration(keys: List[str])`

get the index of the last iteration from a list of step keys.

`dpngen2.utils.dflow_query.get_last_scheduler(wf: Any, keys: List[str])`

get the output Scheduler of the last successful iteration

`dpngen2.utils.dflow_query.get_subkey(key: str, idx: int = -1)`

`dpngen2.utils.dflow_query.matched_step_key(all_keys: List[str], step_keys: Optional[List[str]] = None)`

returns the keys in `all_keys` that matches any of the `step_keys`

`dpngen2.utils.dflow_query.print_keys_in_nice_format(keys: List[str], sliced_subkey: List[str],
idx_fmt_len: int = 8)`

`dpngen2.utils.dflow_query.sort_slice_ops(keys: List[str], sliced_subkey: List[str])`

sort the keys of the sliced ops. the keys of the sliced ops contains `sliced_subkey`

dpngen2.utils.download_dpngen2_artifacts module

class `dpngen2.utils.download_dpngen2_artifacts.DownloadDefinition`

Bases: `object`

Methods

add_def	
add_input	
add_output	

add_def(*tdict*, *key*, *suffix=None*)

add_input(*input_key*, *suffix=None*)

add_output(*output_key*, *suffix=None*)

`dpngen2.utils.download_dpngen2_artifacts.download_dpngen2_artifacts(wf: Workflow, key: str, prefix: Optional[str] = None, chk_pnt: bool = False)`

download the artifacts of a step. the key should be of format 'iter-xxxxxx-subkey-of-step-xxxxxx' the input and output artifacts will be downloaded to prefix/iter-xxxxxx/key-of-step/inputs/ and prefix/iter-xxxxxx/key-of-step/outputs/

the downloaded input and output artifacts of steps are defined by `op_download_setting`

dpngen2.utils.obj_artifact module

`dpngen2.utils.obj_artifact.dump_object_to_file(obj, fname)`

pickle dump object to a file

`dpngen2.utils.obj_artifact.load_object_from_file(fname)`

pickle load object from a file

dpngen2.utils.run_command module

`dpngen2.utils.run_command.run_command(cmd: Union[str, List[str]], shell: bool = False) → Tuple[int, str, str]`

dpngen2.utils.step_config module

`dpngen2.utils.step_config.dispatcher_args()`

free style dispatcher args

`dpngen2.utils.step_config.gen_doc(*, make_anchor=True, make_link=True, **kwargs)`

`dpngen2.utils.step_config.init_executor(executor_dict)`

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